

FEATURES

High common-mode input voltage range

± 120 V at $V_S = \pm 15$ V

Gain range 0.1 to 100

Operating temperature range: -40°C to $+85^\circ\text{C}$

Supply voltage range

Dual supply: ± 2.25 V to ± 18 V

Single supply: 4.5 V to 36 V

Excellent ac and dc performance

Offset temperature stability RTI: $10 \mu\text{V}/^\circ\text{C}$ maximum

Offset: ± 1.5 mV maximum

CMRR RTI: 75 dB minimum, dc to 500 Hz, $G = +1$

APPLICATIONS

High voltage current shunt sensing

Programmable logic controllers

Analog input front end signal conditioning

+5 V, +10 V, ± 5 V, ± 10 V, and 4 to 20 mA

Isolation

Sensor signal conditioning

Power supply monitoring

Electrohydraulic controls

Motor controls

GENERAL DESCRIPTION

The AD628 is a precision difference amplifier that combines excellent dc performance with high common-mode rejection over a wide range of frequencies. When used to scale high voltages, it allows simple conversion of standard control voltages or currents for use with single-supply ADCs. A wideband feedback loop minimizes distortion effects due to capacitor charging of Σ - Δ ADCs.

A reference pin (V_{REF}) provides a dc offset for converting bipolar to single-sided signals. The AD628 converts +5 V, +10 V, ± 5 V, ± 10 V, and 4 to 20 mA input signals to a single-ended output within the input range of single-supply ADCs.

The AD628 has an input common mode and differential mode operating range of ± 120 V. The high common mode, input impedance makes the device well suited for high voltage measurements across a shunt resistor. The inverting input of the buffer amplifier is available for making a remote Kelvin connection.

FUNCTIONAL BLOCK DIAGRAM

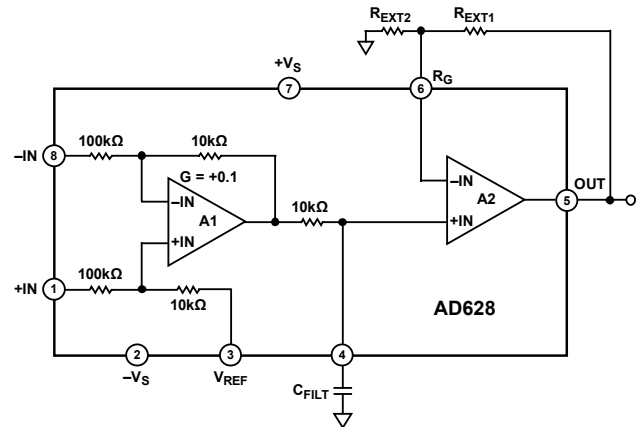


Figure 1.

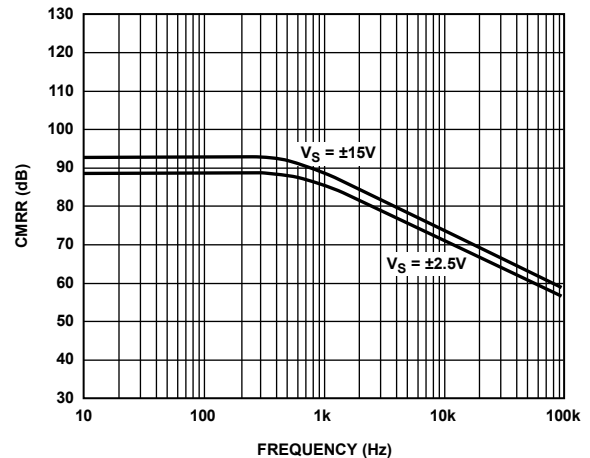


Figure 2. CMRR vs. Frequency of the AD628

A precision 10 k Ω resistor connected to an external pin is provided for either a low-pass filter or to attenuate large differential input signals. A single capacitor implements a low-pass filter. The AD628 operates from single and dual supplies and is available in an 8-lead SOIC_N or an 8-lead MSOP. It operates over the standard industrial temperature range of -40°C to $+85^\circ\text{C}$.

Rev. G

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11/02—Rev. 0: Initial Version

SPECIFICATIONS

$T_A = 25^\circ\text{C}$, $V_S = \pm 15\text{ V}$, $R_L = 2\text{ k}\Omega$, $R_{EXT1} = 10\text{ k}\Omega$, $R_{EXT2} = \infty$, $V_{REF} = 0\text{ V}$, unless otherwise noted.

Table 1.

| Parameter | Conditions | AD628AR | | | AD628ARM | | | Unit |
|-----------------------------------|--|------------------|-------|------|------------------|-------|------|---|
| | | Min | Typ | Max | Min | Typ | Max | |
| DIFFERENTIAL AND OUTPUT AMPLIFIER | | | | | | | | |
| Gain Equation | $G = +0.1 (1 + R_{EXT1}/R_{EXT2})$ | | | | | | | V/V |
| Gain Range | See Figure 29 | 0.1 ¹ | | 100 | 0.1 ¹ | | 100 | V/V |
| Offset Voltage | $V_{CM} = 0\text{ V}$; RTI of input pins ² ; output amplifier $G = +1$ | -1.5 | | +1.5 | -1.5 | | +1.5 | mV |
| vs. Temperature | | | 4 | 8 | | 4 | 8 | $\mu\text{V}/^\circ\text{C}$ |
| CMRR ³ | RTI of input pins; $G = +0.1$ to $+100$ | 75 | | | 75 | | | dB |
| | 500 Hz | 75 | | | 75 | | | dB |
| Minimum CMRR Over Temperature | -40°C to $+85^\circ\text{C}$ | 70 | | | 70 | | | dB |
| vs. Temperature | | | 1 | 4 | | 1 | 4 | $(\mu\text{V}/\text{V})/^\circ\text{C}$ |
| PSRR (RTI) | $V_S = \pm 10\text{ V}$ to $\pm 18\text{ V}$ | 77 | 94 | | 77 | 94 | | dB |
| Input Voltage Range | | | | | | | | |
| Common Mode | | -120 | | +120 | -120 | | +120 | V |
| Differential | | -120 | | +120 | -120 | | +120 | V |
| Dynamic Response | | | | | | | | |
| Small Signal Bandwidth -3 dB | $G = +0.1$ | | 600 | | | 600 | | kHz |
| Full Power Bandwidth | | | 5 | | | 5 | | kHz |
| Settling Time | $G = +0.1$, to 0.01%, 100 V step | | | 40 | | | 40 | μs |
| Slew Rate | | | 0.3 | | | 0.3 | | $\text{V}/\mu\text{s}$ |
| Noise (RTI) | | | | | | | | |
| Spectral Density | 1 kHz | | 300 | | | 300 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| | 0.1 Hz to 10 Hz | | 15 | | | 15 | | $\mu\text{V p-p}$ |
| DIFFERENTIAL AMPLIFIER | | | | | | | | |
| Gain | | | 0.1 | | | 0.1 | | V/V |
| Error | | -0.1 | +0.01 | +0.1 | -0.1 | +0.01 | +0.1 | % |
| vs. Temperature | | | | 5 | | | 5 | $\text{ppm}/^\circ\text{C}$ |
| Nonlinearity | | | | 5 | | | 5 | ppm |
| vs. Temperature | | | 3 | 10 | | 3 | 10 | ppm |
| Offset Voltage | RTI of input pins | -1.5 | | +1.5 | -1.5 | | +1.5 | mV |
| vs. Temperature | | | | 8 | | | 8 | $\mu\text{V}/^\circ\text{C}$ |
| Input Impedance | | | | | | | | |
| Differential | | | 220 | | | 220 | | $\text{k}\Omega$ |
| Common Mode | | | 55 | | | 55 | | $\text{k}\Omega$ |
| CMRR ⁴ | RTI of input pins; $G = +0.1$ to $+100$ | 75 | | | 75 | | | dB |
| | 500 Hz | 75 | | | 75 | | | dB |
| Minimum CMRR Over Temperature | -40°C to $+85^\circ\text{C}$ | 70 | | | 70 | | | dB |
| vs. Temperature | | | 1 | 4 | | 1 | 4 | $(\mu\text{V}/\text{V})/^\circ\text{C}$ |
| Output Resistance | | | 10 | | | 10 | | $\text{k}\Omega$ |
| Error | | -0.1 | | +0.1 | -0.1 | | +0.1 | % |

AD628

| Parameter | Conditions | AD628AR | | | AD628ARM | | | Unit |
|--------------------------|-------------------------------------|------------|-----|----------|------------|-----|----------|------------------------------|
| | | Min | Typ | Max | Min | Typ | Max | |
| OUTPUT AMPLIFIER | | | | | | | | |
| Gain Equation | $G = (1 + R_{EXT1}/R_{EXT2})$ | | | | | | | V/V |
| Nonlinearity | $G = +1, V_{OUT} = \pm 10\text{ V}$ | | | 0.5 | | | 0.5 | ppm |
| Offset Voltage | RTI of output amp | -0.15 | | +0.15 | -0.15 | | +0.15 | mV |
| vs. Temperature | | | | 0.6 | | | 0.6 | $\mu\text{V}/^\circ\text{C}$ |
| Output Voltage Swing | $R_L = 10\text{ k}\Omega$ | -14.2 | | +14.1 | -14.2 | | +14.1 | V |
| | $R_L = 2\text{ k}\Omega$ | -13.8 | | +13.6 | -13.8 | | +13.6 | V |
| Bias Current | | | 1.5 | 3 | | 1.5 | 3 | nA |
| Offset Current | | | 0.2 | 0.5 | | 0.2 | 0.5 | nA |
| CMRR | $V_{CM} = \pm 13\text{ V}$ | 130 | | | 130 | | | dB |
| Open-Loop Gain | $V_{OUT} = \pm 13\text{ V}$ | 130 | | | 130 | | | dB |
| POWER SUPPLY | | | | | | | | |
| Operating Range | | ± 2.25 | | ± 18 | ± 2.25 | | ± 18 | V |
| Quiescent Current | | | | 1.6 | | | 1.6 | mA |
| TEMPERATURE RANGE | | | | | | | | |
| | | -40 | | +85 | -40 | | +85 | $^\circ\text{C}$ |

¹ To use a lower gain, see the Gain Adjustment section.

² The addition of the difference amplifier and output amplifier offset voltage does not exceed this specification.

³ Error due to common mode as seen at the output: $V_{OUT} = \left[\frac{(0.1)(V_{CM})}{\frac{75}{10^{20}}} \right] \times [\text{Output Amplifier Gain}]$.

⁴ Error due to common mode as seen at the output of A1: $V_{OUT\ A1} = \left[\frac{(0.1)(V_{CM})}{\frac{75}{10^{20}}} \right]$.

T_A = 25°C, V_S = 5 V, R_L = 2 kΩ, R_{EXT1} = 10 kΩ, R_{EXT2} = ∞, V_{REF} = 2.5 V, unless otherwise noted.

Table 2.

| Parameter | Conditions | AD628AR | | | AD628ARM | | | Unit |
|--|--|------------------|-------|-------|------------------|-------|-------|-----------|
| | | Min | Typ | Max | Min | Typ | Max | |
| DIFFERENTIAL AND OUTPUT AMPLIFIER | | | | | | | | |
| Gain Equation | $G = +0.1(1 + R_{EXT1}/R_{EXT2})$ | | | | | | | V/V |
| Gain Range | See Figure 29 | 0.1 ¹ | | 100 | 0.1 ¹ | | 100 | V/V |
| Offset Voltage | V _{CM} = 2.25 V; RTI of input pins ² ; output amplifier G = +1 | -3.0 | | +3.0 | -3.0 | | +3.0 | mV |
| vs. Temperature | | | 6 | 15 | | 6 | 15 | μV/°C |
| CMRR ³ | RTI of input pins; G = +0.1 to +100 | 75 | | | 75 | | | dB |
| | 500 Hz | 75 | | | 75 | | | dB |
| Minimum CMRR Over Temperature | -40°C to +85°C | 70 | | | 70 | | | dB |
| vs. Temperature | | | 1 | 4 | | 1 | 4 | (μV/V)/°C |
| PSRR (RTI) | V _S = 4.5 V to 10 V | 77 | 94 | | 77 | 94 | | dB |
| Input Voltage Range | | | | | | | | |
| Common Mode ⁴ | | -12 | | +17 | -12 | | +17 | V |
| Differential | | -15 | | +15 | -15 | | +15 | V |
| Dynamic Response | | | | | | | | |
| Small Signal Bandwidth – 3 dB | G = +0.1 | | 440 | | | 440 | | kHz |
| Full Power Bandwidth | | | 30 | | | 30 | | kHz |
| Settling Time | G = +0.1; to 0.01%, 30 V step | | 15 | | | 15 | | μs |
| Slew Rate | | | 0.3 | | | 0.3 | | V/μs |
| Noise (RTI) | | | | | | | | |
| Spectral Density | 1 kHz | | 350 | | | 350 | | nV/√Hz |
| | 0.1 Hz to 10 Hz | | 15 | | | 15 | | μV p-p |
| DIFFERENTIAL AMPLIFIER | | | | | | | | |
| Gain | | | 0.1 | | | 0.1 | | V/V |
| Error | | -0.1 | +0.01 | +0.1 | -0.1 | +0.01 | +0.1 | % |
| Nonlinearity | | | | 3 | | | 3 | ppm |
| vs. Temperature | | | 3 | 10 | | 3 | 10 | ppm |
| Offset Voltage | RTI of input pins | -2.5 | | +2.5 | -2.5 | | +2.5 | mV |
| vs. Temperature | | | | 10 | | | 10 | μV/°C |
| Input Impedance | | | | | | | | |
| Differential | | | 220 | | | 220 | | kΩ |
| Common Mode | | | 55 | | | 55 | | kΩ |
| CMRR ⁵ | RTI of input pins; G = +0.1 to +100 | 75 | | | 75 | | | dB |
| | 500 Hz | 75 | | | 75 | | | dB |
| Minimum CMRR Over Temperature | -40°C to +85°C | 70 | | | 70 | | | dB |
| vs. Temperature | | | 1 | 4 | | 1 | 4 | (μV/V)/°C |
| Output Resistance | | | 10 | | | 10 | | kΩ |
| Error | | -0.1 | | +0.1 | -0.1 | | +0.1 | % |
| OUTPUT AMPLIFIER | | | | | | | | |
| Gain Equation | $G = (1 + R_{EXT1}/R_{EXT2})$ | | | | | | | V/V |
| Nonlinearity | G = +1, V _{OUT} = 1 V to 4 V | | | 0.5 | | | 0.5 | ppm |
| Output Offset Voltage | RTI of output amplifier | -0.15 | | +0.15 | -0.15 | | +0.15 | mV |
| vs. Temperature | | | | 0.6 | | | 0.6 | μV/°C |
| Output Voltage Swing | R _L = 10 kΩ | 0.9 | | 4.1 | 0.9 | | 4.1 | V |
| | R _L = 2 kΩ | 1 | | 4 | 1 | | 4 | V |
| Bias Current | | | 1.5 | 3 | | 1.5 | 3 | nA |
| Offset Current | | | 0.2 | 0.5 | | 0.2 | 0.5 | nA |
| CMRR | V _{CM} = 1 V to 4 V | 130 | | | 130 | | | dB |
| Open-Loop Gain | V _{OUT} = 1 V to 4 V | 130 | | | 130 | | | dB |

AD628

| Parameter | Conditions | AD628AR | | | AD628ARM | | | Unit |
|-------------------|------------|---------|-----|-----|----------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| POWER SUPPLY | | | | | | | | |
| Operating Range | | ±2.25 | | +36 | ±2.25 | | +36 | V |
| Quiescent Current | | | | 1.6 | | | 1.6 | mA |
| TEMPERATURE RANGE | | -40 | | +85 | -40 | | +85 | °C |

¹ To use a lower gain, see the Gain Adjustment section.

² The addition of the difference amplifier and output amplifier offset voltage does not exceed this specification.

³ Error due to common mode as seen at the output: $V_{OUT} = \left[\frac{(0.1)(V_{CM})}{\frac{75}{10^{20}}} \right] \times [Output\ Amplifier\ Gain]$.

⁴ Greater values of voltage are possible with greater or lesser values of V_{REF} .

⁵ Error due to common mode as seen at the output of A1: $V_{OUT\ A1} = \left[\frac{(0.1)(V_{CM})}{\frac{75}{10^{20}}} \right]$.

ABSOLUTE MAXIMUM RATINGS

Table 3.

| Parameter | Rating |
|--------------------------------------|---------------------|
| Supply Voltage | ±18 V |
| Internal Power Dissipation | See Figure 3 |
| Input Voltage (Common Mode) | ±120 V ¹ |
| Differential Input Voltage | ±120 V ¹ |
| Output Short-Circuit Duration | Indefinite |
| Storage Temperature Range | −65°C to +125°C |
| Operating Temperature Range | −40°C to +85°C |
| Lead Temperature (Soldering, 10 sec) | 300°C |

¹ When using ±12 V supplies or higher, see the Input Voltage Range section.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL CHARACTERISTICS

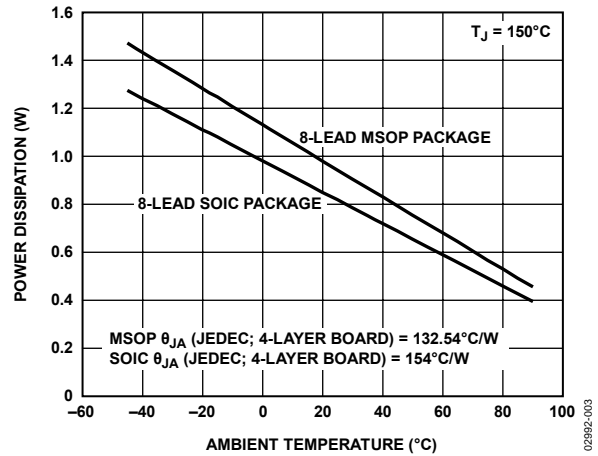


Figure 3. Maximum Power Dissipation vs. Temperature

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

AD628

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

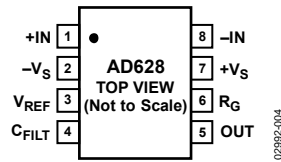


Figure 4. Pin Configuration

Table 4. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
|---------|-------------------|----------------------------------|
| 1 | +IN | Noninverting Input |
| 2 | -Vs | Negative Supply Voltage |
| 3 | V _{REF} | Reference Voltage Input |
| 4 | C _{FILT} | Filter Capacitor Connection |
| 5 | OUT | Amplifier Output |
| 6 | R _G | Output Amplifier Inverting Input |
| 7 | +Vs | Positive Supply Voltage |
| 8 | -IN | Inverting Input |

TYPICAL PERFORMANCE CHARACTERISTICS

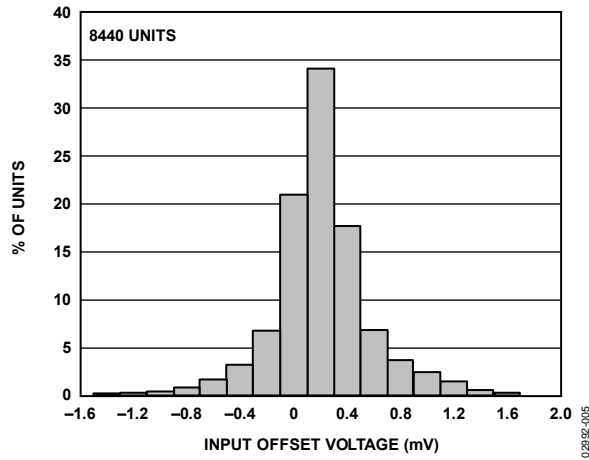


Figure 5. Typical Distribution of Input Offset Voltage, $V_s = \pm 15\text{ V}$, SOIC_N Package

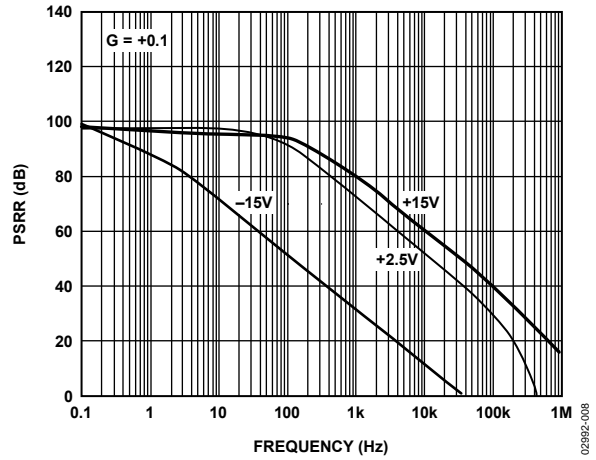


Figure 8. PSRR vs. Frequency, Single and Dual Supplies

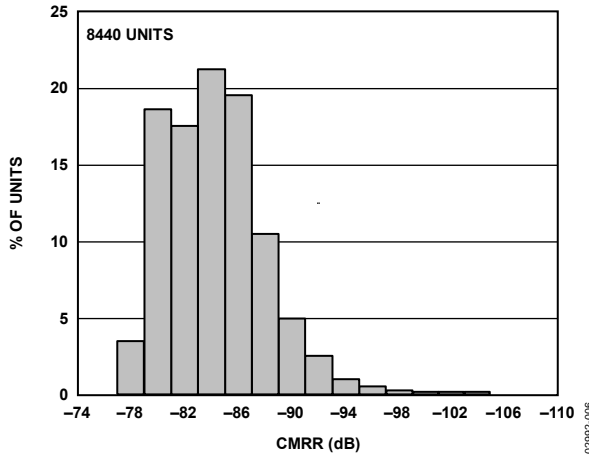


Figure 6. Typical Distribution of CMRR, SOIC_N Package

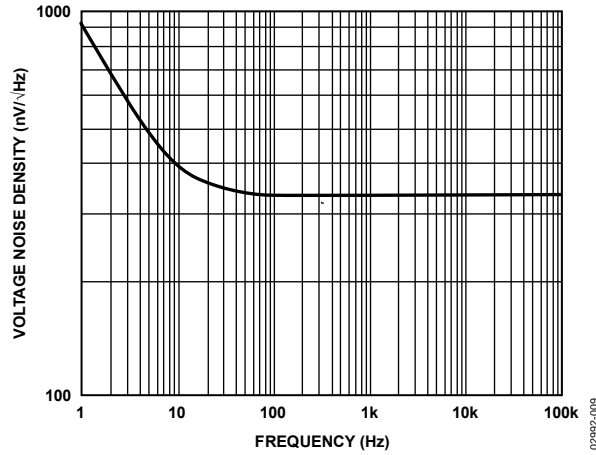


Figure 9. Voltage Noise Spectral Density, RTI, $V_s = \pm 15\text{ V}$

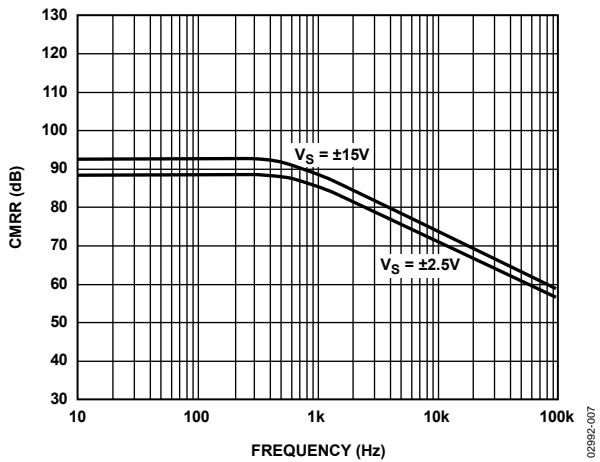


Figure 7. CMRR vs. Frequency

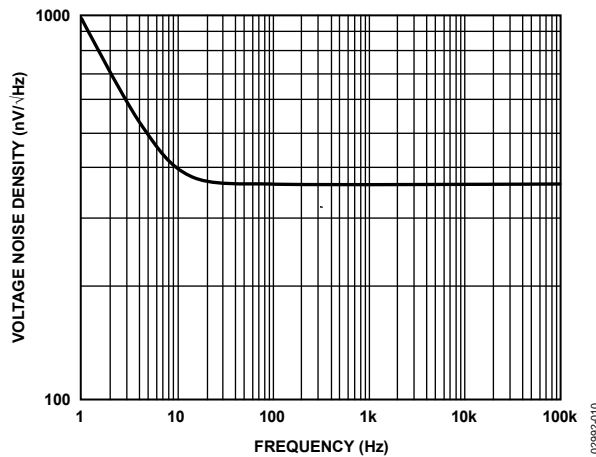


Figure 10. Voltage Noise Spectral Density, RTI, $V_s = \pm 2.5\text{ V}$

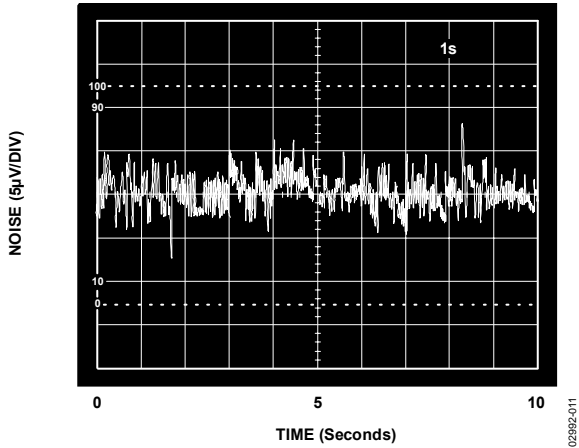


Figure 11. 0.1 Hz to 10 Hz Voltage Noise, RTI

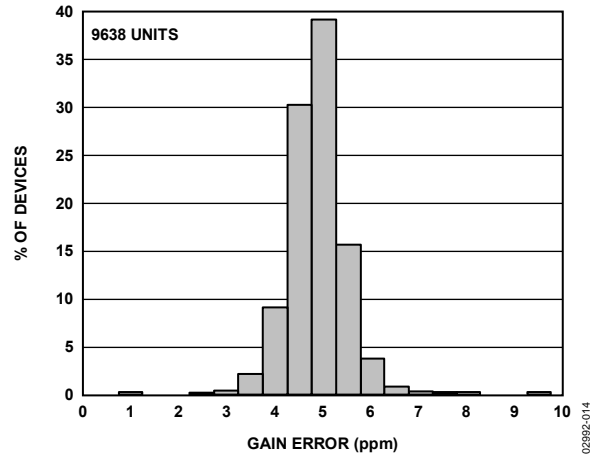


Figure 14. Typical Distribution of +1 Gain Error

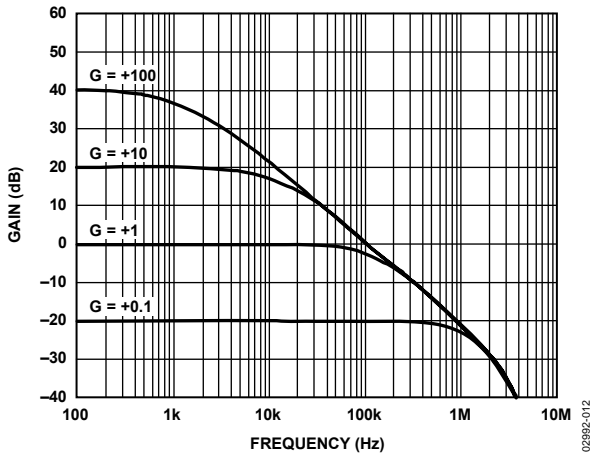


Figure 12. Small Signal Frequency Response, $V_{OUT} = 200\text{ mV p-p}$, $G = +0.1, +1, +10, \text{ and } +100$

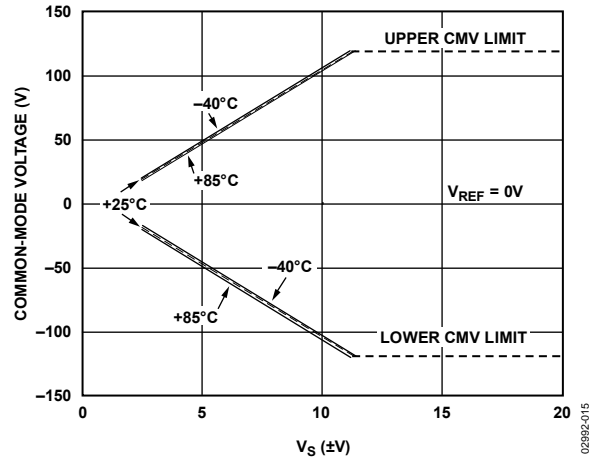


Figure 15. Common-Mode Operating Range vs. Power Supply Voltage for Three Temperatures

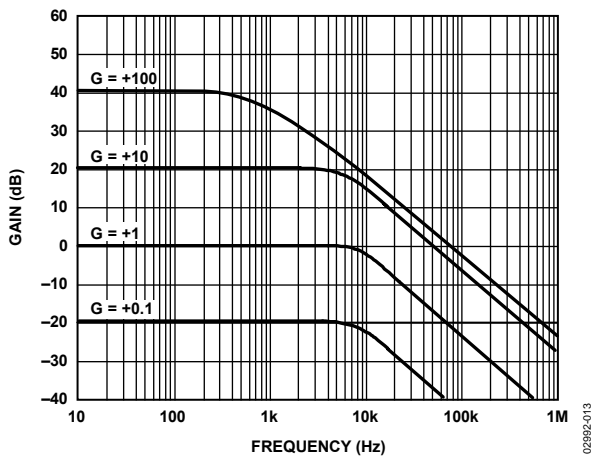


Figure 13. Large Signal Frequency Response, $V_{OUT} = 20\text{ V p-p}$, $G = +0.1, +1, +10, \text{ and } +100$

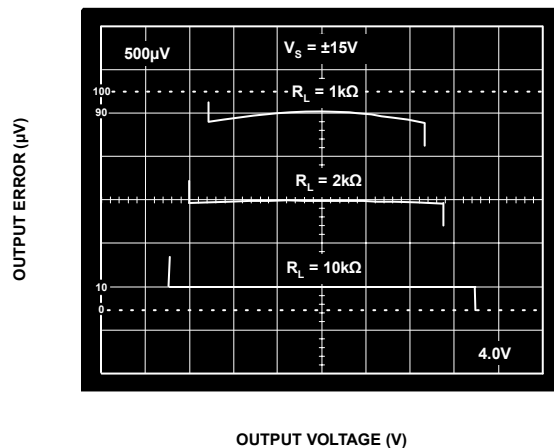


Figure 16. Normalized Gain Error vs. V_{OUT} , $V_S = \pm 15\text{ V}$

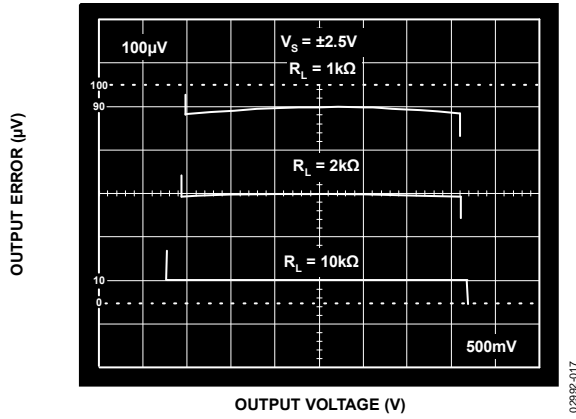


Figure 17. Normalized Gain Error vs. V_{OUT} , $V_S = \pm 2.5V$

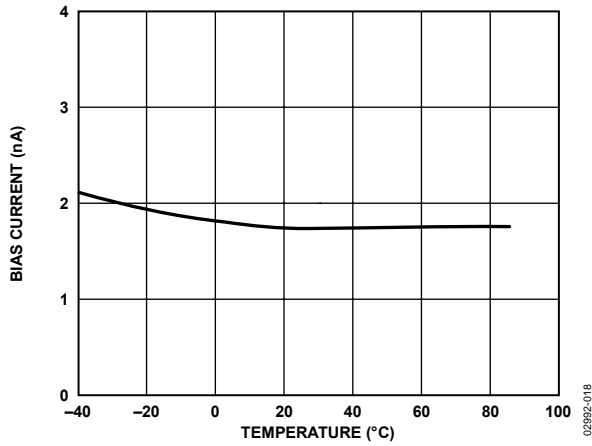


Figure 18. Bias Current vs. Temperature Buffer

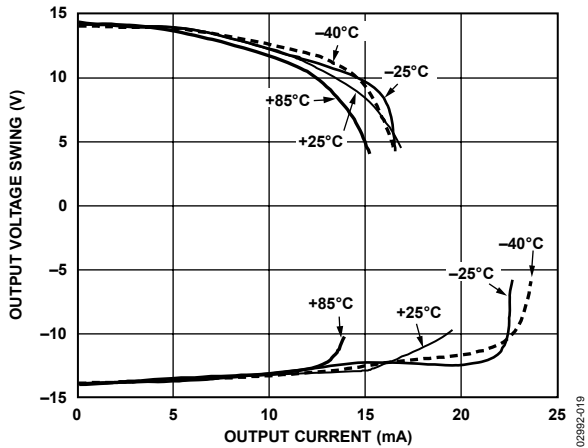


Figure 19. Output Voltage Operating Range vs. Output Current

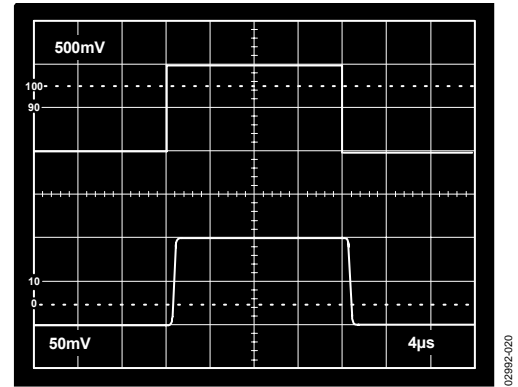


Figure 20. Small Signal Pulse Response, $R_L = 2k\Omega$, $C_L = 0pF$, Top: Input, Bottom: Output

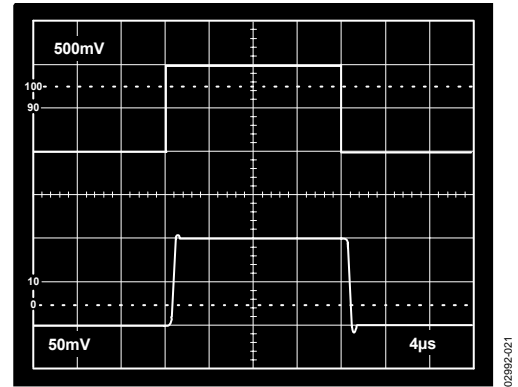


Figure 21. Small Signal Pulse Response, $R_L = 2k\Omega$, $C_L = 1000pF$, Top: Input, Bottom: Output

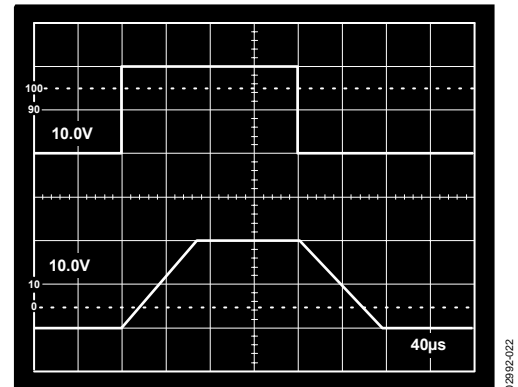


Figure 22. Large Signal Pulse Response, $R_L = 2k\Omega$, $C_L = 1000pF$, Top: Input, Bottom: Output

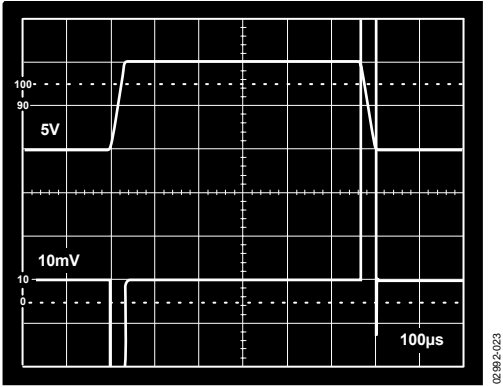


Figure 23. Settling Time to 0.01%, 0 V to 10 V Step

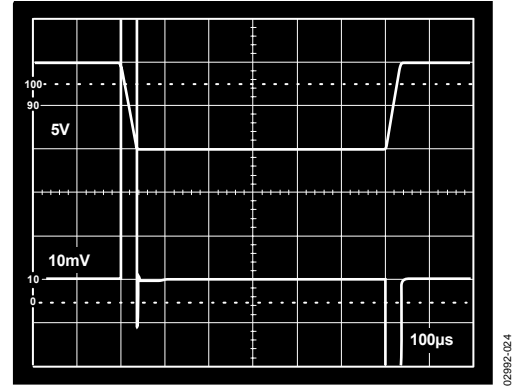


Figure 24. Settling Time to 0.01% 0 V to -10 V Step

TEST CIRCUITS

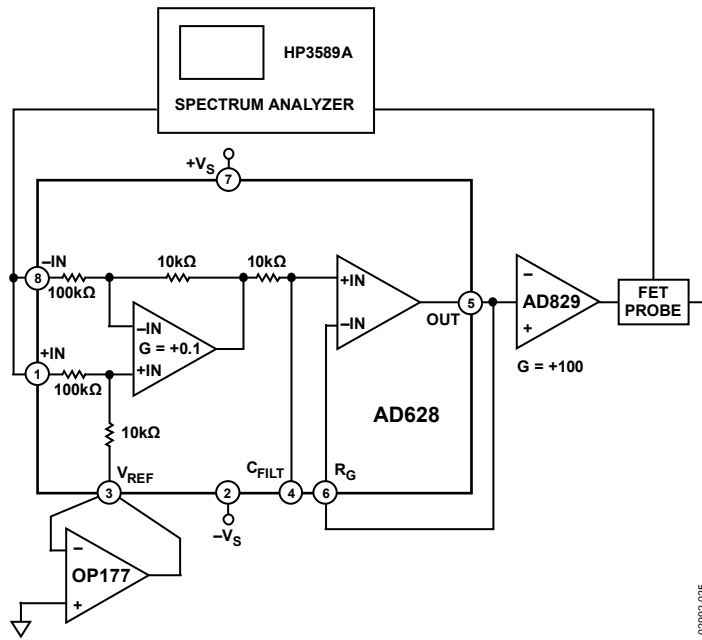


Figure 25. CMRR vs. Frequency

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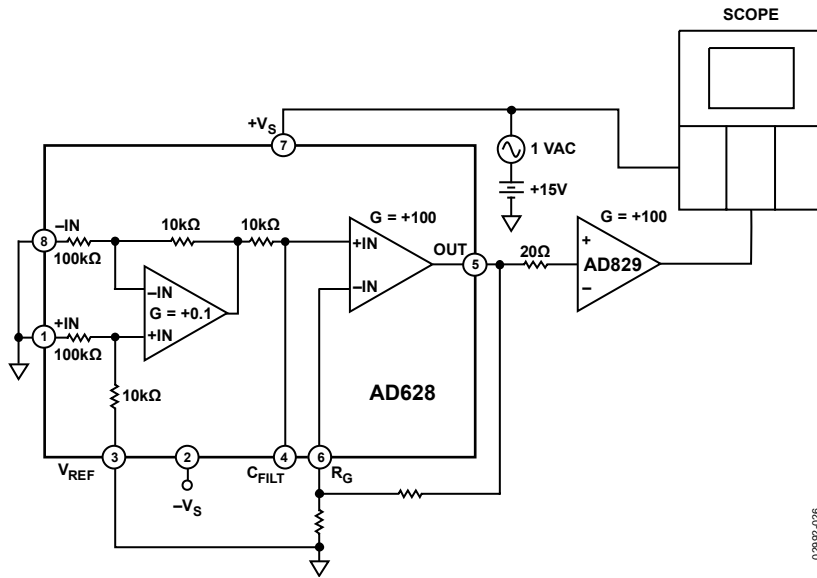
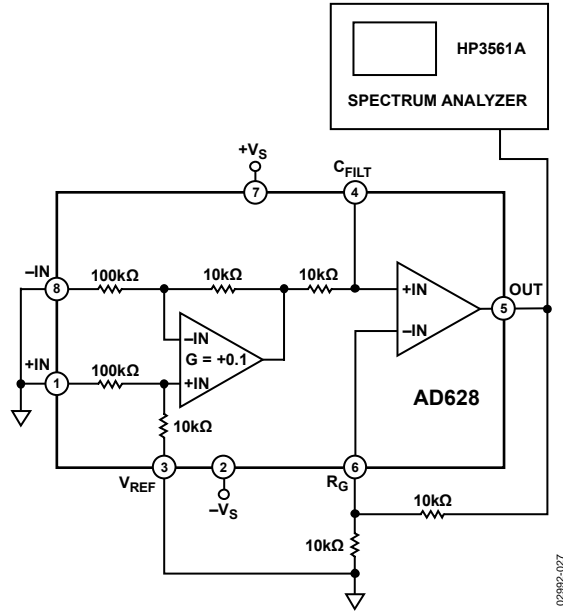


Figure 26. PSRR vs. Frequency

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AD628



THEORY OF OPERATION

The AD628 is a high common-mode voltage difference amplifier, combined with a user-configurable output amplifier (see Figure 28 and Figure 29). Differential mode voltages in excess of 120 V are accurately scaled by a precision 11:1 voltage divider at the input. A reference voltage input is available to the user at Pin 3 (V_{REF}). The output common-mode voltage of the difference amplifier is the same as the voltage applied to the reference pin. If the uncommitted amplifier is configured for gain, connect Pin 3 to one end of the external gain resistor to establish the output common-mode voltage at Pin 5 (OUT).

The output of the difference amplifier is internally connected to a 10 k Ω resistor trimmed to better than $\pm 0.1\%$ absolute accuracy. The resistor is connected to the noninverting input of the output amplifier and is accessible at Pin 4 (C_{FILT}). A capacitor can be connected to implement a low-pass filter, a resistor can be connected to further reduce the output voltage, or a clamp circuit can be connected to limit the output swing.

The uncommitted amplifier is a high open-loop gain, low offset, low drift op amp, with its noninverting input connected to the internal 10 k Ω resistor. Both inputs are accessible to the user.

Careful layout design has resulted in exceptional common-mode rejection at higher frequencies. The inputs are connected to Pin 1 (+IN) and Pin 8 (-IN), which are adjacent to the power pins, Pin 2 ($-V_S$) and Pin 7 ($+V_S$). Because the power pins are at ac ground, input impedance balance and, therefore, common-mode rejection are preserved at higher frequencies.

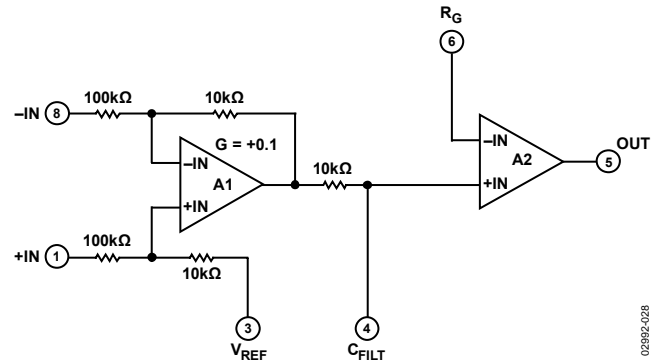


Figure 28. Simplified Schematic

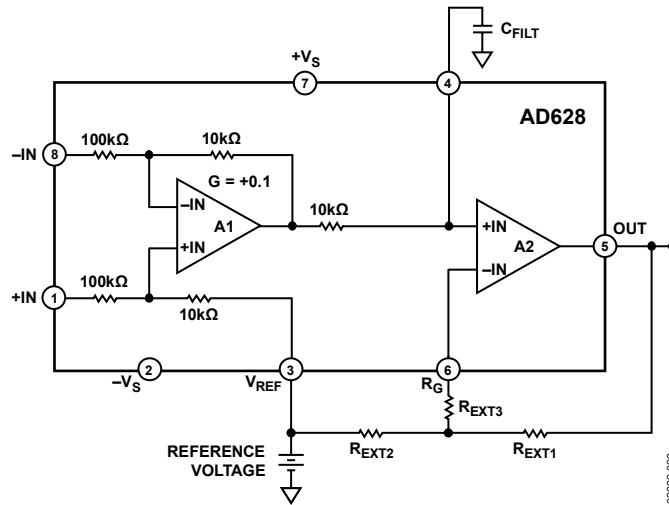


Figure 29. Circuit Connections

APPLICATIONS INFORMATION

GAIN ADJUSTMENT

The AD628 system gain is provided by an architecture consisting of two amplifiers (see Figure 29). The gain of the input stage is fixed at 0.1; the output buffer is user adjustable as $G_{A2} = 1 + R_{EXT1}/R_{EXT2}$. The system gain is then

$$G_{TOTAL} = 0.1 \times \left(1 + \frac{R_{EXT1}}{R_{EXT2}} \right) \quad (1)$$

At a 2 nA maximum, the input bias current of the buffer amplifier is very low and any offset voltage induced at the buffer amplifier by its bias current may be neglected ($2 \text{ nA} \times 10 \text{ k}\Omega = 20 \text{ }\mu\text{V}$). However, to absolutely minimize bias current effects, select R_{EXT1} and R_{EXT2} so that their parallel combination is 10 k Ω . If practical resistor values force the parallel combination of R_{EXT1} and R_{EXT2} below 10 k Ω , add a series resistor (R_{EXT3}) to make up for the difference. Table 5 lists several values of gain and corresponding resistor values.

Table 5. Nearest Standard 1% Resistor Values for Various Gains (see Figure 29)

| Total Gain (V/V) | A2 Gain (V/V) | R_{EXT1} (Ω) | R_{EXT2} (Ω) | R_{EXT3} (Ω) |
|------------------|---------------|-------------------------|-------------------------|-------------------------|
| 0.1 | 1 | 10 k | ∞ | 0 |
| 0.2 | 2 | 20 k | 20 k | 0 |
| 0.25 | 2.5 | 25.9 k | 18.7 k | 0 |
| 0.5 | 5 | 49.9 k | 12.4 k | 0 |
| 1 | 10 | 100 k | 11 k | 0 |
| 2 | 20 | 200 k | 10.5 k | 0 |
| 5 | 50 | 499 k | 10.2 k | 0 |
| 10 | 100 | 1 M | 10.2 k | 0 |

To set the system gain to <0.1 , create an attenuator by placing Resistor R_{EXT4} from Pin 4 (C_{FILT}) to the reference voltage. A divider is formed by the 10 k Ω resistor that is in series with the positive input of A2 and Resistor R_{EXT4} . A2 is configured for unity gain.

Using a divider and setting A2 to unity gain yields

$$G_{W/DIVIDER} = 0.1 \times \left(\frac{R_{EXT4}}{10 \text{ k}\Omega + R_{EXT4}} \right) \times 1$$

INPUT VOLTAGE RANGE

V_{REF} and the supply voltage determine the common-mode input voltage range. The relation is expressed by

$$\begin{aligned} V_{CM,UPPER} &\leq 11(V_{S+} - 1.2 \text{ V}) - 10 V_{REF} \\ V_{CM,LOWER} &\geq 11(V_{S-} + 1.2 \text{ V}) - 10 V_{REF} \end{aligned} \quad (2)$$

where:

V_{S+} is the positive supply.

V_{S-} is the negative supply.

1.2 V is the headroom needed for suitable performance.

Equation 2 provides a general formula for calculating the common-mode input voltage range. However, keep the AD628 within the maximum limits listed in Table 1 to maintain optimal performance. This is illustrated in Figure 30 where the maximum common-mode input voltage is limited to $\pm 120 \text{ V}$. Figure 31 shows the common-mode input voltage bounds for single-supply voltages.

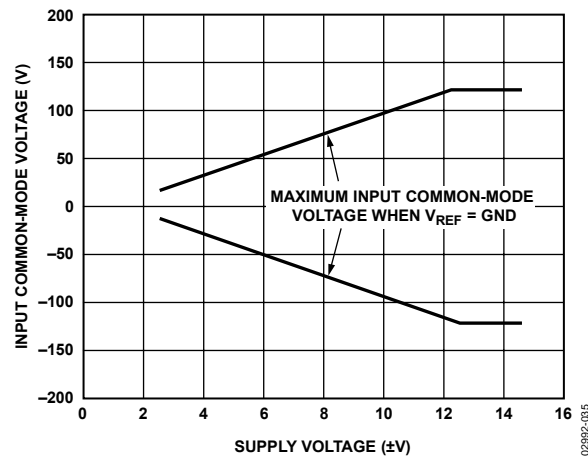


Figure 30. Input Common-Mode Voltage vs. Supply Voltage for Dual Supplies

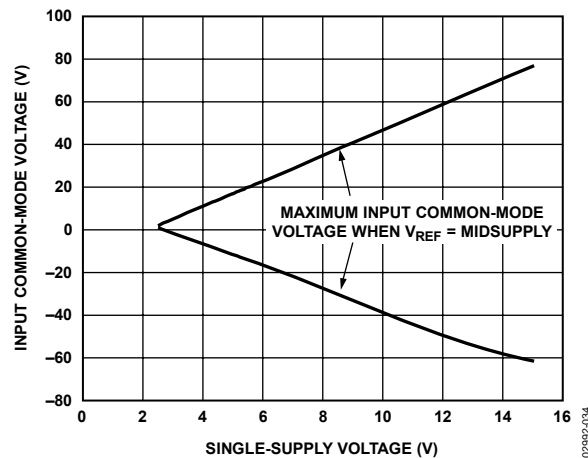


Figure 31. Input Common-Mode Voltage vs. Supply Voltage for Single Supplies

The differential input voltage range is constrained to the linear operation of the internal amplifiers, A1 and A2. The voltage applied to the inputs of A1 and A2 should be between $V_{S-} + 1.2\text{ V}$ and $V_{S+} - 1.2\text{ V}$. Similarly, the outputs of A1 and A2 should be kept between $V_{S-} + 0.9\text{ V}$ and $V_{S+} - 0.9\text{ V}$.

VOLTAGE LEVEL CONVERSION

Industrial signal conditioning and control applications typically require connections between remote sensors or amplifiers and centrally located control modules. Signal conditioners provide output voltages of up to $\pm 10\text{ V}$ full scale. However, ADCs or microprocessors operating on single 3.3 V to 5 V logic supplies are now the norm. Thus, the controller voltages require further reduction in amplitude and reference.

Furthermore, voltage potentials between locations are seldom compatible, and power line peaks and surges can generate destructive energy between utility grids. The AD628 offers an ideal solution to both problems. It attenuates otherwise destructive signal voltage peaks and surges by a factor of 10 and shifts the differential input signal to the desired output voltage.

Conversion from voltage-driven or current-loop systems is easily accomplished using the circuit shown in Figure 32. This shows a circuit for converting inputs of various polarities and amplitudes to the input of a single-supply ADC.

To adjust common-mode output voltage, connect Pin 3 (V_{REF}) and the lower end of the 10 k Ω resistor to the desired voltage. The output common-mode voltage is the same as the reference voltage.

Designing such an application can be done in a few simple steps, which includes the following:

- Determine the required gain. For example, if the input voltage must be changed from $\pm 10\text{ V}$ to $+5\text{ V}$, the gain now needs to be $+5/+20$ or $+0.25$.
- Determine if the circuit common-mode voltage should be changed. An AD7940 ADC is illustrated for this example. When operating from a 5 V supply, the common-mode voltage of the AD7940 is half the supply, or 2.5 V. If the AD628 reference pin and the lower terminal of the 10 k Ω resistor are connected to a 2.5 V voltage source, the output common-mode voltage is 2.5 V.

Table 6 shows resistor and reference values for commonly used single-supply converter voltages. R_{EXT3} is included as an option to balance the source impedance into A2. This is described in more detail in the Gain Adjustment section.

Table 6. Nearest 1% Resistor Values for Voltage Level Conversion Applications

| Input Voltage (V) | ADC Supply Voltage (V) | Desired Output Voltage (V) | V_{REF} (V) | R_{EXT1} (k Ω) | R_{EXT2} (k Ω) |
|-------------------|------------------------|----------------------------|---------------|--------------------------|--------------------------|
| ± 10 | 5 | 2.5 | 2.5 | 15 | 10 |
| ± 5 | 5 | 2.5 | 2.5 | 39.7 | 10 |
| +10 | 5 | 2.5 | 0 | 39.7 | 10 |
| +5 | 5 | 2.5 | 0 | 89.8 | 10 |
| ± 10 | 3 | 1.25 | 1.25 | 2.49 | 10 |
| ± 5 | 3 | 1.25 | 1.25 | 15 | 10 |
| +10 | 3 | 1.25 | 0 | 15 | 10 |
| +5 | 3 | 1.25 | 0 | 39.7 | 10 |

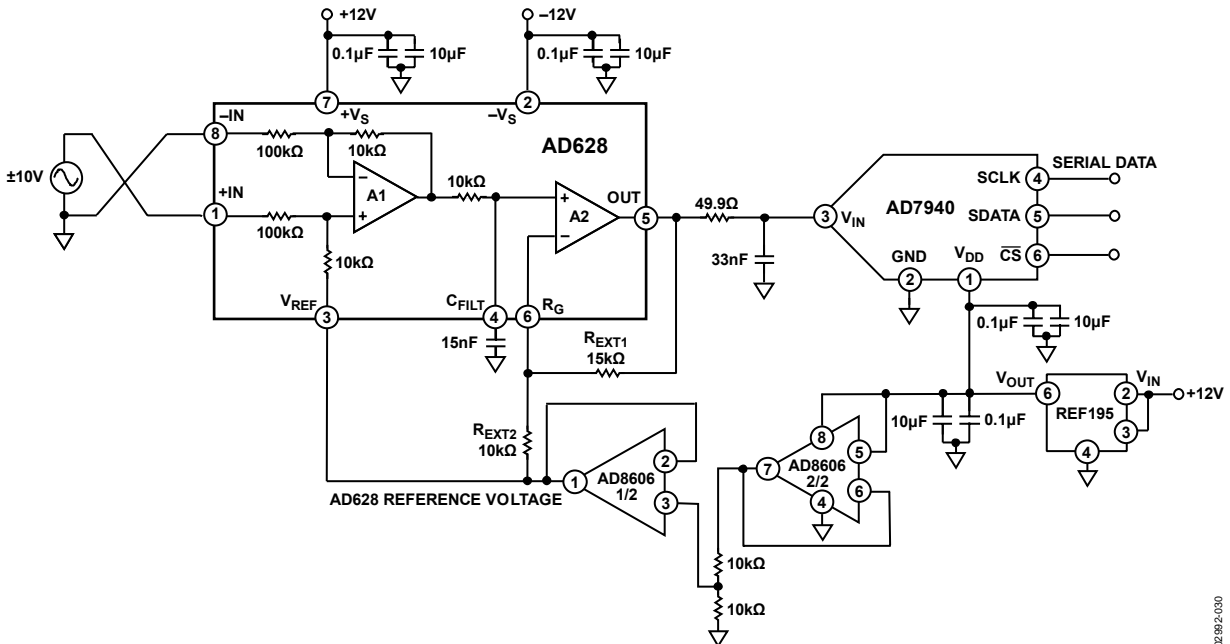


Figure 32. Level Shifter

CURRENT LOOP RECEIVER

Analog data transmitted on a 4 to 20 mA current loop can be detected with the receiver shown in Figure 33. The AD628 is an ideal choice for such a function because the current loop is driven with a compliance voltage sufficient to stabilize the loop, and the resultant common-mode voltage often exceeds commonly used supply voltages. Note that with large shunt values, a resistance of equal value must be inserted in series with the inverting input to compensate for an error at the noninverting input.

MONITORING BATTERY VOLTAGES

Figure 34 illustrates how the AD628 is used to monitor a battery charger. Voltages approximately eight times the power supply voltage can be applied to the input with no damage. The resistor divider action is well suited for the measurement of many power supply applications, such as those found in battery chargers or similar equipment.

For proper operation, the common-mode voltage must satisfy the input specifications in Table 1, as well as Equation 2.

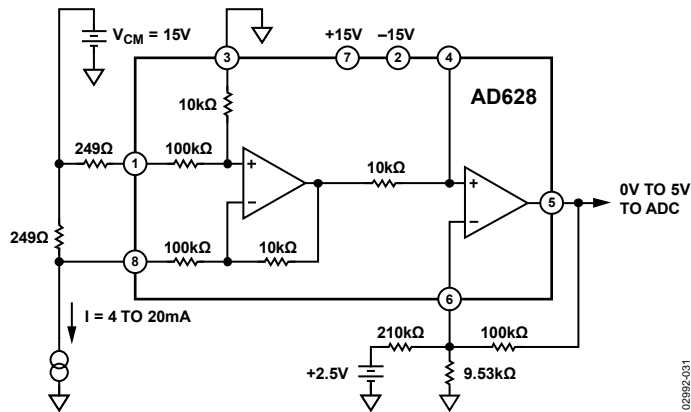


Figure 33. Level Shifter for 4 to 20 mA Current Loop

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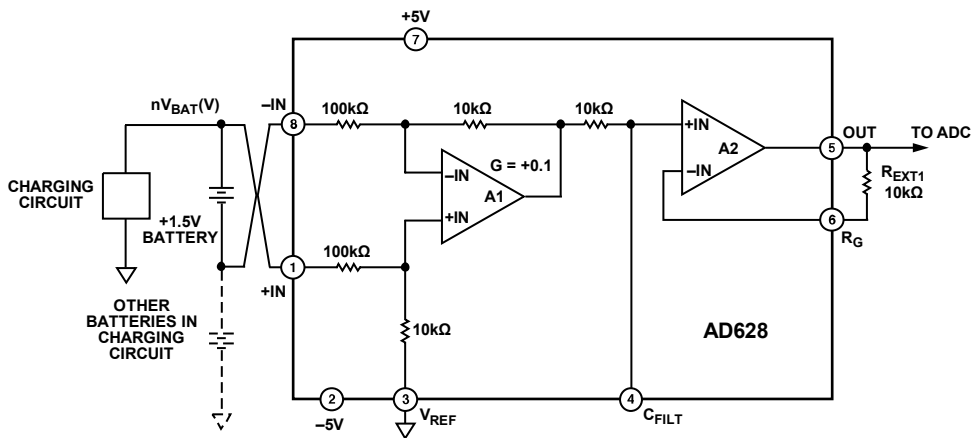


Figure 34. Battery Voltage Monitor

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FILTER CAPACITOR VALUES

Connect a capacitor to Pin 4 (C_{FILT}) to implement a low-pass filter. The capacitor value is

$$C = 15.9/f_i (\mu\text{F})$$

where f_i is the desired 3 dB filter frequency.

Table 7 shows several frequencies and their closest standard capacitor values.

Table 7. Capacitor Values for Various Filter Frequencies

| Frequency (Hz) | Capacitor Value (μF) |
|----------------|-----------------------------------|
| 10 | 1.5 |
| 50 | 0.33 |
| 60 | 0.27 |
| 100 | 0.15 |
| 400 | 0.039 |
| 1 k | 0.015 |
| 5 k | 0.0033 |
| 10 k | 0.0015 |

KELVIN CONNECTION

In certain applications, it may be desirable to connect the inverting input of an amplifier to a remote reference point. This eliminates errors resulting in circuit losses in inter-connecting wiring. The AD628 is particularly suited for this type of connection. In Figure 35, a 10 k Ω resistor added in the feedback matches the source impedance of A2. This is described in more detail in the Gain Adjustment section.

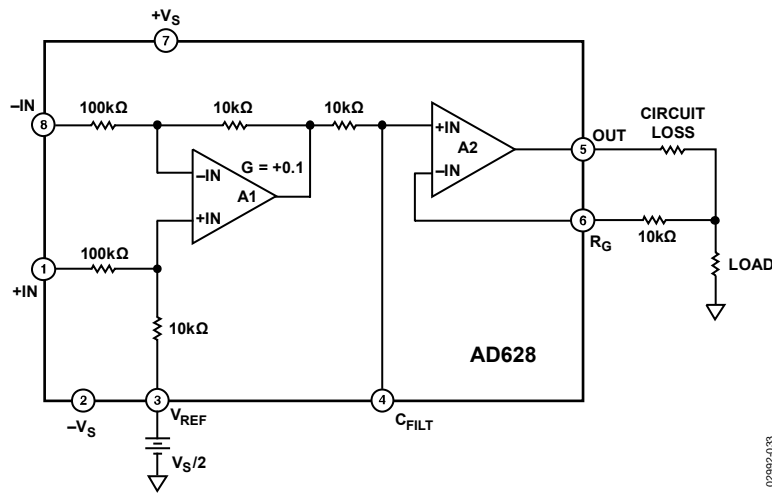


Figure 35. Kelvin Connection

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