

# Anybus<sup>®</sup> Communicator<sup>™</sup>

# PROFINET to Modbus RTU/Serial

# **USER MANUAL**

SCM-1202-176 1.0 en-US ENGLISH





# **Important User Information**

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# 1 Preface

# 1.1 About This Document

This manual describes the installation and configuration of the Anybus Communicator.

For additional documentation and software downloads, FAQs, troubleshooting guides and technical support, please visit <u>www.anybus.com/support</u>.

# **1.2** Document Conventions

Numbered lists indicate tasks that should be carried out in sequence:

- 1. First do this
- 2. Then do this

Bulleted lists are used for:

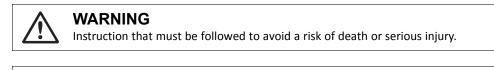
- Tasks that can be carried out in any order
- Itemized information
- An action
  - $\rightarrow$  and a result

User interaction elements (buttons etc.) are indicated with bold text.

Program code and script examples

Cross-reference within this document: Document Conventions, p. 5

External link (URL): www.hms-networks.com



## Caution

Instruction that must be followed to avoid a risk of personal injury.

Instruction that must be followed to avoid a risk of reduced functionality and/or damage to the equipment, or to avoid a network security risk.

ig( ig) Additional information which may facilitate installation and/or operation.

## **1.3** Trademarks

Anybus<sup>\*</sup> is a registered trademark of HMS Networks AB.

All other trademarks are the property of their respective holders.

# 2 Safety

# 2.1 Intended Use

The intended use of this equipment is as a communication interface and gateway.

The equipment receives and transmits data on various physical layers and connection types.

If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

# 2.2 General Safety



#### Caution

Ensure that the power supply is turned off before connecting it to the equipment.



# Caution

This equipment contains parts that can be damaged by electrostatic discharge (ESD). Use ESD prevention measures to avoid damage.



#### Caution

To avoid system damage, the equipment should be connected to ground.



Using the wrong type of power supply can damage the equipment. Ensure that the power supply is connected properly and of the recommended type.

# 3 Preparation

# 3.1 Cabling

Have the following cables available:

- Ethernet cable for configuration
- Ethernet cable for connecting to the high level network
- Power cable

# **3.2** System Requirements

#### 3.2.1 Supported Operating Systems

Operating System	Description
Windows 7 SP1, 32-bit	Windows 7 32-bit with Service Pack 1
Windows 7 SP1, 64-bit	Windows 7 64-bit with Service Pack 1
Windows 10 64-bit	Windows 10 64-bit

#### 3.2.2 Supported Web Browsers

The Communicator built-in web interface can be accessed from the following standard web browsers.

- Google Chrome
- Microsoft Edge
- Mozilla Firefox

## 3.3 Tools

Have the following tools available:

• Flat-head screwdriver, size 5.5 mm

Needed when removing the Communicator from DIN-rail.

• Flat-head screwdriver, size 3 mm

Needed when connecting the cables to the 7-pin connector.

## **3.4** Support and Resources

For additional documentation and software downloads, FAQs, troubleshooting guides and technical support, please visit <u>www.anybus.com/support</u>.

Have the product article number available, to search for the product specific support web page. You find the product article number on the product cover.

# 3.5 HMS Software Applications

Download the software installation files and user documentation from www.anybus.com/support.

#### IPconfig

Use the HMS software application IPconfig and scan your network to discover and change the Communicator IP address and to access the Communicator built-in web interface.

As an alternative, you can set a static IP address within the same IP address range as the Communicator IP address on the computer accessing the Communicator built-in web interface.

(1) IPconfig is only available for Windows.

# **3.6 Third-Party Software Applications**

Microsoft Excel, or equivalent software application that supports the Office Open XML Workbook (xlsx) file format.

Needed to open and read the I/O data mapping file.

# 4 About Anybus Communicator

## 4.1 Serial Protocol Communication

#### 4.1.1 Serial Protocol Types

The gateway features three distinct modes of operation for the subnetwork communication, called **Modbus RTU**, **Custom Request/Response** and **Custom Produce/Consume**.

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version: 1.2.1
✿ Home	Communication
Configuration	Serial protocol
Serial RS-232/485	Modbus RTU Use Modbus transactions on nodes in the serial network.
Nodes & transactions	Custom Request/Response Create transaction templates and use transaction templates on nodes in the serial network.
Rofinet	Custom Produce/Consume
🔀 I/O data map	Create transaction templates and use transaction templates on nodes in the serial network.

#### Modbus RTU

By default the Communicator uses the Modbus RTU serial protocol.

The Communicator uses Modbus transactions defined by the Modbus standard.

The Communicator acts as a client on the subnetwork, and the serial communication takes place in a request/response fashion.

The nodes on the network are not permitted to issue messages unless they have been addressed by the Communicator first.

#### **Custom Request/Response**

In this mode, you can define your own serial transactions to handle a wide range of custom serial protocols.

The Communicator acts as a generic serial client on the subnetwork.

The serial communication takes place in a request/response fashion.

#### **Custom Produce/Consume**

In this mode, you can define your own serial transactions to handle a wide range of custom serial protocols.

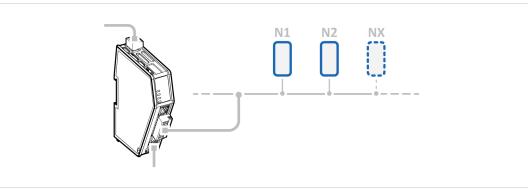
The Communicator may consume and/or produce messages on the subnetwork.

There is no client-server relationship between the nodes on the network, messages are spontaneously produced or consumed when data is available.

#### 4.1.2 Serial Protocol Building Blocks

The following building blocks are used to describe the subnetwork communication.

#### Node



A node represents a single device on the subnetwork.

Each node can be associated with a number of transactions.

#### **Nodes and Transactions**

Anybus Communic Article Number: ABC3007-A Version: 1.2.3 Seri		Apply			
Nodes	Node settings Node address 1 Transactions	Name My Drive	Timeout time - 1000	ms Reconnection ti Retries 0	
Custom request/response	+ Add V	Transaction name	Transaction template name	Size to EtherNet/IP** (bytes) Size from EtherNet	Delete
My Drive		Control Word	Write Parameter (0x02)	0	2
		Speed	Write Parameter (0x02)	0	2
		Status Word	Read Parameter (0x01)	2	0
		Actual Speed	Read Parameter (0x01)	2	0

Transactions are based on standard Modbus RTU transactions (Modbus RTU serial protocol) or transactions templates (Custom Request/Response or Produce/Consume serial protocol) and define the data to be sent or received.

Each transaction has a number of parameters that need to be configured to define how data is to be sent / received.

#### **Frame Fields**

The Frame editor is used to design custom transaction templates.

The Frame editor with Frame fields is available when either the Custom Request/Response or Custom Produce/Consume serial protocol is enabled.

Custom commands	Custom command settings	
+ Add v	Command name New command (1)	
New command (1)	Frame editor	
	S Node add	Data 🕜 Variable d 🕼 🕞 Checksum
	((→ 1)	Ĩ <b>→</b> Ĩ
	Request	Response

Frame fields are low level entities used to compose transactions.

A frame field can represent a:

- fixed value, a constant
- range of values, limit objects
- block of data or a calculated checksum

#### **Transaction Templates**

The Transaction templates are available when either the Custom Request/Response or Custom Produce/Consume serial protocol is enabled.

Anybus Communicator Bide Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 G	UI Version: 1.3.1	Apply					
Fransaction templates	Transaction ter	nplate settings					
+ Add V	Read parame						
Read parameter (0x01)	Frame editor						
	E A Node ad	d C Constant	Limit	D Data	Variable d.	. 📴 🕼 Checksum	
	()→ ()			( <b>-</b> )			
	Request			Response			
	Byte offset	Field	* *	Byte offset	Field		:
	0	Function code	:	0	C	Function code 1	:
	1	Node ID	:	1		Node ID	:
	2 3	Index 2	:	2 3		Index 2	:
	4	Sub index	:	4		Sub index 1	:
	5 6	CS Checksum	:	5 6		Data	:
				78	:: <b>C</b> s	Checksum	:

A transaction represents a complete serial telegram, and consists of a number of frame fields.

Each frame field is associated with a set of parameters controlling what is transmitted on the subnetwork.

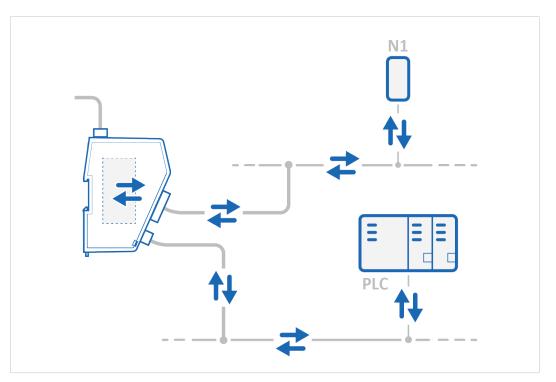
The transaction templates are stored in the Communicator and can be reused multiple times.

#### Examples:

If you have a common read transaction. Then you can create one single transaction template for the read transaction and reuse it multiple times times on your node(s).

If you have a function code in your protocol similar to a standard Modbus RTU transaction. Then you can create a transaction template based on the Modbus RTU transaction for the read operation. When you reuse the template on your node(s), you only have to change the function code each time it is used.

# 4.2 How the Communication Works



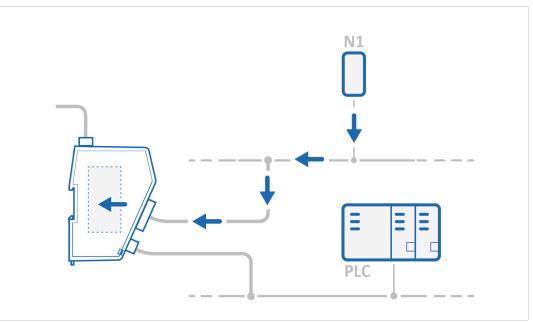
The Communicator enables communication, data exchange, between one or more server devices connected to a *serial subnetwork* and a client device connected to a *high level network*.

For example:

- The client device can be a PLC controller or a PC.
- A server devices can be a sensor, scanner, industrial robot or sniffer.

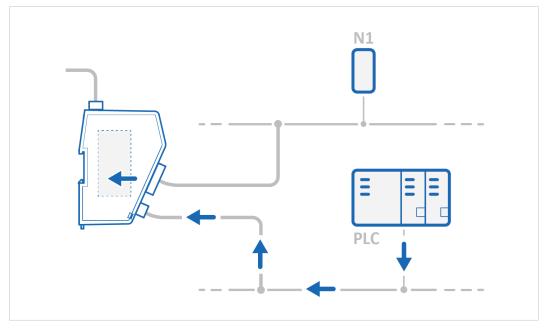
The Communicator main task is to cyclically send the transactions that the server(s) are configured to execute, in order to request and transfer process data.

#### Request process data



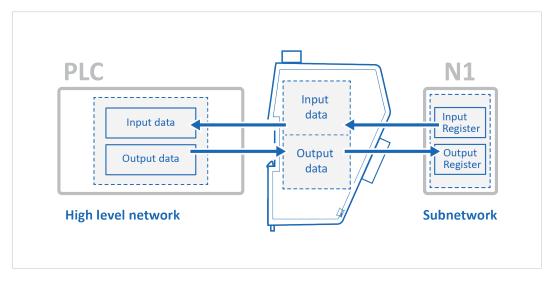
Request process data from the *serial subnetwork* nodes, specified in the Communicator configuration, and make the process data available on the server interface and for the *high level network* client device.

#### Transfer process data



Transfer process data from the *high level network* client device and make it available on the server interface and for the *serial subnetwork* nodes included in the configuration.

## 4.3 How the Data Exchange Works



The data exchanged between the Communicator and the *serial subnetwork* and the *high level network* resides in the Communicator internal memory buffer.

To exchange data with the *serial subnetwork*, the *high level network* reads and writes data to the Communicator internal memory buffer.

The same memory locations are exchanged on the serial subnetwork.

The memory locations are specified when configuring the Communicator, using the Communicator built-in web interface.

The Communicator internal memory buffer is divided into two areas: Input data and Output data.

#### Input Data

This Input data area is read by the high level network.

The Communicator can handle up to 1500 bytes input data.

#### **Output Data**

The Output data area is read/written by the high level network.

The Communicator can handle up to 1500 bytes output data.

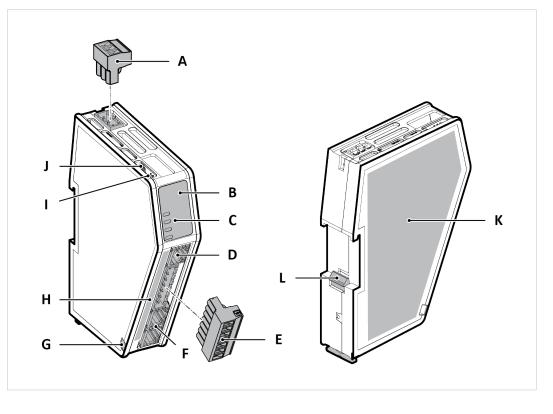
#### 4.4 Data Integrity

A snapshot of the process data buffer between the Modbus Client and the server interface is used during the operation of executing all the transactions within one cycle.

When the cycle is completed, the process data available on the server interface is updated and a new snapshot is created for the next cycle.

# 5 Installation

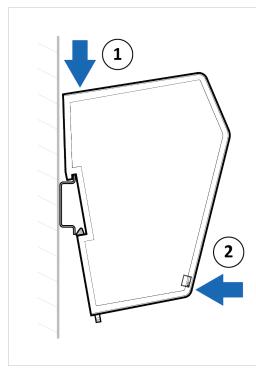
# 5.1 External Parts



- A. Power connector
- B. Label with LED designation
- C. Status LEDs
- D. Configuration port
- E. 7-pin connector
- F. Ethernet port x 2
- G. Cable tie mount
- H. Laser engraved connectors designation
- I. Security switch
- J. Factory reset button
- K. Laser engraved label with product information
- L. DIN rail locking mechanism

# 5.2 DIN Rail Mounting

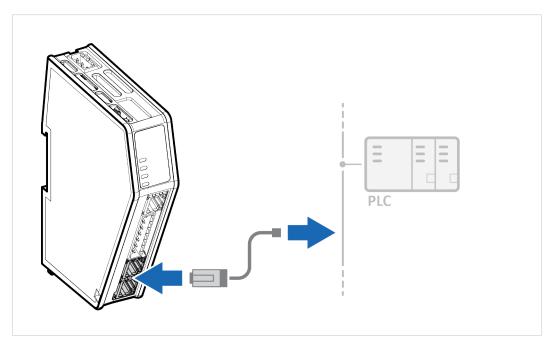
The equipment must be electrically grounded through the DIN rail for EMC compliance. Make sure that the equipment is correctly mounted on the rail and that the rail is properly grounded.



To attach the Communicator on the DIN rail:

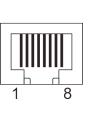
- 1. Insert the upper end of the *DIN rail clip* into the DIN rail.
- 2. Push the bottom of the *DIN rail clip* into the DIN rail.

# 5.3 Connecting to PROFINET Network



1. Connect the Communicator to your PROFINET network.

#### **PROFINET** Connector



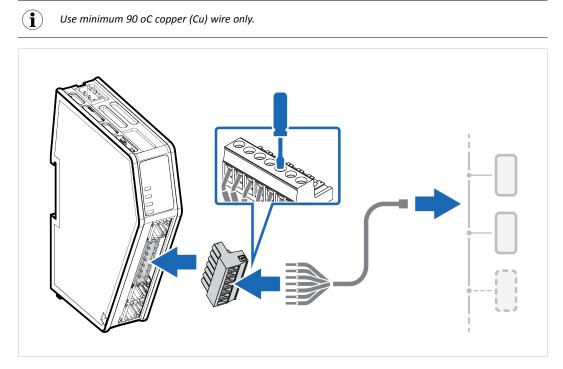
 Pin	Description
1	TD+
2	TD-
3	RD+
4	
5	
6	RD-
7	
8	

#### To Do Next

Connect the Communicator to the serial subnetwork and to power.

Check LED status, refer to Communicator LED Indicators, p. 86.

# 5.4 Connecting to Serial RS232/RS485 Subnetwork



1. Insert the cable wires into the 7-pin connector and tighten the wire clamp screws.

#### 7-pin connector

	Pin	Signal
	1	+5 V OUT
	2	RS485- A
	3	RS485+ B
	4	Signal GND
2	5	Functional Earth (FE)
	6	RS232 Tx Output
3	7	RS232 Rx Input
4		
5		
6		
7		

- 2. Connect the 7-pin connector to the Communicator.
- 3. Connect the Communicator to your serial subnetwork.

#### To Do Next

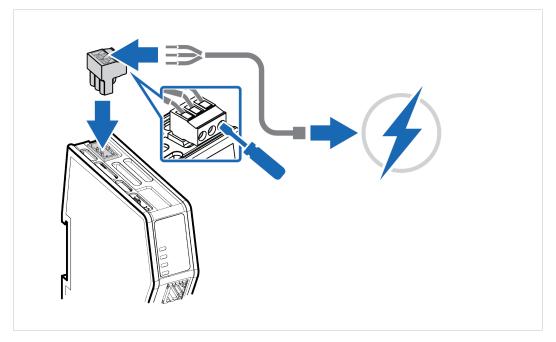
Connect the Communicator to the PROFINET network and to power.

Check LED status, refer to Communicator LED Indicators, p. 86.

## 5.5 Connecting to Power

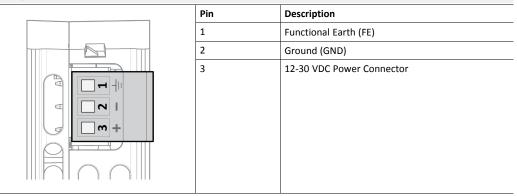
**Caution** Ensure that the power supply is turned off before connecting it to the equipment.

Using the wrong type of power supply can damage the equipment. Ensure that the power supply is connected properly and of the recommended type.



1. Insert the cable wires to the terminal block and tighten the wire clamp screws.

#### Power port



- 2. Connect the terminal block to the Communicator.
- 3. Connect the Communicator to a power supply.
- 4. Turn on the power supply.

#### To Do Next

Connect the Communicator to the PROFINET and serial subnetwork.

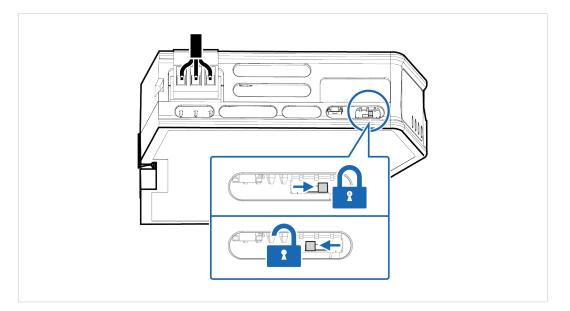
Check LED status, refer to Communicator LED Indicators, p. 86.

## 5.6 Security Switch

After completing the configuration of the Communicator, lock the security switch to prevent unauthorized access to the Communicator built-in web interface.

When the *security switch* is in its locked position, the Communicator built-in web interface can not be accessed and the Communicator can not be configured. Network specific parameters, configured via the PLC is still available.

#### To Lock and Unlock the Security Switch



Use a pointed object, such as a ballpoint pen.

- To lock the security switch, push the toggle towards the Communicator front.
- To **unlock** the security switch, push the toggle towards the **Communicator back**.

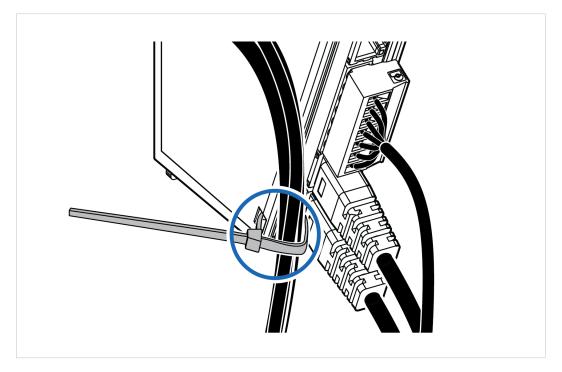
#### Security Switch Status LED



When the security switch is in its:

- locked position, the security switch status LED turn solid green.
- unlocked position, the security switch status LED is turned off.

# 5.7 Locking the Cables



To strain relieve the cables, place a cable tie in the holder and lock the cables.

# 5.8 DIN Rail Demount

#### **Before You Begin**



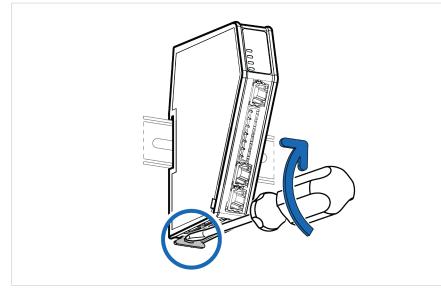
Be careful when removing the Communicator from the DIN-rail. If not removed properly, the DIN rail locking mechanism and the product cover can break.

Have a flat-blade screwdriver, size 5.5 mm, available.

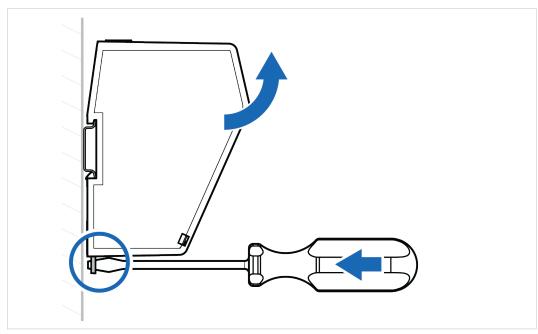
#### Procedure

Remove the Communicator from the DIN Rail:

- 1. Insert the screwdriver into the Communicator *DIN rail locking mechanism*.
- 2. To unlock the Communicator DIN rail locking mechanism, turn the screwdriver clockwise.



3. Hold the screwdriver in the *DIN rail locking mechanism* while you unhook the Communicator from the DIN rail.



# 6 Configuration Quick Guide

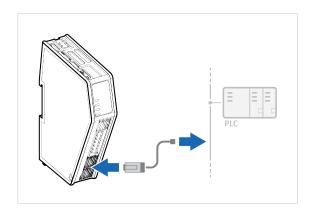
This section is intended to give you a short overview of the tasks you need to perform to configure the Communicator.

For detailed information, please refer to *Communicator Configuration, p. 31*.

# 6.1 Prepare Configuration

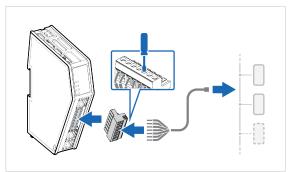
#### 1. Connecting to the high level network

Connect the Communicator to the PROFINET high level network.



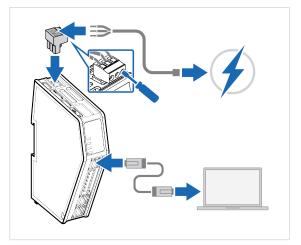
#### 2. Connecting the Communicator to the subnetwork

Connect the Communicator to the serial RS232/RS485 subnetwork.



#### 3. Connecting to PC and power

- a. Connect an *Ethernet cable* between the *Communicator configuration port* and your PC.
- b. Connect the Communicator to a power supply.



#### 4. Finding the Communicator on your PC

The Communicator default IP address is 192.168.0.10.

#### **Option 1**

**Option 2** 

PC.

On the PC accessing the Communicator built-in web interface, set a static IP address within the same IP address range as the Communicator IP address.

Communicator configuration port to one within the same IP address range as your

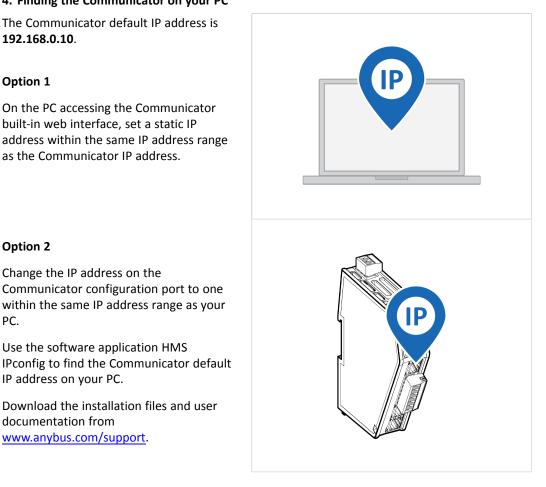
Change the IP address on the

Use the software application HMS

Download the installation files and user

IP address on your PC.

documentation from www.anybus.com/support.



## 5. Access the Communicator built-in web interface

Open the Communicator built-in web interface in HMS IPconfig or enter the Communicator IP address in your web browser.

The Communicator built-in web interface overview page opens in your browser.

	Anybus Profocol Galeway Accession to the or of backway answer any any and any configuration	
Conferences	C EtherNet/IP     Incensorgen     1521466.512 Zhyne     Mages → Zzhyne     Mages → Zzhyne	
A concessor A	Anybus Protocol Gateway	
Communication Settings Nonless and Commands	E halong Disclar Disclar	
36 LiCOver Messing	V Serial RS-232/485	
B Fistandings Firman	Nacio tori inflatization Nocibus HTU ↓ 22 Sylfest ↑ 34 Sylfest	
Disperter v	Movinformation	
Q Sect		

## 6.2 Setup New Configuration

Follow these steps to setup a new Communicator configuration.

#### 1. Subnetwork configuration

On the **Communication** page:

- a. Select a serial protocol:
  - Modbus RTU (default)
  - Custom Request/Response
  - Custom Produce/Consume

For information about the serial protocol types, refer to *Serial Protocol Types, p. 9.* 

b. Configure the basic settings Physical standard, Baud rate, Data bits, Parity and Stop bits.

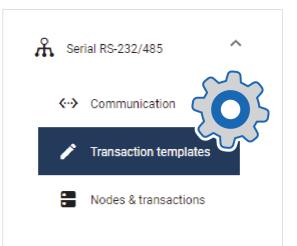
#### 2. Create Transaction Templates

This step applies when the serial protocol **Custom Request/Response** or **Custom Produce/Consume** is selected.

On the **Transaction templates** page: Add a transaction template for each way information can be requested/received or produced/consumed.

Repeat until you have added and configured all your transaction templates.

# Configuration Image: Serial RS-232/485 Image: Serial RS-232/485

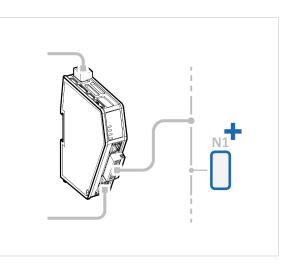


#### 3. Add Nodes and Transactions

On the Nodes & transactions page:

- a. Add a node and configure the Node settings.
- b. Add transactions to request/receive data or produce/consume data and configure the transaction settings.

Repeat until you have added and configured all your nodes.



#### 4. High level network configuration

#### On the **PROFINET** page:

a. Use Automatic I/O sizes provided by the subnetwork or choose to set them manually.

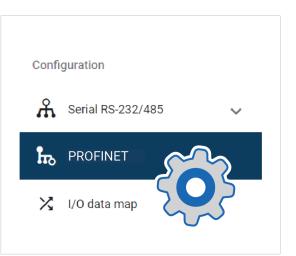
Max I/O size is 1024 bytes.

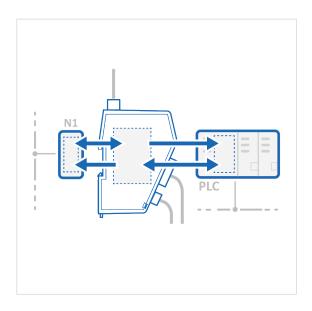
- b. Enable DHCP server or choose to set a specific IP address.
- c. Apply the IP settings.
- d. To be able to identify the Communicator on the PROFINET network, give the Communicator a Station name.

#### 5. I/O Data Mapping

The transactions you added to the nodes are automatically mapped to the Communicator internal memory area.

View the added nodes and transactions on the **I/O data map** page.





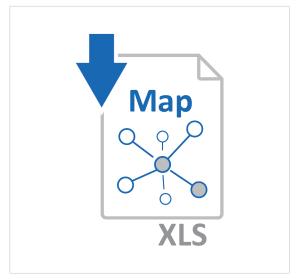
# 6.3 PLC Configuration

#### In the Communicator built-in web interface:

#### 1. Export I/O data map

When you configure the communication between the Communicator and the PLC, you can use the I/O data map as a specification to ensure that the transactions match.

On the **I/O data map** page: You can download the I/O data mapping in a spreadsheet to your PC.



#### 2. Download GSDML File

Option if the PLC program requires a GSDML (Generic Station Description Markup Language) file.

On the **PROFINET** page: Download the GSDML file to your PC.



#### In the PLC program:

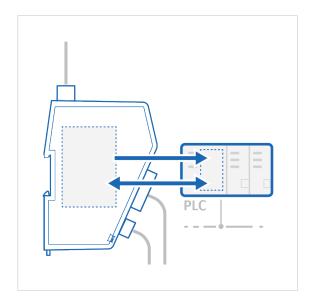
#### 3. Import product file

Option if the PLC program requires a GSDML (Generic Station Description Markup Language) file.

Import the GSDML file into your PLC project.

#### 4. Configure the communication

Configure the PLC to communicate with the Communicator according to the I/O data map created in the Communicator.



#### 1. Apply the configuration

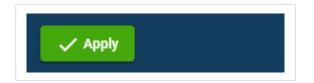
When you have completed and verified the configuration, click **Apply** for the settings to take effect.

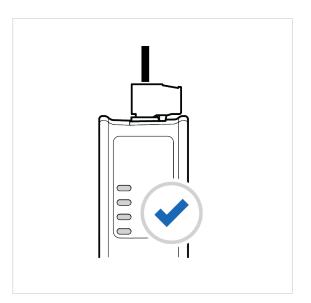
#### 2. Verify status and LED indications

On the **Home** page:

Monitor the Communicator, network and node status.

You can also view the Communicator LED indications remotely.





#### 3. Verify and monitor communication

In **Diagnostics**, use the:

- Serial RS-232/485 page to verify that the serial transactions are sent and received by the Communicator.
- **Event log** page to detect failures and unexpected behavior over time.



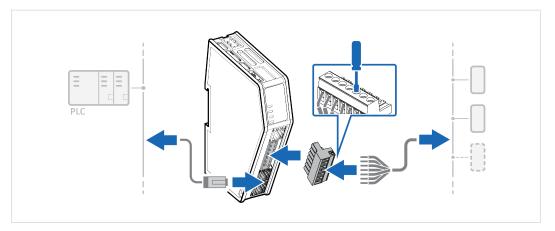
# 7 Communicator Configuration

This section is intended to give you detailed information about the tasks you need to perform to setup a new Communicator configure.

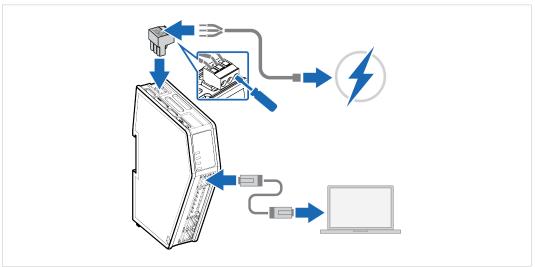
For a more brief overview of the configuration steps, please refer to *Configuration Quick Guide, p.* 24.

# 7.1 Connecting the Communicator

Procedure



- 1. Connect the Communicator to the high level network.
- 2. Connect the Communicator to the subnetwork.



- 3. Connect an *Ethernet cable* between the *Communicator configuration port* and your PC.
- 4. Connect the Communicator to a power supply.

# 7.2 Access the Built-In Web Interface From HMS IPconfig

#### **Before You Begin**

Download the software application HMS IPconfig installation files and user documentation from <a href="http://www.anybus.com/support">www.anybus.com/support</a>.

$(\mathbf{i})$	The Communicator default IP address is <b>192.168.0.10</b> .
i	To access the Communicator built-in web interface, ensure that Port 80 TCP is open in your Firewall. This applies to any Firewall between the web browser and the gateway.

**1** To access the Communicator built-in web interface from HMS IPconfig, ensure that port Port 3250 UDP is open in your PC Windows Firewall.

Make sure the security switch is unlocked. HMS IPconfig cannot configure the Communicator if the security switch is locked.

#### Procedure

- 1. Install HMS IPconfig on your PC.
- 2. Open HMS IPconfig.
  - ightarrow HMS IPconfig automatically starts scanning for compatible and active HMS devices.
  - $\rightarrow$  Found HMS devices are added to the device list.

HMS IPconfig								×
C								φ
Туре	IP	DHCP	Version	MAC	Comment			
Anybus Communicator	192.168.0.10	Disabled	3.03.01	00-30-11-27-B2-F0		♥ ₹		

#### 3. To open the settings pane, click on the Communicator in the device list.

4. Change the Communicator IP address to one within the same IP address range as your PC.

G	<b>\$</b>	Davies Confirmation
Scanned Devices:	4	Device Configuration Apply
Anybus Communicator Add a description here 192.168.0.10 00-30-11-27-82-F0		DHCP Configuration Retrieve IP settings dynamically from a DHCP server
		IP Configuration
		IP address
		192.168.0.10

5. To open the Communicator built-in web interface, click **Open web page**.

HMS IPconfig							_	×
G								\$
Туре		IP	DHCP	Version	MAC	Comment		
Anybus Communicator	•	Open web pa Send wink	ge	3.03.01	00-30-11-27-B2-F0			

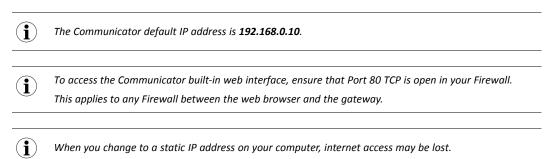
#### Result

 $\rightarrow$  You are redirected to the Communicator built-in web interface Home page.

	Anybus Communicator Article Number: ARC2007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version: 1.0.1
✿ Home	V     EtherNet/IP™       Setup in progress
Configuration	P: 192,168.0.111 ↑ 2 byte(s) ↓ 0 byte(s)
A Serial RS-232/485 V	More information
	V Anybus Communicator
🔀 I/O data map	

# 7.3 Access the Built-In Web Interface From a Web Browser

#### **Before You Begin**



#### Procedure

1. On the PC accessing the Communicator built-in web interface, set a static IP address within the same IP address range as the Communicator IP address.



- 2. Open a web browser.
- 3. Click to select the Address bar and enter the Communicator IP address.

New Tab	× +	- 🗆 X
$\leftarrow \rightarrow$ C $\triangle$	G http://IP address	☆ 📕 \varTheta 🗄
Apps		

4. To open the built-in web interface Home page, press Enter.

	Anybus Communicator Article Number: ABC2007-A Version: 1.23 Bena Number: ABC122456 GUI Version: 1.01.1
↑ Home	V     EtherNet/IP™       Setup in progress
Configuration	IP: 192.168.0.111 ↑ 2 byte(s) ↓ 0 byte(s)
A Serial RS-232/485 🗸	More information
	V Anybus Communicator
X I/O data map	

# 7.4 Communicator Built-In Web Interface Overview

Use the Communicator built-in web interface to configure, maintain and troubleshoot the Communicator.

	Anybus Communicator Andici Number: ABC2007-A Version: 1.2.3 Bensi Number: ABC122456 GUI Version: 1.01.1
↑ Home	V     EtherNet/IP™       Setup in progress
Configuration	IP: 192.168.0.111 ↑ 2 byte(s) ↓ 0 byte(s)
A Serial RS-232/485 🗸	More information
ROFINET	V Anybus Communicator
🄀 I/O data map	
Maintenance	Gateway EtherNet/IP*
Files & firmware	
Troubleshooting	1
🕎 Diagnostics 🗸 🗸	V Serial RS-232/485 Ready for initialization
G Support	Modbus RTU, RS-232, 9600 baud $\oint 0$ byte(s) $\bigstar$ 2 byte(s)
	More information
	New node

Home	View the Communicator, network and node status.
Apply	After configuration changes are made and verified, press Apply to make the settings take effect.
Serial RS-232/485	Serial Subnetwork with Nodes.
	Select a Serial protocol, use Modbus RTU standard transactions or create your own transaction templates.
	Configure communication and add nodes and transactions.
PROFINET	High Level Network with Client. Configure I/O Size, IP settings and Station Name.
I/O data map	View the added transactions mapped to the Communicator internal memory area.
Files & firmware	Save settings in a configuration files, upload configuration files and upgrade firmware.
Diagnostics	Monitor and troubleshoot the Communicator.
Support	Contains Communicator product information, Anybus contact information, link to Anybus support website, and product file for download.
	Here you can generate a support package with product information, to send to your Anybus support technician.

# 7.5 General Subnetwork Settings

### 7.5.1 Communication Serial Protocol

#### **Before You Begin**

Before starting the configuration, select the Serial protocol you want to use:

- Modbus RTU: Default setting. Use for serial devices that conform to the Modbus communication specification.
- Custom Request/Response: Create your own custom request/response transactions.
   The transactions can be based on the Modbus communication specification or fully customized.
- Custom Produce/Consume: Create your own custom produce/consume transactions.

When changing the serial protocol, all settings are reset to default and all added nodes, transactions, and transaction templates are deleted.

#### Procedure

On the Communication page, Serial protocol:

1. To choose a Serial protocol, select Modbus RTU, Generic Request/Response or Custom Produce/Consume.

	Anybus Communicator Article Number: ABC2007-A Version: 1.2.3 Berliel Number: ABC122456 GUI Version: 1.2.1
A Home	Communication
Configuration	Serial protocol
A Serial RS-232/485	Modbus RTU Use Modbus transactions on nodes in the serial network.
Nodes & transactions	Custom Request/Response Create transaction templates and use transaction templates on nodes in the serial network.
PROFINET	Custom Produce/Consume
🔀 I/O data map	Create transaction templates and use transaction templates on nodes in the serial network.

2. To confirm the selected protocol, click Change serial protocol.

Confirm change of	serial protocol
Changing the serial protoco Serial RS-232/485 part of th	ol will reset all settings in the he configuration.
Do you want to change the	serial protocol?
Cancel	Change serial protocol

#### Apply configuration

3. To apply the settings, click Apply in the web-interface header, and follow the instructions.

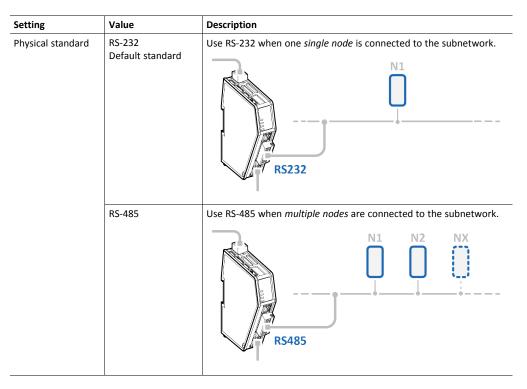
### 7.5.2 Communication Basic Settings

Anybus Communicator Article Number: AB7710-A Version: 1.2.3 Serial Number: ABC123456 GUI Version: 0.44.1	🗸 Apply	
Communication		
Basic settings		

### **Physical standard**

Specify the physical interface type for the device connected to the Communicator.

1. Select a *physical standard* from the **Physical standard** drop-down menu.



#### **Baud rate**

Specify the baud rate; the serial transfer speed, maximum bits per second.

2. Select a *baud rate* value from the **Baud rate** drop-down menu.

Setting	Value
Baud rate	1200 baud
	1800 baud
	2400 baud
	4800 baud
	9600 baud   Default value
	19200 baud
	35700 baud
	38400 baud

Setting	Value
	57600 baud
	115200 baud
	128000 baud

### Data bits

Data bits is the number of bits used in the data representation of characters in the telegrams.

The rate for Modbus RTU is 8 data bits and can not be changed.

#### Parity

Specify if parity should be used to detect errors in the data.

3. Select *parity* value from the **Parity** drop-down menu.

Setting	Value	Description
Parity	None   Default value	No parity checking Parity bit is not transmitted
	Odd	Odd parity checking
	Even	Even parity checking

#### Stop bits

Specify the number of stop bits used to indicate the end of data transmission.

4. Select a *stop bits* value from the **Stop bits** drop-down menu.

Setting	Value
Stop bits	1 stop bit   Default value
	2 stop bit

#### Apply configuration

5. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

# 7.5.3 Communication Advanced Settings

#### Inter-Telegram Timeout Mode Settings

By default, Inter-telegram timeout mode Default (3.5 characters) is used.

This is according the Modbus RTU standard, which advocates the use of a silent period equivalent to 3.5 characters between each message. The silent period is used to find out where one message ends and the next begins.

Inter-telegram timeout mo	ode	Inter-telegram timeout —		- Inter-telegram	delay
Custom	*	17	bits	38	bits

You can use Custom settings to set the desired Inter-telegram timeout and Inter-telegram delay.

The following must be applied on all nodes:

- The time between two adjacent characters in the same telegram must be less than Intertelegram timeout.
- The time between two characters in two different telegrams the same or more than Intertelegram delay.

# 7.6 About Transaction Templates

This section applies when the **Custom Request/Response** or **Custom Produce/Consume** serial protocol is applied, refer to *Communication Serial Protocol, p. 36* 

### 7.6.1 Transaction Template Example

### **Custom Request/Response**

Request/Response transaction template example:

Anybus Communicator ricle Number: ABC3007-A Version: 1.2.3 Serial Number: ABC123456 (	UI Version: 1.3.1	Apply						
Fransaction templates	Transaction ten	nplate settings						
+ Add V	Read parame							
Read parameter (0x01)	Frame editor							
	A Node add	C Consta	int 🚺 🗋 L	mit	🗄 D Data	Variable d	Cs Checksum	
	()→ ()				( <b>) - </b>			
	Request				Response			
	Byte offset	Field		:	Byte offset	Field		:
	0	Fu	nction code 1	:	0	:: <b>C</b>	Function code 1	:
	1		Node ID	:	1		Node ID	:
	2 3	<b>C</b>	Index 2	:	2 3		Index 2	:
	4		Sub index 1	:	4		Sub index 1	:
	5 6		Checksum	:	5 6		Data	:
					7 8		Checksum	:)

The transaction named Read parameter (0x01) consists of a number of frame fields.

In the Request field there are three Constants, a Node address and a Checksum field.

In the Response field there are three Constants, a Node address, a Data field and a Checksum field.

#### **Custom Produce/Consume**

Produce transaction template example:

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 Gl	JI Version: 1.66.1
A Home	Transaction templates	Transaction template settings
Configuration	+ Add V	Transaction name Read Barcode Data Template
A Serial RS-232/485	Read Barcode Data Template	Transaction type
<ul><li>↔ Communication</li></ul>		O Produce O Consume
Nodes & transactions		Frame editor
Transaction templates		The template transaction is in use. Changes to the template will directly affect the node attached transactions using it.
ROFINET		(1) No (1) (2) Co (1) (1) (1) (1) (1) (1) (1) (1) (1) (1)
🄀 🛛 I/O data map		
Maintenance		Consume
Files & firmware		Byte offset Field
Troubleshooting		0 30
Diagnostics 🗸		
G Support		
		32 Line Feed character (LF)

The transaction named Read Barcode Data Template consists of a number of frame fields.

The Transaction type can be Produce or Consume. In this example the Transaction type Consume is selected.

In the frame field we have added one Variable data field and two Constant fields.

### 7.6.2 Transaction Template Types

There are two types of transaction templates, Empty template and Modbus template.

#### **Empty template**

When using the **Empty template**, you start with an empty transaction and build a desired structure by adding and arranging frame fields.

	Anybus Communicator Article Number: ABIC2007 A Version: 12.3 Serial Number: ABIC122456 (	GGN/www.131 ✓ Apply
A Home	Transaction templates	Transaction template settings
Configuration	+ Add V	Transaction name New template (1)
Serial RS-232/485	New templat	Frame editor
<ul> <li>↔ Communication</li> </ul>	Modbus templates 🕨	A Node add
Transaction templates		
Nodes & transactions		Request Response

For the produce/consume transactions you select; **Empty produce template** or **Empty consume template**.

	Anybus Communicator Article Hamber: ABC2007-A Version: 1.2.3 Serial Namber: ABC123456 G	Lil Version: 1.2.1	
A Home	Transaction templates	Transaction template settings	
Configuration	+ Add V	Transaction name New template (1)	
A Serial RS-232/485 ^	New templat Empty produce template	Transaction type	
<> Communication	Empty consume template	Produce      Consume	
Transaction templates		Frame editor	
Nodes & transactions		Node address	Variable data
		Produce	

#### **Modbus templates**

Modbus templates are available for request/response and transactions.

When using the Modbus template, you first select the Modbus template from which you want to start. You can then restructure the transaction by rearranging, adding or removing frame fields.

Transaction templates	Transaction template settings
+ Add v	My "Read Discrete Inputs (2)" T
My *Read Die Empty template	Frame editor
My Empty Tr Modbus templates >	Read Coils (1)
	Read Discrete Inputs (2)
	Read Holding Registers (3)
	Read Input Registers (4)
	Write Single Coil (5)
	Write Single Register (6)
	Write Multiple Coils (15)
	Write Multiple Registers (16)
	Mask Write Register (22)
	Read Write Multiple Registers (23)

Example, new transaction template based on the Modbus template Read Discrete Inputs:

+ Add v	Custom command settin Command name New command base	ngs d on "Read Discrete Inputs (2)"				
New command based on *_ :	Frame editor	Constant	🗄 🝘 Variable d 🚦 🕲 Checksum			
	(+0			(+)		
	Request Byte offset	Frame object		Response Byte offset Frame	object	
			;	0	Node Address	1
	0	II S Node Address	· •	· · · ·		
	0	Node Address		1	Function Code	ĩ
			•		2	1
	1	Function Cod		1	2 Byte Count 1	

### 7.6.3 Frame Field Types

Each transaction consists of frame fields which makes up the serial telegram frame.

Each frame field specifies how the Communicator shall interpret or generate a particular part of the telegram.

The following frame fields are available:

Frame editor				
Node add	Limit	D Data	Variable d	Cs Checksum

#### Node address

Frame field representing the Node address of the Node.

A constant byte that holds a copy of the nodes address when the transaction is used by a node.

#### Constant

Constant frame fields are handle	ed differently depending on the direction of the transaction:
Produce/Request Transactions	The Communicator sends the value as it is without processing it.
Consume/Response Transactions	The Communicator checks if the received byte/word/dword matches the specified value. If the message does not fit, it is discarded.

### Limit

1		
(	Ť.	
Γ.		

Limit is not available for the Transaction Type Produce.

The Communicator checks if the received byte/word/dword fits inside the specified
boundaries. If the message does not fit, it is discarded.

#### Data

Data frame fields are used to represent raw data as follows:

Produce/Request Transactions	The specified data block is forwarded from the higher level network to the sub- network.
Consume/Response Transactions	The specified data block is forwarded from the sub-network to the high level network.

#### Variable data

Produce/Request Transactions:

The specified data block will be forwarded from the higher level network to the sub-network.

The control system must supply an End or Length character in order for the Communicator to know the size of the data block.

The End- or Length-character itself may either be forwarded to the sub-network or discarded.

#### **Consume/Response Transactions:**

The specified data block is forwarded from the sub-network to the higher level network.

The End- or Length-character will be generated by the Communicator automatically (if applicable).

The End- or Length-character itself may either be forwarded to the higher level network or discarded.

#### Checksum

Most serial protocols features some way of verifying that the data has not been corrupted during transfer.

The checksum frame field calculates and includes a checksum in a transaction.

# 7.7 Build Transaction Templates

### **Before You Begin**

Ensure that you have applied the **Custom Request/Response** or **Custom Produce/Consume** serial protocol, refer to *Communication Serial Protocol, p. 36*.

# 7.7.1 Add Transaction Template

### Procedure

Add a transaction template:

1. In the web-interface left sidebar menu, click **Transaction templates**.

A Home	Transaction templates
Configuration	+ Add V
Serial RS-232/485	
<ul> <li>↔ Communication</li> </ul>	
Transaction templates	
Nodes & transactions	

2. To select the template you want to use, click the **Add** drop-down button.

Options for the Custom Request/Response Protocol:

• To add a new empty template without any frame fields, select **Empty template**.

Transaction	templates
+ Add v	
My "Read Di:	oty template
My Empty Tr	ibus templates 🕨

Example, a new empty request/response template is added to the transaction template list:

Transaction templates	Transaction template settings	
+ Add V	New template (1)	
New template (1)	Frame editor	
	A Node add	Data Variable 🕞 Checksum
	() → ()	<b>() ← ()</b>
	Request	Response
	Drop fields here	Drop fields here
	Drag a field from the toolbar above.	Drag a field from the toolbar above.

Transaction templates	Transaction template settings Transaction name My "Read Discrete Inputs (2)" T
My 'Read Di	Frame editor
My Empty T <sub>t</sub> Modbus templates ►	Read Coils (1)
	Read Discrete Inputs (2)
	Read Holding Registers (3)
	Read Input Registers (4)
	Write Single Coil (5)
	Write Single Register (6)
	Write Multiple Coils (15)
	Write Multiple Registers (16)
	Mask Write Register (22)
	Read Write Multiple Registers (23)

 To add a new template based on a standard Modbus transaction, select Modbus templates and then the desired Modbus transaction.

Example, a new request/response template based on "Read Coils (1)" is added to the transaction template list:

ransaction templates	Transaction ten		ngs					
+ Add V	New templat	e based o	n "Read Coils (1)"					
New template based on 'Read	Frame editor							
	Node add		Constant	nit	D Data	V Variable d	C Checksum	
	()→ ()				() <b>-</b> ()			
	Request				Response			
	Byte offset	Field		:	Byte offset	Field		:
	0	:: <b>A</b>	Node Address	:	0		Node Address	:
	1	:: C	Function Code 1	:	1		Function Code 1	:
	2 3	:: C	Start Address 0	:	2		Byte Count 1	:
	4 5	:: C	Quantity of Coils 1	:	3		Coil Status	:)
	6 7		Error Check	:	4 5		Error Check	:

Option for the **Custom Produce/Consume** Protocol:

• Select **Empty produce template** or **Empty consume template**.

You can change the Transaction type after the transaction template is added.

Transac	tion templates
+ Add	
New templa	Empty produce template
	Empty consume template

Example, a new produce template is added to the transaction template list:

Anybus Communicator ticle Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 G	UlVersion: 1.2.1
ransaction templates	Transaction template settings Transaction name New template (1)
New template (1)	Transaction type  Produce Consume  Consume
	Frame editor
	<b>(</b> → <b>D</b> ) Produce
	Drop fields here Drag a field from the toolbar above.

3. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

### To Do Next

Add frame fields to the transaction template, refer to Add Frame Fields, p. 50.

### 7.7.2 Add Frame Fields

### Procedure

1. In the transaction template list, select a transaction template to add frame fields to.

Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC12	3456 GUI Version: 1.2.1	
Custom commands	Custom command settings	
(+ Add ~	Command name New command (1)	
New command (1)	Frame editor	
	S Node add	D) Data
	()→ ()	Ĩ <b>←</b> Ĵ
	Request	Response

- 2. Build the transactions.
- To add frame fields: In the **Frame editor** frame fields menu, drag and drop the desired frame fields into the drag and drop fields.

Frame editor	
A Node add	🗄 🐌 Data 🗮 🔍 Variable d
	<b>() ← ()</b>
Request	Response
Drop fields here	Node add Drop fields here
Drag a field from the toolbar above.	Drag a field from the toolbar above.

To duplicate a frame field: On the frame field that you want to delete, click the three dots icon and then click Duplicate.

0 Node address	:
	·
1 Constant 0	:
	Duplicate
	Delete

To change the order of the frame fields: Drag and drop the frame fields in the list to change the order.

Request			
Request			
Byte offset Field		:	
	Node address	:)	
	Constant 0		

To delete a frame field: On the frame field that you want to delete, click the three dots icon . Click Delete and then Yes to confirm.

Byte offset	Field			0 0 0
0		Node addre	SS	:
1		Constant 0		:)
				Duplicate
			Ð	Duplicate to related frame
			$\rightarrow$	Move to related frame
			Î	Delete

3. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

#### To Do Next

• Configure the frame field settings, refer to *Configure Frame Field Settings, p. 52*.

# 7.7.3 Configure Frame Field Settings

# Procedure

Home	Transaction templates	Fransaction template settings	:
nfiguration	+ Add V	Transaction name My Write Single Coil (5) Trans	Constant
Serial RS-232/485		rame editor	Function Code
↔ Communication	My Empty Tans	Node add.      Constant     O Limit     O Data     O Variable d.     O Constant     O Limit     O Data	Type Byte
Transaction templates	My Write Single Coil (5) Trans		Eixed field
Nodes & transactions			Yes, set here
		Request Response	Value
PROFINET		Byte offset Field Byte offset Field	5
I/O data map		0	Dec Hex
ntenance		1 Function Code : 1 Function Code : 5	)
Files & firmware		23 (:: C Output Address : 23 (:: C Output Address : 0 : 0 : 0 : 0 : 0 : 0 : 0 : 0 : 0 :	)
ubleshooting		4 (III D Output Value : 4 (III D Output Value :	)
Diagnostics 🗸 🗸		5 Always Zero : 5 E Always Zero :	)
Support		6 7 Error Check : 6 7 Error Check :	)

- 1. In the Transaction templates list, select a transaction template to configure.
- 2. In the Transaction template settings select a **Field** to configure.
  - $\rightarrow$  The Field sidebar opens, on the right side of the screen.
- 3. Configure the Field settings.

(1) Limit can only be added as a Response frame field.

#### Node address

Frame field representing the Node address of the node. A constant byte that holds a copy of the nodes address when the transaction is used by a node.

When the transaction template is used by a node, the Node address field will automatically be replaced with the actual node address of the node.

#### Constant

- Name: You can name the Frame Field to make it easier to identify.
- **Type:** Specify the number of bytes in the frame. Select Byte (1 byte) (Default), Word (2 bytes), Double word (4 bytes), Array of bytes or String.
- Endianess: Select Big-endian (Default) or Little-endian.
- Fixed field\*: Select Yes, set here (Default) or No, set when used.
- Length: Valid for Array of bytes. Enter a byte offset value between 0 and 32 byte. Default value is 1 byte. Enter a Value for each Byte (0–31).
- Value: The value of the Constant in the frame. Enter a value between 0 (Default) and 255.
- Min value: Specify the minimum value that can be set when the template is used.
- Max value: Specify the maximum value that can be set when the template is used.
- **Default value:** Default value set when the template is used.

#### Limit

- Name: You can name the Frame Field to make it easier to identify.
- **Type:** Specify the number of bytes in the frame. Select Byte (1 byte) (Default), Word (2 bytes), Double word (4 bytes).
- Endianess: Select Big-endian (Default) or Little-endian.
- Min value: The lowest value of the limit range.
- Max value: The highest value of the limit range.
- Base number system: Select Decimal Dec (Default) or Hexadecimal Hex.

#### Data

- Name: You can name the Frame Field to make it easier to identify.
- Fixed field\*: Select Yes, set here (Default) or No, set when used.
- Length: Enter a value between 1 (Default) and 512 bytes.
- Min length: Specify the minimum length that can be set when the template is used.
- Max length: Specify the maximum length that can be set when the template is used.
- Default length: Specify the default length that can be set when the template is used.

#### Variable data

- Name: You can name the Frame Field to make it easier to identify.
- Fixed field\*: Select Yes, set here (Default) or No, set when used.
- **Minimum payload length:** Specify the minimum payload length that can be set when the template is used.
- **Maximum payload length:** Specify the maximum payload length that can be set when the template is used.
- **Default max payload length:** Specify the default payload length that can be set when the template is used.
- **Data delimiter:** Specify how to detect/define the length of the variable data of the high level network. Select Byte counter, End pattern or None (Default).

For information about End- and Length character, refer to *Data Delimiter and Subnet Delimiter Options, p. 55*.

• **Subnet delimiter:** Specify how to detect/define the length of the variable data of the serial subnetwork. Select Byte counter, End pattern or None (Default).

For information about End- and Length character, refer to *Data Delimiter and Subnet Delimiter Options, p. 55*.

- End pattern: Specify the value defining the end of the payload, when a delimiter is set to end pattern.
- **Fill padding:** Fill up unused data mapped to the high level network or the general area with a field padding value.

To deactivate/activate Fill padding, click the **slide toggle**. When Fill padding is activated, enter a Fill padding value between 0 and 255.

• Base number system: Select Decimal Dec (Default) or Hexadecimal Hex.

- Name: You can name the Frame Field to make it easier to identify.
- Checksum type: Specify the algorithm used to calculate the checksum. Select CRC (CRC-16-IBM) (Default), LRC (ISO 1155:1978), XOR or ADD.
- **Start offset:** Specify the offset from where to start the checksum calculation. Enter a value between 0 (Default) and 511.
- **Error check type:** Specify how the checksum is converted. Select None (Default), One's complement or Select None, Two's complement.
- Representation: Specify how the checksum is represented. Select Binary (Default) or ASCII.

#### **About Fixed field\***

- **Yes, set here:** The Value set here is fixed and cannot be changed when the transaction is used on a node. The value must be updated in the transaction template.
- **No, set when used:** The Default value set here can be edited when the transaction is used on a node. The allowed range is the min/max values.

#### Total size including delimiters:

- High Level Network: 1 byte(s)
- Subnetwork: 1 byte(s)
- 4. Repeat step 1 to 3 until you have configured all the desired frame fields.

#### Apply configuration

5. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

In a variable data object, the length of the data field may vary depending on the type of data being read in a specific case.

In order to present the variable data correctly on the corresponding network, the length of the data field must be identified.

In a Variable data object, there are three ways to identify the data length; by length character, end character or length of message.

#### Data delimiter - Data is forwarded from the Communicator to the PLC

The Communicator can be configured to forward data as process data.

Different Data delimiter options can be used for data sent from the subnetwork to the Communicator and for data forwarded from the Communicator to the high level network, to fit the requirements in the PLC.

In most cases, when a stream of data is sent from the Communicator to the PLC the Byte counter (length character) or End pattern (end character) format is used.

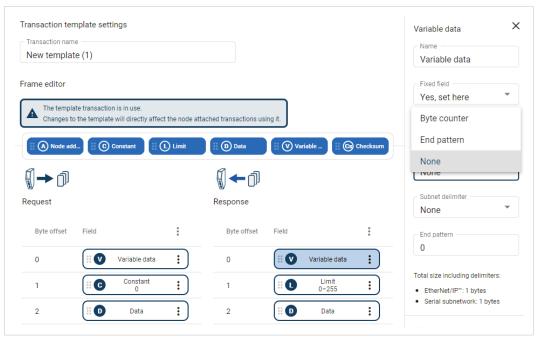
#### Subnet delimiter - Incoming data from a serial node to the Communicator

The Communicator can be configured to expect data from one of the three Subnet delimiter options; Byte counter, End pattern or None.

If the incoming data match the Subnet delimiter format the data is captured and the data section is forwarded to the high level network.

If the incoming data do not match the Subnet delimiter format, the data is ignored and will be matched with the next consume transaction.

#### **Transaction template Variable data settings**



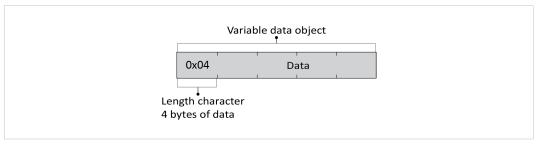
1. Select a desired Variable data object.

- 2. In the **Data delimiter** and/or **Subnet delimiter** drop down menu, select one of the following options:
  - Byte counter

The data packet consists of a length character, indicating the length of the data section, followed by the variable data object itself.

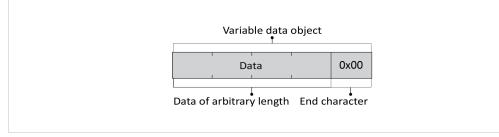
In order to copy the exact data size from the transaction message, the length of the variable data object is first identified.

In this example we have added a length character with 4 bytes of data.



### End pattern

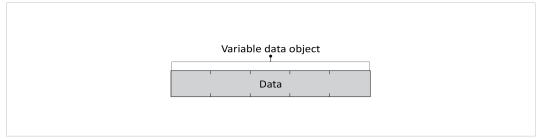
The package consists of a data section followed by an end character to indicate where the data section ends.



#### - None

The package contains only the data section.

By measuring the total length of the message, the length of the data section can be calculated.



3. When a delimiter is set to End pattern: In the **End pattern** field, enter the value that will define the end of the payload.

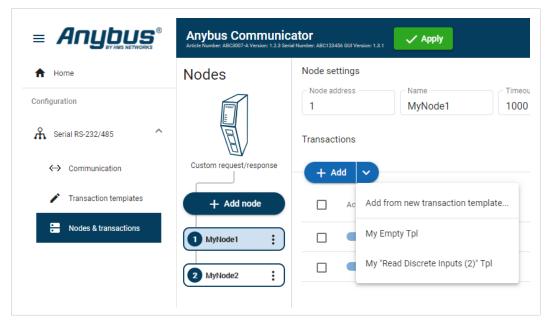
End pattern is used to define whether the delimiter is an end character or an end pattern, which depends on whether the message is forwarded from the subnetwork or sent as process data.

### 7.7.5 Store Transaction Templates

The transaction templates are stored on the **Transaction templates** page.

	Anybus Communicator Article Number: ABC1007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version: 1.2.1				
A Home	Transaction templates	Transaction template settings			
Configuration	+ Add V	Transaction name My Mask Write Register (22) Tpl			
Serial RS-232/485	My Mask Write Register (22) Tpl	Frame editor			
<ul><li>↔ Communication</li></ul>	My template (1)	A Node add			
Transaction templates	My template (2)	(] → (ĵ			
Nodes & transactions	My Write Single Register (6) Tpl	Request			

The transaction templates are available for use on the **Nodes & transaction** page, when you add transactions to a node.



For information on how to add the transaction templates to the nodes, refer to *Transaction Settings, p. 64*.

# 7.8 Nodes and Transactions

A node represents a single device on the serial subnetwork.

Add nodes and set up the communication between the nodes and the client.

#### **Before You Begin**

Obtain user documentation, from the manufacturers of the devices to communicate with, describing available registers and how to address them.

### 7.8.1 Node and Broadcast Node

You can add two types of nodes, Node and Broadcast Node.

A Home	Nodes
Configuration	
A Serial RS-232/485	
<b>↔</b> Communication	Custom produce/consume
Nodes & transactions	+ Add V
Transaction templates	Broadcast :
	1 New node

#### Broadcast node

- You can add one single Broadcast node.
- The Broadcast node can only hold produce transactions.

#### Node

- You can add up to 31 Nodes.
- The type of transactions a node can hold depends on the serial protocol used, refer to *About Transaction Templates, p. 40.*

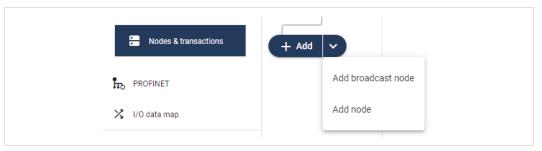
### 7.8.2 Add Node

You can add one single Broadcast node.

The maximum number of Nodes that can be added is 31.

#### Procedure

- 1. In the web-interface left sidebar menu, click **Nodes & transactions**.
- 2. Click Add node .
- 3. Select Add broadcast node or Add node.



#### $\rightarrow$ A new node/brodcats node is added to the nodes list.

	Anybus Communic Article Namber: AB7710-A Version: 1.2.3 Serial	
A Home	Nodes	Node settings
Configuration		Slave address         Name         Timeout time         Reconnection till         Retries           1         New node         1000         ms         Retries         0
Serial RS-232/485 ^		Address format
Communication settings	Modbus RTU	
Nodes and commands		Modbus commands
	+ Add node	+ Add
	New node	Active Command name Function Quantity Address

#### To Do Next

Configure the Node Settings, *Node Settings*, *p. 60*.

# 7.8.3 Node Settings

### **Before You Begin**

Ensure that the Communicator Basic settings, on the Communication page, match the Node settings.

There are no Node settings for the Broadcast node, except Name.

### Procedure

Anybus Communic Article Number: AB7710-A Version: 1.2.3 Seria	
Nodes	Node settings       Slave address       Name       Timeout time       Reconnection ti       Retries         1       New node       1000       ms       0       0         Address format
+ Add node	Active Command name Function Quantity Address

1. In the nodes list, select a node to configure.

### 2. Configure the *Node settings*.

Setting	Value	Description
Node address	1 to 247	Node ID, also called node address, is the node's identity on the subnetwork.
		The node id is a number between 1 and 247.
		By default, the node is assigned the next available number.
		The same node id cannot be used on multiple nodes.
Name	N/A	By default, the node is assigned the name New node and the corresponding Server address. The node name can be changed
Timeout time	10 ms to 10 000 ms Default value: 1000 ms.	If a transaction in a transaction fulfills the specified timeout time value for all specified retries, the remaining transactions defined for the node will be skipped in the current cycle.
		The maximum addition to the cycle length is only one instance of the timout setting.
		Specify how long the Communicator should wait before sending the message again, when no response is received from the node.
		If the timeout time is exceeded, the Communicator continues to send the message until the maximum number of retries has been reached.
Reconnection time	Min 10 ms Max 60 0000 ms	Specify for how long the Communicator should wait before attempting to reconnect, if the node is disconnected.
	Default 10 000 ms	The default value is 10 000 ms.
		Reconnect time (10 ms) is not applicable for the <i>broadcast</i> node, that hold transactions destined to all nodes.
Retries	0 to 10 Default value: 3	Specify the number of attempts the Communicator should make, when no response is received from the node.
Address format	Default format: Address	Specify the address format for the node.
Available for the	Register	Address: 0, 1, 2,
Modbus TCP serial	Modicon Modicon extended	Register: 1, 2, 3,
protocol.		Modicon: 00001/10001/30001/40001
		Modicon extended: 000001/100001/

3. To apply the settings, click **Apply** in the web-interface header, and follow the instructions..

### To Do Next

Add Transactions, Add Transactions, p. 62.

### 7.8.4 Add Transactions

(i) The maximum number of transactions that can be added to a node is 150.

- 1. In the nodes list, select a node to configure.
- 2. In the transactions list, click Add.
- 3. Choose one of the following alternative:

#### When using the Modbus RTU Serial Protocol

Click Add and select a transaction from the list of standard Modbus RTU transactions.

A Home	Nodes	Node settings
Configuration	A	Node address         Name           1         New node
A Serial RS-232/485		Transactions
< ↔ > Communication	Modbus RTU	+ Add v
Nodes & transactions	+ Add V	Read Coils (1)
	New node	Read Discrete Inputs (2) [1]
🔀 I/O data map		Read Holding Registers (3)
Maintenance		Read Input Registers (4)
Files & firmware		Write Single Coil (5)
Troubleshooting		Write Single Register (6)
Diagnostics V		Write Multiple Coils (15)
G Support		Write Multiple Registers (16)
		Mask Write Register (22)
		Read Write Multiple Registers (23)

### When using the Request/Response or Produce/Consume Serial Protocol

✿ Home	Nodes	Node settings
Configuration		Node address Name New node
Serial RS-232/485		Transactions
<> Communication	Custom request/response	+ Add V
Nodes & transactions	+ Add ~	Add from new transaction template
	New node	New template (1)

- Click Add and select Add from new transaction template.
  - $\rightarrow$  You are redirected to the **Transaction template** page.

A new empty template is added to the Transaction templates list.

You need to build the transactions before you can use the template, refer to *Build Transaction Templates, p. 46*.

A Home	Transaction templates	Transaction template settings
Configuration	+ Add V	Transaction name New template (1)
A Serial RS-232/485	New template (1)	Frame editor
<ul> <li>←&gt; Communication</li> </ul>		The template transaction is in use.     Changes to the template will directly affect the node attached transactions using it.
Nodes & transactions		O Node add     O Constant     O Limit     O Data     O Variable d     O Constant     O Constant
Transaction templates		
		Request

- If you already have created Transaction templates, click Add and select the desired template from the list.
  - $\rightarrow$  A new transaction is added to the transactions list.

	Anybus Communicator Article Number: AB7710-A Version: 1.2.3 Serial Number: ABC12	23456 OUI Version: 0.44.1
Nodes	Node settings	
	Slave address         Name           1         New node	Timeout time         Reconnection ti_         Retries           1000         ms         10000         ms         0
E	Address format Address (0, 1, *	
Modbus RTU	Modbus commands	
+ Add node	+ Add	Duplicate 📋 Delete
1 New node	Active Command name	Function Quantity Address
	New command	Read Holding Registers (3) 1 0

#### To Do Next

Configure the Transactions settings, Transaction Settings, p. 64.

### 7.8.5 Transaction Settings

### **Before You Begin**

(j) w/

When a custom transaction is selected, the custom transaction template is locked for editing.

For Modbus transaction reference guide, refer to *Modbus Transactions, p. 121*.

#### Procedure

Modbus RTU Protocol:

	Anybus Communicator Artisk Nueteer A77164 Version: 12.3 Strid Nueteer ALCT2265 031 Version: 8.4.1	
Nodes	Node settings Stave address Stave address Name Timeout time Beconnection time Retries Contended Retrie	Command name New command Modbus command Read Holding Regist * Address 0
New node	Active Command name Function Quantity Address	1
	New command Read Holding Registers (3) 1 0	Update mode Cyclically Update time 1000 ms

#### Custom Request/Response Protocol:

Nodes	Node settings		2
	Node address	Name         Timeout time         Reconnection ti         Retries           My first Node         1000         ms         10000         ms         0	Command name New command (1)
E	Commands		Custom command My first custom com *
Custom request/response	+ Add	I Duplicate	Delete
+ Add node	Active	Command name Custom command name Size to EtherNet/IP <sup>~</sup> (bytes) Size from EtherNet/IP <sup>~</sup>	(bytes) Update mode Cyclically
1 My first Node		New command (1) My first custom command 1	0 Update time
			1000 ms

- 1. In the nodes list, select a node to configure.
- 2. In the transactions list, select a transaction to configure.
  - $\rightarrow$  The transaction sidebar opens, on the right side of the screen.
- 3. Enter a transaction name.

By default, the node is assigned the name New transaction.

4. Select a transaction type from the **Modbus transaction/Custom transaction** drop-down menu.

The transaction type defines what the node should perform when the transaction is executed.

5. Configure the Transaction settings.

Setting	Value	Description
Transaction name	N/A	You can name the transaction to make it easier to identify.
Read quantity	1 to 125	Specifies the number of registers to read in the read data field. Appear when Modbus transaction Read Write Multiple Registers (23) is selected.
Address	0 to 65 535	Specify the start address for the read/write transaction.
		The address acts as an address to the data position, where the data is read from or written to. Modbus holding register addresses starts at 0.
Write quantity	Read Write Multiple Registers (23) 1 to 123	Modbus address 0 = Register 1 Specifies the quantity of registers/coils to write in the write data field. Appear when Modbus transaction Read Write Multiple Registers (23) is selected.
Quantity	Read Holding Registers (3) Read Input Registers (4) 1 to 125	The Quantity parameter appear when you select a Modbus transaction that can address more than one data object.
	Write Multiple Coils (15) 1 to 1968	Example when Quantity is set: For the Modbus Transaction <i>Read Input Registers (4)</i> you need to set the Quantity in order to define the array of data.
	Write Multiple Registers (16) 1 to 123	Example when no Quantity is set: For the Modbus Transaction <i>Write Single Coil (5)</i> you do not need to set the Quantity parameter because there can not be an array of data. The transaction is used to write a single output to either ON or OFF in a remote device.
	Read Coils (1) Read Discrete Inputs (2) 1 to 2000	For Write Single Coil (5), Write Single Register (6) and Mask Write Register (22) Quantity cannot be set.
Constant	0 to 255	The value of the Constant in the frame.
Data	0 to 512	The length of the data field.
Variable data	0 to 255	The maximum payload length of the variable data field.
Update mode	Cyclically On data change Single shot Change of state on trigger	Specify when a transaction shall be sent to the server. The transaction is issued cyclically, at the interval specified in the Update time parameter.
		Cyclically: The transaction is sent cyclically, at the interval specified in the Update time parameter.
		On data change: The transaction is sent when the data is changed
		Single shot: The transaction is issued once at start up.
		Change of state on trigger: The transaction is triggered when the content of a specified byte changes. In the I/O data map, the node will be marked with a flash icon.In the I/O data map you car also configure the area map and the trigger byte address. Refer to <i>Trigger Byte, p. 74</i> .
Update time	3 ms to 60 000 ms	Update mode parameter must be set to Cyclically. The Update time parameter appear when Cyclically is select.
		Specify how often, in steps of 10 ms, the transaction are going to be issued.
Positive ack	N/A	When Positive Acknowledgement is enabled, the positive ack data byte in the I/O data map is incremented each time this transaction succeeds.
Negative ack	N/A	When Negative Acknowledgement is enabled, the negative ack data byte in the I/O data map is incremented each time this transaction fails.

6. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

### 7.8.6 Activate/Deactivate Transaction

Modbus	command	ds			
- + A	dd			Duplicate	<b>Delete</b>
$\checkmark$	Active	Command name	Function	Quantity Add	ress
		New command	Read Holding Registers (3)	1 0	

The transaction default status is Active.

To deactivate/activate a transaction, select the transaction and click the **slide toggle**.

### 7.8.7 Duplicate Transaction

When you duplicate a transaction, all settings are preserved.

M	odbus o	command	s			
-(	+ Ad	ld			Duplicate	<b>Delete</b>
	<ul> <li>Image: A start of the start of</li></ul>	Active	Command name	Function	Quantity	Address
			New command	Read Holding Registers (3)	1	0

To duplicate:

- One transaction, select the transaction and click **Duplicate**.
- Multiple transactions, select the checkbox in front of each transaction you want to duplicate and click **Duplicate**.
- $\rightarrow$  The duplicated transaction are added at the bottom of the transactions list.

### 7.8.8 Delete Transaction

Modbus	command	ds			
+ 4	dd			Duplicate	<b>Delete</b>
$\checkmark$	Active	Command name	Function	Quantity	Address
		New command	Read Holding Registers (3)	1	0

- 1. To delete:
  - One transaction, select the transaction and click **Delete**.
  - Multiple transactions, select the checkbox in front of each transaction and click **Delete**.
- 2. To confirm, click Yes.

# 7.9 High Level Network Settings

Configure the PROFINET network settings.

# 7.9.1 To Use Automatic I/O Sizes

Anybus Communicat Article Number: AB7710-A Version: 1.2.3 Serial Num	
PROFINET	
I/O sizes	
Use automatic I/O size When "Use automatic I/O sizes" is Data size to EtherNet/IP"	Checked the size of the I/O data to and from the OT network will be set to the same size as provided by the serial subnetwork.

By default, the Communicator is set to use automatic I/O sizes.

The size of the input data, *Data Size to PROFINET*, and the output data, *Data Size from PROFINET*, is determined by the subnetwork configuration.

The Data sizes can be between 0-1024 bytes.

In the Communicator built-in web interface, the Use Automatic I/O Sizes checkbox is selected.

### 7.9.2 To Configure I/O Sizes Manually

Anybus Communicat Article Number: AB7710-A Version: 1.2.3 Serial Nur	
PROFINET	
I/O sizes	
Use automatic I/O size When "Use automatic I/O sizes" is Data size to EtherNet/IP <sup>™</sup> 2	PS checked the size of the I/O data to and from the OT network will be set to the same size as provided by the serial subnetwork.

- 1. Deselect the Use Automatic I/O Sizes checkbox.
- 2. Enter a value for Data Size to PROFINET and a value for Data Size from PROFINET.

# 7.9.3 To Use DHCP Server

Anybus Communi Article Number: AB7710-A Version: 1.2.3 Ser	cator ial Number: ABC123456 GUI Version: 0.44.1	r Apply
IP Settings		
✓ DHCP enabled		
IP address 192.168.0.111	Subnet mask	Gateway address 192.168.0.1
Primary DNS	Secondary DNS 0.0.0.0	

By default, the IP settings are provided by the high level network DHCP server.

The **DHCP enabled** checkbox is selected.

#### **Default Communicator IP Settings**

The Communicator comes with the following factory default IP settings:

Setting	Default value
Web configuration IP address	192.168.0.10
Subnet mask	255.255.255.0
Gateway address	There is no default Gateway address.
Primary DNS server	There is no default Primary DNS server.
Secondary DNS server	There is no default Secondary DNS server.
DHCP	Enabled
Host name	There is no default Host name.

# 7.9.4 To Configure IP Settings Manually

Anybus Communi Article Number: AB7710-A Version: 1.2.3 Ser	cator ial Number: ABC123456 GUI Version: 0.44.1	Apply
IP Settings		
DHCP enabled		
IP address	Subnet mask	Gateway address
192.168.0.10	255.255.255.0	0.0.0.0
Primary DNS	Secondary DNS	
0.0.0.0	0.0.0.0	

- 1. Deselect the **DHCP enabled** checkbox.
- 2. Configure the IP settings.

Setting	Description
IP address	The PROFINET network IP address in IPv4 dot-decimal notation
Subnet mask	The PROFINET network Subnet mask in IPv4 dot-decimal notation.
Gateway address	ThePROFINET network Gateway address in IPv4 dot-decimal notation. If there is no gateway available, set the Gateway address to: 0.0.0.0
Primary DNS	The PROFINET network Primary DNS in IPv4 dot-decimal notation.
Secondary DNS	The PROFINET network Secondary DNS in IPv4 dot-decimal notation.

If you change a value and click **Refresh**, the value is reset to the last applied value.

3. To apply the settings, click Apply IP Settings.

# 7.10 Naming the Host

	on: 1.2.3 Serial Number: ABC123456	- GOT VETSION: 0.444.1		
Hostname				
€ <b>f</b> Refresh	🗸 Apply IP sett	tings		

You can label the Communicator.

- The maximum allowed length of the *Hostname* is 64 characters.
- No symbol characters, punctuation characters, or whitespace are permitted.
- Write the *Hostname* as one single word.

# 7.11 Station Name

	Anybus Communicator PIR Article Number: ABC3007:4 PIR Version: 1.2.3 Serial Number: ABC122456 PIR GUI Version: 2.1.1
A Home	PROFINET settings
Configuration	Station name
	Cy Refresh V Apply station name
X I/O data map	

A PROFINET device is identified by its Station name in the PROFINET network.

Enter a Station name for the Communicator.

- The maximum allowed length of the *Station name* is 240 characters.
- No symbol characters, punctuation characters, or whitespace are permitted.
- Write the *Station name* as one single word.

# 7.12 I/O Data Map

data map				
				Optimize Expor
		Data from PROFINE		
ddress Node		Address	Node	
1 1 My Machine Read Colls		0 1	My Machine Write Multiple Colls	
2 5 My Machine Read Write Multiple Registers		2 11	My Machine Read Write Multiple Registers	
i 9 My Machine Read Holding Registers		12 1499		
	to PROFINET  doless Node 1  My Machine Read Colls 5  My Machine Registers	to PROFINET  doftess Node	to PROFINET         Data from PROFINE           odress         Node	to PROFINET         Data from PROFINET           odress         Node

On the **I/O data map** page the data communication between the subnetwork (Node) and the high level network (PLC) is mapped.

The allocated I/O area is auto-generated based on how the settings on the **Serial communication** page and the **Nodes and transactions** page are configured.

It is possible to set the I/O area manually, if you want to pro-actively allocate more I/O for future expansions without re-configuring the PLC. Refer to *To Configure I/O Sizes Manually, p. 67*.

There are three areas: Data from PROFINET, Data to PROFINET and General Areas. Refer to *Map Area*, *p.* 73.

# 7.12.1 Optimize the I/O Data Map

The optimize function is used to automatically remove gaps between the mapping.

Optimize remove gaps between the data objects in the map and should be used with care on already commissioned systems. Expected mapping in the PLC may change.

 ${igin i}$  If you optimize the I/O data map, the current I/O data map will be overwritten.

Anybus Communicator Article Number: ASC3007 A Version: 1.2.3 Gardi Number: ASC122455 GUI Version: 1.01.1	yiqq
I/O data map	
	Image: Second
Data to PROFINET	Data from PROFINET

To optimize the map:

- 1. Click Optimize.
- 2. To confirm, click OK.

# 7.12.2 Map Area Transactions Order

I/O data map			
$ \underbrace{\blacksquare}_{\text{RC}} \rightarrow \underbrace{\blacksquare}_{\text{RC}} - $ Data from PROFIN		Data to PROFINET	
Address 0	Node If My Node Transaction 1 Data 1	Address Node I My Node Transaction 1 Data 3 0 II My Node Transaction 1 Data 2	
1 1499		1 2 1499	

To change the order of the transactions in a map area, drag and drop the desired transaction to a new location.

Data from PROF	→ ĴĴ INET	Data to PROFINET	
🔵 Data exc	hange control	D Live list	
Address	Node	Address Node	
0	My Node New transaction (1) Data	0 My Node New transaction (1) Data 1	
1 1499		0 My Node New transaction (1) Data2	
		1 1499	

Transactions can not share the same I/O are.

If multiple transactions are placed in the same I/O area, the area is highlighted.

# 7.12.3 Map Area

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC123456 GUI Version	• 199.1 <b>Apply</b>	
Ame Home	I/O data map		:
onfiguration			Map area
Jungulation		Optimize Export	Input/Output
Serial RS-232/485			O General
			O Unmapped
<ul> <li>↔ Communication</li> </ul>	Data from PROFINET	Data to PROFINET	<ul> <li>Start address</li> </ul>
Nodes & transactions	Data exchange control	Dive list	0
	Address Node	Address Node	Endian swap
PROFINET			Bytes, AB ➡ BA 🔍
🗸 I/O data map	0 1499	0 1 New node New transactio	Offline option
yg iyo data map -			Clear
aintenance		2 1499	

#### Map area options

You must specify the map area to use for each transaction in the I/O data map.

Select one of the following Map area options:

- Input/Output: The transaction data is sent/recieved to/from the high level network.
- **General**: This area is used for transferring transaction data between individual nodes on the subnetwork.

When General is selected, the transaction data cannot be accessed from the high level network.

• **Unmapped**: The transaction data is not used.

#### Start address

For Input/Output and General, you can enter a start address for the transaction data.

### 7.12.4 Trigger Byte

Trigger byte is used to enable/disable the trigger functionality for the response.

When Trigger byte is enabled, the Communicator increases the trigger byte by one when the Communicator receives new data from the subnetwork.

The Trigger byte is stored in the **Data from PROFINET** area or the **General** area.

The location of the trigger byte is specified by the address.

O data map			Map area
		Optimize	Export  From EtherNet/IP**
▯→∬→▯		()≠0	O General
-	-	-	O Unmapped
ata from PROFINET	Data to PROFINET	General area	Address
Data exchange control	Dive list		0
Address Node	Address Node	Address Node	
0 New node New transaction (1)	0 1 New node New transaction (1) R.	0 1499	
1 1499	2 1499		

#### How to Enable Trigger Byte on a Node

#### Procedure

- 1. Navigate to the **Nodes & transactions** page.
- 2. Select the decried node and transaction.
- 3. In the transaction sidebar Update mode menu, select Change of state on trigger.
- 4. Navigate to the **I/O data map** page.
- 5. The transaction with the trigger byte enabled is marked with a flash icon.

To open the Map Area sidebar, click on the flash icon.

6. In the Map Area sidebar, specify the map area to use and the trigger byte address:

#### Map area options

- From PROFINET: The trigger byte is stored in the I/O data map Data from PROFINET area.
- **General**: The trigger byte is stored in the I/O data map General area.
- **Unmapped**: The transaction data is not used.

#### Address

 Enter an Address, the location in the specified Map area (From PROFINET or General) where the trigger byte will be saved.

Value: 0 (default) to 1499

#### 7.12.5 Endian Swap

In most PLCs, PROFINET can be configured to use either Little-endian format or Big-endian format.

#### **Big-endian**

The big-endian format places the most significant byte of the data at the byte with the lowest memory address.

#### Little-endian

The little-endian format places the least significant byte of the data at the byte with the lowest memory address.

To convert between big-endian and little-endian you must reverse the byte order.

O data map		
	Optimize	Export Data mapped to I/O
<b>←</b> ()	$\frac{\mathbf{I} + \mathbf{I}}{\mathbf{r}_{c}} \rightarrow \mathbf{I} \rightarrow \mathbf{I}$	0
ata to PROFINET	Data from PROFINET	No swapping
Address Node	Address Node	Bytes, ABCD ➡ BADC
0 1 New node New command	0 1499	Words, ABCD ➡ CDAB Bytes and words, ABCD ➡ DCBA

To reverse the byte order:

- 1. In the web-interface left sidebar menu, click **I/O data map**.
- 2. In the data map, select the transaction for which you want to do swap the byte order.
- 3. Select the swapping type from the Endian swap drop-down menu.

Setting	Description
No swapping	Default setting No swapping is performed on the data.
Byte swap	Swap 2 bytes A B C D becomes B A D C
Word swap	Swap 4 bytes A B C D becomes C D A B
Byte and Word swap	A B C D becomes D C B A

4. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

# 7.12.6 Offline Option

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version	ae: 1.1.1 Apply	
A Home	I/O data map		>     Data mapped to I/O
Configuration		Optimize Export	Start address
A Serial RS-232/485 V			0
PROFINET	Data to PROFINET	Data from PROFINET	Endlan swap
🗙 I/O data map	Live list	Data exchange control	Bytes, AB ➡ BA ▼
Maintenance	Address Node	Address Node	Clear
Files & firmware	0 1499	0 New node New transaction (1)	Freeze
roubleshooting	0 1499	New transaction (1)	No scanning
		1 1499	

Offline mode is used to define what data to send if the network connection or connection with a specific node is lost.

You must specify the offline mode to use for each transaction on the I/O data map.

Select one of the following Offline options:

- Clear (Default): The data is cleared and the value 0 is sent.
- Freeze: The Communicator holds the value until the connection is restored.
- No scanning: Stop sending this transaction on the sub-network. This option is only valid for produce and request transactions.

# 7.12.7 Live List

	<b>⊷ () ←</b> (	<u>ן</u>	
Data to F	ROFINET		
💶 Li	ve list		
Addre	SS	Node	
0	3	Reserved area for the live list.	
4		New node Cons	
5	1499		

By default Live list is disabled.

When Live list is enabled, the first four bytes of process data on the PROFINET network contain the live list.

The Live list holds 32 bits.

Each bit in the Live list can hold the status for a total of 32 nodes connected to the Communicator.

The bit is 0 when the bit does not correspond to the configured node. For example, this occurs when the number of configured nodes is less than 32.

Each bit is 1 when the corresponding node is online.

## 7.12.8 Data Exchange Control

Data from PROF	► Ĵ
🔲 Data exc	hange control
Address	Node
0 3	Reserved area for the data exchange control.
4 1499	

By default Data exchange control is disabled.

When Data exchange control is enabled, the first four bytes of process data on the PROFINET network contain the data exchange control.

The Data exchange control holds 32 bits.

Each bit in the Data exchange control can be used to enable/disable data exchange for individual nodes on the subnetwork.

If control bit does not correspond to a configured node, the control bit is ignored. For example, this occurs when the number of configured nodes is less than 32.

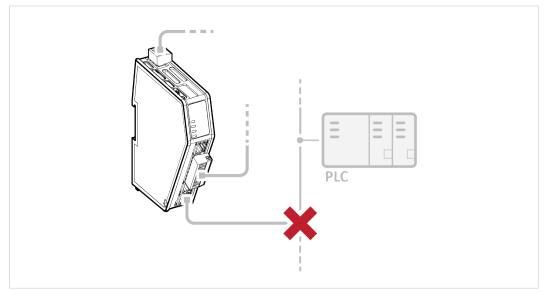
When the data exchange is enabled for the corresponding node, the control bit is 1.

# 7.13 Apply Configuration

## **Before You Begin**

 ${ig i}$  When you apply the configuration, any existing configuration is overwritten.

#### Disconnect the Communicator from the PROFINET network



Before you can apply the configuration, ensure that there is no active communication on the PROFINET network where the Communicator is connected.

#### Procedure

To make the settings take effect, download the configuration to the Communicator:

1. In the web-interface header, click **Apply** 

Anybus Communicator Article Number: AB7710-A Version: 1.2.3 Serial Number: ABC123456 GUI Version: 0.44.1
---

#### 2. To confirm download, click Apply.

Apply configuration
Do you want to apply the configuration? Any exist configuration in the Communicator will be overwi
Cancel

 $\rightarrow$  The configured settings are downloaded and applied to the system.

If you have made changes to the IP settings you are prompted to apply these settings.

3. To apply the IP settings, click **Apply IP settings**.

Apply IP settings
The configuration was successfully applied. The IP settings differ from the previous configuration and are not applied. Do you want to apply the IP settings?
Cancel Apply IP settings

# 7.14 Use an Existing Configuration

When you have configured a Communicator and want to use the same settings to configure additional Communicators, do the following.

#### Procedure

	Anybus Communicator Article Number: AB7710A Version: 1.2.3 Bental Number: ABC122455 GUI Version: 0.44.1
A Home	Files & firmware
Configuration	Configuration
A Serial RS-232/485 🗸	En Import Export
PROFINET	Import or export the configuration locally on PC or handheld device.
X I/O data map	X Clear
Maintenance	Clear all settings in the configuration to their default values. This will not affect the module until the "Apply" button is pressed.
Files & firmware	<ol> <li>Revert</li> </ol>
Troubleshooting	Revert all settings in the configuration to the values in the module's current configuration.

In the built-in web-interface of the Communicator with the configuration you want to use:

- 1. On the Files & firmware page, click Export
  - $\rightarrow$  The configuration is saved in an conf file and downloaded to your PC.

In the built-in web-interface of the new Communicator to be configured:

- 2. On the Files & firmware page, click Import
- 3. In the Import configuration window, click Select file (.conf).
- 4. In the Open dialog box, browse to and select the configuration file and click **Open**
- 5. To import the configuration file, click **Import**.

#### Result

All the configuration settings are imported.

To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

# 8 PLC Configuration

# 8.1 Export I/O Data Map

When configuring the communication between the PLC and the nodes on the subnetwork, use the I/O data map as a specification to ensure that the transactions match.

In the Communicator built-in web-interface:

Anybus Communicator Antice Kunter: ABC0207-A Version: 1.2.3 Grind Number: ABC123456 GUI Version: 1.01.1		
I/O data map		
		Optimize Export
Data to PROFINET	Data from PROFINET	

On the I/O data map page you can exported the I/O data map in an Excel XLS file, where all the nodes and transactions are listed.

To export the I/O data map:

- 1. Click Export.
  - $\rightarrow~$  An Excel XLS file with the mapping is downloaded to your PC.

# 8.2 Export Product GSDML File

Option if the PLC program requires a product file, GSDML (Generic Station Description Markup Language) file, describing how the Communicator can be used on the high level network.

	Anybus Communicator Article Number: AB7710-A Version: 1.2.3 Serial Number: ABC123456 GUI Version: 0.44.1
Configuration	PROFINET GSDML file
Serial RS-232/485 🗸	GSDML file
PROFINET	Extract the GSDML file from the archive and use it to configure the PROFINET PLC to use
🔀 I/O data map	the Communicator.
Maintenance	
Files & firmware	

You find the PROFINET GSDML file on the Communicator built-in web interface PROFINET page, Files & firmware page and on the Support page.

To export the GSDML file:

- 1. Click GSDML file.
  - $\rightarrow$  The GSDML file is downloaded to your PC.

# 8.3 Configure the PROFINET Connection

#### **Before You Begin**

- Configure the Communicator, refer to Communicator Configuration, p. 31.
- Download the PROFINET GSDML file from the Communicator built-in web interface, refer to *Export Product GSDML File, p. 82*.

#### Procedure

To configure the PROFINET connection:

- 1. Import the PROFINET GSDML file into your PLC configuration tool.
- 2. Select the input module and output module.

Ensure that the I/O data sizes match the I/O data sizes configured on the Communicator built-in web interface PROFINET page, refer to *To Use Automatic I/O Sizes, p. 67* and *To Configure I/O Sizes Manually, p. 67*.

# 9 Verify Operation

### **Before You Begin**

Ensure that the Communicator is connected to your PC, to a power supply and to the OT network.

Refer to Installation, p. 16.

# 9.1 Communicator Status Monitor

On the Home page, you can get a quick overview of the network and the Communicator operating status.

	Anybus Communicator Article Number: ABC2007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version: 1.01.1
Home       Configuration       ♣ Serial RS-232/485       ♣ PROFINET       ↓ //O data map	<ul> <li>PROFINET Setup in progress IP: 192.168.0.111 ↑ 2 byte(s) ↓ 0 byte(s) More information</li> <li>Anybus Communicator Initial state</li> </ul>
Maintenance Files & firmware	Anybus* Gateway EtherNet/IP* Serial â
Troubleshooting	Serial RS-232/485 Ready for initialization Modbus RTU, RS-232, 9600 baud ↓ 0 byte(s) ↑ 2 byte(s) More information

#### **Gateway status**

Overview the Communicator LED indications remotely.

Refer to Communicator LED Indicators, p. 86.

#### **Node Status**

Overview the status for each node added to the subnetwork.

#### **Network Status and Settings**

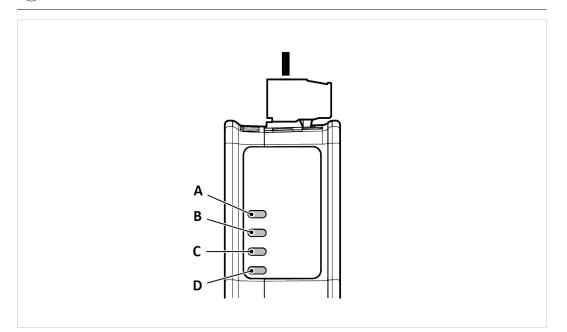
Overview communication status and the current networks settings.

Symbol	Description
	Internal error has occurred and operation cannot be guaranteed.
2	Out of Specification.
7	Check Function: <ul> <li>Initial state where non network components are started and configured.</li> <li>Network startup in progress.</li> <li>Invalid configuration detected.</li> </ul>
	Normal operation.

## Status Symbols

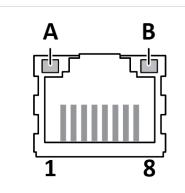
# 9.2 Communicator LED Indicators

Before you can verify operation you must configure the Communicator.



	LED A	LED B	LED C	LED D
Operation Status	Gateway status	PROFINET Slave	Subnetwork	Security switch
Off	No power	No connection with IO controller	No power/Exception/ Subnetwork not running	No power/Security switch is unlocked/ Exception/Fatal error
Green, flashing	Startup phase	Used by engineering tools to identify the node on the network	Running, one or more nodes are offline	N/A
Green, one flash	Startup phase	Connection with IO controller establish IO controller in STOP state or IO data bad	Running, one or more nodes are offline	N/A
Green	Operational	PROFINET network online, one or more connections established	Running	Security switch is locked
Red	Exception/Fatal error	FATAL event	Fatal error	N/A
Red, one flash	Exception/Fatal error	Station name not set.	Fatal error	N/A
Red, two flash	Exception/Fatal error	IP address not set.	Fatal error	N/A
Red, three flash	Exception/Fatal error	Expected Identification differs from Real Identification	Fatal error	N/A
Red, flashing	Invalid configuration	One or more connections timed out	All nodes are offline	N/A
Green/Red, flashing	Power up self-test/ Firmware update/ Firmware recovery	N/A	N/A	N/A

# 9.3 Ethernet LED Indicators



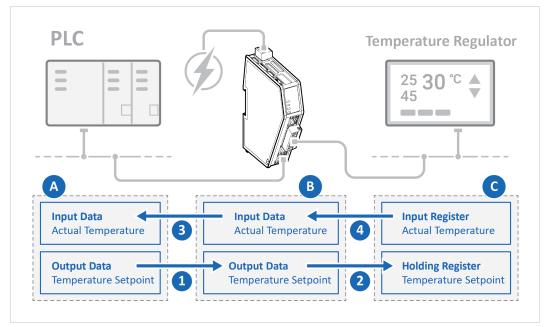
LED A	Function
Off	No link (or no power)
Green	Link (100 Mbit/s) established
Green, flashing	Activity (100 Mbit/s)
Yellow	Link (10 Mbit/s) established
Yellow, flashing	Activity (10 Mbit/s)
LED B	Function
Off	Not used

# 10 Use Cases

# **10.1** Temperature Regulator - Modbus RTU Use Case

# 10.1.1 About the Use Case

The purpose of this use case is to explain how to use the Modbus RTU serial protocol.



In this use case we use the Communicator to enable data exchange between an Temperature Regulator and a PLC.

The use case describes how to map the communication in the Communicator.

The Temperature Regulator is connected to the serial subnetwork via a custom RS-232 protocol.

The PLC is connected to an PROFINET network (high level network).

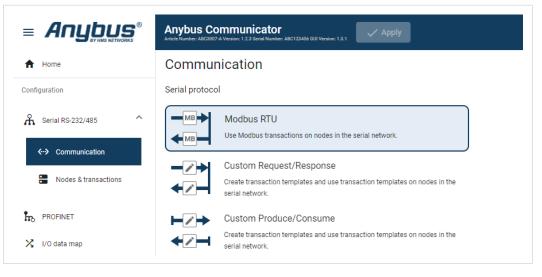
#### 10.1.2 Before You Begin

- Connect the Communicator configuration port to your computer.
- Power on the Communicator.
- Ensure that your computer can find the Communicator IP address.
- Enter the Communicator built-in web interface of the.

For more information refer to Communicator Configuration, p. 31.

## 10.1.3 Choose Serial Protocol Type

The Temperature Regulator is using a request/response protocol to access parameters addressed with index and sub index.



On the Serial RS232/485 page, select Modbus RTU.

### 10.1.4 Set Up Serial Communication

Set up the communication between the Communicator and the Temperature Regulator.

In the Serial RS232/485 page, configure the Communication settings.

isic settings									
Physical standard	I	– Baud rate –––––		– Data bits –––––		Parity ———		Stop bits ———	
RS232	-	19200 baud	-	8 data bits	-	None	-	2 stop bit	-

# Frame fields Value Physical standard RS-232 Baud rate 19200 baud Data bits 8 bits Parity None Stop bits 2 stop bit

#### Used the following settings:

# 10.1.5 Set Up the Node

	Anybus Communic Article Number: ABC3007-A Version: 1.2.3 Serie	ator Number ABC12265 608 Version: 1.95 1
A Home	Nodes	Node settings
Configuration	A	Node address         Name         Timeout time         Reconnection time           1         Temp Regulator         1000         ms         1000         ms
Serial RS-232/485		Address format
<ul> <li>↔ Communication</li> <li>■ Nodes &amp; transactions</li> </ul>	Modbus RTU	Transactions
Nodes & transactions	+ Add ~	+ Add V
	Temp Regulat.	Active Transaction name Modbus transaction Address Quantity

- 1. Add a node and select it.
- 2. In Node settings configure the node with the following settings:

Node settings	Value
Slave address	240
Name	Temp Regulator
Timeout time	1000 ms
Reconnection time	1000 ms
Retries	1
Address format	Register

### **10.1.6** Set Up Transactions

Set up the communication between the node and the master.

In this example, the communication between the Temperature Regulator and the PLC.

The Temperature Regulator has two Modbus transactions:

- One registers holding the setpoint temperature.
- One registers holding the actual temperature.

#### Procedure

1. Select the **Temp Regulator** node.

Configure the **temperature setpoint** transaction:

	Anybus Communio Article Number: ABIC3007 A Version: 1.2.3 Ge	Cator and human ANCI 2014 (60 Version 1 181	
★ Home	Nodes	Node settings	×
Configuration	E C	Node address         Name         Timeout time         Reconnection time           1         Temp Regulator         1000         ms         1000         ms	Transaction name Temp Setpoint
A Serial RS-232/485	E	Retries Address format	Modbus transaction Write Multiple Regi *
<ul> <li>↔ Communication</li> </ul>	Modbus RTU	Transactions	Address
- Nodes & transactions	+ Add ~	+ Add V Duplicate (1)	Quantity
ROFINET	Temp Regulat	Active Transaction name Modbus transaction Address Quantity	1
🔀 I/O data map		Temp Setpoint Write Multiple Registers (16) 0 1	Transaction
Maintenance			Cyclically
Files & firmware			Update time
Troubleshooting			1000 ms
Diagnostics V			Positive ack
G Support			Negative ack

- 2. To add a transaction, click Add.
- 3. Select the transaction to configure.
- 4. In the transaction sidebar, on the right side of the screen.

Enter values for the transaction settings.

Setpoint terr	perature trans	action settings:						
Setting	Value	Description						
Transaction name	Temp Setpoint	Give the transaction a name.						
Modbus transaction	Write Multiple Registers (16)	The PLC writes a block of contiguous registers to the temperature regulator.						
Address/ Register	Address: 0 Register: 1	Address 0 is Register 1.						
Quantity	1	The transaction will address one data object.						
Update mode	Cyclically	The temperature regulator sends a new message cyclically, every 1000 ms.						
Update time	1000 ms	The update cycle is 1000 ms.						

	Anybus Communicat Article Number: ABC2007-A Version: 1.2.3 Berlal No	OF ACTIZIÓN GOLVersier 19.1	
✿ Home	Nodes	Node settings	×
Configuration	A	Node address         Name         Timeout time         Reconnection time           1         Temp Regulator         1000         ms         1000         ms	Actual Temp
A Serial RS-232/485	E	Retries Address format Address (0, 1, 👻	Nodbus transaction Read Holding Regis 💙
←→ Communication     Nodes & transactions	Hodbus RTU	Transactions	Address 0
ROFINET	Temp Regulat.	Add      Transaction name Modbus transaction Address Quantity	Quantity 1
🄀 I/O data map		Temp Setpoint Write Multiple Registers (16) 0 1	Transaction
Maintenance		Actual Temp Read Holding Registers (3) 0 1	Update mode Cyclically
Troubleshooting			Update time 1000 ms
Diagnostics V			Positive ack
G Support			Negative ack

Configure the **actual temperature** transaction:

- 5. To add a second transaction, click **Add**.
- 6. Select the transaction to configure.
- 7. In the transaction sidebar, on the right side of the screen.

Enter values for the transaction settings.

Actual temp	erature transac	tion settings:						
Setting	Value	Description						
Transactio name	Actual Temp	Give the transaction a name.						
Modbus transaction	Read Holding Registers (3)	This register read the actual temperature from the temperature regulator to the PLC.						
Address	Address: 0 Register: 1	Address 0 is Register 1.						
Quantity	1	The transaction will address one data object.						
Update mode	Cyclically	Default value, can not be changed.						
Update time	1000 ms	The update cycle is 1000 ms.						

# Actual temperature transaction settings

# 10.1.7 Check the I/O Data Map

0-1

The transactions to and from the Temperature Regulator are mapped as follows in the **I/O data map** page.

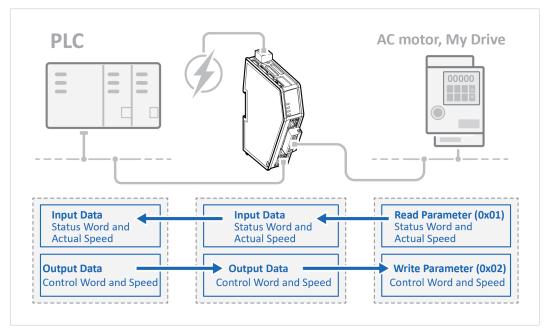
	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Berial Number: ABC122456 GUI Version: 1.99	a Apply	
A Home	I/O data map		
Configuration			Optimize
A Serial RS-232/485			¶≠⊅
<ul> <li>✓·· Communication</li> </ul>	Data from PROFINET	Data to PROFINET	General area
Nodes & transactions	Data exchange control	Live list	
B PROFINET	Address Node	Address Node	Address Node
🔀 I/O data map	U I Temp Setpoint	O T	0 1499
Maintenance	2 1499	2 1499	
ddress	Data to PROFINET		
-1	Setpoint temperature from PRC	FINET to the Temperature Regulator	r.
	1		
ddress	Data from PROFINET		

Actual temperature speed from the Temperature Regulator to PROFINET.

# **10.2** AC Motor Drive - Custom Request/Response Use Case

# **10.2.1** About the Use Case

The purpose of this use case is to explain how to use the **Custom Request/Response** serial protocol.



In this use case we use the Communicator to enable data exchange between an AC motor, of the type My Drive, and a PLC.

The use case describes how to map the communication in the Communicator.

My Drive is connected to the serial subnetwork via a custom RS-485 protocol.

The PLC is connected to an PROFINET network (high level network).

We use the Custom Request/Response serial protocol and create customized transaction templates to map up:

- Status word and actual speed from My Drive to the PROFINET network.
- Control word and speed from the PROFINET network to My Drive.

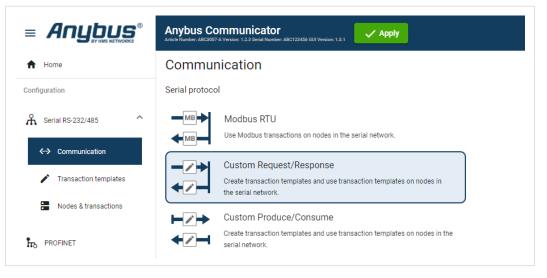
# 10.2.2 Before You Begin

- Connect the Communicator configuration port to your computer.
- Power on the Communicator.
- Ensure that your computer can find the Communicator IP address.
- Enter the Communicator built-in web interface of the.

For more information refer to Communicator Configuration, p. 31.

# 10.2.3 Choose Serial Protocol Type

My Drive is using a request/response protocol to access parameters addressed with index and sub index.



• On the Serial RS232/485 page, select Custom Request/Response.

# 10.2.4 Set Up Serial Communication

Set up the communication between the Communicator and My Drive.

In the Serial RS232/485 page, configure the Communication settings.

asic settings									
Physical standard		Baud rate		Data bits		Parity		Stop bits	
RS-485	*	57600 baud	•	8 data bits	*	None	*	1 stop bit	*

Used the following settings:	
Frame fields	Value
Physical standard	RS-485
Baud rate	57600 baud
Data bits	8 bits
Parity	None
Stop bits	1 stop bit

# Used the following settings:

#### **10.2.5** Create Transaction Templates

All frames are verified using a CRC-16-IBM checksum.

My Drive is using a request/response protocol to access parameters addressed with index and sub index.

Map up control word, speed from PROFINET to My Drive and status word and actual speed from the drive to PROFINET.

#### Create Read parameter (0x01)

The Communicator reads values delivered from to the My Drive node on to the PLC.

Anybus Communicator Article Number: ABC1207-A Version: 1.2.3 Serial Number: ABC123456 G	JI Version: 1.3.1	Apply						
Transaction templates	Transaction ten	nplate sett	tings					
+ Add V	Read parame		)					
Read parameter (0x01)	Frame editor							
	A Node add	) (= ©	Constant	Limit	D Data	V Variable d	📑 🕞 Checksum	
	<b>()→</b> ()				( <b>-</b> )			
	Request				Response			
	Byte offset	Field		:	Byte offset	Field		:
	0		Function code 1	:	0		Function code 1	:
	1		Node ID	:	1		Node ID	:
	2 3		Index 2	:	2 3		Index 2	:
	4		Sub index 1	:	4		Sub index 1	:
	5 6		Checksum	:	5 6		Data	:
					7 8		Checksum	:

- 1. Add an Empty template and select it.
- 2. Name the template **Read parameter (0x01)**.
- 3. In the Frame editor **Request** area, add five **frame fields** with the following settings:

Request frame fields										
Frame fields	Name	Bytes/ Length	Type/ Checksum type	Endianess	Fixed field	Value				
Constant	Function code	1	Byte	N/A	Yes	N/A				
Node address	Node ID	1	Byte	N/A	N/A	N/A				
Constant	Index	2	Word (two bytes)	Big-endian	No	Min 0 Max 1000				
Constant	Sub index	1	Byte	N/A	No	Min 0 Max 255				
Checksum	Checksum	2	CRC	N/A	N/A	N/A				

4. In the Frame editor **Response** area, add six **frame fields** with the following settings:

Response frame fields										
Frame field			Type/ Checksum type	Endianess	Fixed field	Value				
Constant	Function code	1	Byte	N/A	Yes	N/A				
Node address	Node ID	1	Byte	N/A	N/A	N/A				
Constant	Index	2	Word (two bytes)	Big-endian	No	Min 0 Max 1000				
Constant	Sub index	1	Byte	N/A	No	Min 0 Max 255				
Data	Data	2	Byte	N/A	Yes	N/A				
Checksum	Checksum	2	CRC	N/A	N/A	N/A				

# Response frame fields

#### Create Write Parameter (0x02)

The Communicator writes values delivered from the PLC to the My Drive node.

ransaction templates	Transaction ter	e						
Read parameter (0x01)	Frame editor	eter (0x02,	)					
Write Parameter (0x02)	Node add	1 ©	Constant	Limit	D Data	V Variable	d	n
	()→()				() <b></b> ()			
	Request				Response			
	Byte offset	Field		• •	Byte offset	Field		:
	0		Function code 1	:	0		Function code	:
	1		Node ID	:	1		Node ID	:
	2 3	:: C	Index 1	:	2 3	:: C	Index 2	:
	4		Sub index 1	:	4		Sub index 1	:
	56		Data	:	5 6	:: 🕒	Checksum	:

- 1. Add an Empty template and select it.
- 2. Name the template Write parameter (0x02).
- 3. In the Frame editor **Request** area, add six **frame fields** with the following settings:

Frame field	Name	Bytes/Length	Type/ Checksum type	Endianess	Fixed field	Value (Hex)
Constant	Function code	1	Byte	N/A	Yes	N/A
Node address	Node ID	1	Byte	N/A	N/A	N/A
Constant	Index	2	Word (two bytes)	Big-endian	No	Min 0 Max 1000
Constant	Sub index	1	Byte	N/A	No	Min 0 Max 255
Data	Data	2	Byte	N/A	Yes	N/A
Checksum	Checksum	2	CRC	N/A	N/A	N/A

4. In the Frame editor **Response** area, add five **frame fields** with the following settings:

Response frame fields									
Frame fields	Name	Bytes	Type/ Checksum type	Endianess	Fixed field	Value (Hex)			
Constant	Function code	1	Byte	N/A	Yes	N/A			
Node address	Node ID	1	Byte	N/A	N/A	N/A			
Constant	Index	2	Word (two bytes)	N/A	No	Min 0 Max 1000			
Constant	Sub index	1	Byte	N/A	No	Min 0 Max 255			
Checksum	Checksum	2	CRC	N/A	N/A	N/A			

# 10.2.6 Set Up Node and Transactions

odes	Node se	-	Name My Drive	Timeout time	ms 10000 n	ns 0	Transaction name Control Word
	Transact	ions					Transaction template Write Paramet *
Custom request/response	+ A	dd 🗸				Duplicate 📄 Delete	Request
+ Add node		Active	Transaction name	Transaction template name	Size to EtherNet/IP" (bytes)	Size from EtherNet/IP" (bytes)	Index
1 My Drive			Control Word	Write Parameter (0x02)	0	2	_ Sub idex
			Speed	Write Parameter (0x02)	0	2	1
			Status Word	Read Parameter (0x01)	2	0	Response
			Actual Speed	Read Parameter (0x01)	2	0	Index

1. Add a node and select it.

### 2. In Node settings configure the node with the following settings:

Node settings	Value
Node address	1 My Drive is set up as a node with Node address 1.
Name	My Drive
Timeout time	1000 ms (default)
Reconnecting time	10000 ms (default)
Retries	0 (default)

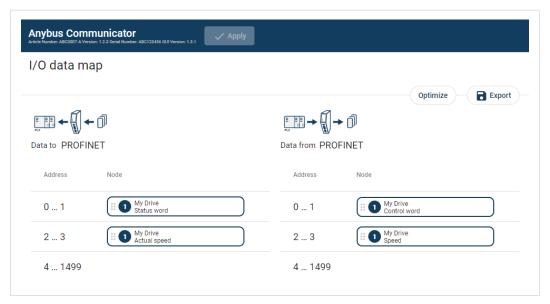
3. Add four transactions to the My Drive node and configure them with the following settings:

Transaction name	Transaction template	Index	Sub index
Control Word	Write Parameter (0x02)	1	1
Speed	Write Parameter (0x02)	1	2
Status Word	Read Parameter (0x01)	2	1
Actual Speed	Read Parameter (0x01)	2	2

#### My Drive contains the following parameters

## 10.2.7 Check the I/O Data Map

The control word, speed from PROFINET to My Drive and status word and actual speed from My Drive to PROFINET are mapped as follows in the **I/O data map** page.



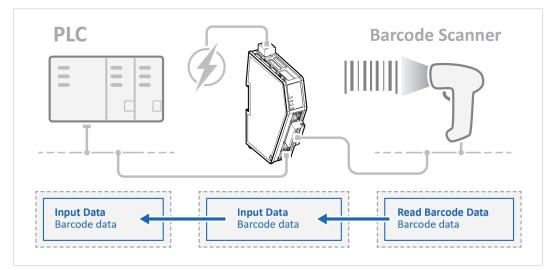
Control word and speed from PROFINET to My Drive							
Address	Data to PROFINET						
0-1	Control Word						
2-3	Speed						

Status word and actu	Status word and actual speed from My Drive to PROFINET					
Address	Data from PROFINET					
0-1	ontrol Word					
2-3	Speed					

# **10.3** Barcode Scanner - Custom Produce/Consume Use Case

# 10.3.1 About the Use Case

The purpose of this use case is to explain how to use the **Custom Produce/Consume** serial protocol.



In this use case we use the Communicator to enable data exchange between an Barcode Scanner and a PLC.

The use case describes how to map the communication in the Communicator.

The Barcode Scanner is connected to the serial subnetwork via a custom RS-232 protocol.

The PLC is connected to an PROFINET network (high level network).

We use the Custom Produce/Consume serial protocol and create a customized transaction template.

# 10.3.2 Before You Begin

- Connect the Communicator configuration port to your computer.
- Power on the Communicator.
- Ensure that your computer can find the Communicator IP address.
- Enter the Communicator built-in web interface of the.

For more information refer to Communicator Configuration, p. 31.

# 10.3.3 Choose Serial Protocol Type

The Barcode Scanner is using a produce/consume protocol to access parameters addressed with index and sub index.

	Anybus Communicator Article Number: ABC2807-A Version: 1.2.3 Benal Number: ABC122456 GUI Version: 1.99.1
A Home	Communication
Configuration	Serial protocol
<ul> <li>Serial RS-232/485</li> <li>←&gt; Communication</li> </ul>	MB Modbus RTU Use Modbus transactions on nodes in the serial network.
Nodes & transactions     Transaction templates	Custom Request/Response Create transaction templates and use transaction templates on nodes in the serial network.
	Custom Produce/Consume Create transaction templates and use transaction templates on nodes in the serial network.
🔀 🛛 I/O data map	

• On the Serial RS232/485 page, select Custom Produce/Consume.

# 10.3.4 Set Up Serial Communication

Set up the communication between the Communicator and the Barcode Scanner.

In the Serial RS232/485 page, configure the Communication settings.

sic settings									
Physical standard		Baud rate		Data bits		Parity		Stop bits	
RS-232	•	9600 baud	*	8 data bits	*	None	*	1 stop bit	-

Used the following settings:					
Frame fields	Value				
Physical standard	RS-232				
Baud rate	9600 baud				
Data bits	8 bits				
Parity	1				
Stop bits	1 stop bit				

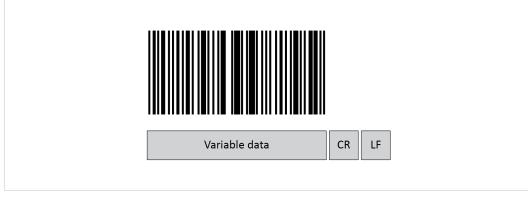
## **10.3.5** Create Transaction Templates

#### **Create Read Barcode Data Parameter**

#### **Before You Begin**

The Communicator reads values delivered from to the Barcode Scanner node on to the PLC.

The Barcode Scanner sends data whenever it is available, without any request or handshake from the Communicator.



In this example we have added three frame fields for the barcode data transaction:

- One Variable data frame for the length of the barcode.
  - We use a fixed value.

The maximum payload length is 31 (ASCII).

- The Barcode Scanner is configured to append:
  - One Carriage Return character (CR) to the barcode.

So we create one Constant frame with the Value 13 (ASCII).

– One Line Feed character (LF) to the barcode.

So we create one Constant frame with the Value 10 (ASCII).

### Procedure

	Anybus Communicator Article Number: ABIC102456 (	UlVersion: 198.1 Apply
✿ Home	Transaction templates	Transaction template settings
Configuration	+ Add V	Transaction name Read Barcode Data Template
Serial RS-232/485	Read Barcode Data Template	Transaction type O Produce  O Consume
Nodes & transactions		Frame editor
Transaction templates		The template transaction is in use. Changes to the template will directly affect the node attached transactions using it.
ROFINET		[]         []<
🔀 I/O data map		
Maintenance		Consume
Files & firmware		Byte offset Field
Troubleshooting		0 30 🛛 🐨 Barcode Data 🗄
Diagnostics		31 Carriage Return character (CR)
G Support		32 Line Feed character (LF)

- 1. Add an Empty consume template and select it.
- 2. Name the template **Read Barcode Data**.
- 3. In the Frame editor, add four **frame field** with the following settings:

Consume	Consume frame fields								
Frame fields	Name	Туре	Value	Fixed field	Maximum payload length	Process data delimiter	Subnet delimiter	End pattern	
Variable data	Barcode Data	N/A	N/A	Yes, set here	31 bytes	None	None	0	
Constant	Carriage Return character (CR)	Byte (1 byte)	13	Yes, set here	N/A	N/A	N/A	N/A	
Constant	Line Feed character (LF)	Byte (1 byte)	10	Yes, set here	N/A	N/A	N/A	N/A	

Set Up Node and Transactions

Anybus <sup>®</sup>	Anybus Communic Article Number: ABC2007-A Version: 1.2.2 Serie	ator Il Number: ABC1234		9.1 🗸 Apply	·			
Home	Nodes	Node set	-	Name	Scanner 1000		nnection time	Transaction name Read Barcode Data
Serial RS-232/485		Retries		Darcode	Scanner	ms 1000	00 ms	Transaction template Read Barcod *
Communication	Custom produce/consume	Transact	ions					Transaction
<ul> <li>Transaction templates</li> </ul>	+ Add ∨ Barcode Scan_ :	+ A	dd 🗸	Transaction	Transaction template	Duplicate (1)	Delete (1)	Positive ack
PROFINET			Active	name Read Barcode Data	name Read Barcode Data Template	(bytes)	(bytes) - 31	

- 1. Add a node and select it.
- 2. In Node settings configure the node with the following settings:

Node settings	Value
Node address	The Barcode Scanner is set up as a node with Node address 1.
Name	Barcode Scanner
Timeout time	1000 ms (default)
Reconnecting time	1000 ms (default)
Retries	0 (default)

3. Add one transactions to the Barcode Scanner node and configure it with the following settings:

The Barcode Scanner contains the following parameters	
Transaction name	Transaction template
Read Barcode Data	Read Barcode Data Template

# Check the I/O Data Map

The transactions from the Barcode Scanner is mapped as follows in the I/O data map page.

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC123456 GUI Version		
A Home	I/O data map		
Configuration			Optimize
A Serial RS-232/485	$\underset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}{\overset{H_{\mathcal{C}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}$		
<ul> <li>↔ Communication</li> </ul>	Data from EtherNet/IP™	Data to EtherNet/IP™	General area
Nodes & transactions	Data exchange control	Live list	
Transaction templates	Address Node	Address Node	Address Node
PROFINET	0 1499	0 30 Barcode Scanner Read Barcode Data	) 0 1499
🄀 I/O data map		31 1499	

Status word and actual speed from My Drive to PROFINET

Address	Barcode Scanner Parameter
0-31	The variable data, 31 bytes, are forwarded from the Barcode Scanner to the PLC.

# 11 Maintenance

# 11.1 Configuration File Handling

# **11.1.1** Export Configuration

You can export the current configuration, in order to import and use the same settings to configure additional Communicators.

	Anybus Communicator Article Number: AB7710A Version: 1.2.3 Genal Number: ABC122456 GDI Version: 0.44.1
A Home	Files & firmware
Configuration	Configuration
A Serial RS-232/485 V	import Export
PROFINET	Import or export the configuration locally on PC or handheld device.
🔀 I/O data map	X Clear
Maintenance	Clear all settings in the configuration to their default values. This will not affect the module until the "Apply" button is pressed.
Files & firmware	4 Revert
Troubleshooting	Revert all settings in the configuration to the values in the module's current configuration.

To export a configuration file:

- 1. In Files & firmware, click **Export**.
  - $\rightarrow$  The configuration settings are stored in a *.conf* file and downloaded to your PC.

#### **11.1.2** Import Configuration

To easily configure multiple Communicators with the same settings, you can import a configuration file.

#### **Before You Begin**

(1) Importing a configuration replaces the current applied configuration.

Supported file format is .conf.

#### Procedure

	Anybus Communicator Artice Number: AB7/10-A Version: 1.2.3 Berial Number: ABC/128456 GUI Version: 0.44.1								
A Home	Files & firmware								
Configuration	Configuration								
A Serial RS-232/485 🗸	Import Export								
PROFIBUS	Import or export the configuration locally on PC or handheld device.								
🔀 I/O data map	× Clear								
Maintenance	Clear all settings in the configuration to their default values. This will not affect the module until the "Apply" button is pressed.								
Files & firmware	C Revert								
Troubleshooting	Revert all settings in the configuration to the values in the module's current configuration.								

Import configuration file:

- 1. On the Files & firmware page, click **Import**.
- 2. In the Import configuration window, click Select file (.conf).
- 3. In the Open dialog box, browse to and select the configuration file and click **Open**.
- 4. In the Import configuration window, click **Import**.
- 5. In the Communicator address settings window:
  - To import *IP settings* from the selected configuration file, click **Imported settings**.
     All configuration settings are imported.
  - To continue using the current *IP settings*, click **Configured settings**.
     All configuration settings except the IP settings are imported.
- 6. The configuration file is parsed.
  - $\rightarrow$  If the configuration is compatible, the settings are imported.
  - $\rightarrow$  If any compatibility mismatches occurs, a message about the mismatch appears.
- 7. To apply the settings, click **Apply** in the web-interface header, and follow the instructions.

# 11.2 Clear and Revert Configuration

You can restore all settings in a configuration to the default settings.

#### Procedure

	Anybus Communicator Andre Number AB2710-A Version: 1.2.3 Setal Number: ABC123A56 GBU Version: 0.44.1
A Home	Files & firmware
Configuration	Configuration
A Serial RS-232/485 🗸	import Export
PROFINET	Import or export the configuration locally on PC or handheld device.
🔀 🛛 I/O data map	X Clear
Maintenance	Clear all settings in the configuration to their default values. This will not affect the module until the "Apply" button is pressed.
Files & firmware	C Revert
Troubleshooting	Revert all settings in the configuration to the values in the module's current configuration.

To clear the configuration:

- 1. On the Files & firmware page, click Clear.
- 2. In the Confirm clear window, click Clear.
- 3. To apply the change, click **Apply** in the web-interface header, and follow the instructions.

You can revert all changes done to the settings in the current configuration.

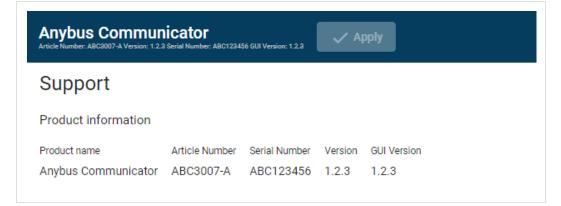
To Revert the configuration:

- 1. On the Files & firmware page, click **Revert**.
- 2. In the Confirm revert window, click Revert.
- 3. To apply the change, click **Apply** in the web-interface header, and follow the instructions.

### 11.3 Firmware Management

### 11.3.1 View the Firmware Version

On the **Support** page, you can view the current applied firmware version.



## 11.3.2 Firmware and Configuration Compatibility

#### Compatibility after firmware upgrade

Current configuration is still compatible after upgrading the firmware.

#### Compatibility after firmware downgrade



Compatibility after a firmware downgrade can not be guaranteed. The current configuration may use features not available in the older firmware version. Before the firmware file is imported into the system, the firmware upgrade function perform a validation of the file, to ensure that:

- the firmware is compatible with the Communicator hardware
- the firmware is suited for the product
- that the officially HMS software signatures are valid
- that the firmware file is not corrupt or damaged

If the firmware file does not pass the validation, the firmware file is rejected and an error message appear.

#### 11.3.4 Update Firmware

#### **Before You Begin**

To eliminate the risk of interference with plant operation, firmware update is only available when the Communicator is disconnected from the OT networks.

Ensure that the Communicator is disconnected from the OT networks.

#### Procedure

	Anybus Communicator Ande Number, AU7716 A Version: 1.23 Seniel Number All: 123456 GUI Version: 6.44.1								
A Home	Files & firmware								
Configuration	Configuration								
A Serial RS-232/485 🗸	Import Export								
ho profibus	Import or export the configuration locally on PC or handheld device.								
🔀 I/O data map	Clear Clear all settings in the configuration to their default values. This will not affect the module until the 'Apply' button is pressed.								
Maintenance	€ Revert								
Files & firmware	Revert all settings in the configuration to the values in the module's current configuration.								
Troubleshooting	Firmware management								
Diagnostics V									
G Support	Select new firmware file and upload it to the gateway.								

#### To update the firmware:

- 1. On the Files & firmware page, click **Upload**.
- 2. In the Upload Firmware window, click Select firmware (.hiff).
- 3. In the Open dialog box, browse to and select the firmware file and click **Open**.
- 4. To start the firmware upgrade, click Update firmware.
  - $\rightarrow$  The firmware file is validated and transferred.

#### Result

- → If the firmware file pass the validation: The firmware is upgraded and then the Communicator automatically reboots, for the upgrade to take effect.
- $\rightarrow$  If the firmware file is rejected: An error message appear.

# 12 Troubleshooting

## 12.1 Diagnostics

## 12.1.1 Serial RS-232/485 Data Monitor

On the Serial RS-232/485 page you can monitor how the data flow between the nodes and the gateway changes over time.

Home	Serial RS-232/485
nfiguration	Start Clear L Auto scroll Hex Dec Ascii BExport
PROFINET	Time (dihtmm:ss.ms) Direction Data
🕻 I/O data map	003:53:36.759 J 2 3 c 88 41 97 f2 5b 3a 55 1c ba 42 33 88 70 a8 bf 90 71 e4 31 ec b8 09 37 88 08 30 9c 13 94 df d9 fc 5a f3 a4 c3 11 ba 5c b 7a a7 f8 fa 17 d 21 c c b 76 7a a4 ed be 66 ad f0 24 1c a3 f0 d7 0a 4f 2b 6b 80 89 29 75 cf a8 b1 cf 69 04 3c f2 1c 89 fd d7 dl b e 27 92 dc 23 se ac 20 c fd 77 ue 88 150 9c 13 9c 12 5c 10 9c
intenance	003:53:36.810 () + 03:37 a f 4 4 6 e 3 10 6 d e b b 6 2 e f 9 d a 0 f 0 2 e c 8 a 51 c 8 98 e c 6f 89 92 49 3d 13 a0 80 b 7 f 8 5e 84 58 e 4 1d c a a 3 e 8 e b 5 40 4 12 5 c a 92 d 7 3 d e 7 e e 5 b d 2 6 0 a f 4 2 e c 40 e 1 d c 8 d d b c b 0 e c 0 1 5 a e 3 e 7 f 55 1b a f a 1 11 4d f a 8 c 95 7 6 d 2 5 b a f a 3 a d 2 0 92 1 5 a e 3 d 2 0 9 c 1 5 a e 3 d 6 c f e c 3 3 6 d c f e c 3 a 6 d f e c 3 a 6 d e c 6 c 3 a 6 d e c 6 c 3 a 6 d e c 6 c 3 a 6 d e c 6 c 3 a 6 d e c 6 c 3 a 6 d e c 6 c 6 c 6 c 6 c 6 c 6 c 6 c 6 c 6 c
Files & firmware	0.02:53:36.859
Diagnostics	0.02:53:36.910 Ø + + + + + + + + + + + + + + + + + + +
←* Serial RS-232/485	0:02:52:36:059 0:02:52:52:52:52:52:52:52:52:52:52:52:52:52

The table can contain at most 10000 messages. When the limit is reached, the oldest messages are discarded when new messages are added.

#### Choose how data is displayed

To choose if the data should be displayed in Hexadecimal, Decimal or ASCII, click **Hex**, **Dec** or **Ascii**.

#### Start and Stop Data flow

- To start the data flow, click **Start**.
- To end the data flow, click **Stop**.

#### Export data flow

To export the data flow, click **Export**.

 $\rightarrow$  An Excel file with the data flow is downloaded to your PC.

## 12.1.2 Event Log

	Anybus Communicator Antick Humber: AB7716A Version: 1.23 Senid Number: AB5712456 GUI Version: 6.45.1									
A Home	Event log									
Configuration					Clear					
A Serial RS-232/485 🗸	Time (d:hh:mm:ss.ms)	Message	Severity	Source	Sub-source					
PROFINET	0:00:16:40.000	Node 5 is online		Serial RS-232/485	Node 5					
X I/O data map	0:00:33:20.000	Node 5 is offine	۵	Serial RS-232/485	Node 5					
laintenance	0:00:50:00.000	Node 5 out of Specification	2	EtherNet/IP**	Node 5					
roubleshooting	0:01:06:40.000	Node 5 network startup in progress	7	Communicator	Node 5					
Diagnostics	0:01:23:20.000	Node 5 internal error	8	Communicator	Node 5					
← Serial RS-232/485										
≔ Event log										

### How To Analyze the Information

The log follows the FIFO principle, first in and first out. The oldest (first) value is processed first.

Time (d:hh:mm: ss.ms)	The o	The date and time when the event occurred.							
Message	A bri	brief description of the event.							
Severity		e severity of the event occurred. r description of the symbols, refer to <i>Communicator Status Monitor, p. 84</i> .							
Source	0	Communicator							
	1	High level network, PROFINET							
	2 Subnetwork, Serial RS-232/485								
Sub-source	If the	nodes connected to the subnetwork and the PLC connected to the high level network. There is a problem with a node the node name is displayed in the Sub-source column. The place is the node name is 5, number 5 is displayed in the Sub-source column.							

To clear the current log, click Clear log.

## 12.1.3 LED Status

On the Home page, you can remotely monitor the Communicator LED status.

	Anybus Communicator Article Number: ABC3007-A Version: 1.2.3 Serial Number: ABC122456 GUI Version: 1.01.1
Home       Configuration	V       EtherNet/IP™         Setup in progress       PLC         IP: 192.168.0.111       ↑ 2 byte(s) ↓ 0 byte(s)         More information       Image: Comparison of the setup of the se
ĥo PROFINET	Anybus Communicator Initial state      Anybus"
Maintenance	Gateway EtherNet/IP* Serial
Troubleshooting	

For information about the LED indication, refer to Communicator LED Indicators, p. 86.

## 12.2 Reset to Factory Settings

#### **Before You Begin**

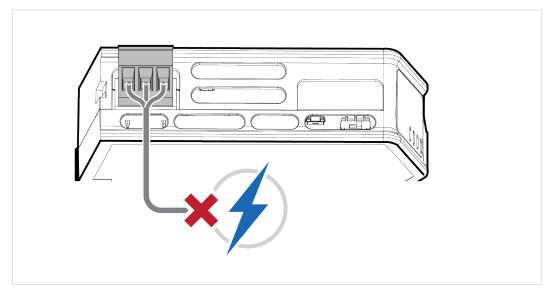
Factory reset will reset any on site made configuration changes and set the Communicator to the same state as leaving HMS production.

If the Firmware has been updated, factory reset will revert the Communicator configuration to initial state after the update.

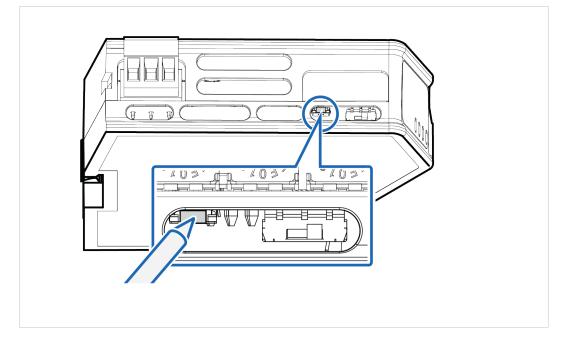
#### Procedure

To reset the Communicator:

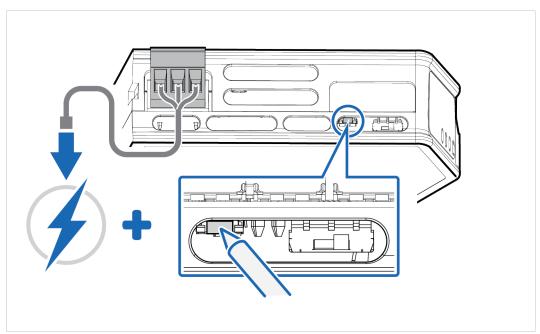
1. Disconnect the Communicator from power.



2. Use a pointed object, such as a ballpoint pen to press and hold the **reset** button.



3. While holding the **reset** button, reconnect the Communicator to power.



- 4. Release the **reset** button.
  - $\rightarrow$  The Communicator enters Exception state.
- 5. Reboot the Communicator.

#### Result

→ When the Communicator has successfully rebooted, the Communicator configuration is reset to the factory default configuration or the current configuration after firmware upgrade.

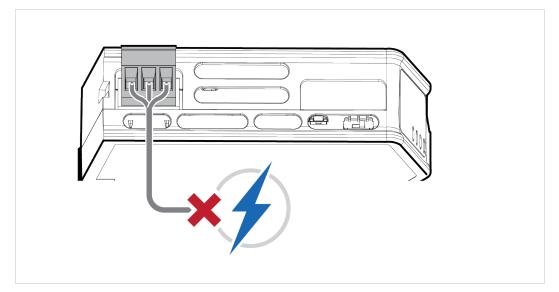
# 12.3 Firmware Upgrade Error Management

If the firmware update process is interrupted or if the power is lost during the update process, the Communicator goes into fallback mode.

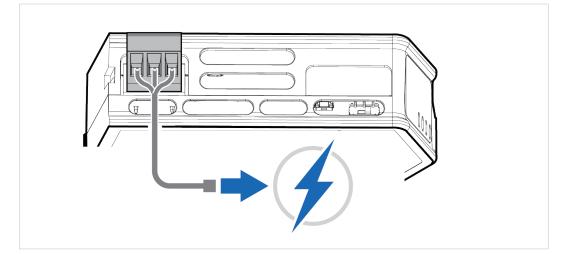
The last working firmware is still available on the flash, but it is not active.

To complete the interrupted firmware update:

1. Disconnect the Communicator from power.

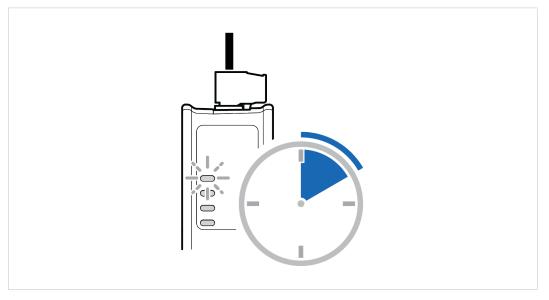


2. Reconnect the Communicator to power.



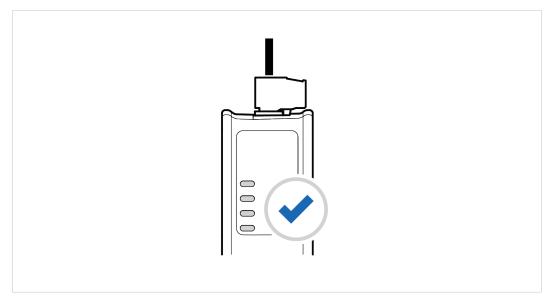
3. Leave the Communicator for 10 minutes.

The *Gateway status* led indicator flashes red and green until the firmware upgrade is completed.



#### Result

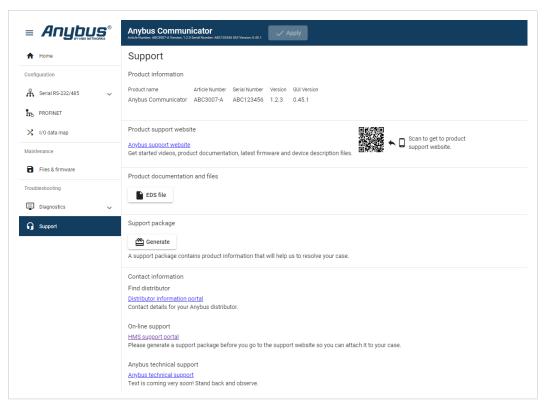
 $\rightarrow$  The Communicator recover and return to normal operation.



To check LED status, refer to *Communicator LED Indicators, p. 86*.

## 12.4 Support

## 12.4.1 Support Package



Before you create a ticket for technical support, generate a support package.

The support package contain information about what has occurred and will help the Anybus technical support team resolve the support case as quickly and efficiently as possible.

#### Support Package Content

The information in the support package are available to open and read, the files are not locked or encrypted.

#### **Generate Support Package**

- 1. On the **Support** page, click **Generate**.
  - $\rightarrow$  A zip file with the support files is downloaded to your PC.

#### **Create a Support Ticket**

- 1. On the Support page, click Anybus support website.
  - $\rightarrow$  You are redirected to the Anybus support website.
- 2. On the Anybus support website, create a support ticket and upload the support package.

# 13 Technical Data

# **13.1** Technical Specifications

Article identification	ABC3013-A					
Communication connector	RJ45 x 2					
Configuration connector	RJ45					
Serial connector	7-pin screw connector					
Power connector	3-pin screw connector					
Power supply	12-30 VDC Reverse voltage protection and short circuit protection					
Power consumption	Typical: 160 mA @ 24 V Max: 400 mA @ 12 V					
Storage temperature	-40 to +85 °C					
Operating temperature	-25 to +70 °C					
Humidity	EN 600068-2-78: Damp heat, +40°C, 93% humidity for 4 days EN 60068-2-30: Damp heat, +25°C – +55°C, 95% RH, 2 cycles					
Vibration	See datasheet					
Housing material	Plastic See datasheet for details					
Protection class	IP20					
Product weight	150 g					
Dimensions	27 x 144 x 98 mm (H x W x D) with connectors included					
Mounting	DIN-rail					

Additional technical data and information related to the installation and use of this product can be found at <u>www.anybus.com/support</u>.

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# A Reference Guides

## A.1 About Input Registers and Holding Registers

Modbus data is most often read and written as registers which are 16-bit pieces of data.

Holding registers and Input registers are both 16-bit registers.

#### Input registers

Input registers can only be read.

#### **Holding registers**

Holding registers can be read or written.

These registers can be used for a variety of things such as inputs, outputs, configuration data, or other requirement for holding data.

## A.2 Modbus Data Model

Discretes Input Single bit		Read-Only	Data can be provided by the I/O system.				
Coils Single bit		Read-Write	Data can be alterable by the application program.				
Input Registers	16-bit word	Read-Only	Data can be provided by the I/O system				
Holding Registers	16-bit word	Read-Write	Data can be alterable by the application program.				

Reference: MODBUS Application Protocol Specification V1.1b3, April 26 2012

For more information refer to the Modbus organisation website.

# A.3 Modbus Transactions

Nr	Transaction	Function Code	Description					
1	Read Coils	0x01	Read from 1 to 2000 contiguous status of coils in a remote device.					
2	Read Discrete Inputs	0x02	Read from 1 to 2000 contiguous status of discrete inputs in a remote device.					
3	Read Holding Registers	0x03	Read the contents of a contiguous block of holding registers in a remote device.					
4	Read Input Registers	0x04	Read from 1 to 125 contiguous input registers in a remote device.					
5	Write Single Coil	0x05	Write a single output to ON or OFF in a remote device.					
6	Write Single Register	0x06	Write a single holding register in a remote device.					
15	Write Multiple Coils	0x0F	In a sequence of coils, force each coil to either ON or OFF in a remote device.					
16	Write Multiple Registers	0x10	Write a block of contiguous registers in a remote device.					
22	Mask Write Register	0x16	In a single transaction, modify the contents of a specified holding register using a combination of an AND mask, an OR mask, and the register's current contents. Can be used to set or clear individual bits in the register.					
23	Read/Write Multiple     0x17     Performs a combination of one read operation and one will operation.       Registers     The write operation is performed before the read.							

Reference: MODBUS Application Protocol Specification V1.1b3, April 26 2012

For more information refer to the Modbus organisation website.

# A.4 Modus Exception Codes

Exception Code	Name	Description						
01	Illegal Function	The server does not recognize or permit the function code.						
02	Illegal Data Address	The data address (register, discrete input or coil number) is not an permitted address for the server. If multiple registers were requested, at least one was not permitted.						

Reference: MODBUS Application Protocol Specification V1.1b3, April 26 2012

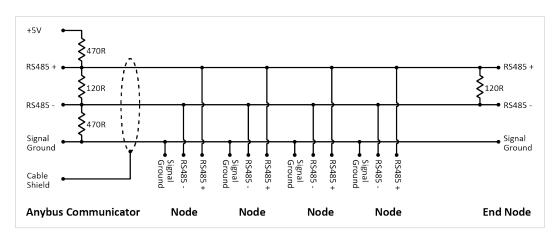
For more information refer to the Modbus organisation website.

## A.5 ASCII Table

	x0	x1	x2	х3	x4	x5	x6	x7	x8	x9	хА	хВ	хC	хD	хE	хF
0x	NUL	SOH	STX	ETX	EOT	ENQ	ACK	BEL	BS	HT	LF	VT	FF	CR	SO	SI
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1x	DLE	DC1	DC2	DC3	DC4	NAK	SYN	ETB	CAN	EM	SUB	ESC	FS	GS	RS	US
	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
2x	(sp)	!	"	#	\$	%	&	'	(	)	*	+	,	-		/
	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
3х	0	1	2	3	4	5	6	7	8	9	:	;	<	=	>	?
	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63
4x	@	A	В	C	D	E	F	G	H	І	J	K	L	M	N	0
	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79
5x	Р	Q	R	S	Т	U	V	W	X	Y	Z	[	\	]	^	_
	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95
6x	)	а	b	с	d	е	f	g	h	i	j	k	ا	m	n	0
	96	97	98	99	100	101	102	103	104	105	106	107	108	109	110	111
7x	р	q	r	s	t	u	v	w	x	у	z	{		}	~	DEL
	112	113	114	115	116	117	118	119	120	121	122	123	124	125	126	127

# A.6 RS485/RS232 Electrical Connection

## A.6.1 RS485 Typical Connection



# A.6.2 RS232 Typical Connection

