

SE-330HV MANUAL NEUTRAL-GROUNDING-RESISTOR MONITOR

REVISION 5-M-101817

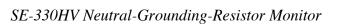


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Document Number: PM-1215-EN

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1. GENERAL

1.1 Modern Resistance-Grounded Systems

A high-resistance-grounded system uses a neutral-grounding resistor (NGR) with a low let-through current to limit ground-fault current. This is an improvement over low-resistance or solidly-grounded systems because, in those systems, a ground-fault flash hazard exists and a ground fault can result in substantial point-of-fault damage. High-resistance grounding eliminates these problems and modern ground-fault protection operates reliably at low current levels. Furthermore, the probability of an arc-flash incident is significantly reduced in a high-resistance-grounded system.

NGR selection depends on system charging current and whether the system is an alarm-only or a tripping system. Alarm-only systems are usually restricted to system voltages up to 5 kV with NGR let-through currents of 5 A or less. Occasionally, alarm-only systems up to 15 kV and up to 10 A are used; however, they are not common because a ground fault on such a system tends to escalate to a phase-to-phase fault before the ground fault can be located and cleared. Consult CEC 10-1102, NEC 250.36, and NEC 250.186 for application details.

System charging current is the capacitive current that flows to ground when a bolted ground fault occurs. This current can be calculated or measured. For small systems, the magnitude of charging current can be conservatively estimated as ½ A per 1,000 kVA on low-voltage systems and 1 A per 1,000 kVA on medium-voltage systems.

In an alarm-only system or in a tripping system without selective coordination, choose an NGR with a let-through current larger than the system charging current and set the pick-up current of ground-fault devices at or below 50% of the NGR let-through current.

In a tripping system with selective coordination, use ground-fault devices with a definite-time characteristic to achieve time coordination. Use the same pick-up current for all ground-fault devices—this value must be larger than the charging current of the largest feeder. Select an NGR with a let-through current between five and 10 times the pick-up current of the ground-fault devices.

Do not use a grounding transformer with a low-voltage resistor:

- The combined cost of a transformer and a lowvoltage resistor is more than the cost of a resistor rated for line-to-neutral voltage.
- A transformer saturated by a ground fault through a rectifier can make ground-fault protection inoperative.
- Transformer inrush current up to 12 times rated current can cause a ground-fault voltage larger than expected.
- A parallel transformer winding makes it difficult to monitor NGR continuity.

 A transformer can provide the inductance necessary to cause ferroresonance if the NGR opens.

Following these guidelines will reduce the flash hazard, reduce point-of-fault damage, achieve reliable ground-fault protection, and ensure a stable system not subject to ferroresonance.

1.2 SE-330HV NGR MONITORING

The SE-330HV is a microprocessor-based neutral-grounding-resistor monitor that detects NGR failures and ground faults in resistance-grounded systems. The SE-330HV measures NGR resistance, NGR current, and transformer or generator neutral-to-ground voltage. The components required to monitor an NGR are an SE-330HV, a 100- or 200-k Ω ER-series sensing resistor, and a current transformer (CT).

Power-circuit elements, other than neutral-connected NGR's, that purposefully connect the power system to ground are often not compatible with SE-330HV NGR monitoring. These elements include single-phase grounding transformers, grounded-wye-primary potential transformers (PT's), and grounded-wye-primary power transformers.

SE-330HV continuously measures NGR resistance in an unfaulted system. It will trip on resistor fault if NGR resistance varies from its calibrated value. When a ground fault occurs, voltage is present on the neutral and NGR current will flow if the NGR is healthy. The SE-330HV will trip on ground fault if fault current exceeds the GF TRIP LEVEL setting for an interval equal to the GF TRIP TIME setting. However, if the NGR fails open during a ground fault, it is possible for fault resistance to satisfy the NGR resistance measurement. To detect this double-fault condition, the SE-330HV measures neutral voltage. If neutral voltage exceeds the V_N TRIP LEVEL setting, and if NGR current is less than 5% of the current transformer (CT) rating, the SE-330HV will trip on resistor fault. If the resistor-fault circuit is tripped and the neutral voltage exceeds the V_N TRIP LEVEL setting for an interval greater than the GF TRIP TIME setting, the ground-fault circuit will also trip.

Ground-fault current is sensed by a CT with a 1- or 5-A secondary, or by a CT (EFCT-x or SE-CS30-x) with a 50-mA secondary. The trip level of the ground-fault circuit is adjustable from 2 to 100% of the CT rating and trip time is adjustable from 0.1 to 10.0 seconds.

The SE-330HV has four output relays. Relay K1 is the trip relay. Relays K2 and K3 provide ground-fault and resistor-fault indication. K4 is a solid-state relay that provides UNIT HEALTHY indication. Relay K1 will operate on either a resistor fault or a ground fault, and it can be set to operate in the fail-safe or non-fail-safe mode for undervoltage or shunt-trip applications.



Additional features include LED trip indication, trip memory, front-panel and remote reset, 4-20-mA analog output, trip event recorder, USB local communications, microSD $^{\text{TM}}$ data logging, and optional network communications.

The SE-330HV provides the following additional features:

- When the trip level is set to MEM, the ground-fault trip setting is defined by an internal non-volatile memory variable. Range is 2 to 100% in 1% increments of the CT-primary rating.
- Indication relays can be set to fail-safe or non-fail-safe.
- The number of trip records has been increased to 100 and includes date and time stamping.
- A microSD[™] card interface can be used for longterm data logging and firmware updates. A microSD[™] card and a microSD-to-SD adapter is included. See Section 4.1.
- For ease of connection to new devices, the RS-232 interface has been replaced by a Mini B USB port.
- Dual Ethernet ports are available with support for fiber-optic and RJ45 interfaces.
- The IEC 61850 protocol has been added.

TABLE 1. TYPICAL VALUES FOR TRIPPING SYSTEMS

| SYSTEM VOLTAGE (LINE-LINE) | NEUTRAL-GROUNDING RESISTOR | | | NSING SISTOR | GROUND- FAULT TRIP LEVEL | V _N TRIP LEVEL |
|----------------------------------|-------------------------------|----------------------|---------|--------------------------------------|--------------------------------|------------------------------|
| (VOLTS) | CURRENT (AMPERES) | RESISTANCE (OHMS) | MODEL | RESISTANCE (SWITCH S5 SETTING) | (AMPERES) | (VOLTS) |
| 7,200 | 15 | 277 | ER-15KV | 100 kΩ | 3.0 | 850 |
| 14,400 | 15 | 554 | ER-15KV | 100 kΩ | 3.0 | 1,700 |
| 7,200 | 25 | 166 | ER-15KV | $100 \mathrm{k}\Omega$ | 5.0 | 850 |
| 14,400 | 25 | 332 | ER-15KV | 100 kΩ | 5.0 | 1,700 |
| 25,000 | 25 | 577 | ER-25KV | $100 \mathrm{k}\Omega$ | 5.0 | 4,000 |
| 35,000 | 25 | 808 | ER-35KV | 100 kΩ | 5.0 | 6,000 |
| 72,000 | 100 | 420 | ER-72KV | $200~\mathrm{k}\Omega$ | 20.0 | $6,000 \times 2 = 12,000$ |

TABLE 2. GROUND-FAULT TRIP LEVELS FOR SELECTED CT'S

| GF TRIP LEVEL ⁽¹⁾ | EFCT-X 5:0.05 | SE-CS30-X 30:0.05 | 50:1 50:5 | 100:1 100:5 | 200:1 200:5 | 400:1 400:5 |
|---------------------------------|------------------|----------------------|--------------|----------------|----------------|----------------|
| (%) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) | (AMPERES) |
| 2 | 0.10 | 0.60 | * | * | * | * |
| 4 | 0.20 | 1.20 | * | * | * | 16 |
| 6 | 0.30 | 1.80 | * | * | 12 | 24 |
| 8 | 0.40 | 2.40 | * | 8 | 16 | 36 |
| 10 | 0.50 | 3.00 | 5 | 10 | 20 | 40 |
| 20 | 1.00 | 6.00 | 10 | 20 | 40 | 80 |
| 40 | 2.00 | 12.0 | 20 | 40 | 80 | 160 |
| 60 | 3.00 | 18.0 | 30 | 60 | 120 | 240 |
| 80 | 4.00 | 24.0 | 40 | 80 | 160 | 320 |
| 100 | 5.00 | 30.0 | 50 | 100 | 200 | 400 |

⁽¹⁾ When set to MEM, range is 2 to 100% in 1% increments.

^{*} Setting not recommended.



2. OPERATION

2.1 SETTINGS

2.1.1 GF TRIP TIME

GF TRIP TIME (definite time) is adjustable from 0.1 to 10.0 seconds. Time-coordinated ground-fault protection requires this setting to be longer than the trip times of downstream ground-fault devices.

A trip-time accumulator provides a ground-fault memory function for detection of intermittent faults. The accumulated time increases when a ground fault is detected and decreases when a ground fault is not detected. A trip will eventually occur when the time for fault current above the trip level is greater than the time for fault current below the trip level.

2.1.2 GF TRIP LEVEL

The SE-330HV uses a Discrete-Fourier Transform (DFT) Algorithm to measure the fundamental component of NGR current.

Choose an NGR let-through current and a ground-fault trip level according to the guidelines in Section 1.1. Set the ground-fault trip level as a percentage (2 to 100) of the CT-primary rating. When the GF Trip Level is set to MEM, the ground-fault setting stored in non-volatile memory is used. This parameter must be set using a PC running the SE-MON330 software connected to the USB interface. The setting range is 2 to 100% of CT primary rating in 1% increments. The default value is 15%. Inputs are provided for 5-, 1-, and 0.05-A-secondary CT's. Typical values for 15-, 25-, and 100-A tripping systems are shown in Table 1. Ground-fault trip levels for selected CT's are shown in Table 2. Refer to NGR Monitor Set-Point Assistant at www.littelfuse.com/relayscontrols for other systems. The Set-Point Assistant is included with the SE-MON330 software.

2.1.3 V_N TRIP LEVEL

The SE-330HV uses a DFT algorithm to measure the fundamental component of neutral voltage (V_N) .

If neutral voltage is greater than the V_N TRIP LEVEL setting for the duration of the resistor-fault trip time and ground-fault current is less than 5% of the CT rating, the SE-330HV will trip on resistor fault. If the resistor-fault circuit is tripped and the neutral voltage exceeds the V_N TRIP LEVEL setting for an interval greater than the GF TRIP TIME setting, the ground-fault circuit will also trip.

The V_N TRIP LEVEL range is 100 to 10,000 V with switch S5 in the 100-k Ω (Vx1) position, and the range is 200 to 20,000 V with switch S5 in the 200-k Ω (Vx2) position. Calculate the voltage across the NGR when NGR current is equal to the pick-up current of the ground-fault circuit. Set the V_N TRIP LEVEL at the next largest value. See Fig. 1 and Section 2.1.4.4.

Typical values for 15-, 25- and 100-A tripping systems are shown in Table 1. Refer to the NGR Monitor Set-Point Assistant at www.littelfuse.com/relayscontrols for other systems.

NOTE: A resistor-fault trip is held off if the ground-fault current is above 5% of the CT rating.

2.1.4 CONFIGURATION SETTINGS

Eight configuration switches (S1 to S8) and a calibration button are located behind the access cover on the front panel. See Fig. 1.

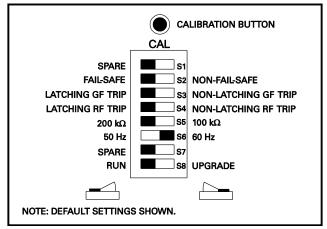


FIGURE 1. Configuration Switches.

2.1.4.1 TRIP-RELAY MODE AND TRIP-MEMORY MODE (S2)

Set switch S2 to select the operating mode of trip relay K1. In the non-fail-safe mode, relay K1 energizes and its contact closes when a trip occurs. The non-fail-safe mode can be used to trip shunt-trip circuit breakers. In the non-fail-safe mode, SE-330HV trips are reset when supply voltage is cycled.

In the fail-safe mode, relay K1 energizes and its contact closes if there are no trips. Contacts open if there is a trip, a loss of supply voltage, or a processor failure. In the fail-safe mode, SE-330HV trips are not reset when supply voltage is cycled.

NOTE: Switch S2 does not affect the operating modes of relays K2, K3, and K4.

2.1.4.2 GROUND-FAULT-TRIP LATCH (S3)

Set switch S3 to select latching or non-latching ground-fault-circuit operation. Non-latching operation defeats ground-fault trip-memory. See Section 2.3.

2.1.4.3 RESISTOR-FAULT-TRIP LATCH (S4)

Set switch S4 to select latching or non-latching resistor-fault-circuit operation. Non-latching operation defeats resistor-fault trip-memory. See Section 2.3

2.1.4.4 SENSING-RESISTOR SELECTION (S5)

Set switch S5 to the resistance of the sensing resistor. For the ER-15KV, ER-25KV, and ER-35KV, select 100 k Ω . For the ER-1000HV and ER-72KV, select 200 k Ω . Switch S5 sets the resistor-fault trip value and the V $_{\rm N}$ TRIP LEVEL range. See Section 2.1.3.



2.1.4.5 FREQUENCY (S6)

Set switch S6 to 50 or 60 Hz to tune the digital filter to the line frequency of the monitored system.

2.1.4.6 UPGRADE MODE (S8)

The microSDTM card is used for firmware upgrades. See Section 4.1.2 for upgrade instructions.

NOTE: An upgrade causes an SE-330HV restart and this may cycle the output relays.

2.1.5 RESISTOR-FAULT TRIP TIME

The resistor-fault trip time can be adjusted from 12 (default) to 60 seconds using the SE-MON330 software or via network communications.

2.1.6 RESISTOR-FAULT TRIP LEVEL

The resistor-fault trip level can be adjusted using the SE-MON330 software or via network communications. See Section 6.1.

2.1.7 GEO-MAGNETIC FILTER

A low-frequency ground current can be caused by the Earth's magnetic field and from charged clouds passing overhead during a thunderstorm. In some rare conditions, this can cause a false resistor-fault trip. Enabling the geomagnetic filter and increasing the resistor-fault trip time can help counteract these effects.

A trip time of 30 seconds is recommended when the geo-magnetic filter is enabled.

The geo-magnetic filter is disabled by default, but can be enabled using the SE-MON330 software or via network communications.

2.2 CALIBRATION

The SE-330HV measures the resistance change of the NGR relative to the NGR-resistance value determined at the time of calibration. When the resistance change is greater than a threshold amount (2,500 Ω for 100-k Ω systems, 5,000 Ω for 200-k Ω systems), a resistor-fault trip occurs. Calibrate the SE-330HV on new installations, if the NGR is changed, or if the sensing resistor is changed.

NOTE: If the SE-330HV is not calibrated and is supplied from the load side of the breaker (non-fail-safe mode), calibrate within the resistor-fault trip time after power-up or it may trip and interrupt its supply. See Section 2.1.5.

The CALIBRATION button is located behind the access cover on the front panel, and it is recessed to prevent inadvertent activation.

NOTE: Calibration must be performed with the SE-330HV connected to the sensing resistor and NGR of the installed system.

To calibrate, press and hold the CALIBRATION button until the green CALIBRATED LED turns off and returns to on (if the LED is already off, press and hold until the LED turns on). Calibration takes approximately two seconds. If calibration is not successful, a resistor-fault trip occurs, the RESISTOR FAULT TRIP LED will be on, the CALIBRATED LED will be off, and the DIAGNOSTIC LED will flash the calibration-error code. See Section 2.7.

The SE-330HV may be calibrated remotely using the SE-MON330 software with the USB interface or the communications options.

If latching resistor fault (switch S4) is selected, the calibration-error code flashes until RESET is pressed even if the CALIBRATED LED is on.

The calibration value is stored in non-volatile memory.

2.3 TRIP INDICATION AND RESET

Red LED's and indication relays indicate ground-fault and resistor-fault trips. The indication relays K2 (GF) and K3 (RF) operate in fail-safe or non-fail-safe mode. The default is non-fail-safe mode. In this mode, the relays are energized when a fault occurs. The relay mode setting is stored in non-volatile memory and can be set using the SE-MON330 software or network communications.

When a trip occurs with latching operation selected, the SE-330HV remains tripped until reset with the front panel button or the remote-reset input. See Sections 2.1.4.3 and 2.1.4.4. Terminals 15 and 16 are provided for remote reset as shown in Fig. 3. The reset circuit responds only to a momentary closure so that a jammed or shorted button does not prevent a trip. The front-panel RESET button is inoperative when terminal 15 is connected to terminal 16. If non-latching operation is selected, trips and corresponding indication automatically reset when the fault clears and power-up trip memory is defeated even when configuration switch S2 is set to fail-safe. The maximum automatic reset time is 2.8 s.

The red DIAGNOSTIC LED annunciates latched calibration-error and remote trips. See Section 2.7.

When supply voltage is applied with switch S2 set to FAIL-SAFE, the SE-330HV returns to its state prior to loss of supply voltage. When supply voltage is applied with switch S2 set to NON-FAIL-SAFE, SE-330HV trips are reset. When a local, remote, or network reset is issued, both trip LED's will flash if they are off.

Resistor-fault-trip reset can take up to one second. Resistor-fault trip-memory can take up to three seconds after SE-330HV power up.

2.4 REMOTE OPERATION

Relays K2 and K3 can be used for remote indication, and terminals 15 and 16 are provided for remote reset. RK-332 Remote Indication and Reset components are shown in Fig. 18. Connect them as shown in Fig. 3. RK-332 components are not polarity sensitive.

Indication relays can be set to fail-safe or non-fail-safe operation using the SE-MON330 software or network



communications. The default mode is non-fail-safe. In non-fail-safe mode, relays energize on fault.

Network-enabled SE-330HV's can be remotely tripped and reset by the network master. The red DIAGNOSTIC LED indicates a network-initiated trip. See Section 2.7. Refer to the appropriate SE-330HV communications manual.

2.5 RELAY K1 LED

The yellow RELAY K1 LED follows the state of relay K1 and is on when K1 is energized (contact closed).

2.6 UNIT HEALTHY OUTPUT

UNIT HEALTHY relay K4 is energized when the processor is operating. It can be ordered with N.O. or N.C. contacts. See Section 7.

NOTE: The output changes state momentarily during a processor reset.

NOTE: K4-contact rating is 100 mA maximum.

2.7 DIAGNOSTIC LED

The DIAGNOSTIC LED is used to annunciate trips without individual LED indication. The number of short LED pulses between pauses indicates the cause of the trip.

By default, both critical and non-critical diagnostic flash codes are shown. Non-critical diagnostic codes include SD Card status and USB Error status. All other diagnostic codes are considered critical.

Starting with SE-330HV firmware version 2.60 and SE-MON330 software version 3.8, the SE-330HV can be configured to show only critical diagnostic codes. In this configuration, non-critical diagnostic codes will not be indicated with the DIAGNOSTIC LED.

Diagnostic messages are always visible with the SE-MON330.

See Sections 4.2 and 5.

2.8 ANALOG OUTPUT

An isolated 4-20-mA output indicates NGR current with full-scale output corresponding to the CT rating. An internal 24-Vdc supply allows the analog output to be connected as a self-powered output. Power from an external supply is required for loop-powered operation. See Fig. 2. A PGA-0520 analog meter can be panel-mounted to display the NGR current. See Fig. 19 and Section 7.

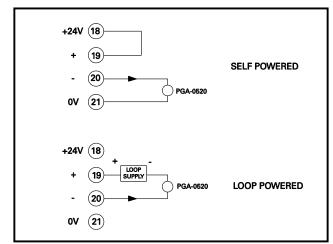


FIGURE 2. Analog-Output Connections.



3. Installation

3.1 SE-330HV

Outline and panel-cutout dimensions for the SE-330HV are shown in Fig. 4. To panel mount the SE-330HV, insert it through the panel cutout and secure it with the four included 8-32 locknuts and flat washers.

If an optional SE-IP65CVR-G Hinged Cover is used, follow the included installation instructions. See Figs. 6 and 7.

All connections to the SE-330HV are made with plugin, wire-clamping terminal blocks. Each plug-in terminal block can be secured to the SE-330HV by two captive screws for reliable connections.

Outline dimensions and mounting details for surface mounting the SE-330HV are shown in Fig. 5. Fasten the optional surface-mount adapter to the mounting surface and make connections to the adapter terminal blocks. Follow Fig. 5 instructions to mount or remove the SE-330HV.

Ground terminal 7 (G) and connect terminal 6 (R) to the sensing-resistor R terminal.

Use terminal 1 (L1) as the line terminal on ac systems, or the positive terminal on dc systems. Use terminal 2 (L2/N) as the neutral terminal on ac systems or the negative terminal on dc systems. Connect terminal 3 ($\stackrel{\textcircled{\tiny }}{\oplus}$) to ground.

NOTE: Disconnect terminal 1 (L1) and terminal 2 (L2/N) before performing dielectric strength testing of the control panel.

NOTE: Connections to terminals 4 (SPG) and 5 (SPGA) are not required when using the SE-330HV hardware revision 10 and higher. However, it is recommended to connect terminal 4 to terminal 5 to maintain backwards compatibility with the older SE-330HV series (hardware revision 01A and lower).

3.2 SENSING RESISTOR

Outline and mounting details for the ER-15KV, ER-25KV, ER-35KV and ER-72KV sensing resistors are shown in Figs. 8, 9, 10, 11, and 12. Install the NGR and the sensing resistor near the transformer or generator. When installed outdoors, a sensing resistor must be installed in a suitable enclosure. Ground sensing-resistor terminal G. Pass the sensing-resistor-to-neutral conductor and the NGRto-neutral conductor through the ground-fault-CT window as shown in Fig. 3. Separately connect sensing-resistor terminal N and the NGR to the neutral to include neutral connections in the monitored loop. Alternately, if the NGR connection to system neutral need not be monitored, connect terminal N to the NGR neutral terminal. If a ground fault in the sensing-resistor conductor is unlikely, a minimal loss of protection will result if it does not pass through the ground-fault-CT window. See Note 3 in Fig. 3.

Outline and mounting details for the ER-1000HV Sensing Resistor are shown in Fig. 13. This sensing resistor can be used to monitor a low-voltage very-high-resistance NGR. See the simplified diagram in Fig. 14.

NOTE: Voltage at terminal N rises to line-to-neutral voltage when a ground fault occurs. The same clearances are required for sensing resistors as for NGR's.

NOTE: A parallel ground path created by moisture can result in a false resistor-fault trip. Moisture sources include wind-driven rain or snow, and condensation. Sensing-resistor terminal R and its connection to SE-330HV terminal R, including interposing terminal blocks, must remain dry.

NOTE: The neutral-to-sensing-resistor-terminal-N connection is not a neutral conductor as defined in Canadian Electrical Code Section 10-1108 and National Electrical Code Section 250.36(B). It is not required to be 8 AWG (8.36 mm²) or larger. Since current through this conductor is always less than 250 mA, a 14 AWG (2.08 mm²) conductor insulated to the system voltage is more than sufficient.



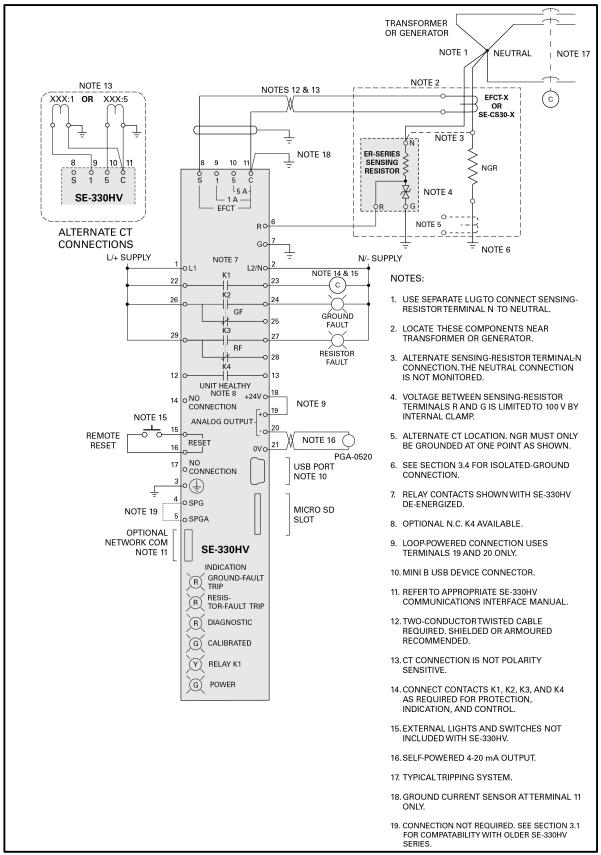


FIGURE 3. SE-330HV Connection Diagram.



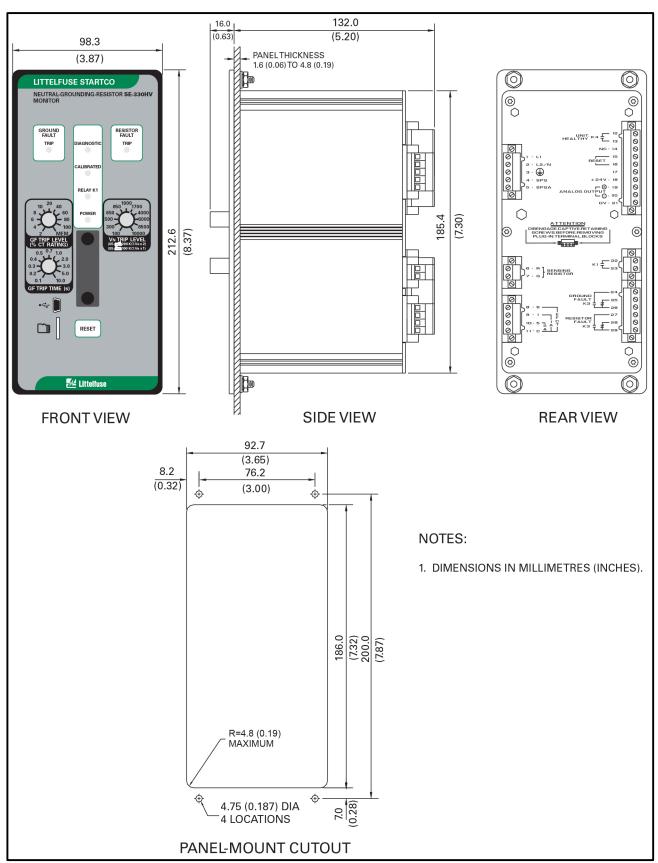


FIGURE 4. SE-330HV Outline and Panel-Mounting Details.



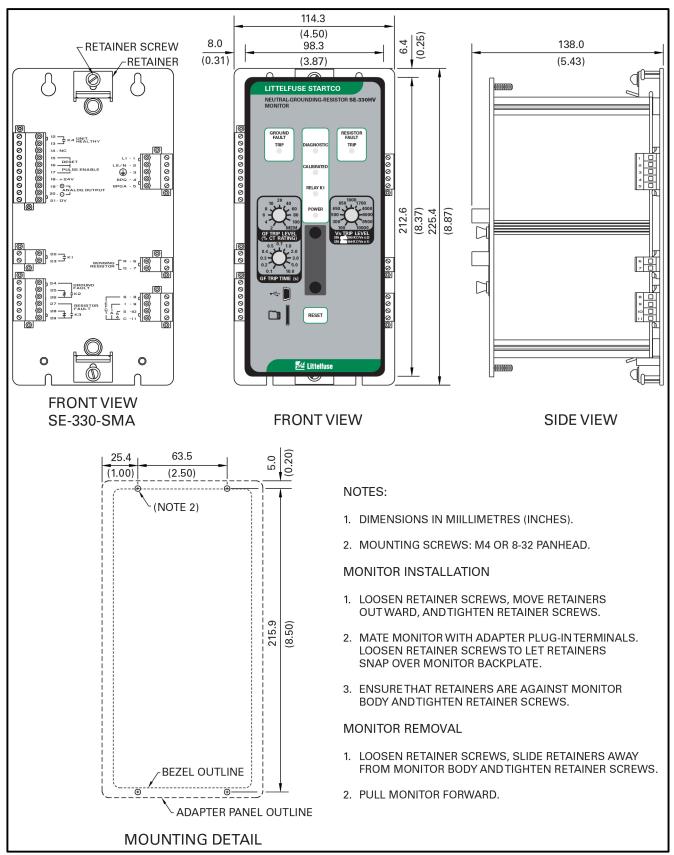


FIGURE 5. SE-330HV Outline and Surface-Mounting Details.



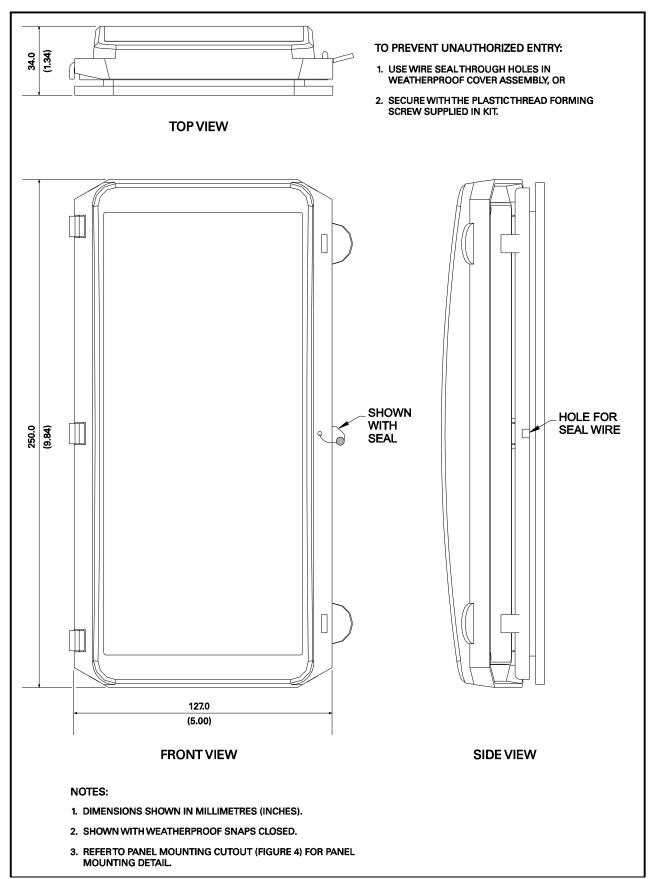


FIGURE 6. SE-IP65CVR-G Weatherproof Cover Outline.



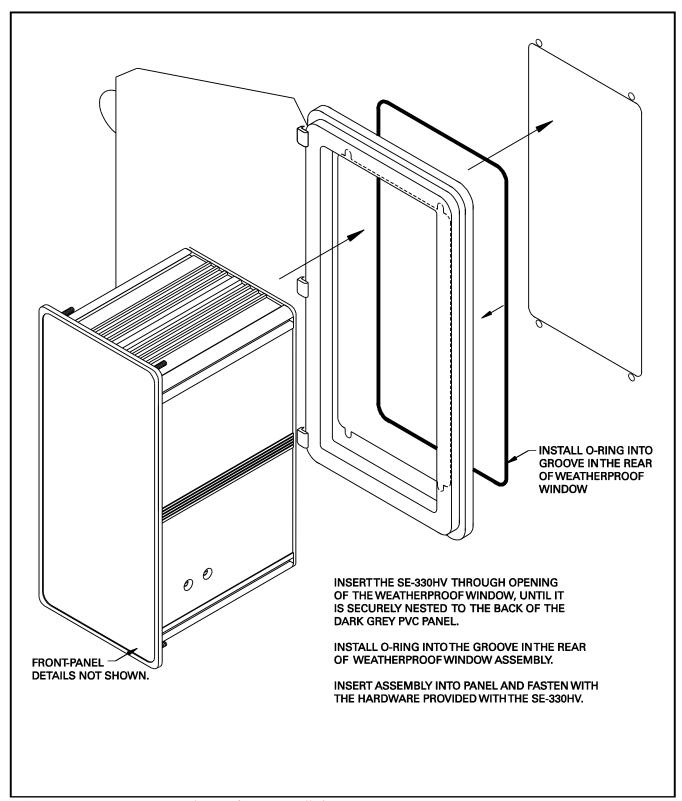


FIGURE 7. SE-IP65CVR-G Weatherproof Cover Installation.



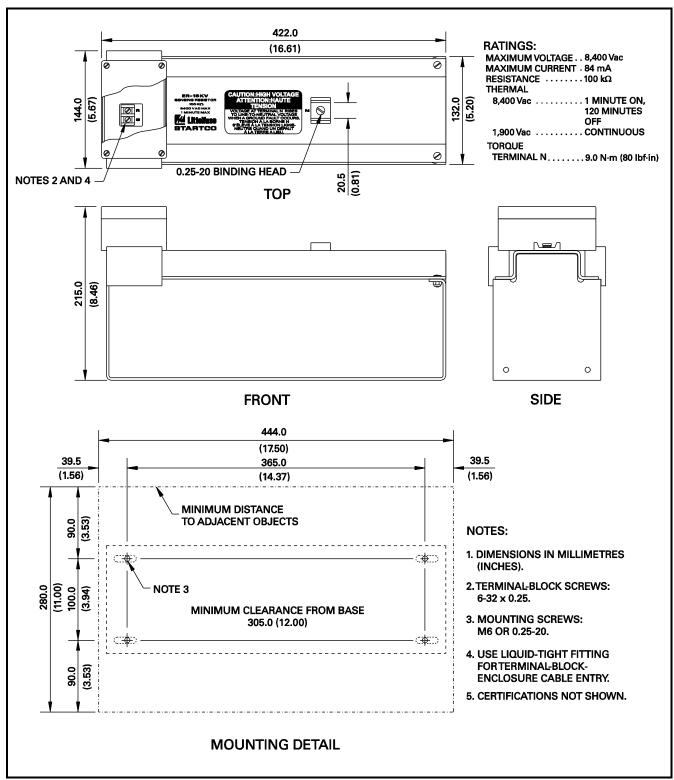


FIGURE 8. ER-15KV Sensing Resistor.



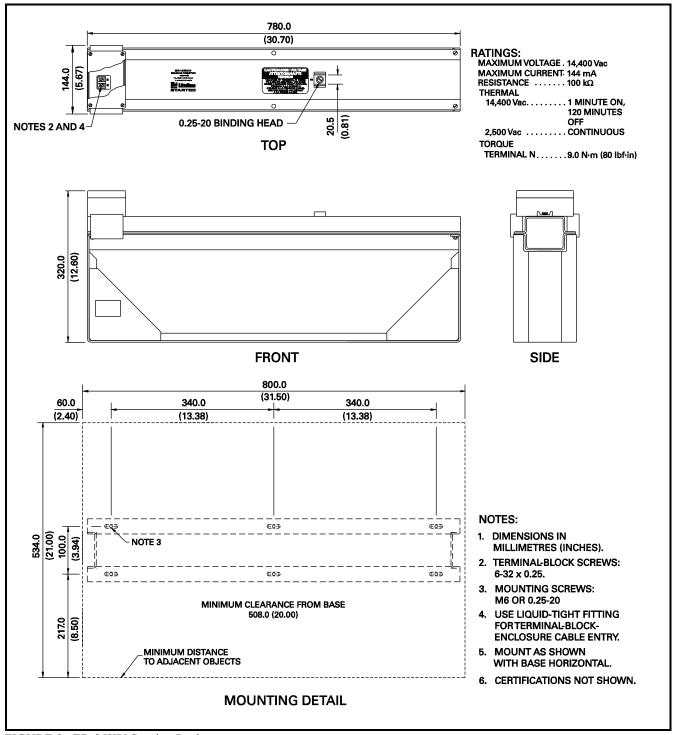


FIGURE 9. ER-25KV Sensing Resistor.



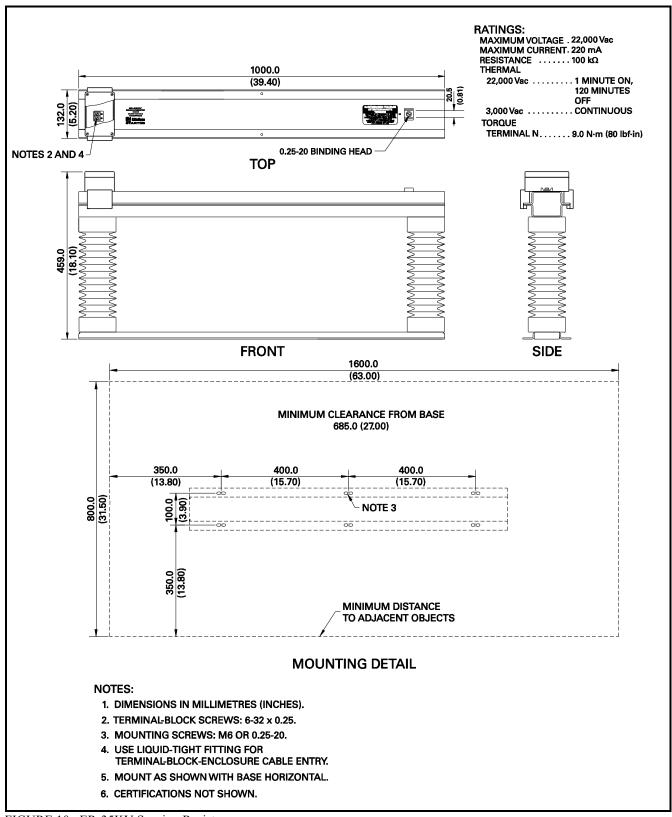


FIGURE 10. ER-35KV Sensing Resistor.



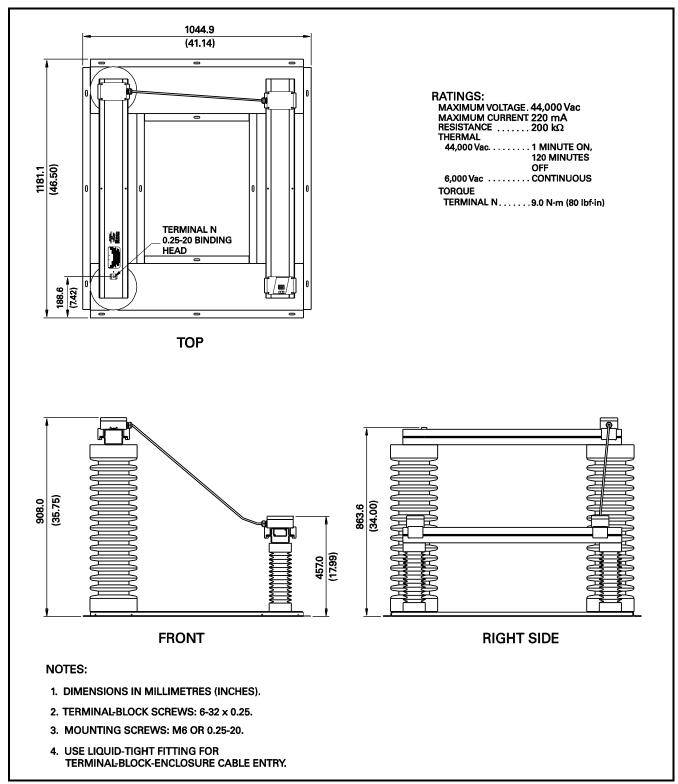


FIGURE 11. ER-72KV Sensing Resistor Outline.



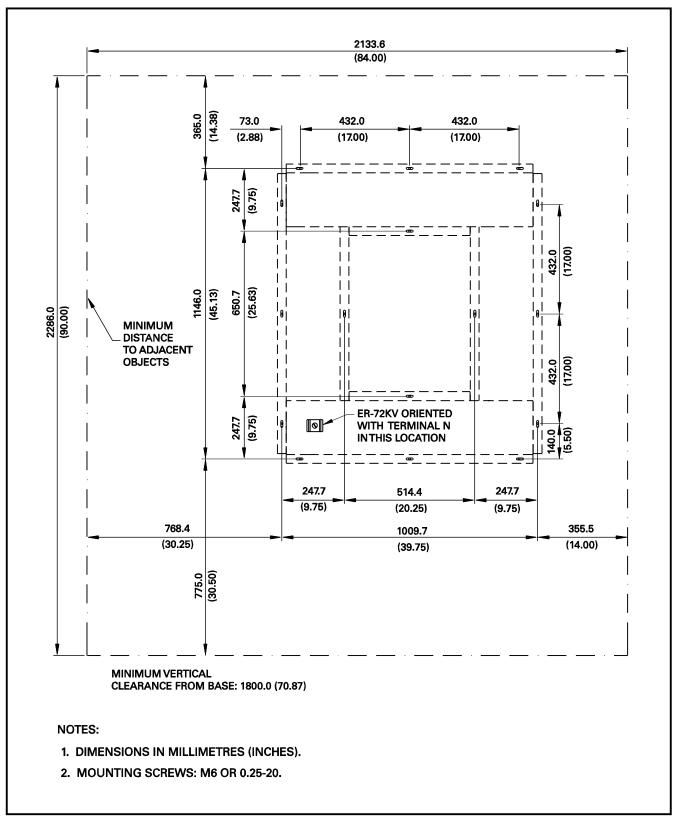
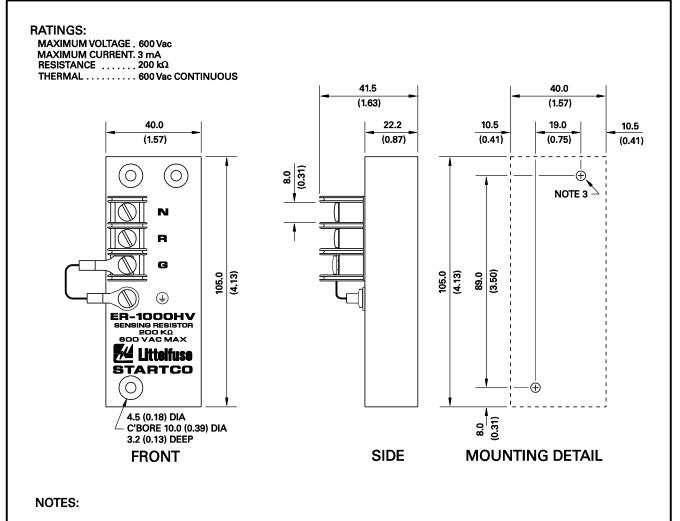


FIGURE 12. ER-72KV Sensing Resistor Mounting Details.





- 1. DIMENSIONS IN MILLIMETRES (INCHES).
- 2. TERMINAL-BLOCK SCREWS: 6-32 x 0.25.
- 3. MOUNTING SCREWS: M4 OR 8-32.
- 4. ENCLOSURE IS ELECTRICALLY CONNECTED TO TERMINAL G THROUGH JUMPER FROM TERMINAL G TO ⊕ SCREW.

 THIS CONNECTION MAY BE REMOVED FOR DIELECTRIC STRENGTH TESTING. ENSURE THAT THE JUMPER IS INSTALLED AFTERTESTING.

FIGURE 13. ER-1000HV Sensing Resistor.



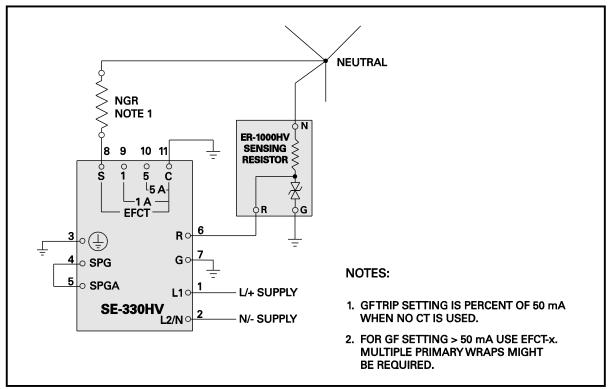


FIGURE 14. ER-1000HV Simplified Connection Diagram.

3.3 GROUND-FAULT CT

Select and install a ground-fault CT that will provide the desired trip level. Typically, the CT-primary rating should be approximately equal to the NGR let-through-current rating. This provides an appropriate GF TRIP LEVEL setting range and analog-output scaling. See Sections 2.1.2 and 2.8.

Outline and mounting details for the EFCT- and SE-CS30-series current sensors are shown in Figs. 15, 16, and 17. Ground-fault-CT connections and the preferred ground-fault-CT location are shown in Fig. 3. If a ground fault in the NGR is unlikely, a minimal loss of protection will result if the ground-fault CT monitors the NGR connection to ground rather than its connection to neutral. A minimal loss of protection will also result if the sensing-resistor-to-neutral connection does not pass through the CT window. This alternate CT location is shown in Fig. 3.

The accuracy of a typical current sensor decreases below 5% of its current rating. CT-primary current-injection testing is recommended to verify trip levels below 5% of the CT-primary rating. See Section 9.4. Littelfuse Startco current sensors are designed for use at low levels and respond linearly to 2% current rating.

NOTE: The current-sensor insulation class is of no consequence if its secondary is grounded and the conductors through its window are insulated for the system voltage. Bushing type CT's are required for applications using bare conductors on the NGR's neutral side.



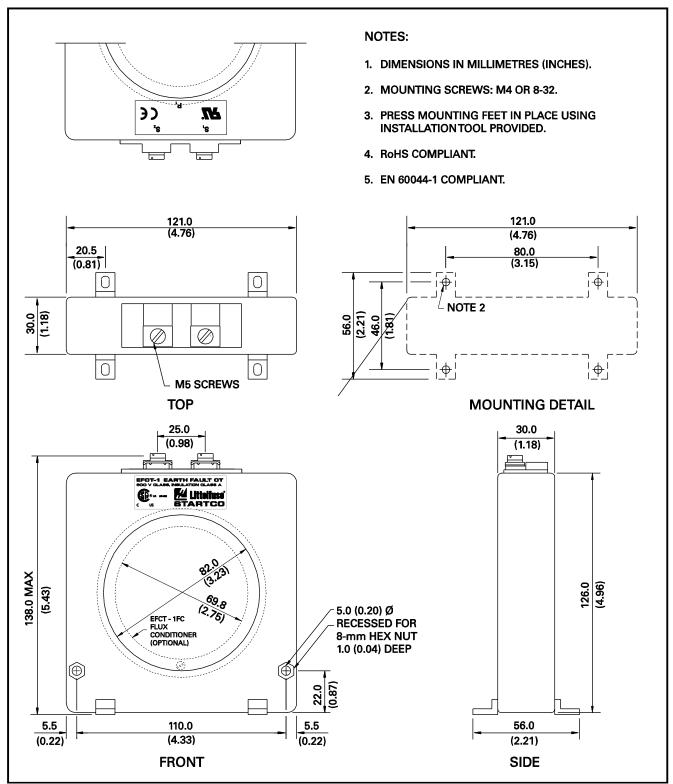


FIGURE 15. EFCT-1 Ground-Fault Current Sensor.



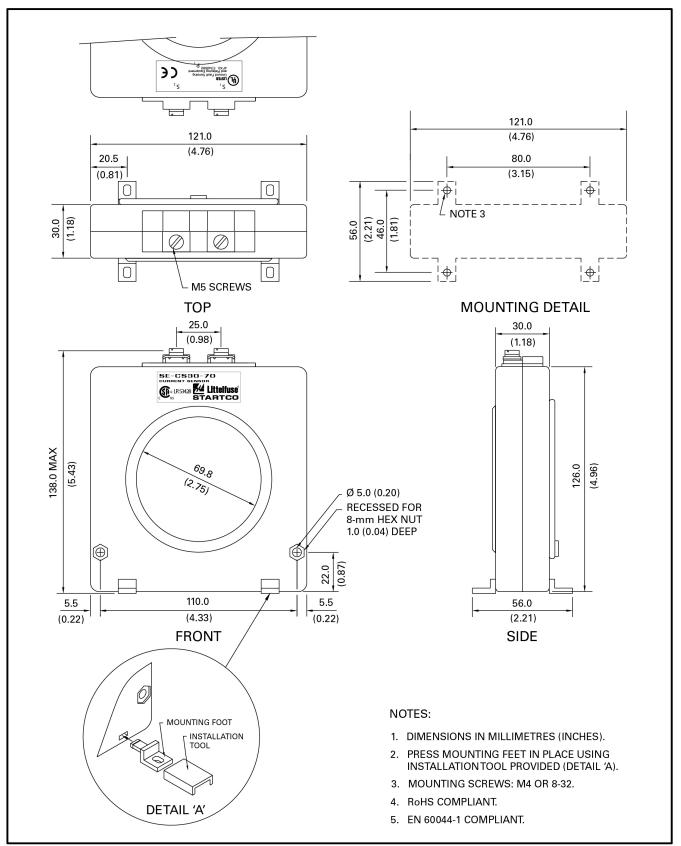


FIGURE 16. SE-CS30-70 Ground-Fault Current Sensor.



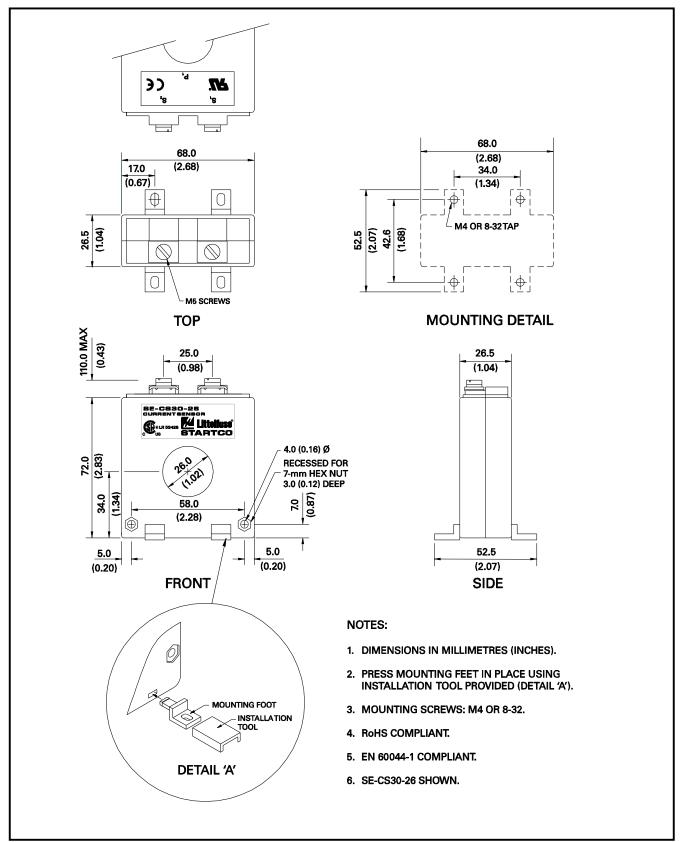


FIGURE 17. EFCT-26 and SE-CS30-26 Ground-Fault Current Sensors.



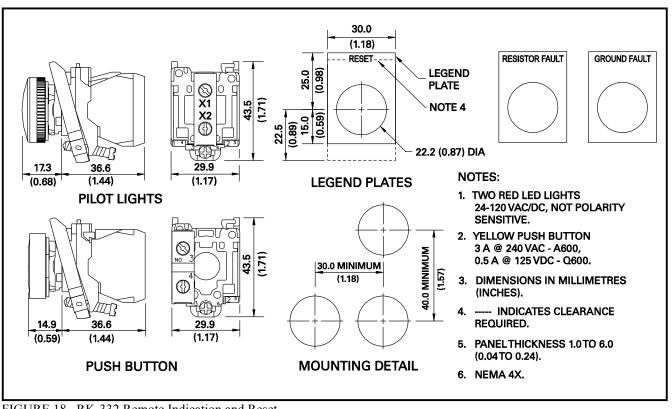


FIGURE 18. RK-332 Remote Indication and Reset.

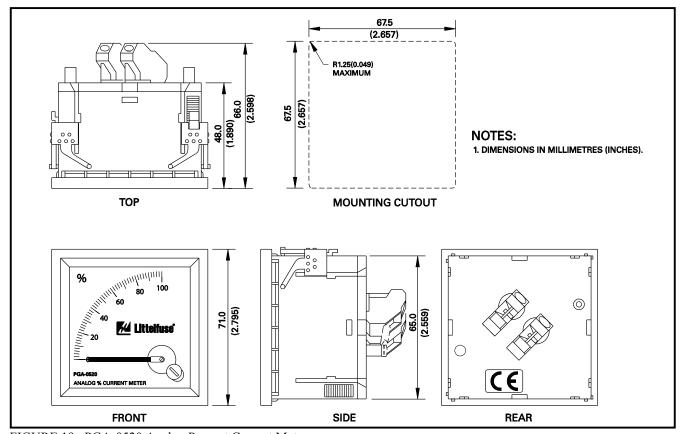


FIGURE 19. PGA-0520 Analog Percent Current Meter.



3.4 ISOLATED GROUND CONNECTION

An isolated ground bed can prevent a ground potential rise (GPR) from being transferred to remote equipment. If the G terminals on the sensing resistor and the SE-330HV are connected to an isolated ground, the SE-330HV will be exposed to the GPR. If the GPR is greater than the terminal-block rating, the SE-330HV must be isolated from station ground and precautions must be taken with the power supply and the trip contacts. See Technical Note RG-1 "NGR Monitoring with Isolated Ground Beds" at www.littelfuse.com/relayscontrols.

An alternate configuration which allows an SE-330HV to be connected to station ground is shown in Fig. 20. The SE-330HV monitors the series combination of the NGR and the two ground beds. This configuration is acceptable provided the series resistance of the NGR and the ground beds is within the NGR calibration range and ground-bed-resistance changes remain within the trip range. See Section 6.1.

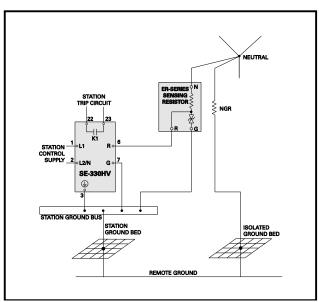


FIGURE 20. Simplified Isolated-Ground Connection.



4. DATA INTERFACES

4.1 SD CARD

The SE-330HV supports microSDTM data storage. The microSDTM card port is located on the front panel just below the USB port. The microSDTM card is used for long-term data logging of measured values and for firmware upgrades.

NOTE: SD card performance may vary by manufacturer, model, and with varying environmental conditions. The included microSDTM card has a temperature rating of -25 to 85° C (-13 to 140° F). For applications colder than -25°C (-13°F), use an Industrial-Grade microSDTM card.

NOTE: SD card usage is intended for use with the SE-330HV only. Do not store other data on the SD card – files may be automatically deleted.

4.1.1 DATALOGGING

When a microSD™ card is installed, the SE-330HV looks for a directory called "Datalogging". If this directory exists, data logging will automatically start after the card is indexed (indexing may take several minutes depending on the size of the card and the number of files).

The log is updated every two seconds and it includes measured values, configuration parameters, and trip status. A new log file is created at the start of each day. If previous log files exist and the microSDTM card has less than 20 MB of free space, the oldest datalogging file will automatically be deleted before a new file is created.

The red DIAGNOSTIC LED may indicate an SD Card error. See Sections 2.7 and 5. Approximately 3 GB of data is generated per year of logging.

4.1.2 FIRMWARE UPGRADE

Firmware upgrades are performed using a microSD™ card in conjunction with configuration switch S8. See Section 2.1.4.6. The SE-Flash software is not required.

To upgrade the SE-330HV firmware, insert a microSD™ card containing the firmware upgrade file (.S19 format) in the root directory of the SD card and set switch S8 to UPGRADE within 30 seconds of card installation. If S8 is switched to UPGRADE after 30 seconds, the upgrade process will not occur. If the microSD™ card is inserted after S8 is switched to UPGRADE, switch S8 to RUN and then back to UPGRADE. The SE-330HV evaluates firmware upgrade files found in the root directory of the microSD™ card and uses the first valid file.

Ensure that the DIAGNOSTIC LED is off before beginning the firmware upgrade process.

The red DIAGNOSTIC LED blinks rapidly while the firmware upgrade is running and the SE-330HV may reset multiple times during the upgrade process. Do not remove the SD card or power off the SE-330HV until the DIAGNOSTIC LED has stopped blinking rapidly for at least 30 seconds. If the upgrade is not successful, the DIAGNOSTIC LED will indicate an SD Upgrade Error. See Section 5. Set switch S8 back to RUN for normal operation.

If a firmware upgrade fails, the existing firmware is not overwritten.

A record of the upgrade can be found in "upgrade_log_<SN>.txt" on the microSDTM card. This file is updated each time an upgrade is performed.

NOTE: The maximum microSDTM card storage capacity is 32 GB for SE-330HV hardware revision 16 and higher. The maximum microSDTM card storage capacity is 4 GB for SE-330HV hardware revision 15 and lower.

4.2 USB INTERFACE

Use the SE-MON330 software (version 3.8 or newer) to access set-points, measured values, and trip records through the mini B USB interface located on the front panel. The following data can be viewed:

- Front-panel and configuration-switch settings
- Neutral voltage and neutral current
- Resistance change from the calibrated value
- Trip status
- Trip records, 100 date and time stamped
- Firmware version and serial number

The following values can be viewed and adjusted:

- Ground-fault trip setting (when front-panel GF Trip Level is set to MEM)
- K2 ground-fault relay output operating mode
- K3 resistor-fault relay output operating mode
- Clock settings
- Trip records can be cleared
- Remote calibration
- Resistor-fault trip time
- Resistor-fault trip level
- Geo-magnetic filter
- Critical and non-critical diagnostics codes

Ensure the real-time clock is set to the correct time prior to normal operation. Trip records and on-board datalogging information include date and time readings from the clock. Refer to the SE-MON330 software help file.

4.3 NETWORK COMMUNICATIONS

The optional communications interfaces include a single CAN port and dual Ethernet ports supporting cable, fiber⁽¹⁾, or both cable and fiber. Protocols include:

- DeviceNet over CAN (ordering option 1)
- EtherNet/IP over cable or fiber (ordering options 3, 4, and 5)
- Modbus TCP over cable or fiber (ordering options 3, 4, and 5)
- IEC 61850 over cable or fiber (ordering options 6, 7, and 8) also includes Modbus TCP

Refer to the appropriate SE-330HV communications-interface manual for details.

⁽¹⁾ Uses the plug-in style SC connector.



5. TROUBLESHOOTING

| Problem | DIAGNOSTIC LED FLASH CODE ⁽¹⁾ | SOLUTION |
|---|---|--|
| POWER LED off. | TLASH CODE | Check if supply voltage is present on terminals 1 and 2. If present, an overvoltage may have caused the power supply to shutdown. Cycle supply voltage. If POWER LED remains off, return unit for repair. |
| POWER LED flashes. | | A power-supply overload has occurred. Cycle supply voltage. If problem persists, consult Littelfuse Startco. |
| Calibration-Error Trip DIAGNOSTIC LED flash code | 1 L - 1 S - 1 L | The total resistance of the NGR and sensing-resistor circuit is outside the calibration range. Verify that switch S5 is set to match the resistance of the sensing resistor, check the resistance of the NGR, and verify the sensing-resistor circuit. See Section 9.2 for sensing-resistor tests. Repeat the calibration procedure after the open or shorted condition has been corrected. Critical diagnostic code. GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : ON, K1:Trip |
| Remote Trip DIAGNOSTIC LED flash code | 1 L - 2 S - 1 L | The SE-330HV was tripped by a signal from network communications. Press RESET to clear the trip. Critical diagnostic code. GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| A/D-Converter-Error Trip DIAGNOSTIC LED flash code | 1 L - 4 S - 1 L | An A/D-converter error was detected. Press RESET to clear the trip. If the problem persists, consult Littelfuse Startco. Critical diagnostic code. GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : ON, K1:Trip |
| SD Card DIAGNOSTIC LED flash code | 1 L - 5 S - 1 L | SD Card is full or a write error occurred. Delete files or use a different microSD™ card. Non-critical diagnostic code. GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : No Change, K1:No Change If this diagnostic was caused during an attempt to upgrade the firmware, follow this alternate process: - remove supply from SE-330HV - insert a microSD card containing the firmware upgrade file in the root directory of the SD card - power on the SE-330HV - set switch S8 to UPGRADE within 30 seconds - the upgrade should continue as described in Section 4.1.2 |
| Watchdog Trip DIAGNOSTIC LED flash code | 1 L - 6 S - 1 L | A watchdog trip results in a processor reset. During reset, UNIT HEALTHY relay K4 will be de-energized. After a reset, UNIT HEALTHY relay K4 will be energized. Press RESET to clear the trip. If the problem persists, consult Littelfuse Startco. Critical diagnostic code. GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| CPU Trip DIAGNOSTIC LED flash code | 1 L - 7 S - 1 L | The CPU has detected a system fault. Press RESET to clear the trip. Critical diagnostic code. GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| Non-Volatile Memory Error Trip DIAGNOSTIC LED flash code | 1 L - 8 S - 1 L | An error was detected in the Non-Volatile Memory. Press RESET to clear the trip. If the problem persists, consult Littelfuse Startco. Critical diagnostic code. GF LED ⁽²⁾ : ON, RF LED ⁽²⁾ : ON, K1:Trip |
| SD Upgrade Error DIAGNOSTIC LED flash code | 1 L - 9 S - 1 L | An error occurred during the flash-memory upgrade procedure. Ensure that the firmware upgrade file is correct or use a different microSD™ card. Critical diagnostic code. GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : No Change, K1:No Change |



| PROBLEM | DIAGNOSTIC LED | SOLUTION |
|--|---------------------------|---|
| | FLASH CODE ⁽¹⁾ | |
| USB Error | 1 L – 10 S – 1 L | A USB algorithm timeout has been detected. Remove and reconnect |
| Diagnostic LED Flash Code | | the USB cable and cycle supply voltage. If the problem persists |
| | | contact Littelfuse Startco. |
| | | Non-critical diagnostic code. |
| | | GF LED ⁽²⁾ : No Change, RF LED ⁽²⁾ : No Change, K1:No Change |
| DIAGNOSTIC LED = Solid Red | | SE-330HV processor failed to start. Cycle supply. If problem |
| | | persists, consult Littelfuse Startco. K1: De-energized. |
| Pressing RESET does not clear trips. | | Trip condition is still present. Locate and correct. |
| | | The RESET button is disabled if remote-reset terminals 15 and 16 are connected. Replace shorted remote-reset switch or issue Reset command from the communications network. |
| UNIT HEALTHY relay K4 momentarily changes state. | | Occurs when processor is reset. |
| No analog-output current. | | The output at terminals 19 and 20 requires a voltage source. See |
| | | Fig. 2 for analog-output connections. See Section 9.3 for the analog-output tests. |

 $[\]label{eq:NOTES:} \begin{array}{l} \textbf{NOTES:} \\ \text{$^{(1)}$ $L = long pause, $S = short flash.} \\ \text{$^{(2)}$ When LED is on, corresponding indication relay is energized when in the non-fail-safe mode or de-energized when in the (1) (1) (2) (2) (3) fail-safe mode.



| 6. TECHNICAL SPECIFIC | CATIONS | Trip-Time Accuracy | 10% of Setting, 20 ms minimum |
|------------------------------|--|-------------------------------|-------------------------------------|
| 6.1 SE-330HV | | 3 dB Frequency Response: | |
| Supply: | | S6 = 50 Hz | 25 to 85 Hz |
| Option 0 | 30 VA, 120 to 240 Vac (+10, - | S6 = 60 Hz | 30 to 90 Hz |
| | 45%) 50/60 Hz, | | |
| | 20 W, 110 to 250 Vdc (+10, - | Maximum CT Lead Resistance | |
| 0 .: 2 | 25%) | EFCT & SE-CS30 | |
| Option 2 | | Other CT's | Consult CT Curve |
| | (+50, -25%), 35 VA, 48 Vac | CT-Input Burden: | .0.01.0 |
| | (+10, -45%) 50/60 Hz | 5-A Input1-A Input | <0.01 \(\text{1} \) |
| | (110, 13%) 30/00 112 | EFCT Input | ~ 10 O |
| Power-Up Time | 3 s at 120 Vac | Li Ci input | < 10 22 |
| _ | | Thermal Withstand: | |
| AC Measurements | Discrete Fourier Transform. 16 | 1-A and 5-A Input: | |
| | samples per cycle, 50 or 60 Hz | Continuous | 2 x CT Rating |
| | | 1-Second | 20 x CT Rating |
| Resistor-Fault Circuit: | (1) | EFCT Input: | |
| Neutral-To-Ground Voltage | | Continuous | |
| ER-15KV to ER-35KV | 100; 300; 500; 650; 850; 1,000; | 1-Second | 25 x CT Rating |
| | 1,700; 4,000; 6,000; 8,500; 10,000 | Measurement Range | |
| ED 10001W/ ED 701/W | Vac | Trip Mode | Latching/Non-Latching |
| ER-1000HV, ER-72KV | 200; 600; 1,000; 1,300; 1,700; | Trin Dalay V1 Contacts | |
| | 2,000; 3,400; 8,000; 12,000; | Trip Relay K1 Contacts: | NO (Form A) |
| | 17,000; | Configuration | Fail-Safe or Non-Fail-Safe |
| Accuracy | 20,000 Vac | | 8 A resistive 250 Vac, 5 A |
| 3 dB Frequency Response | 10 % of setting | Corver Contact Ratings | resistive 30 Vdc |
| S6 = 50 Hz | | Supplemental Contact Ratir | |
| S6 = 60 Hz | | Make/Carry 0.2 s | |
| NGR Calibration Range: | 50 to 50 112 | Break: | |
| ER-15KV to ER-35KV | 0 to 10 kO | dc | 75 W resistive, |
| ER-1000HV, ER-72KV | | | 35 W inductive |
| Trip Resistance, $V_N = 0$: | 0 to 20 ks2 | | (L/R = 0.04 s) |
| ER-15KV to ER-35KV: | | ac | 2,000 VA resistive, |
| | 1.25 to 3.75-k Ω change | | 1,500 VA inductive |
| Runge | $\pm 1 \text{ k}\Omega$ | | (PF = 0.4) |
| Default | | Subject to maximums of 8 | 3 A at 250 Vac, 5 A resistive at 30 |
| ER-1000HV, ER-72KV: | ± 2.5-K22 change | Vdc, and 0.4 A resistive a | t 250 Vdc. |
| Range ⁽⁵⁾ | 2.5 to 7.5 kO change | | |
| Kange | $\pm 2 k\Omega$ | GF (K2) and RF (K3) Relay Co | |
| Default | | Configuration | |
| DC-Voltage Rejection: | ± 3-ks2 change | | Non-Fail-Safe or Fail-Safe |
| ER-15KV to ER-35KV | 125 Vdc | CSA/UL Contact Ratings | |
| ER-1000HV, ER-72KV | | C 1 (1C ()D (| 8 A resistive 30 Vdc |
| Trip Time | | Supplemental Contact Ratings: | 20. 4 |
| | 5% of CT-Primary Rating | Make/Carry 0.2s Break: | 20 A |
| Trip Mode | | dc | 50 W recictive |
| 114P 1/12/02 | gr. ten zuening | uc | 25 W inductive |
| Ground-Fault Circuit: | | | (L/R = 0.04 s) |
| Trip Level | 2, 4, 6, 8, 10, 20, 40, 60, 80, 100% | ac | |
| | of CT-Primary Rating or 2 to | | 1,500 VA inductive |
| | 100% using MEM parameter | | (PF = 0.4) |
| Trip Time | 0.1, 0.2, 0.3, 0.4, 0.5, 0.7, 1.0, 2.0, | | (-2 5) |
| Trin I aval A | 3.0, 5.0, 10.0 s | | |
| Trip-Level Accuracy | Maximum of 1% of CT-Primary Rating or 3% of Setting ⁽²⁾ | | |
| | Kating of 5 % of Setting | | |





| | | Dimensions: | |
|--------------------------------|-------------------------------|-----------------------------------|------------------------------|
| Subject to maximums of | 8 A at 250 Vac, 8 A resistive | Height | 213 mm (8 4") |
| at 30 Vdc, and 0.4 A resis | | Width | |
| at 50 vac, and 0.4 11 lesis | sive at 150 vac. | Depth | |
| Unit Healthy Output K4 (Option | on ()). | Shipping Weight | |
| Configuration | | Simpping Weight | 2.0 kg (4.4 lb) |
| Operating Mode | | Environment: | |
| | 100 mA, 250 V (ac or dc) | | 40 to 60°C (-40 to 140°F) |
| Closed Resistance | | | 55 to 80°C (-67 to 176°F) |
| Closed Resistance | 50 to 50 \$2 | Humidity | |
| Unit Healthy Output K4 (Option | on 1): | IP Rating | IP30 |
| Configuration | | | |
| Operating Mode | | Surge Withstand | ANSI/IEEE C37.90.1-1989 |
| | 100 mA, 250 V (ac or dc) | | (Oscillatory and Fast |
| Closed Resistance | | | Transient) |
| Closed Resistance | 25 to 50 \$2 maximum | EMC Tests: | |
| Auto-reset time | 2.8 s maximum | Verification tested in accorda | ance with IEC 60255-26:2013. |
| | | Radiated and Conducted | |
| 4-20-mA Analog Output: | | Emissions | CISPR 11:2009 |
| Type | | Emissions | CISPR 22:2008, |
| _ | Loop Powered | | EN 55022:2010 |
| Range | | | Class A |
| Loop Voltage | | | Class 11 |
| Load | , | Current Harmonics and | |
| | 24-Vdc supply) | Voltage Fluctuations | IEC 61000-3-2 |
| Isolation | | , cruige 1 100 countrelle toution | and IEC 61000-3-3 |
| Parameter | | | Class A |
| | CT Primary Current | | 01455 11 |
| Hap a | | Electrostatic Discharge | IEC 61000-4-2 |
| USB Communications: | 1036:4 | | ± 6 kV contact discharge |
| Baud Rate | | | (direct and indirect) |
| Protocol | | | ± 8 kV air discharge |
| Connector | Nini B | | C |
| SDM C 1 | | Radiated RF Immunity | IEC 61000-4-3 |
| SD Memory Card: | 0, 1.10, 1 | • | 10 V/m, 80-1,000 MHz, |
| Type Form Factor | | | 80% AM (1 kHz) |
| Form Factor | microSDHC ^{TM (3)} | | 10 V/m, 1.0 to 2.7 GHz, |
| E 4 | | | 80% AM (1 kHz) |
| Format Capacity: | FA132 | | |
| SE-330HV Hardware | | Fast Transient | IEC 61000-4-4 |
| Revision 16 and higher | 512 MR to 32 GR | | Zone B |
| SE-330HV Hardware | 312 WIB to 32 GB | | ± 2 kV (power supply |
| Revision 15 and lower | 512 MP to 4 CP | | port), ± 1 kV (all other |
| Revision 13 and lower | 312 MID to 4 GD | | ports) |
| Operating Temperature: | | Surge Immunity | IEC 61000-4-5 |
| Standard Grade | | Surge minimity | Zone B |
| | 25 to 85°C (-13 to 140°F) | | ± 1 kV differential mode |
| Industrial Grade | 40 to 85°C (-40 to 140°F) | | ± 2 kV common mode |
| PWB Conformal Coating | MII -1-46058 qualified | | |
| 1.1.D Comorniai Coating | UL QMJU2 recognized | Conducted RF Immunity | |
| | OL VIII OL ICCOGNIZEC | | 10 V, 0.15-80 MHz, |
| Mounting Configurations | Panel Mount and Optional | | 80% AM (1 kHz) |
| Comigatations | Surface Mount | | |
| | Saliuve Infount | | |

 $\,^{(2)}\,$ Accuracy included for EFCT-x and SE-CS30-x current



| | | · · | C1-x and SE-CS30-x current |
|--------------------------------|--|--|---|
| Magnetic Field | | sensors only. (3) microSDTM and microSD | |
| Immunity | | illiciosid and illiciosid | HC [™] are trademarks of |
| | 50 Hz and 60 Hz | SD-3C, LLC. | |
| | 30 A/m and 300 A/m | (4) Remote-reset wiring is lin | |
| | | | odified using SE-MON330 |
| Power Frequency ⁽⁴⁾ | IEC 61000-4-16 | software. See Section 4.2 | ·• |
| 1 | Zone A: differential mode | | |
| | 100 Vrms | 6.2 Sensing Resistors | |
| | Zone A: common mode | Environment: | |
| | 300 Vrms | | 40 to 60°C (-40 to 140°F) |
| | | | 55 to 80°C (-67 to 176°F) |
| 1 MHz Burst | IEC 61000-4-18 | ER-15KV: | 22 12 23 2 (3, 12 1/2 1) |
| T TITLE BUILD WITH | ± 1 kV differential mode | Maximum Voltage | 8 400 Vac |
| | (line-to-line) | Maximum Current | 84 m A |
| | ± 2.5 kV common mode | Resistance | |
| | ± 2.5 k v common mode | Thermal: | 100 KS2 |
| Voltage Interruption | IEC 61000 4 11 | | 1 |
| voltage interruption | IEC 61000-4-11; | 8,400 Vac | |
| | 0% for 10, 20, 30, | 1 000 W | 120 minutes off |
| | 50 ms (dc) | 1,900 Vac | |
| | 0% for 0.5, 1, 2.5, | Torque (Terminal N) | |
| | | Shipping Weight | 5.0 kg (11 lb) |
| | 5 cycles (60 Hz) IEC 61000-4-17 | Extended Operating | 55 · C00G / C5 · |
| | | Temperature | 55 to 60°C (-67 to |
| | Level 4, 15% of rated dc value | ED ASIMI | $140^{\circ} \text{F})^{(1)}$ |
| | value | ER-25KV: | 14 400 \$7 |
| Certification | CSA, Canada and USA | Maximum Voltage | |
| Certification | | Maximum Current | |
| | (\$ P ® LR 53428 | Resistance | 100 kΩ |
| | cus | Thermal: | |
| | UL Listed | 14,400 Vac | |
| | (ŲL) LISTED | 2 500 M | 120 minutes off |
| | Ground Fault Sensing and Relaying Equipment 4FX9 E340889 | 2,500 Vac | |
| | | Torque (Terminal N) | |
| | Australia | Shipping Weight | 20 kg (44 lb) |
| | | Extended Operating | 55 · 600G |
| | | Temperature | |
| | CE, European Union | | $(-67 \text{ to } 140^{\circ}\text{F})^{(1)}$ |
| | CF | ED ASIMI | |
| | FCC | ER-35KV: | 22 000 17 |
| | | Maximum Voltage | |
| | HC. | Maximum Current | |
| To: CS A C22 2 No. 14 | Industrial Control Equipment | Resistance | 100 kΩ |
| UL 508 Industrial C | | Thermal: | |
| | ault Sensing and Relaying | 22,000 Vac | |
| Equipment | aun sensing and Kelaying | 2.006.77 | 120 minutes off |
| | ry Compliance Mark (RCM) | 3,000 Vac | |
| CE Low Voltage D | | Torque (Terminal N) | |
| | (3 rd Edition) + AMD 1:2016 | Shipping Weight | 40 kg (88 lb) |
| FCC CFR47, Part 1 | | Extended Operating | ## . coog |
| Class A – Unintenti | | Temperature | |
| | Dalle Danding | | $(-67 \text{ to } 140^{\circ}\text{F})^{(1)}$ |
| | | | |

NOTES:

ComplianceRoHS Pending

⁽¹⁾ See sensing resistor specifications for applicable voltage limits.

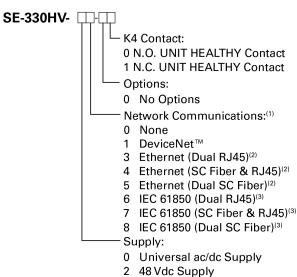


| ER-72KV: | | EFCT-26: | |
|----------------------|---|---|---|
| | 44 000 Vac | Current Ratio5:0.05 A | |
| Maximum Voltage | | Insulation600-V Class | |
| Maximum Current | | Window Diameter26 mm (1.0") | |
| Resistance | 200 KΩ | Shipping Weight | |
| Thermal: | | CertificationsCSA, UL, CE | |
| 44,000 Vac | | ComplianceRoHS, IEC 60044-1 | |
| | 120 minutes off | Extended Operating | |
| 6,000 Vac | | | |
| Torque (Terminal N) | 9.0 N•m (80 lbf•in) | Temperature55 to 60°C | |
| Shipping Weight | 95 kg (210 lb) | $(-67 \text{ to } 140^{\circ}\text{F})^{(1)}$ | |
| | - | Supplemental | |
| ER-1000HV: | | Specifications: | |
| Maximum Voltage | 600 Vac | Trip Level Accuracy: | |
| Maximum Current | | $\leq 1 \text{ A} \dots 1\%$ of CT-Primary Rating | |
| Resistance | | > 1 A3% of CT-Primary Rating | |
| Thermal | | | |
| | | | |
| Shipping Weight | 300 g (0.7 lb) | SE-CS30-26: | |
| G .:5: .: | | Current Ratio30:0.05 A | |
| Certification | CSA, Canada and USA | Insulation600-V Class | |
| | ® LR 53428 | Window Diameter26 mm (1.0") | |
| | cus | Shipping Weight0.45 kg (1.0 lb) | |
| | UL Listed | CertificationsCSA, UL, CE | |
| | | ComplianceRoHS, IEC 60044-1 | |
| | (ŲL) LISTED | Extended Operating | |
| | Grounding Equipment, Neutral Grounding Devices 4GG4 E346992 | Temperature55 to 60°C | |
| | 4GG4 E346992 Australia | (-67 to 140°F) ⁽¹⁾ | |
| | Australia | , | |
| | | SE-CS30-70: | |
| | | Current Ratio30:0.05 A | |
| | CE, European Union | Insulation600-V Class | |
| | CE | Window Diameter70 mm (2.7") | |
| | | Shipping Weight1.2 kg (2.5 lb) | |
| NOTES: | | CertificationsCSA, UL, CE | |
| - | have been verified at a | ComplianceRoHS, IEC 60044-1 | |
| Littelfuse lab. | | Extended Operating | |
| | | Temperature55 to 60°C | |
| 6.3 CURRENT SENSORS | | $(-67 \text{ to } 140^{\circ}\text{F})^{(1)}$ | |
| Environment: | | (0/101101) | |
| | 40 to 60°C (-40 to 140°F) | CT200: | |
| | 55 to 80°C (-67 to 176°F) | Current Ratio200:5 A | |
| 2g | (, | Insulation600-V Class | |
| EFCT-1: | | Window Diameter | |
| Current Ratio | 5:0.05 A | Shipping Weight | |
| Insulation | | CertificationsCSA, UL | |
| Window Diameter | | ComplianceRoHS | |
| Shipping Weight | | Extended Operating | |
| Certifications | | Temperature55 to 60°C | |
| Compliance | | (-67 to 140°F) ⁽¹⁾ | |
| Extended Operating | Kons, iEe 000111 | | |
| Temperature | -55 to 60°C | NOTES: | _ |
| remperature | (-67 to 140°F) ⁽¹⁾ | (1) Electrical specifications have been verified at a | l |
| Cumplemental | (-07 to 140 r) | Littelfuse lab. | |
| Supplemental | | | |
| Specifications: | | | |
| Trip Level Accuracy: | | | |
| | 1% of CT-Primary Rating | | |
| | 3% of CT-Primary Rating | | |

> 1 A3% of CT-Primary Rating



7. ORDERING INFORMATION



NOTE: Please refer to the SE-330 Product Change Notice (PCN) document for updated ordering information and new revision details, available at www.littelfuse.com/se-330hv.

NOTE: The SE-330-SMA Surface Mount Adapter is available as an accessory only.

| Sensing Resistors: | |
|--------------------|---------------------------------------|
| ER-15KV | For system voltages up to |
| | 15 kVac |
| ER-25KV | For system voltages up to |
| | 25 kVac |
| ER-35KV | For system voltages up to |
| | 35 kVac |
| ER-72KV | For system voltages up to |
| | 72 kVac |
| ER-1000HV | For system voltages up to |
| | 1 kVac |
| Current Sensors: | |
| EFCT-1 | Current Sensor, |
| | 5-A-primary rating, |
| | 82 mm (3.2") window, |
| | 6 m (19.5') of 22 AWG |
| | (3.3 mm ²) shielded cable |
| | included |
| EFCT-26 | Current Sensor. |
| | 5-A-primary rating, |
| | 26 mm (1.0") window, |
| | 6m (19.5') of 22 AWG |
| | (3.3 mm ²) shielded cable |
| | included |
| | meradea |
| SE-CS30-26 | Current Sensor |
| 5L 5550-20 | |
| | 30-A-primary rating, |
| | 26 mm (1.0") window |

| SE-CS30-70 | Current Sensor, |
|---------------------|----------------------------|
| | 30-A-primary rating, |
| | 70 mm (2.7") window |
| CT200 | |
| | 200-A-primary rating, |
| | 56 mm (2.2") window |
| 5SHT-101-E | |
| | 100-A-primary rating, |
| | 40 mm (1.6") window |
| 5SHT-151-E | |
| | 150-A-primary rating, |
| | 40 mm (1.6") window |
| 5SHT-500-E | |
| | 50-A-primary rating, |
| | 40 mm (1.6") window |
| 7SHT-301-E | Current Sensor, |
| | 300-A-primary rating, |
| | 64 mm (2.5") window |
| 7SHT-401-E | |
| | 400-A-primary rating, |
| | 64 mm (2.5") window |
| Accessories: | |
| RK-332 | Remote Indication and |
| | Reset, includes two 120-V |
| | pilot lights, a reset push |
| | button, and legend plates |
| SE-IP65CVR-G | Hinged transparent cover, |
| | IP65 |
| PGA-0520 | |
| SE-330-SMA | |
| AC300-MEM-00 | _ |
| 40 | microSD™ Card |
| Software: (4) | |
| SE-MON330 Software | |
| | Program for PC, version |
| | 3.5 or newer |
| NGR Monitor | |
| Set-Point Assistant | Setting Guide |
| | |

NOTES

- ⁽¹⁾ Profibus models only available on legacy SE-330HV.
- (2) Includes Modbus TCP and Ethernet/IP protocols.
- (3) Includes IEC 61850 and Modbus TCP protocols.
- (4) Available at www.littelfuse.com/relayscontrols.



8. WARRANTY

The SE-330HV Neutral-Grounding-Resistor Monitor is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an SE-330HV that is determined by Littelfuse Startco to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.

9. TEST PROCEDURES

NOTE: Ensure the real-time clock is set. See Section 4.2.

9.1 RESISTOR-FAULT TESTS

Perform tests with system de-energized and supply voltage applied to the SE-330HV.

9.1.1 CALIBRATION AND OPEN TEST

Test Equipment: $100-k\Omega$ and $200-k\Omega$, 1/4-watt, 1% calibration resistors (calibration resistors supplied with SE-330HV).

Procedure:

- Remove connections to terminals 6 and 7.
- Connect the 100-k Ω resistor to terminals 6 and 7.
- Set switch S5 to the $100-k\Omega$ position.
- Perform calibration as per Section 2.2.
- The CALIBRATED LED should be on. Press RESET.
- Remove the 100-k Ω resistor and wait for the resistor-fault trip time.

PASS: The SE-330HV should trip on resistor fault.

- Connect the 200- $k\Omega$ resistor to terminals 6 and 7.
- Set switch S5 to the 200-k Ω position.
- Perform calibration as per Section 2.2. The CALIBRATED LED should be on.
- Press RESET.
- Remove the 200-k Ω resistor and wait for the resistor-fault trip time.

PASS: The SE-330HV should trip on resistor fault.

NOTE: Resistor-fault-trip reset can take up to one second.

9.1.2 VOLTAGE TEST

Test Equipment: 0 to 250 Vac voltage source, multimeter, and ER sensing resistor.

NOTE: Use an isolation transformer if the test-voltage source does not provide dc continuity for the SE-330HV resistance-measuring circuit.

Note: Applying the test voltage to the R and G terminals will damage the SE-330HV and the ER sensing resistor. The $V_{\rm N}$ TRIP LEVEL is the trip voltage at terminal N, not terminal R.

Procedure:

- Connect the ER sensing resistor to the SE-330HV and calibrate the SE-330HV.
- Disconnect the wire from sensing-resistor terminal N. A resistor-fault will occur.
- Set the voltage source to 0 V.
- Connect the voltage source between sensing resistor N and G terminals.
- Set the V_N TRIP LEVEL (VAC) to 100.
- Press RESET.
- The RESISTOR FAULT TRIP LED should be off.
- Increase the test voltage to 120 Vac for $100\text{-}k\Omega$ sensors or 240 Vac for $200\text{-}k\Omega$ sensors and wait the resistor-fault trip time.

PASS: The SE-330HV should trip on RESISTOR FAULT. A time-delayed ground-fault trip follows the resistor-fault trip if neutral voltage persists after the resistor fault. For legacy units with firmware revision 6 or less, this does not apply.

9.2 SENSING-RESISTOR TEST

Test Equipment: Multimeter.

Procedure:

- Disconnect the sensing resistor.
- Measure the resistance between sensing-resistor terminals R and N.

PASS: Resistance should be between 98 and $102 \text{ k}\Omega$ for $100\text{-k}\Omega$ sensing resistors. Resistance should be between 196 and $204 \text{ k}\Omega$ for $200\text{-k}\Omega$ sensing resistors.

 Measure the resistance between sensing-resistor terminals R and G in both directions.

PASS: Resistance should be greater than 10 M Ω in both directions.

9.3 ANALOG-OUTPUT TEST

Test Equipment: Multimeter with a mAdc scale.

Procedure:

• Connect the 4–20-mA output as a self-powered output as shown in Fig. 3. Measure the current from terminal 20 to terminal 21.

PASS: With no CT current, the analog output should be 4 mA.

Output is linear to 20 mA. Output is 20 mA when CT-primary current is equal to the CT-primary rating.



9.4 GROUND-FAULT PERFORMANCE TEST

To meet the requirements of the National Electrical Code (NEC), as applicable, the overall ground-fault protection system requires a performance test when first installed. A written record of the performance test is to be retained by those in charge of the electrical installation in order to make it available to the authority having jurisdiction. A test-record form is provided for recording the date and the final results of the performance tests. The following ground-fault system tests are to be conducted by qualified personnel:

- a) Evaluate the interconnected system in accordance with the overall equipment manufacturer's detailed instructions.
- b) Verify proper installation of the ground-fault current sensor. Ensure the cables pass through the ground-fault-current-sensor window. This check can be done visually with knowledge of the circuit. The connection of the current-sensor secondary to the SE-330HV is not polarity sensitive.
- c) Verify that the system is correctly grounded and that alternate ground paths do not exist that bypass the current sensor. High-voltage testers and resistance bridges can be used to determine the existence of alternate ground paths.
- d) Verify proper reaction of the circuit-interrupting device in response to a simulated or controlled ground-fault current. To simulate ground-fault current, use CT-primary current injection (does not apply for bushing-type CT's). Fig. 21 shows a test circuit using an SE-400 Ground-Fault-Relay Test Unit. The SE-400 has a programmable output of 0.5 to 9.9 A for a duration of 0.1 to 9.9 seconds. Set the test current to 120% of GF TRIP LEVEL. Inject the test current through the current-sensor window for at least 2.5 seconds. Verify that the circuit under test has reacted properly. Correct any problems and re-test until the proper reaction is verified.
- e) Record the date and the results of the test on the attached test-record form.

NOTE: Do not inject test current directly into CT-input terminals 8, 9, 10, and 11.

NOTE: For accurate trip-time measurement, the fault current should not be re-applied for the time defined by the GF TRIP TIME setting to allow the trip accumulator to initialize.

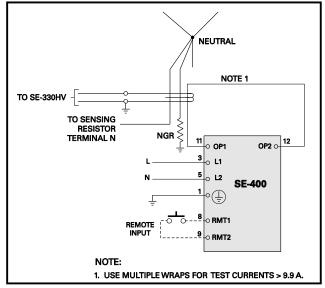


FIGURE 21. Ground-Fault-Test Circuit.

TABLE 3. GROUND-FAULT-TEST RECORD

| DATE | TEST RESULTS |
|------|--------------|
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Retain this record for the authority having jurisdiction.



APPENDIX A SE-330HV REVISION HISTORY

| MANUAL RELEASE DATE | MANUAL REVISION | HARDWARE REVISION (REVISION NUMBER ON PRODUCT LABEL) | FIRMWARE REVISION |
|------------------------|--------------------|--|-------------------|
| October 18, 2017 | 5-M-101817 | 17 | 2.60 |
| December 7, 2016 | 5-L-120716 | 16 | 2.55 |
| September 21, 2016 | 5-K-092116 | | 2.54 2.53 |
| June 30, 2016 | 5-J-063016 | | 2.52 |
| September 11, 2015 | 5-I-091115 | 15 | |
| June 22, 2015 | 5-H-062215 | | 2.50 |
| May 20, 2015 | 5-G-052015 | | 2.40 |
| March 3, 2015 | 5-F-030315 | | |
| July 8, 2014 | 5-E-070814 | 14 | 2.31 2.30 |
| April 14, 2014 | 5-D-041414 | 13 | 2.20 |
| January 9, 2014 | 5-C-010914 | 12 | |
| | | 11 | |
| November 29, 2013 | 5-B-112913 | 10A | 2.10 |
| October 8, 2013 | 5-A-100813 | 10A | 2.08 |

MANUAL REVISION HISTORY

REVISION 5-M-101817

SECTION 2

New features described in Section 2.7.

SECTION 3

Updated installation instructions.

SECTION 4

SD Card note added.

SECTION 5

Troubleshooting information added.

SECTION 7

Ordering information updated.

REVISION 5-L-120716

APPENDIX A

Revision history updated.

REVISION 5-K-092116

SECTION 4

Updated firmware upgrade instructions.

APPENDIX A

Revision history updated.

REVISION 5-J-063016

SECTION 4

Section 4.1.2 updated.

SECTION 6

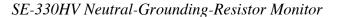
microSDTM storage capacity increased to 32 GB.

RCM certification added.

REVISION 5-I-091115

SECTION 4

Section 4.1.2 updated.





SECTION 5

SD card diagnostic troubleshooting updated.

REVISION 5-H-062215

SECTION 2

Section 2.1.6 added.

SECTION 4

SD Card approximate yearly data logging usage updated.

SE-MON330 software version updated.

SECTION 6

Resistor-fault trip level ranges added.

REVISION 5-G-052015

SECTION 4

SD Card storage capacity updated.

SECTION 6

SD Card storage capacity specification updated.

REVISION 5-F-030315

SECTION 2

Sections 2.1.5 and 2.1.6 added.

SECTION 4

Section 4.2 new features added.

SECTION 6

Resistor-fault circuit trip time updated.

REVISION 5-E-070814

SECTION 6

Added CE, C-Tick, and FCC information.

REVISION 5-D-041414

APPENDIX A

Hardware revision updated.

REVISION 5-C-010914

SECTION 6

Extended operating temperatures added to the ER-15KV, ER-25KV, and ER-35KV sensing resistors and SE-CS30 $\,$

current sensors.

REVISION 5-B-112913

SECTION 6

CE added to sensing resistors.

SECTION 7

Ordering information updated.

REVISION 5-A-100813

SECTION 1

Faceplate updated.

New features added.

SECTION 2

Communications options updated.

Configuration switches updated.

Indication relays explanation added.

Non-volatile-memory error added.

SECTION 3

Connection drawing updated.

SECTION 4

Section heading changed to Data Interfaces.

Updated with microSD™ and USB interfaces.

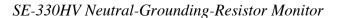
Upgrade procedure added.

Real Time Clock note added in Section 4.2.

SECTION 5

Non-volatile-memory error added.

Switch S8 diagnostic LED error removed.





LED and relay status added to troubleshooting solutions.

SECTION 6

Ground-fault circuit trip level updated.

USB communications specifications added.

Resistor-fault accuracy changed.

microSDTM memory card specifications added.

SECTION 7

Ordering information updated.

SE-330-SMA Surface Mount Adapter is now listed as an accessory only.

APPENDIX A

Added revision history.

HARDWARE REVISION HISTORY

HARDWARE REVISION 17

Enhanced transient protection added.

HARDWARE REVISION 16

microSDTM storage capacity increased to 32 GB.

HARDWARE REVISION 15

RTC circuit updated.

HARDWARE REVISION 14

Added CE and C-Tick compliance.

HARDWARE REVISION 13

Reduced ESD sensitivity of front-panel dials.

HARDWARE REVISION 12

Improved Fiber Ethernet support.

HARDWARE REVISION 11

Reduced ESD sensitivity of USB and SD card connectors.

HARDWARE REVISION 10A

Updated SE-330HV platform to include USB and microSD™ interfaces, programmable trip level (MEM) feature, and ability to add future options.

Real-time clock added.

Added dual cable and fiber Ethernet ports.

Update to RTC circuit.

FIRMWARE REVISION HISTORY

FIRMWARE REVISION 2.60

Added option to display only critical diagnostic codes with DIAGNOSTIC LED.

FIRMWARE REVISION 2.55

Corrected IEC 61850 Network watchdog resets.

FIRMWARE REVISION 2.54

NAND FLASH bit-error-correction update to prevent solid-red diagnostic LED error when bit errors are correctable.

Resistor-Fault Trip Level added to web interface.

Corrected MODBUS® TCP/IP write response byte count.

TCP Keep Alive network setting no longer resets to 5s after power cycle.

FIRMWARE REVISION 2.53

Fixed NAND FLASH bit error correction code to prevent solid-red diagnostic error.

FIRMWARE REVISION 2.52

Improved compatibility with Internet Explorer™ web browser.

FIRMWARE REVISION 2.50

Added support for adjustable resistor-fault trip level.

Web page functionality re-enabled for Ethernet options.

FIRMWARE REVISION 2.40

Added support for geo-magnetic filter.

Added support for 12 to 60 s resistor-fault trip time.

Improved log file descriptions.



SE-330HV Neutral-Grounding-Resistor Monitor

IEC 61850 GOOSE network input support now always enabled.

Improved compatibility for Modbus TCP.

Web page disabled for Ethernet options. This will be enabled in a future firmware release.

IP setting changes for Ethernet options now require power cycle to take effect.

FIRMWARE REVISION 2.31

SD Card and USB diagnostic events no longer cause a trip.

FIRMWARE REVISION 2.30

Remote calibration feature added.

FIRMWARE REVISION 2.20

Added support for EtherNet/IP protocol.

IED name now reported correctly through IEC 61850 interface.

EtherNet/IP and Modbus communications card LED status updated.

Hardware version viewable in the SE-MON330 software and through the Modbus and IEC 61850 servers.

FIRMWARE REVISION 2.10

Added support for IEC 61850 and DeviceNet protocols.

FIRMWARE REVISION 2.08

Updated firmware to include USB and microSDTM interfaces, datalogging, and firmware update via microSDTM. K2 and K3 indication relays can be configured for fail-safe or non-fail-safe operation.

Trip records increased to 100 with date and time stamping.

Added support for communications options.