

Data Sheet **AD736**

FEATURES

- **Converts an ac voltage waveform to a dc voltage and then converts to the true rms, average rectified, or absolute value 200 mV rms full-scale input range (larger inputs with input attenuator)**
	- **High input impedance: 1012 Ω**
	- **Low input bias current: 25 pA maximum**
	- **High accuracy: ±0.3 mV ± 0.3% of reading**
	- **RMS conversion with signal crest factors up to 5**
	- **Wide power supply range: +2.8 V, −3.2 V to ±16.5 V**
	- **Low power: 200 µA maximum supply current**
	- **Buffered voltage output**

No external trims needed for specified accuracy

Related device: the [AD737—](http://www.analog.com/AD737)features a power-down control with standby current of only 25 μA; the dc output voltage is negative and the output impedance is 8 kΩ

GENERAL DESCRIPTION

The AD736 is a low power, precision, monolithic true rms-todc converter. It is laser trimmed to provide a maximum error of ± 0.3 mV \pm 0.3% of reading with sine wave inputs. Furthermore, it maintains high accuracy while measuring a wide range of input waveforms, including variable duty-cycle pulses and triac (phase)-controlled sine waves. The low cost and small size of this converter make it suitable for upgrading the performance of non-rms precision rectifiers in many applications. Compared to these circuits, the AD736 offers higher accuracy at an equal or lower cost.

The AD736 can compute the rms value of both ac and dc input voltages. It can also be operated as an ac-coupled device by adding one external capacitor. In this mode, the AD736 can resolve input signal levels of 100 μV rms or less, despite variations in temperature or supply voltage. High accuracy is also maintained for input waveforms with crest factors of 1 to 3. In addition, crest factors as high as 5 can be measured (introducing only 2.5% additional error) at the 200 mV full-scale input level.

The AD736 has its own output buffer amplifier, thereby providing a great deal of design flexibility. Requiring only 200 µA of power supply current, the AD736 is optimized for use in portable multimeters and other battery-powered applications.

Low Cost, Low Power, True RMS-to-DC Converter

FUNCTIONAL BLOCK DIAGRAM

The AD736 allows the choice of two signal input terminals: a high impedance FET input ($10^{12} \Omega$) that directly interfaces with High-Z input attenuators and a low impedance input $(8 \text{ k}\Omega)$ that allows the measurement of 300 mV input levels while operating from the minimum power supply voltage of +2.8 V, −3.2 V. The two inputs can be used either single ended or differentially.

The AD736 has a 1% reading error bandwidth that exceeds 10 kHz for the input amplitudes from 20 mV rms to 200 mV rms while consuming only 1 mW.

The AD736 is available in four performance grades. The AD736J and AD736K grades are rated over the 0°C to +70°C and −20°C to +85°C commercial temperature ranges. The AD736A and AD736B grades are rated over the −40°C to +85°C industrial temperature range. The AD736 is available in three low cost, 8-lead packages: PDIP, SOIC, and CERDIP.

PRODUCT HIGHLIGHTS

- 1. The AD736 is capable of computing the average rectified value, absolute value, or true rms value of various input signals.
- 2. Only one external component, an averaging capacitor, is required for the AD736 to perform true rms measurement.
- 3. The low power consumption of 1 mW makes the AD736 suitable for many battery-powered applications.
- 4. A high input impedance of $10^{12} \Omega$ eliminates the need for an external buffer when interfacing with input attenuators.
- 5. A low impedance input is available for those applications that require an input signal up to 300 mV rms operating from low power supply voltages.

Rev. I

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REVISION HISTORY

SPECIFICATIONS

At 25°C ± 5 V supplies, ac-coupled with 1 kHz sine wave input applied, unless otherwise noted. Specifications in **bold** are tested on all production units at final electrical test. Results from those tests are used to calculate outgoing quality levels.

Table 1.

' Accuracy is specified with the AD736 connected as shown i[n Figure 18](#page-9-2) with Capacitor C_c.
? Nonlinearity is defined as the maximum deviation (in percent error) from a straight line connecting the readings at 0 mV rms and

ABSOLUTE MAXIMUM RATINGS

Table 2.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL RESISTANCE

 θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 3. Thermal Resistance

ESD CAUTION

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD.
Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

Table 4. Pin Function Descriptions

TYPICAL PERFORMANCE CHARACTERISTICS

Figure 3. Additional Error vs. Supply Voltage

Figure 6. Frequency Response Driving Pin 1

Figure 8. Additional Error vs. Crest Factor with Various Values of CAV

Figure 14. RMS Input Level vs. Frequency for Specified Averaging Error

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4.0 3.5 INPUT BIAS CURRENT (pA) **INPUT BIAS CURRENT (pA) 3.0 2.5 2.0 1.5** $1.0₀$ 00834-014 00834-014 **0 2 4 6 8 10 12 14 16 SUPPLY VOLTAGE (±V)**

Figure 15. Pin 2 Input Bias Current vs. Supply Voltage

Figure 17. Pin 2 Input Bias Current vs. Temperature

Figure 16. RMS Input Level for Various Values of CAV vs. Settling Time

THEORY OF OPERATION

Figure 18. AD736 True RMS Circuit

As shown b[y Figure 18,](#page-9-2) the AD736 has five functional subsections: the input amplifier, full-wave rectifier (FWR), rms core, output amplifier, and bias section. The FET input amplifier allows both a high impedance, buffered input (Pin 2) and a low impedance, wide dynamic range input (Pin 1). The high impedance input, with its low input bias current, is well suited for use with high impedance input attenuators.

The output of the input amplifier drives a full-wave precision rectifier that, in turn, drives the rms core. The essential rms operations of squaring, averaging, and square rooting are performed in the core using an external averaging capacitor, CAV. Without CAV, the rectified input signal travels through the core unprocessed, as is done with the average responding connection (see [Figure 19\)](#page-11-3).

A final subsection, an output amplifier, buffers the output from the core and allows optional low-pass filtering to be performed via the external capacitor, CF, which is connected across the feedback path of the amplifier. In the average responding connection, this is where all of the averaging is carried out. In the rms circuit, this additional filtering stage helps reduce any output ripple that was not removed by the averaging capacitor, CAV.

TYPES OF AC MEASUREMENT

The AD736 is capable of measuring ac signals by operating as either an average responding converter or a true rms-to-dc converter. As its name implies, an average responding converter computes the average absolute value of an ac (or ac and dc) voltage or current by full-wave rectifying and low-pass filtering the input signal; this approximates the average. The resulting output, a dc average level, is scaled by adding (or reducing) gain; this scale factor converts the dc average reading to an rms equivalent value for the waveform being measured. For example, the average absolute value of a sine wave voltage is 0.636 times V_{PEAK} ; the corresponding rms value is $0.707 \times V_{\text{PEAK}}$. Therefore, for sine wave voltages, the required scale factor is 1.11 (0.707/0.636).

In contrast to measuring the average value, true rms measurement is a universal language among waveforms, allowing the magnitudes of all types of voltage (or current) waveforms to be compared to one another and to dc. RMS is a direct measure of the power or heating value of an ac voltage compared to that of a dc voltage; an ac signal of 1 V rms produces the same amount of heat in a resistor as a 1 V dc signal.

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Mathematically, the rms value of a voltage is defined (using a simplified equation) as

$$
V \text{ rms} = \sqrt{Avg(V^2)}
$$

This involves squaring the signal, taking the average, and then obtaining the square root. True rms converters are smart rectifiers; they provide an accurate rms reading regardless of the type of waveform being measured. However, average responding converters can exhibit very high errors when their input signals deviate from their precalibrated waveform; the magnitude of the error depends on the type of waveform being measured. For example, if an average responding converter is calibrated to measure the rms value of sine wave voltages and then is used to measure either symmetrical square waves or dc voltages, the converter has a computational error 11% (of reading) higher than the true rms value (se[e Table 5\)](#page-10-2).

CALCULATING SETTLING TIME USING FIGURE 16

[Figure 16](#page-8-0) can be used to closely approximate the time required for the AD736 to settle when its input level is reduced in amplitude. The net time required for the rms converter to settle is the difference between two times extracted from the graph (the initial time minus the final settling time). As an example, consider the following conditions: a 33 µF averaging capacitor, a 100 mV initial rms input level, and a final (reduced) 1 mV input level. From [Figure 16,](#page-8-0) the initial settling time (where the 100 mV line intersects the 33 µF line) is approximately 80 ms.

The settling time corresponding to the new or final input level of 1 mV is approximately 8 seconds. Therefore, the net time for the circuit to settle to its new value is 8 seconds minus 80 ms, which is 7.92 seconds. Note that because of the smooth decay characteristic inherent with a capacitor/diode combination, this is the total settling time to the final value (that is, not the settling time to 1%, 0.1%, and so on, of the final value). In addition, this graph provides the worst-case settling time because the AD736 settles very quickly with increasing input levels.

RMS MEASUREMENT—CHOOSING THE OPTIMUM VALUE FOR CAV

Because the external averaging capacitor, C_{AV} , holds the rectified input signal during rms computation, its value directly affects the accuracy of the rms measurement, especially at low frequencies. Furthermore, because the averaging capacitor appears across a diode in the rms core, the averaging time constant increases exponentially as the input signal is reduced. This means that as the input level decreases, errors due to nonideal averaging decrease, and the time required for the circuit to settle to the new rms level increases. Therefore, lower input levels allow the circuit to perform better (due to increased averaging) but increase the waiting time between measurements. Obviously, when selecting C_{AV} , a trade-off between computational accuracy and settling time is required.

Table 5. Error Introduced by an Average Responding Circuit when Measuring Common Waveforms

RAPID SETTLING TIMES VIA THE AVERAGE RESPONDING CONNECTION

Because the average responding connection shown i[n Figure 19](#page-11-3) does not use the CAV averaging capacitor, its settling time does not vary with the input signal level. It is determined solely by the RC time constant of C_F and the internal 8 k Ω resistor in the output amplifier's feedback path.

Figure 19. AD736 Average Responding Circuit

DC ERROR, OUTPUT RIPPLE, AND AVERAGING ERROR

[Figure 20](#page-11-4) shows the typical output waveform of the AD736 with a sine wave input applied. As with all real-world devices, the ideal output of $V_{\text{OUT}} = V_{\text{IN}}$ is never achieved exactly. Instead, the output contains both a dc and an ac error component.

As shown in [Figure 20,](#page-11-4) the dc error is the difference between the average of the output signal (when all the ripple in the output is removed by external filtering) and the ideal dc output. The dc error component is therefore set solely by the value of the averaging capacitor used. No amount of post filtering (that is, using a very large C_F) allows the output voltage to equal its ideal value. The ac error component, an output ripple, can be easily removed by using a large enough post filtering capacitor, CF.

In most cases, the combined magnitudes of both the dc and ac error components need to be considered when selecting appropriate values for Capacitor C_{AV} and Capacitor C_F. This combined error, representing the maximum uncertainty of the measurement, is termed the averaging error and is equal to the peak value of the output ripple plus the dc error.

Figure 20. Output Waveform for Sine Wave Input Voltage

As the input frequency increases, both error components decrease rapidly; if the input frequency doubles, the dc error and ripple reduce to one quarter and one half of their original values, respectively, and rapidly become insignificant.

AC MEASUREMENT ACCURACY AND CREST FACTOR

The crest factor of the input waveform is often overlooked when determining the accuracy of an ac measurement. Crest factor is defined as the ratio of the peak signal amplitude to the rms amplitude (crest factor = V_{PEAK}/V rms). Many common waveforms, such as sine and triangle waves, have relatively low crest factors (≤2). Other waveforms, such as low duty-cycle pulse trains and SCR waveforms, have high crest factors. These types of waveforms require a long averaging time constant (to average out the long periods between pulses)[. Figure 8](#page-6-1) shows the additional error vs. the crest factor of the AD736 for various values of CAV.

APPLICATIONS **CONNECTING THE INPUT**

The inputs of the AD736 resemble an op amp, with noninverting and inverting inputs. The input stages are JFETs accessible at Pin 1 and Pin 2. Designated as the high impedance input, Pin 2 is connected directly to a JFET gate. Pin 1 is the low impedance input because of the scaling resistor connected to the gate of the second JFET. This gate-resistor junction is not externally accessible and is servo-ed to the voltage level of the gate of the first JFET, as in a classic feedback circuit. This action results in the typical 8 kΩ input impedance referred to ground or reference level.

This input structure provides four input configurations as shown in [Figure 21,](#page-12-2) [Figure 22,](#page-12-3) [Figure 23,](#page-12-4) and [Figure 24.](#page-12-5) [Figure 21](#page-12-2) an[d Figure 22](#page-12-3) show the high impedance configurations, and [Figure 23](#page-12-4) an[d Figure 24](#page-12-5) show the low impedance connections used to extend the input voltage range.

Figure 21. High-Z AC-Coupled Input Connection (Default)

Figure 22. High-Z DC-Coupled Input Connection

Figure 24. Low-Z DC-Coupled Input Connection

SELECTING PRACTICAL VALUES FOR INPUT COUPLING (C_C), AVERAGING (C_{AV}), AND FILTERING **(CF) CAPACITORS**

[Table 6](#page-13-1) provides practical values of C_{AV} and C_{F} for several common applications.

The input coupling capacitor, C_c , in conjunction with the 8 kΩ internal input scaling resistor, determine the −3 dB low frequency roll-off. This frequency, F_L, is equal to

2π (8000)(Value of C_C in Farads) 1 $F_L = \frac{1}{2\pi (8000)(Value of C_c in Farads)}$ $E_L = \frac{1}{2\pi (8000)(Value of C_C)}$

Table 6. Capacitor Selection Chart

Note that at FL, the amplitude error is approximately −30% (**–**3 dB) of the reading. To reduce this error to 0.5% of the reading, choose a value of Cc that sets FL at one-tenth of the lowest frequency to be measured.

In addition, if the input voltage has more than 100 mV of dc offset, then the ac-coupling network shown in [Figure 27](#page-15-0) should be used in addition to C_c .

¹ Settling time is specified over the stated rms input level with the input signal increasing from zero. Settling times are greater for decreasing amplitude input signals.

ADDITIONAL APPLICATION CONCEPTS

[Figure 25](#page-14-1) throug[h Figure 28](#page-15-1) show four application concepts. [Figure 25](#page-14-1) shows the high input impedance FET input connected to a multitap attenuator network used in various types of instruments requiring wide ranges of voltages. For a direct network connection, the gate-charge bleeding resistor is not required. The impedance of the FET input is high enough (10^{12} Ω) so that the loading error is negligible. Manufacturers and distributors of the matched precision resistor networks shown in these figures can easily be found on the Web. The voltages shown in the diagrams are the input levels corresponding to 200 mV at each tap. Finally, the

 $47 \text{ k}\Omega$, 1 W resistor and diode pair are a practical input protection scheme for ac line connection measurements.

[Figure 26](#page-14-2) shows both inputs connected differentially[. Figure 27](#page-15-0) shows additional components used for offset correction of the output amplifier, and [Figure 28](#page-15-1) shows connections for singlesupply operation such as is the case for handheld devices.

Further information can be found in the [AN-268](http://www.analog.com/AN-268) Application Note—*RMS-to-DC Converters Ease Measurement Tasks*—and the [RMS to DC Converter Application Guide,](http://www.analog.com/rms-dc-appguide) both of which can be found on the Analog Devices, Inc., website.

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Figure 25. AD736 with a High Impedance Input Attenuator

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EVALUATION BOARD

An evaluation board, AD736-EVALZ, is available for experimentation or becoming familiar with rms-to-dc converters. [Figure 29](#page-16-1) is a photograph of the board, an[d Figure 30](#page-16-2) is the top silkscreen showing the component locations[. Figure 31,](#page-16-3) [Figure 32,](#page-16-4) [Figure 33,](#page-16-5) an[d Figure 34](#page-16-6) show the layers of copper, an[d Figure 35](#page-17-0) shows the schematic of the board configured as shipped. The board is designed for multipurpose applications and can be used for the AD737 as well.

Figure 30. Evaluation Board—Component-Side Silkscreen

As shipped, the board is configured for dual supplies and high impedance input. Optional jumper locations enable low impedance and dc input connections. Using the low impedance input (Pin 1) often enables higher input signals than otherwise possible. A dc connection enables an ac plus dc measurement, but care must be taken so that the opposite polarity input is not dc-coupled to ground.

[Figure 35](#page-17-0) shows the board schematic with all movable jumpers. The jumper positions in black are default connections; the dottedoutline jumpers are optional connections. The board is tested prior to shipment and only requires a power supply connection and a precision meter to perform measurements.

Figure 31. Evaluation Board—Component-Side Copper

Figure 32. Evaluation Board—Secondary-Side Copper

Figure 33. Evaluation Board—Internal Power Plane

Figure 34. Evaluation Board—Internal Ground Plane

Figure 35. Evaluation Board Schematic

0.200 (5.08) MAX

012407-A

OUTLINE DIMENSIONS

Dimensions shown in inches and (millimeters)

Dimensions shown in millimeters and (inches)