[AD9704/](https://www.analog.com/ad9704)[AD9705/](https://www.analog.com/ad9705)[AD9706/](https://www.analog.com/ad9706)[AD9707](https://www.analog.com/ad9707)

8-/10-/12-/14-Bit, 175 MSPS TxDAC Digital-to-Analog Converters

FEATURES

- ► 175 MSPS update rate
- ► Low power member of pin-compatible TxDAC product family
- ► Low power dissipation
	- ► 12 mW at 80 MSPS, 1.8 V
	- ► 50 mW at 175 MSPS, 3.3 V
- ► Wide supply voltage: 1.7 V to 3.6 V
- ► SFDR to Nyquist
	- ► AD9707: 84 dBc at 5 MHz output
	- ► AD9707: 83 dBc at 10 MHz output
	- ► AD9707: 75 dBc at 20 MHz output
- ► Adjustable full-scale current outputs: 1 mA to 5 mA
- ► On-chip 1.0 V reference
- ► CMOS-compatible digital interface
- ► Common-mode output: adjustable 0 V to 1.2 V
- ► Power-down mode <2 mW at 3.3 V (SPI controllable)
- ► Self-calibration
- ► [Compact 32-lead LFCSP, RoHS compliant package](#page--1-0)

GENERAL DESCRIPTION

The AD9704/AD9705/AD9706/AD9707 are the fourth-generation family in the TxDAC® series of high performance, CMOS digital-to-analog converters (DACs). This pin-compatible, 8-/10-/12-/14 bit resolution family is optimized for low power operation, while maintaining excellent dynamic performance. The AD9704/AD9705/ AD9706/AD9707 family is pin-compatible with the [AD9748/](https://www.analog.com/ad9748)[AD9740/](https://www.analog.com/ad9740) [AD9742/](https://www.analog.com/ad9742)[AD9744](https://www.analog.com/ad9744) family of TxDAC converters and is specifically optimized for the transmit signal path of communication systems. All of the devices share the same interface, LFCSP package, and pinout, providing an upward or downward component selection path based on performance, resolution, and cost. The AD9704/AD9705/ AD9706/AD9707 offer exceptional ac and dc performance, while supporting update rates up to 175 MSPS.

The flexible power supply operating range of 1.7 V to 3.6 V and low power dissipation of the AD9704/AD9705/AD9706/AD9707 parts make them well suited for portable and low power applications.

Power dissipation of the AD9704/AD9705/AD9706/AD9707 can be reduced to 15 mW, with a small trade-off in performance, by lowering the full-scale current output. In addition, a power-down mode reduces the standby power dissipation to approximately 2.2 mW.

The AD9704/AD9705/AD9706/AD9707 have an optional serial peripheral interface (SPI®) that provides a higher level of programmability to enhance performance of the DAC. An adjustable output,

common-mode feature allows for easy interfacing to other components that require common modes from 0 V to 1.2 V.

Edge-triggered input latches and a 1.0 V temperature-compensated band gap reference have been integrated to provide a complete, monolithic DAC solution. The digital inputs support 1.8 V and 3.3 V CMOS logic families.

PRODUCT HIGHLIGHTS

- **1.** Pin Compatible. The AD9704/AD9705/AD9706/AD9707 line of TxDAC converters is pin-compatible with the [AD9748/](http://www.analog.com/AD9748?doc=AD9704_9705_9706_9707.pdf)[AD9740/](http://www.analog.com/AD9740?doc=AD9704_9705_9706_9707.pdf) [AD9742](http://www.analog.com/AD9742?doc=AD9704_9705_9706_9707.pdf)[/AD9744](http://www.analog.com/AD9744?doc=AD9704_9705_9706_9707.pdf) TxDAC line (LFCSP package).
- **2.** Low Power. Complete CMOS DAC operates on a single supply of 3.6 V down to 1.7 V, consuming 50 mW (3.3 V) and 12 mW (1.8 V). The DAC full-scale current can be reduced for lower power operation. Sleep and power-down modes are provided for low power idle periods.
- **3.** Self-Calibration. Self-calibration enables true 14-bit INL and DNL performance in the AD9707.
- **4.** Twos Complement/Binary Data Coding Support. Data input supports twos complement or straight binary data coding.
- **5.** Flexible Clock Input. A selectable high speed, single-ended, and differential CMOS clock input supports 175 MSPS conversion rate.
- **6.** Device Configuration. Device can be configured through pin strapping, and SPI control offers a higher level of programmability.
- **7.** Easy Interfacing to Other Components. Adjustable commonmode output allows for easy interfacing to other signal chain components that accept common-mode levels from 0 V to 1.2 V.
- **8.** On-Chip Voltage Reference. The AD9704/AD9705/AD9706/ AD9707 include a 1.0 V temperature-compensated band gap voltage reference.
- **9.** Industry-Standard [32-Lead LFCSP Package.](#page--1-0)

Rev. G

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REVISION HISTORY

6/2022-Rev. E to Rev. F

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FUNCTIONAL BLOCK DIAGRAM

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DC SPECIFICATIONS (3.3 V)

 T_{MIN} to T_{MAX} , AVDD = 3.3 V, DVDD = 3.3 V, CLKVDD = 3.3 V, I_{OUTFS} = 2 mA, unless otherwise noted.

Table 1.

Table 1. (Continued)

¹ Measured at IOUTA, driving a virtual ground.

² Normal full scale current, I_{OUTFS} is 32 \times the I_{REF} current.

³ Use an external buffer amplifier with an input bias current <100 nA to drive any external load.

⁴ Measured at f_{CLOCK} = 175 MSPS and f_{OUT} = 1.0 MHz, using a differential clock.

⁵ Measured at f_{CLOCK} = 100 MSPS and f_{OUT} = 1.0 MHz, using a differential clock.

 $6 + 5%$ power supply variation.

DYNAMIC SPECIFICATIONS (3.3 V)

T_{MIN} to T_{MAX}, AVDD = 3.3 V, DVDD = 3.3 V, CLKVDD = 3.3 V, I_{OUTFS} = 2 mA, differential transformer coupled output, 453 Ω differentially terminated unless otherwise noted.

Table 2.

Table 2. (Continued)

¹ Measured single-ended into 500 Ω load.

DIGITAL SPECIFICATIONS (3.3 V)

 T_{MIN} to T_{MAX} , AVDD = 3.3 V, DVDD = 3.3 V, CLKVDD = 3.3 V, I_{OUTFS} = 2 mA, unless otherwise noted.

Table 3.

¹ Includes CLK+ pin in single-ended clock input mode.

² Applicable to CLK+ input and CLK− input when configured for differential clock input mode.

DC SPECIFICATIONS (1.8 V)

 T_{MIN} to T_{MAX} , AVDD = 1.8 V, DVDD = 1.8 V, CLKVDD = 1.8 V, I_{OUTFS} = 2 mA, unless otherwise noted.

Table 4.

Table 4. (Continued)

- ¹ Measured at IOUTA, driving a virtual ground.
- ² Nominal full-scale current, I_{OUTFS} , is 32 \times the I_{REF} current.
- ³ Use an external buffer amplifier with an input bias current <100 nA to drive any external load.
- ⁴ Measured at I_{OUTFS} = 1 mA.
- ⁵ Measured at f_{CLOCK} = 80 MSPS and f_{OUT} = 1 MHz, using a differential clock.
- 6 ±5% power supply variation.

DYNAMIC SPECIFICATIONS (1.8 V)

T_{MIN} to T_{MAX}, AVDD = 1.8 V, DVDD = 1.8 V, CLKVDD = 1.8 V, I_{OUTFS} = 1 mA, differential transformer coupled output, 453 Ω differentially terminated unless otherwise noted.

¹ Measured single-ended into 500 Ω load.

DIGITAL SPECIFICATIONS (1.8 V)

 T_{MIN} to T_{MAX} , AVDD = 1.8 V, DVDD = 1.8 V, CLKVDD = 1.8 V, I_{OUTFS} = 1 mA, unless otherwise noted.

Table 6.

Table 6. (Continued)

¹ Includes CLK+ pin in single-ended clock input mode.

² Applicable to CLK+ input and CLK– input when configured for differential clock input mode.

TIMING DIAGRAM

Figure 2. Parallel Data Interface Timing Diagram

ABSOLUTE MAXIMUM RATINGS

Table 7.

¹ n stands for 7 for the [AD9704,](https://www.analog.com/ad9704) 9 for the [AD9705](https://www.analog.com/ad9705), 11 for the [AD9706](https://www.analog.com/ad9706), and 13 for the [AD9707](https://www.analog.com/ad9707).

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL CHARACTERISTICS

Thermal impedance measurements were taken on a 4-layer board in still air, in accordance with EIA/JESD51-7.

Table 8. Thermal Resistance

ESD CAUTION

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

AD9707

Figure 3. AD9707 Pin Configuration

Table 9. AD9707 Pin Function Descriptions

AD9706

Figure 4. AD9706 Pin Configuration

Table 10. AD9706 Pin Function Descriptions

AD9705

Figure 5. AD9705 Pin Configuration

Table 11. AD9705 Pin Function Descriptions

AD9704

Figure 6. AD9704 Pin Configuration

Table 12. AD9704 Pin Function Descriptions

AD9707

VDD = 3.3 V, I_{OUTFS} = 2 mA, unless otherwise noted.

*Figure 9. SFDR vs. f*_{OUT} at 65 MSPS

Figure 12. SFDR vs. fOUT and IOUTFS at 175 MSPS

*Figure 13. SFDR vs. f*_{OUT} and OTCM at 175 MSPS

*Figure 16. NSD vs. f*_{OUT} and I_{OUTFS} at 175 MSPS

Figure 17. Dual-Tone IMD vs. Lower fOUT and fCLOCK at 0 dBFS

Figure 18. Dual-Tone IMD vs. Lower fOUT and Temperature at 0 dBFS, 175 MSPS

Figure 21. Typical Calibrated INL

Figure 22. Typical Calibrated DNL

Figure 23. SFDR vs. fOUT and Temperature at 175 MSPS

Figure 24. Single-Tone SFDR

Figure 25. Dual-Tone SFDR Figure 26. Four-Tone SFDR

VDD = 1.8 V, I_{OUTFS} = 1 mA, unless otherwise noted.

Figure 29. SFDR vs. f_{OUT} at 80 MSPS

Figure 30. SFDR vs. fOUT and IOUTFS at 65 MSPS

Figure 31. SFDR vs. fOUT and IOUTFS at 80 MSPS

Figure 32. SFDR vs. AOUT at fOUT = fCLOCK/5

Figure 33. NSD vs. fOUT, fCLOCK, and IOUTFS at 0 dBFS

Figure 34. Dual-Tone IMD vs. Lower fOUT at IOUTFS = 1 mA and 0 dBFS

Figure 35. Dual-Tone IMD vs. Lower fOUT at IOUTFS = 2 mA and 0 dBFS

Figure 36. Dual-Tone IMD vs. Lower fOUT and Temperature at 80 MSPS, IOUTFS = 1 mA and 0 dBFS

Figure 37. Dual-Tone IMD vs. Lower fOUT and Temperature at 80 MSPS, IOUTFS = 2 mA and 0 dBFS

Figure 38. Typical Uncalibrated INL

Figure 41. Single-Tone SFDR

Figure 42. Dual-Tone SFDR

Figure 43. Four-Tone SFDR

AD9704, AD9705 AND AD9706

VDD = 3.3 V, I_{OUTFS} = 2 mA, unless otherwise noted.

Figure 44. AD9704/AD9705/AD9706/AD9707 NSD vs. fOUT at 0 dBFS, 175 MSPS

Figure 46. AD9704 Typical Uncalibrated DNL

Figure 47. AD9705 Typical Uncalibrated INL

Figure 48. AD9705 Typical Uncalibrated DNL

Figure 49. AD9706 Typical Uncalibrated INL

Figure 53. AD9705 Single-Tone SFDR

Figure 54. AD9705 Dual-Tone SFDR

Figure 55. AD9706 Single-Tone SFDR

Figure 56. AD9706 Dual-Tone SFDR

VDD = 1.8 V, I_{OUTFS} = 1 mA, unless otherwise noted.

Figure 57. AD9704/AD9705/AD9706/AD9707 NSD vs. fOUT at 0 dBFS, 80 MSPS

Figure 59. AD9704 Typical Uncalibrated DNL

Figure 60. AD9705 Typical Uncalibrated INL

Figure 61. AD9705 Typical Uncalibrated DNL

Figure 62. AD9706 Typical Uncalibrated INL

Figure 66. AD9705 Single-Tone SFDR

Figure 67. AD9705 Dual-Tone SFDR

Figure 68. AD9706 Single-Tone SFDR

Figure 69. AD9706 Dual-Tone SFDR

TERMINOLOGY

Linearity Error (Integral Nonlinearity or INL)

INL is defined as the maximum deviation of the actual analog output from the ideal output, determined by a straight line drawn from zero to full scale.

Differential Nonlinearity (DNL)

DNL is the measure of the variation in analog value, normalized to full scale, associated with a 1 LSB change in digital input code.

Monotonicity

A digital-to-analog converter is monotonic if the output either increases or remains constant as the digital input increases.

Offset Error

Offset error is the deviation of the output current from the ideal of zero. For IOUTA, 0 mA output is expected when the inputs are all 0s. For IOUTB, 0 mA output is expected when all inputs are set to 1.

Gain Error

Gain error is the difference between the actual and ideal output span. The actual span is determined by the output when all inputs are set to 1, minus the output when all inputs are set to 0. The ideal gain is calculated using the measured VREF. Therefore, the gain error does not include effects of the reference.

Output Compliance Range

Output compliance range is the range of allowable voltage at the output of a current output DAC. Operation beyond the maximum compliance limits can cause either output stage saturation or breakdown, resulting in nonlinear performance.

Temperature Drift

Temperature drift is specified as the maximum change from the ambient (25°C) value to the value at either T_{MIN} or T_{MAX} . For offset and gain drift, the drift is reported in ppm of full-scale range (FSR) per °C. For reference drift, the drift is reported in ppm per °C.

Power Supply Rejection

Power supply rejection is the maximum change in the full-scale output as the supplies are varied from nominal to minimum and maximum specified voltages.

Settling Time

Settling time is the time required for the output to reach and remain within a specified error band about its final value, measured from the start of the output transition.

Glitch Impulse

Asymmetrical switching times in a DAC give rise to undesired output transients that are quantified by a glitch impulse. It is specified as the net area of the glitch in picovolt-seconds (pV-s).

Spurious-Free Dynamic Range (SFDR)

SFDR is the difference, in decibels (dB), between the rms amplitude of the output signal and the peak spurious signal over the specified bandwidth. Refer to [Figure 70](#page-29-0) for the basic AC characterization test setup.

Total Harmonic Distortion (THD)

THD is the ratio of the rms sum of the first six harmonic components to the rms value of the measured input signal. It is expressed as a percentage or in decibels (dB).

Multitone Power Ratio

Multitone power ratio is the spurious-free dynamic range containing multiple carrier tones of equal amplitude. It is measured as the difference between the rms amplitude of a carrier tone to the peak spurious signal in the region of a removed tone.

Noise Spectral Density (NSD)

Noise spectral density is the average noise power normalized to a 1 Hz bandwidth, with the DAC converting and producing an output tone.

TERMINOLOGY

Figure 70. Basic AC Characterization Test Setup

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[Figure 1](#page-3-0) shows a simplified block diagram of the AD9707. The AD9704/AD9705/AD9706/AD9707 consist of a DAC, digital control logic, and full-scale output current control. The DAC contains a PMOS current source array capable of providing a nominal fullscale current (I_{OUTFS}) of 2 mA and a maximum of 5 mA. The array is divided into 31 equal currents that make up the five most significant bits (MSBs). The next four bits, or middle bits, consist of 15 equal current sources whose value is 1/16 of an MSB current source. The remaining LSBs are binary weighted fractions of the current sources of the middle bits. Implementing the middle and lower bits with current sources, instead of an R-2R ladder, enhances the AD9704/AD9705/AD9706/AD9707 dynamic performance for multitone or low amplitude signals and helps maintain the high output impedance of the DAC (that is, $>$ 200 MΩ).

All of these current sources are switched to one of the two output nodes (IOUTA or IOUTB) via PMOS differential current switches. The switches are based on the architecture pioneered in the [AD9764](http://www.analog.com/AD9764?doc=AD9704_9705_9706_9707.pdf) family, with further refinements made to reduce distortion contributed by the switching transient. This switch architecture also reduces various timing errors and provides matching complementary drive signals to the inputs of the differential current switches.

The analog and digital sections of the AD9704/AD9705/AD9706/ AD9707 have separate power supply inputs (AVDD, DVDD, and CLKVDD) that can operate over the 1.7 V to 3.6 V range but must have the same voltage levels, that is, all 1.8 V or all 3.3 V. On power-up, ramp all supply rails at the same time.

The digital section, capable of operating at a rate of up to 175 MSPS, consists of edge triggered latches and segment decoding logic circuitry. The analog section includes the PMOS current sources, the associated differential switches, a 1.0 V band gap voltage reference, and a reference control amplifier.

To ensure proper operation of the device in SPI mode, an active high pulse with a minimum pulse width of 50 ns must be applied once to the PIN/SPI/RESET pin after applying power to all three supplies. This ensures that all the control register bits are set to default. Refer to the [SPI Register Map](#page-33-0) section for the default values of each register. To operate the device in pin mode, Pin 17 must be held high. Alternatively, the pin can be pulled up to AVDD.

The DAC full-scale output current is regulated by the reference control amplifier and can be set from 1 mA to 5 mA via an external resistor, R_{SFT} , connected to the full-scale adjust (FS ADJ) pin.

The external resistor, in combination with both the reference control amplifier and voltage reference, V_{REFIO} , sets the reference current, I_{REF} , which is replicated to the segmented current sources with the proper scaling factor. The full-scale current, I_{OUTFS} , is 32 \times I_{REF}.

The AD9704/AD9705/AD9706/AD9707 provide the option of setting the output common mode to a value other than ACOM via the output common mode (OTCM) pin. This facilitates interfacing the output of the AD9704/AD9705/AD9706/AD9707 directly to components that require common-mode levels greater than 0 V.

SERIAL PERIPHERAL INTERFACE

The AD9704/AD9705/AD9706/AD9707 serial port is a flexible, synchronous serial communications port that allows easy interfacing to many industry-standard microcontrollers and microprocessors. The serial I/O is compatible with most synchronous transfer formats, including the Motorola SPI and Intel® SSR protocols. The interface allows read/write access to all registers that configure the AD9704/AD9705/AD9706/AD9707. Single or multiple byte transfers are supported, as well as MSB first or LSB first transfer formats. The serial interface port of the AD9704/AD9705/AD9706/AD9707 is configured as a single pin I/O. SPI terminal voltages are referenced to ACOM.

General Operation of the Serial Interface

There are two phases to a communication cycle with the AD9704/ AD9705/AD9706/AD9707. Phase 1 is the instruction cycle, which is the writing of an instruction byte into the AD9704/AD9705/AD9706/ AD9707, coincident with the first eight SCLK rising edges. The instruction byte provides the AD9704/AD9705/AD9706/AD9707 serial port controller with information regarding the data transfer cycle, which is Phase 2 of the communication cycle. The Phase 1 instruction byte defines whether the upcoming data transfer is read or write, the number of bytes in the data transfer, and the starting register address for the first byte of the data transfer.

Applying an active high pulse with a minimum pulse width of 50 ns to the PIN/SPI/RESET pin resets the SPI port timing to the initial state of the instruction cycle. This is true regardless of the present state of the internal registers or the other signal levels present at the inputs to the SPI port. If the SPI port is in the midst of an instruction cycle or a data transfer cycle, none of the present data is written.

The remaining SCLK edges are for Phase 2 of the communication cycle. Phase 2 is the actual data transfer between the AD9704/ AD9705/AD9706/AD9707 and the system controller. Phase 2 of the communication cycle is a transfer of one, two, three, or four data bytes, as determined by the instruction byte. Using one multibyte transfer is the preferred method. Single byte data transfers are useful to reduce CPU overhead when register access requires one byte only. Registers change immediately upon writing to the last bit of each transfer byte.

Instruction Byte

The instruction byte contains the information shown in the bit map in Table 13.

 R/\overline{W} , Bit 7 of the instruction byte, determines whether a read or a write data transfer occurs after the instruction byte write. Logic 1 indicates a read operation. Logic 0 indicates a write operation. N1 and N0, Bit 6 and Bit 5 of the instruction byte, determine the number of bytes to be transferred during the data transfer cycle. The bit decodes are shown in Table 14.

A4, A3, A2, A1, and A0, which are Bit 4, Bit 3, Bit 2, Bit 1, and Bit 0 of the instruction byte, respectively, determine which register is accessed during the data transfer portion of the communication cycle. For multibyte transfers, this address is the starting byte address. The remaining register addresses are generated by the AD9704/AD9705/AD9706/AD9707, based on the DATADIR bit (Register 0x00, Bit 6).

Table 14. Byte Transfer Count

Serial Interface Port Pin Descriptions

SCLK—Serial Clock. The serial clock pin is used to synchronize data to and from the AD9704/AD9705/AD9706/AD9707 and to run the internal state machines. The SCLK maximum frequency is 20 MHz. All data input to the AD9704/AD9705/AD9706/AD9707 is registered on the rising edge of SCLK. All data is driven out of the AD9704/AD9705/AD9706/AD9707 on the falling edge of SCLK.

CSB—Chip Select. Active low input starts and gates a communication cycle. It allows more than one device to be used on the same serial communications lines. The SDIO pin goes to a high impedance state when this input is high. Chip select must stay low during the entire communication cycle.

SDIO—Serial Data I/O. This pin is used as a bidirectional data line to transmit and receive data.

MSB/LSB Transfers

The AD9704/AD9705/AD9706/AD9707 serial port can support both most significant bit (MSB) first or least significant bit (LSB) first data formats. This functionality is controlled by the DATADIR bit (Register 0x00, Bit 6). The default is MSB first (DATADIR = 0).

When DATADIR = 0 (MSB first), the instruction and data bytes must be written from most significant bit to least significant bit. Multibyte data transfers in MSB first format start with an instruction byte that includes the register address of the most significant data byte. Subsequent data bytes should follow in order from high address to low address. In MSB first mode, the serial port internal byte address generator decrements for each data byte of the multibyte communication cycle.

When DATADIR = 1 (LSB first), the instruction and data bytes must be written from least significant bit to most significant bit. Multibyte data transfers in LSB first format start with an instruction byte that includes the register address of the least significant data byte followed by multiple data bytes. The serial port internal byte address generator increments for each byte of the multibyte communication cycle.

The AD9704/AD9705/AD9706/AD9707 serial port controller data address decrements from the data address written toward 0x00 for multibyte I/O operations if the MSB first mode is active. The serial port controller address increments from the data address written toward 0x1F for multibyte I/O operations if the LSB first mode is active.

Notes on Serial Port Operation

The AD9704/AD9705/AD9706/AD9707 serial port configuration is controlled by Register 0x00, Bit 7. It is important to note that the configuration changes immediately upon writing to the last bit of the register. For multibyte transfers, writing to this register can occur during the middle of the communication cycle. Care must be taken to compensate for this new configuration for the remaining bytes of the current communication cycle.

The same considerations apply to setting the software reset, SWRST (Register 0x00, Bit 5). All registers are set to their default values except Register 0x00, which remains unchanged.

Use of single byte transfers is recommended when changing serial port configurations or initiating a software reset to prevent unexpected device behavior.

In [Figure 75](#page-32-0), the minimum SPI clock period t_{SCLK} is 50 ns. The minimum duration for the high and low pulse widths of the SPI clock, t_{PWH} and t_{PWL}, respectively, is 25 ns.

[Figure 76](#page-32-0) shows the duration t_{DIY} from the SCLK falling edge that data read is driven out of the SDIO pin. The typical value of t_{DIY} is 2 ns.

The input setup time, t_s , and input hold time, t_H , for both read and write operations depend on the operating supply voltage and temperature. Refer to [Table 3](#page-6-0) and [Table 6](#page-8-0).

Figure 71. Serial Register Interface Timing, MSB First Write

Figure 72. Serial Register Interface Timing, MSB First Read

Figure 73. Serial Register Interface Timing, LSB First Write

Figure 74. Serial Register Interface Timing, LSB First Read

Figure 75. Timing Diagram for SPI Register Write

Figure 76. Timing Diagram for SPI Register Read

PIN MODE

For applications without a controller, the AD9704/AD9705/AD9706/ AD9707 can be operated in pin mode. Pin mode allows selecting functions without writing to the serial port.

Pin mode is enabled when the PIN/SPI/RESET pin is held high after applying power to all three supplies (AVDD, DVDD, and CLKVDD). Alternatively, the pin can be pulled up to AVDD.

The CMODE/SCLK, MODE/SDIO, and SLEEP/CSB pins are not latched at power-up. If the data format is changed, it is required to wait 1 μs after power-up to ensure proper function. Table 15 summarizes the SPI pins and their functions in pin mode.

SPI REGISTER MAP

Table 16.

SPI REGISTER DESCRIPTIONS

Table 17. SPI CTL—Register 0x00

Table 18. Data—Register 0x02

Table 19. Version—Register 0x0D

Table 20. CALMEM—Register 0x0E

Table 20. CALMEM—Register 0x0E (Continued)

Table 21. MEMRDWR—Register 0x0F

Table 22. MEMADDR—Register 0x10

Table 23. MEMDATA—Register 0x11

REFERENCE OPERATION

The AD9704/AD9705/AD9706/AD9707 contain an internal 1.0 V band gap reference. The internal reference can be disabled by writing a Logic 1 to Register 0x00, Bit 0 (EXREF) in the SPI.

The internal 1.0 V band gap reference ramps up for around 2 ms when the proper power-up conditions in the [Power Supply](#page-41-0) section are followed.

To use the internal reference, decouple the REFIO pin to ACOM with a 0.1 µF capacitor and enable the internal reference by writing a Logic 0 to Register 0x00, Bit 0 in the SPI. (Note that this setting is the default configuration.) The internal reference voltage is present at REFIO. If the voltage at REFIO is to be used anywhere else in the circuit, an external buffer amplifier with an input bias current of less than 100 nA must be used to avoid loading the reference. An example of the use of the internal reference is shown in Figure 77.

REFIO serves as either an input or an output, depending on whether the internal or an external reference is used. Table 24 summarizes the reference operation.

An external reference is required in applications that need gain tolerances with minimal variation or lower temperature drift. The [ADR130](https://www.analog.com/adr130) precision voltage reference or equivalent is recommended for AD9704/AD9705/AD9706/AD9707, and its analog supply can be connected to AVDD. Refer to [Figure 78.](#page-35-0)

Figure 77. Internal Reference Configuration

Figure 78. External Reference Configuration

Also, a variable external voltage reference can be used to implement a method for gain control of the DAC output. The external reference is applied to the REFIO pin (Note that the 0.1 µF compensation capacitor is not required). The internal reference can be directly overridden by the external reference. It is recommended to power down the internal reference to lessen power consumption. The input impedance of REFIO is 10 kΩ when powered up and 1 MΩ when powered down.

REFERENCE CONTROL AMPLIFIER

The AD9704/AD9705/AD9706/AD9707 contain a control amplifier that regulates the full-scale output current, I_{OUTFS} . The control amplifier is configured as a V-I converter, as shown in [Figure 77.](#page-34-0) The output current, I_{REF} , is determined by the ratio of the V_{REFIO} and an external resistor, R_{SET} , as stated in Equation 4. I_{REF} is mirrored to the segmented current sources with the proper scale factor to set I_{OUTFS} , as stated in Equation 3.

The control amplifier allows a 5:1 adjustment span of I_{OUTFS} from 1 mA to 5 mA by setting I_{RFF} between 31.25 μ A and 156.25 μ A $(R_{SFT}$ between 6.4 kΩ and 32 kΩ). The wide adjustment span of I_{OUTFS} provides several benefits. The first relates directly to the power dissipation of the AD9704/AD9705/AD9706/AD9707, which is proportional to I_{OUTFS} (see the [Power Dissipation](#page-37-0) section). The second benefit relates to the ability to adjust the output over a 14 dB range, which is useful for controlling the transmitted power.

DAC TRANSFER FUNCTION

The AD9704/AD9705/AD9706/AD9707 provide complementary current outputs, IOUTA and IOUTB. IOUTA provides a near full-scale current output, I_{OUTFS} , when all bits are high (that is, DAC CODE = 2 ^N − 1, where N = 8, 10, 12, or 14 for the AD9704/AD9705/AD9706/ AD9707, respectively), while IOUTB, the complementary output, provides no current. The current output appearing at IOUTA and IOUTB is a function of both the input code and I_{OUITFS} and can be expressed as

IOUTA = (*DAC CODE*/2*N*) × *IOUTFS* (1)

 $IOUTB = ((2^N – 1) – DAC CODE)/2^N × I_{OUTES}$ (2)

where *DAC CODE* = 0 to 2^N – 1 (that is, decimal representation).

 I_{OUTFS} is a function of the reference current, I_{REF} , which is nominally set by a reference voltage, V_{REFIO} , and an external resistor, R_{SET} . It can be expressed as

$$
I_{OUTFS} = 32 \times I_{REF} \tag{3}
$$

where

$$
I_{REF} = V_{REFIO}/R_{SET}
$$
 (4)

The two current outputs typically drive a resistive load directly or via a transformer. If dc coupling is required, IOUTA and IOUTB should be connected to matching resistive loads (R_{LOAD}) that are tied to analog common (ACOM). The single-ended voltage output appearing at the IOUTA and IOUTB nodes is

$$
V_{IOUTA} = IOUTA \times R_{LOAD} \tag{5}
$$

$$
V_{IOUTB} = IOUTB \times R_{LOAD}
$$
 (6)

To achieve a 1 V p-p output at the nominal 2 mA output current, R_{LOAD} must be set to 500 Ω.

Also, the full-scale value of V_{IOUTA} and V_{IOUTB} must not exceed the specified output compliance range to maintain specified distortion and linearity performance.

$$
V_{DIFF} = (IOUTA - IOUTB) \times R_{LOAD} \tag{7}
$$

Substituting the values of IOUTA, IOUTB, I_{RFF} , and V_{DIFF} can be expressed as

$$
V_{DIFF} = \{ (2 \times DAC CODE - (2N - 1)) / 2N \} \times
$$

(32 × V_{REFIO}/R_{SET}) × R_{LOAD} (8)

Equation 7 and Equation 8 highlight some of the advantages of operating the AD9704/AD9705/AD9706/AD9707 differentially. First, the differential operation helps cancel common-mode error sources associated with IOUTA and IOUTB, such as noise, distortion, and dc offsets. Second, the differential code dependent current and subsequent voltage, V_{DIFF} , is twice the value of the single-ended voltage output (that is, V_{IOUTA} or V_{IOUTB}), thus providing twice the signal power to the load.

The gain drift temperature performance for a single-ended output $(V_{IOUTA}$ and V_{IOUTB}) or the differential output (V_{DIFF}) of the AD9704/ AD9705/AD9706/AD9707 can be enhanced by selecting temperature tracking resistors for R_{LOAD} and R_{SET} , because of their ratiometric relationship, as shown in Equation 8.

ANALOG OUTPUTS

The complementary current outputs in each DAC, IOUTA, and IOUTB can be configured for single-ended or differential operation. IOUTA and IOUTB can be converted into complementary singleended voltage outputs, V_{IOUTA} and V_{IOUTB} , via a load resistor, R_{LOAD} , as described in the DAC Transfer Function section by Equation 5 through Equation 8. The differential voltage, V_{DIFF} , existing between V_{IOUTA} and V_{IOUTB} , can also be converted to a single-ended voltage via a transformer or a differential amplifier configuration. The ac performance of the AD9704/AD9705/AD9706/ AD9707 is optimum and is specified using a differential transformercoupled output in which the voltage swing at IOUTA and IOUTB is limited to ±0.5 V.

The distortion and noise performance of the AD9704/AD9705/ AD9706/AD9707 can be enhanced when it is configured for differential operation. The common-mode error sources of both IOUTA and IOUTB can be significantly reduced by the common-mode rejection of a transformer or differential amplifier. These commonmode error sources include even-order distortion products and noise. The enhancement in distortion performance becomes more significant as the frequency content of the reconstructed waveform increases and/or its amplitude increases. This is due to the firstorder cancellation of various dynamic common-mode distortion mechanisms, digital feedthrough, and noise.

Performing a differential-to-single-ended conversion via a transformer also provides the ability to deliver twice the reconstructed signal power to the load (assuming no source termination). Because the output currents of IOUTA and IOUTB are complementary, they become additive when processed differentially.

When the AD9704/AD9705/AD9706/AD9707 is being used at its nominal operating point of 2 mA output current and 0.5 V output swing is desired, R_{LOAD} must be set to 250 Ω. A properly selected transformer allows the AD9704/AD9705/AD9706/AD9707 to provide the required power and voltage levels to different loads.

The output impedance of IOUTA and IOUTB is determined by the equivalent parallel combination of the PMOS switches associated with the current sources and is typically 200 MΩ in parallel with 5 pF . It is also slightly dependent on the output voltage (that is, V_{1011T4}) and V_{IOUTB}) due to the nature of a PMOS device. As a result, maintaining IOUTA and/or IOUTB at a virtual ground via an I-V op amp configuration results in the optimum dc linearity. Note that the INL/DNL specifications for the AD9704/AD9705/AD9706/AD9707 are measured with IOUTA maintained at a virtual ground via an op amp.

IOUTA and IOUTB also have a negative and positive voltage compliance range that must be adhered to in order to achieve optimum performance. The absolute maximum negative output compliance range of −1 V is set by the breakdown limits of the CMOS process. Operation beyond this maximum limit can result in a breakdown of the output stage and affect the reliability of the AD9704/AD9705/ AD9706/AD9707.

The positive output compliance range is slightly dependent on the full-scale output current, I_{OUTFS} . It degrades slightly from its nominal 1.0 V for an I_{OUTFS} = 2 mA to 0.8 V for an I_{OUTFS} = 1 mA. The optimum distortion performance for a single-ended or differential output is achieved when the maximum full-scale signal at IOUTA and IOUTB does not exceed 0.5 V.

ADJUSTABLE OUTPUT COMMON MODE

The AD9704/AD9705/AD9706/AD9707 provide the ability to set the output common mode to a value other than ACOM via Pin 19 (OTCM). This extends the compliance range of the outputs and facilitates interfacing the output of the AD9704/AD9705/AD9706/ AD9707 to components that require common-mode levels other

than 0 V. The OTCM pin demands dynamically changing current and should be driven by a low source impedance to prevent a common-mode signal from appearing on the DAC outputs. The OTCM pin also serves to change the DAC bias voltages in the parts, allowing them to run at higher dc output bias voltages. When running the bias voltage below 0.9 V and an AVDD of 3.3 V, the parts perform optimally when the OTCM pin is tied to ground. When the dc bias increases above 0.9 V, set the OTCM pin at 0.5 V for optimal performance. Keep the maximum dc bias on the DAC output at or below 1.2 V when the supply is 3.3 V. When the supply is 1.8 V, keep the dc bias close to 0 V and connect the OTCM pin directly to ground. Note that setting OTCM to a voltage greater than ACOM allows the peak of the output signal to be closer to the positive supply rail. To prevent distortion in the output signal due to limited available headroom, the common-mode level must be chosen such that the following expression is satisfied:

AVDD − *VOTCM* > 1.8 V (9)

DIGITAL INPUTS

The AD9707, AD9706, AD9705, and AD9704 have data inputs of 14, 12, 10, and 8 bits, respectively, and each has a clock input. The parallel data inputs can follow standard positive binary or twos complement coding. IOUTA produces a full-scale output current when all data bits are at Logic 1. IOUTB produces a complementary output with the full-scale current split between the two outputs as a function of the input code.

Figure 79. Equivalent Digital Input

The digital interface is implemented using an edge-triggered master/slave latch. The DAC output updates on the rising edge of the clock and is designed to support a clock rate as high as 175 MSPS. The clock can be operated at any duty cycle that meets the specified latch pulse width. The setup and hold times can also be varied within the clock cycle, as long as the specified minimum times are met, although the location of these transition edges may affect digital feedthrough and distortion performance. Best performance is typically achieved when the input data transitions on the falling edge of a 50% duty cycle clock.

Deskew Mode

The AD9704/AD9705/AD9706/AD9707 provide an optional deskew mode. Turning on the deskew mode can improve the skew glitch behavior of the DAC. With the deskew mode enabled, a one CLK+/CLK− clock cycle register delay is added to the digital input path. By default, the DESKEW bit in the data register (0x02) is set to 0, disabling the deskew mode.

CLOCK INPUT

A configurable clock input allows the device to be operated in a single-ended or a differential clock mode. The mode selection can be controlled either by the CMODE pin, if the device is in pin mode; or through Register 0x02, Bit 2 (CLKDIFF) of the SPI registers, if the SPI is enabled. Connecting CMODE to ACOM selects the single-ended clock input. In this mode, the CLK+ input is driven with rail-to-rail swings, and the CLK− input is left floating. If CMODE is connected to AVDD, the differential receiver mode is selected. In this mode, both inputs are high impedance. Table 25 gives a summary of clock mode control. There is no significant performance difference between the clock input modes.

Table 25. Clock Mode Selection

In differential input mode, the clock input functions as a high impedance differential pair. The common-mode level of the CLK+ and CLK− inputs can vary from 0.75 V to 2.25 V, and the differential voltage can be as low as 0.5 V p-p. This mode can be used to drive the clock with a differential sine wave because the high gain bandwidth of the differential inputs converts the sine wave into a single-ended square wave internally.

DAC TIMING

Input Clock and Data Timing Relationship

Dynamic performance in a DAC is dependent on the relationship between the position of the clock edges and the time at which the input data changes. To achieve the DAC performance specified in this data sheet, data input (DB) and clock (CLK+/CLK−) must meet the setup and hold time requirements specified in the relevant digital specifications.

POWER DISSIPATION

The power dissipation, P_D , of the AD9704/AD9705/AD9706/ AD9707 is dependent on several factors that include

- ► The power supply voltages (AVDD, CLKVDD, and DVDD)
- \triangleright The full-scale current output, I_{OUTFS}
- \blacktriangleright The update rate, f_{CLOCK}
- \blacktriangleright The reconstructed digital input waveform

Power dissipation is directly proportional to the analog supply current, I_{AVDD} , and the digital supply current, I_{DVDD} . I_{AVDD} is equal to a fixed current plus I_{OUTFS} , as shown in Figure 80. I_{DVDD} is proportional to $f_{\text{Cl OCK}}$ and increases with increasing analog output frequencies. [Figure 82](#page-38-0) shows I_{DVDD} as a function of full-scale sine wave output ratios ($f_{\text{OUT}}/f_{\text{CLOCK}}$) for various update rates with DVDD = 3.3 V. I_{CLKVDD} is directly proportional to $f_{\text{Cl OCK}}$ and is higher for differential clock operation than for single-ended operation, as shown in [Figure 84.](#page-38-0) This difference in clock current is due primarily to the differential clock receiver, which is disabled in single-ended clock mode.

Figure 81. IAVDD vs. IOUTFS at AVDD = 1.8 V

Figure 82. IDVDD vs. fOUT/fCLOCK Ratio at DVDD = 3.3 V

Figure 84. ICLKVDD vs. fCLOCK at CLKVDD = 3.3 V

Figure 85. ICLKVDD vs. fCLOCK (Differential Clock Mode) at CLKVDD = 1.8 V

Sleep Operation (Pin Mode)

The AD9704/AD9705/AD9706/AD9707 have a sleep mode that turns off the output current and reduces the total power consumed by the device. This mode is activated by applying a Logic 1 to the SLEEP/CSB pin.

The AD9704/AD9705/AD9706/AD9707 take less than 50 ns to power down and approximately 5 µs to power back up, when 3.3 V AVDD is used.

Sleep and Power-Down Operation (SPI Mode)

The AD9704/AD9705/AD9706/AD9707 offer three power-down functions that can be controlled through the SPI. These powerdown modes can be used to minimize the power dissipation of the device. The power-down functions are controlled through Register 0x00, Bit 1 to Bit 3, of the SPI registers. Table 26 summarizes the power-down functions that can be controlled through the SPI. The power-down mode can be enabled by writing a Logic 1 to the corresponding bit in Register 0x00.

Table 26. Power-Down Mode Selection

SELF-CALIBRATION

The AD9704/AD9705/AD9706/AD9707 have a self-calibration feature that improves the DNL of the device. Performing a self-calibration on the device improves device performance in low frequency applications. The device performance in applications where the analog output frequencies are above 1 MHz are generally influenced more by dynamic device behavior than by DNL, and in these cases, self-calibration is unlikely to provide any benefits for single-tones,

as shown in Figure 86. Figure 87 shows that self-calibration is helpful up to 20 MHz for two-tone IMD spaced 10 kHz apart.

*Figure 86. AD9707 SFDR vs. f*_{OUT} at 175 MSPS and I_{OUTFS} = 2 mA

Figure 87. IMD vs. Lower fOUT at 175 MSPS and IOUTFS = 2 mA

The calibration clock frequency is equal to the DAC clock divided by the division factor chosen by the DIVSEL value. The frequency of the calibration clock must be set to under 10 MHz for reliable calibrations. Best results are obtained by setting DIVSEL[2:0] (Register 0x0E, Bit 2 to Bit 0) to produce the lowest frequency calibration clock frequency that the system requirements of the user allows.

To perform a device self-calibration, use the following procedure:

- **1.** Enable the calibration clock by setting the CALCLK bit (Register 0x02, Bit 0).
- **2.** Enable self-calibration by writing 0x40 to Register 0x0F.
- **3.** Wait approximately 4500 calibration clock cycles. Each calibration clock cycle is between 2 DAC clock cycles and 256 DAC clock cycles, depending on the value of DIVSEL[2:0].
- **4.** Check if the self-calibration has completed by reading the CALSTAT bit (Register 0x0F, Bit 7). A Logic 1 indicates the calibration has completed.
- **5.** When the self-calibration has completed, write 0x00 to Register 0x0F.
- **6.** Disable the calibration clock by clearing the CALCLK bit (Register 0x02, Bit 0).

The AD9704/AD9705/AD9706/AD9707 devices allow reading and writing of the calibration coefficients. There are 33 coefficients in total. The read/write feature of the coefficients can be useful for improving the results of the self-calibration routine by averaging the results of several calibration results and loading the averaged results back into the device. The reading and writing routines follow.

To read the calibration coefficients to the device:

- **1.** Enable the calibration clock by setting the CALCLK bit (Register 0x02, Bit 0).
- **2.** Write the address of the first coefficient (0x00) to Register 0x10.
- **3.** Set the SMEMRD bit (Register 0x0F, Bit 2) by writing 0x04 to Register 0x0F.
- **4.** Wait at least 160 CLK+/CLK− clock cycles.
- **5.** Read the value of the first coefficient by reading the contents of Register 0x11.
- **6.** Clear the SMEMRD bit by writing 0x00 to Register 0x0F.
- **7.** Repeat Step 2 through Step 6 for each of the remaining 32 coefficients by incrementing the address by one for each read.
- **8.** Disable the calibration clock by clearing the CALCLK Bit (Register 0x02, Bit 0).

To write the calibration coefficients to the device:

- **1.** Enable the calibration clock by setting the CALCLK bit (Register 0x02, Bit 0).
- **2.** Set the SMEMWR bit (Register 0x0F, Bit 3) by writing 0x08 to Register 0x0F.
- **3.** Write the address of the first coefficient (0x00) to Register 0x10.
- **4.** Write the value of the first coefficient to Register 0x11.
- **5.** Wait at least 160 CLK+/CLK− clock cycles
- **6.** Repeat Step 3 through Step 5 for each of the remaining 32 coefficients by incrementing the address by one for each write.
- **7.** Clear the SMEMWR bit by writing 0x00 to Register 0x0F.
- **8.** Disable the calibration clock by clearing the CALCLK bit (Register 0x02, Bit 0).

APPLICATIONS INFORMATION

OUTPUT CONFIGURATIONS

The following sections illustrate some typical output configurations for the AD9704/AD9705/AD9706/AD9707. Unless otherwise noted, it is assumed that I_{OUTFS} is set to a nominal 2 mA. For applications requiring the optimum dynamic performance, a differential output configuration is suggested. A differential output configuration can consist of either an RF transformer or a differential op amp configuration. The transformer configuration provides the optimum high frequency performance and is recommended for any application that allows ac coupling. The differential op amp configuration is suitable for applications requiring dc coupling, signal gain, and/or a low output impedance. A single-ended output is suitable for applications where low cost and low power consumption are primary concerns.

DIFFERENTIAL COUPLING USING A TRANSFORMER

An RF transformer can be used to perform a differential-to-singleended signal conversion, as shown in Figure 88. The distortion performance of a transformer typically exceeds that available from standard op amps, particularly at higher frequencies. Transformer coupling provides excellent rejection of common-mode distortion (that is, even-order harmonics) over a wide frequency range. It also provides electrical isolation and can deliver voltage gain without adding noise. Transformers with different impedance ratios can also be used for impedance matching purposes. The main disadvantages of transformer coupling are the low frequency roll-off, lack of power gain, and the higher output impedance.

Figure 88. Differential Output Using a Transformer

The center tap on the primary side of the transformer must be connected to a voltage that keeps the voltages on IOUTA and IOUTB within the output common voltage range of the device. Note that the dc component of the DAC output current is equal to I_{FS}/2 and flows out of both IOUTA and IOUTB. The center tap of the transformer should provide a path for this dc current. In many applications, AGND provides the most convenient voltage for the transformer center tap. The complementary voltages appearing at IOUTA and IOUTB (that is, V_{IOUTA} and V_{IOUTB}) swing symmetrically around AGND and should be maintained with the specified output compliance range of the AD9704/AD9705/AD9706/AD9707.

A differential resistor, R_{DIFF} , can be inserted in applications where the output of the transformer is connected to the load, R_{LOAD} , via a passive reconstruction filter or cable. R_{DIFF} , as reflected by the transformer, is chosen to provide a source termination that results in a low VSWR. Note that approximately half the signal power is dissipated across R_{DIFF} .

SINGLE-ENDED BUFFERED OUTPUT USING AN OP AMP

Figure 89 shows a buffered single-ended output configuration in which the [ADA4899-1](http://www.analog.com/ADA4899-1?doc=AD9704_9705_9706_9707.pdf) op amp performs a single-ended current-tovoltage conversion on the AD9704/AD9705/AD9706/AD9707 output current. The [ADA4899-1](http://www.analog.com/ADA4899-1?doc=AD9704_9705_9706_9707.pdf) maintains IOUTA (or IOUTB) at a virtual ground, minimizing the nonlinear output impedance effect on the INL performance of the DAC as described in the [Analog Outputs](#page-35-0) section. Although this single-ended configuration typically provides optimal dc linearity performance, its ac distortion performance at higher DAC update rates may be limited by the slew rate capabilities of the op amp. The ADA4899-1 provides a negative unipolar output voltage, and its full-scale output voltage is simply the product of the feedback resistor, R_{FB} (200 Ω), and I_{OUTFS} . The full-scale output must be set within the voltage output swing capabilities of the ADA4899-1 by scaling I_{OUTFS} and/or R_{FB} . An improvement in ac distortion performance may result in a reduced I_{OUTFS} because the signal current at the op amp is required to sink less signal current.

Figure 89. Unipolar Buffered Voltage

DIFFERENTIAL BUFFERED OUTPUT USING AN OP AMP

An op amp can also be used to perform a differential-to-singleended conversion, as shown in [Figure 90.](#page-41-0) The AD9704/AD9705/ AD9706/AD9707 is configured with two equal load resistors, R_{LOAD} , of 100 Ω. The differential voltage developed across I_{OUTA} and I_{OUTB} is converted to a single-ended signal via the differential op amp configuration. An optional capacitor can be installed across I_{OUTA} and I_{OUTB} , forming a real pole in a low-pass filter. The addition of this capacitor also enhances the distortion performance of the op amp by preventing the high slewing output of the DAC from overloading the input of the op amp.

The common-mode rejection of this configuration is typically determined by the resistor matching. In this circuit, the differential op amp circuit using the [ADA4899-1](http://www.analog.com/ADA4899-1?doc=AD9704_9705_9706_9707.pdf) is configured to provide some additional signal gain. The op amp must operate from a dual supply because its output is approximately ±1 V. Select a high speed

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amplifier capable of preserving the differential performance of the AD9704/AD9705/AD9706/AD9707 while meeting other system level objectives (such as cost or power). The differential gain, gain setting resistor values, and full-scale output swing capabilities of the op amp must all be considered when optimizing this circuit.

Figure 90. Differential Buffered Voltage Output

POWER SUPPLY

Requirements

The analog and digital sections of the AD9704/AD9705/AD9706/ AD9707 have separate power supply inputs (AVDD, DVDD, and CLKVDD) that can operate over the 1.7 V to 3.6 V range but must have the same voltage levels, that is, all 1.8 V or all 3.3 V. On power-up, ramp all supply rails at the same time.

In SPI mode, an active high pulse with a minimum pulse width of 50 ns must be applied once to the PIN/SPI/RESET pin after applying power to all three supplies. As a result, all the control register bits are set to default. Refer to the [SPI Register Map](#page-33-0) section for the default register values.

To operate in pin mode, Pin 17 must be held high. Alternatively, the pin can be pulled up to AVDD.

Recommendations

The user can employ several different decoupling capacitors to cover both high and low frequencies. These capacitors must be located close to the point of entry at the printed circuit board (PCB) level and close to the devices, with minimal trace lengths. Recommended decoupling capacitor values for each supply pin are one of each of the following: 10 nF, 0.1 μF, and 10 μF. The smallest value capacitor must be placed nearest to the supply pin.