AEAT-601B
Incremental Magnetic Encoder

Avago
TECHNOLOGIES

Data Sheet

Description

Avago Technologies' Incremental Magnetic Encoder provides an integrated solution for angular detection within a complete 360° rotation. The use of magnetic technology for motion control and sensing activities eliminates mechancial contact and enables this device to be free from mechanical wear and tear. Three-channel output provides an additional index channel for every full rotation or revolution of 360°. An additional advantage is that the encoders upper rotational speed limit is typically only limited by the application's bearing speed.

Exploded View

Features

- Resolution of 256 counts per revolution (CPR)
- Contactless sensing technology
- Wide temperature range from -40° to 125°C
- 3-channel output
- Single 5V supply
- Easy assembly and no signal adjustment required
- Direct connectivity through cable output
- RoHS compliant
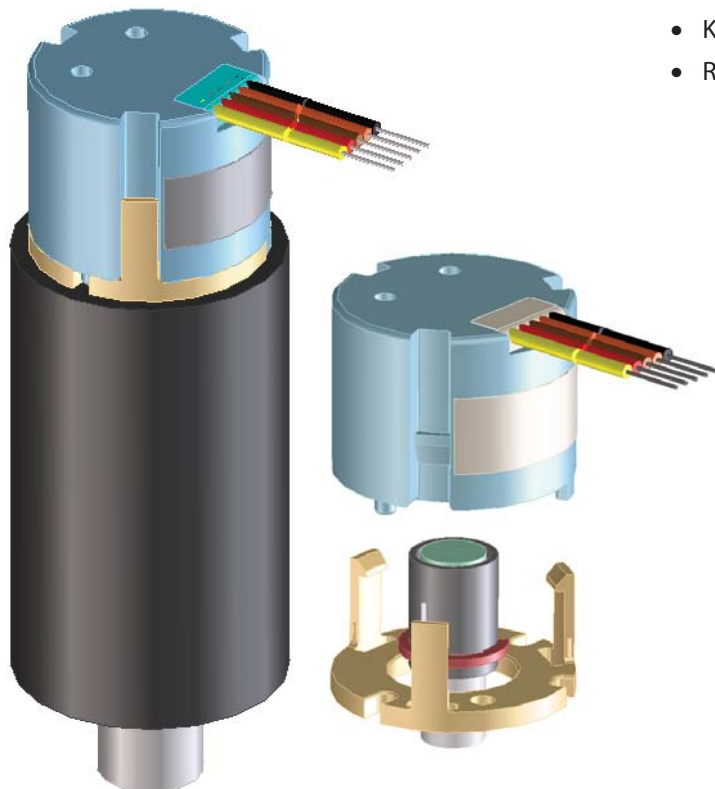
Applications

- Speed detection
- Knob control
- Rotary encoders

Table 1. Absolute Maximum Ratings [1, 2]

Parameter	Symbol	Limits	Units
DC Supply Voltage at pin V_{DD} = 5V	V_{DD}	-0.3 to + 7	V
Input Voltage	V_i	-0.3 to V_{DD}+0.3	V
Storage Temperature	T_{stg}	-40 to 125	°C

Notes:
1. Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.
2. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Table 2. Recommended Operating Condition

Parameters	Symbols	Values	Units	Notes
DC Supply Voltage at pin V_{DD} = 5V	V_{DD}	+4.5 / +5.5	V	
Operating Temperature	T_{amb}	40/125	°C	
Rotational Speed :	Mechanical (max)	12000	RPM	
	Electrical (max)	7000	RPM	

Notes:
1. Under recommended mounting and tolerance, and mechanical shaft play, the incremental encoder's quadrature output (quater cycle phase shift between Channel-A and Channel-B) is always maintained. The dynamic performance of the encoder output are depicted in the figures under Encoding Characteristic.
2. The magnetic incremental output has a fixed hysteresis of 0.7 degrees for all different CPR options (equivalent to 2 quadrature counts at 256 CPR or 0.5 quadrature count at 64 CPR).
3. The quadrature decoding of both the Channel-A and Channel-B would ensure that the incremental counts are maintained even when there is transition noise due to fluctuation of the magnetic field strength.

Table 3. DC Characteristics

DC Characteristics over Recommended Operating Range, typical at 25 °C

Parameter	Symbol	Condition	Values Min	Typ.	Max	Units	Notes
V_{DD} Supply Current	I_{DD}			16	20	mA	
Output High Voltage	V_{OH}		V_{DD}-0.5			V	
Output Low Voltage	V_{OL}				VSS+0.4	V	
Output Current	I_O				4	mA	V_{DD} pin = 4.5V

AEAT-601B Performance Characteristics

State Error
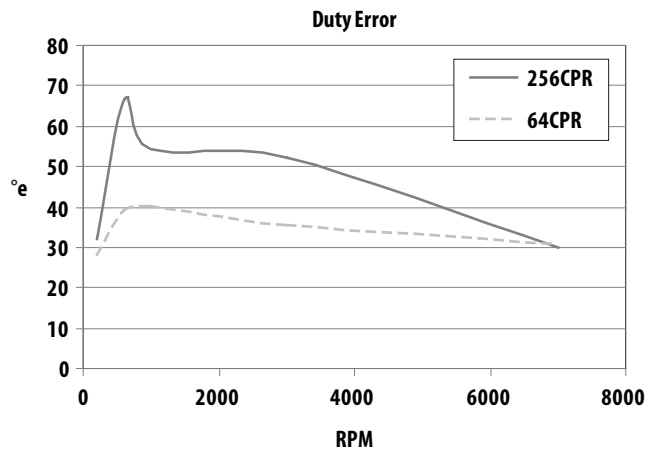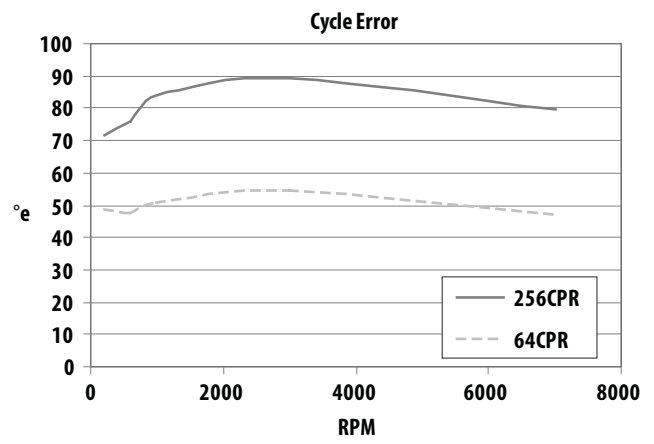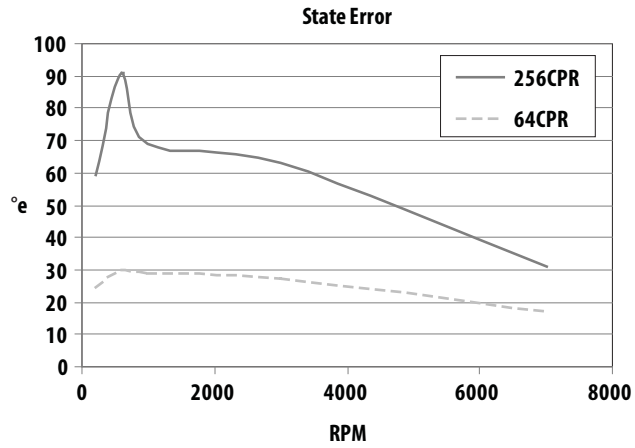

Cycle Error

Duty Error

Table 4. Encoding Characteristics

Encoding Characteristics over Recommended Operating Range, typical at 25 °C over speed range.

Parameter	Symbol	Typ.	Units
Index Pulse Width	Po	150	°e

Package Dimensions
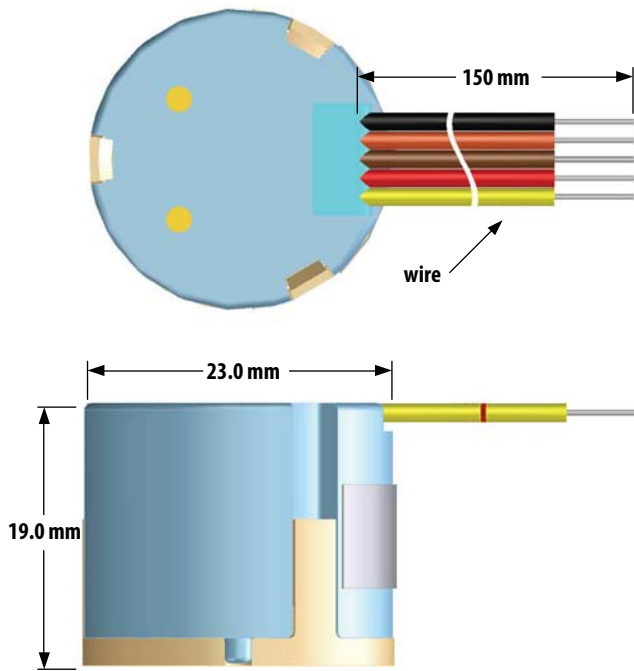
Figure 1. Package and recommended mounting dimension

Mounting Consideration

#	Parameter	Unit	Values
1	Maximum Shaft Axial Play	mm *	± 0.08
2	Maximum Shaft TIR	mm *	0.05
3	Maximum Mechanical Speed	RPM	12,000
4	Shaft Diameter	mm	6 +0 / -0.01
5	Moment Inertia	g-cm2	0.104
6	Shaft Length	mm	8.5 ± 1.0
7	Mounting Screw Size	mm	M2 x 0.4 x 8 (socket head cap screw, head Ø3.8 ± 0.18mm)
8	Recommended screw torque	lb.inch	0.6
9	Encoder base plate thickness	mm	2
10	Bolt Circle	mm *	± 0.13

* Recommended to follow these limits for optimum performance
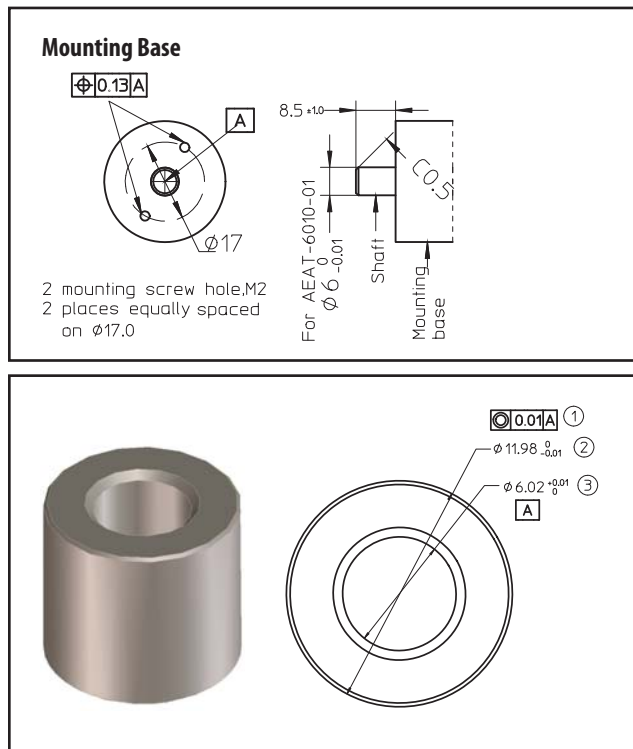
Optional - Centering Jig
(Refer to Application Note for details)
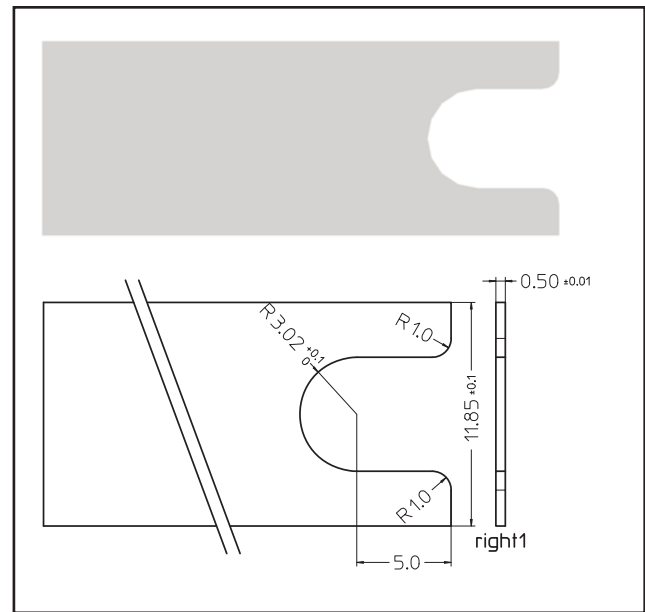
Optional - Base Gap Setting Plate
(Refer to Application Note for details)

Figure 2. Accessories - HEDS-8934, A set of optional centering and gap setting jigs (available for purchase separately)