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The technical content of this austriamicrosystems datasheet is still valid.

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Datasheet

AS1130 132-LED Cross-Plexing Driver with scrolling Function

1 General Description

The AS1130 is a compact LED driver for 132 single LEDs. The devices can be programmed via an I²C compatible interface.

The AS1130 offers a 12x11 LED-Matrix with 1/12 cycle rate. The required lines to drive all 132 LEDs are reduced to 12 by using the cross-plexing feature optimizing space on the PCB. The whole LED-Matrix driving 132 LEDs can be analog dimmed from 0 to 30mA in 256 steps (8 bit).

Additionally each of the 132 LEDs can be dimmed individually with 8bit allowing 256 steps of linear dimming. To reduce CPU usage up to 6 frames can be stored with individual time delays between frames to play small animations automatically.

The AS1130 operates from 2.7V to 5.5V and features a very low shutdown and operational current.

The device offers a programmable IRQ pin. Via a register it can be set on what event (CP request, Interface time out, Error-detection, POR, End of Frame or End of Movie) the IRO is triggered.

Also hardware scroll Function is implemented in the AS1130.

The device is available in a ultrasmall 20-pin WL-CSP and an easy to solder 28-pin SSOP package.

2 Key Features

- 1MHz I²C-Compatible Interface
- Open and Shorted LED Error Detection
- 132 LEDs in Dot Matrix
- Low-Power Shutdown Current
- Individual 8-bit LED PWM Control
- 8-bit Analog Brightness Control
- 8-bit Dot Correction for optimize RGB LED Operation
- Programmable IRQ pin
- Scroll Function
- up to 36 Frames Memory for Animations
- up to 6 Frames Memory for PWM sets
- Supply Voltage Range: 2.7V to 5.5V
- Minimum PCB space required
- Available packages:
- 20-pin WL-CSP
- 28-pin SSOP (planned)

3 Applications

The AS1130 is ideal for dot matrix displays in mobile phones, personal electronic and toys.

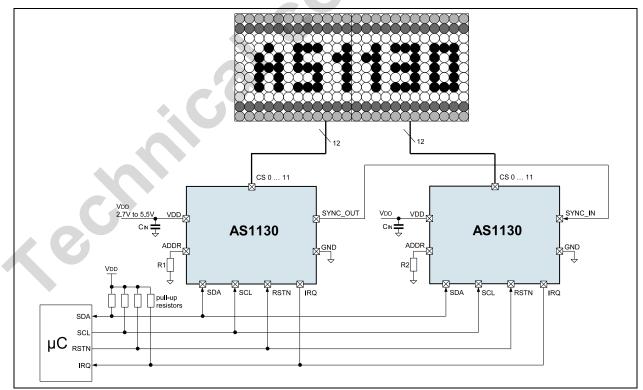
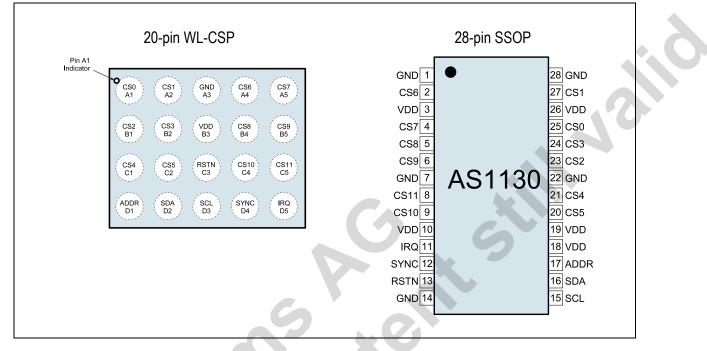


Figure 1. AS1130 - Typical Application

4 Pinout

Pin Assignments

Figure 2. Pin Assignments (Top View)



Pin Descriptions

Table 1. Pin Descriptions

Pin N	umber	Pin Name	Description
20-pin WL-CSP	28-pin SSOP	Fin Name	Description
A3	1, 7, 14, 22, 28	GND	Ground
C3	13	RSTN	Reset Input . Pull this pin to logic low to reset all control registers (set to default values). For normal operation pull this pin to VDD.
D1 17		ADDR	I ² C Address. Connect to external resistor for I ² C address selection. Up to 8 devices can be connected on one bus. (see Table 6 on page 12)
D2 16		SDA	Serial-Data I/O. Open drain digital I/O I ² C data pin.
D3 15		SCL	Serial-Clock Input
В3	3, 10, 18, 19, 26	VDD	Positive Supply Voltage . Connect to a +2.7V to +5.5V supply. Bypass this pin with 10μ F capacitance to GND.
D4	12	SYNC	Synchronization Clock Input or Output. The SYNC frequency for Input and Output is 1MHz. For SYNC_OUT the frequency can be reduced to 32kHz.
D5	11	IRQ	Interrupt Request. Programmable Open drain digital Output. It can be set via an register after which event (Interface Timeout, POK, CP_Request, Error Detection, End of Frame or End of Movie) the pin triggers an Interrupt Request.
A1, A2, A4, A5, B1, B2, B4, B5, C1, C2, C4, C5	25, 27, 2, 4, 23, 24, 5, 6, 21, 20, 9, 8	CS0, CS1, CS6, CS7, CS2, CS3, CS8, CS9, CS4, CS5, CS10, CS11	Sinks and Sources for 132 LEDs.

5 Absolute Maximum Ratings

Stresses beyond those listed in Table 2 may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in Section 6 Electrical Characteristics on page 4 is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Table O	Abaaluta	Mandinaria	Dethere
IADIA Z	ANSOUNA	Maximum	Rannos

Parameter	Min	Max	Units		Comments					
Electrical Parameters										
VDD to GND	-0.3	7	V							
All other pins to GND	-0.3	7 or VDD + 0.3	V		.9					
Sink Current		500	mA							
Segment Current		100	mA							
Input Current (latch-up immunity)	-100	100	mA		Norm: JEDEC 78					
Electrostatic Discharge	- I	ļ	J							
Electrostatic Discharge HBM		2	kV		Norm: MIL 883 E method 3015					
Temperature Ranges and Storage Conditions										
Junction Temperature		+150	°C		6					
Otaria Tanana kun Danan	-55	+125	°C	for 20-pin WL-CSP						
Storage Temperature Range	-55	+150	°C		for 28-pin SSOP					
Package Body Temperature		+260	°C	temperatu J-STD-02 Non-He	reflow peak soldering temperature (body ire) specified is in accordance with <i>IPC/JEDEC</i> 0"Moisture/Reflow Sensitivity Classification for ermetic Solid State Surface Mount Devices". finish for Pb-free leaded packages is matte tin (100% Sn).					
Humidity non-condensing	5	85	85 %							
Moisture Sensitive Level		1		20-pin WL-CSP	Represents a max. floor life time of unlimited					
woisture Sensitive Level		3		28-pin SSOP	Represents a max. floor life time of 168h					

6 Electrical Characteristics

VDD = 2.7V to 5.5V, typ. values are at TAMB = +25°C (unless otherwise specified). All limits are guaranteed. The parameters with min and max values are guaranteed with production tests or SQC (Statistical Quality Control) methods.

Table 3. Electrical Characteristics

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Тамв	Operating Temperature Range	· · ·	-40		85	°C
TJ	Operating Junction Temperature Range		-40		125	°C
Vdd	Operating Supply Voltage		2.7		5.5	V
ldd	Operating Supply Current	All current sources turned ON @ VDD = 5.5V		340		mA
שטו	Operating Supply Current	All current sources turned OFF @ VDD = 5.5V		0.5		S
IDDSSD	Software Shutdown Supply Current	All digital inputs at VDD or GND @ VDD = 5.5V		7	15	μA
IDDFSD	Full Shutdown Supply Current	Pin RSTN = 0V, Тамв = +25℃		0.1	1	μΑ
Idigit	Digit Drive Sink Current (Drive capability of all sources of one digit ¹)	0	0		360	mA
ISEG	Segment Drive Source Current LED ²	VOUT = 1.8V to VDD-400mV	28	30	32	mA
∆lseg	Segment Drive Current Matching LED			1		%
ΔISEG	Device to Device Current Matching LED	Vout = 1.8V, Vdd = 3.3V		1		%
ILEAK	Leakage Output Current	All current sources OFF, VOUT = 0V, VDD = 5.5V, TAMB = +25°C		0.005	0.5	μA
Δ Ilnr	Line Regulation	Vout = 1.8V		0.25		%/V
Δ ILDR	Load Regulation	VOUT = 1.8V to VDD-400mV		0.25		%/V
Vdssat	Saturation Voltage	Current = 30mA, VDD = 3.3V		200		mV
R _{DSON(N)}	Resistance for NMOS			0.3	1	Ω
	Open Detection Level Threshold	5	Vdd- 0.4	Vdd- 0.1		V
	Short Detection Level Threshold			770	900	mV
fosc	Oscillator Frequency		0.9	1	1.1	MHz
frefresh	Display Scan Rate	12x11 matrix	0.29	0.33	0.36	kHz
t RSTN	Reset Pulse Width Low		500			ns

1. guaranteed by design

2.
$$I_{SEG} = \frac{I_{max} - I_{min}}{I_{max} + I_{min}} \times 100$$

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
lih, li∟	Logic Input Current	VIN = 0V or VDD	-1		1	μA
Viн	CMOS Logic High Input Voltage		0.7 x Vdd			V
VIL	CMOS Logic Low Input Voltage				0.3 x Vdd	V
ΔVI	CMOS Hysteresis Voltage			0.3		V
Viн	Mobile Logic High Input Voltage ¹		1.6			V
VIL	Mobile Logic Low Input Voltage ¹				0.6	V
ΔVI	Hysteresis Voltage ¹			0.1		V
VOL(SDA)	SDA Output Low Voltage	ISINK = 3mA			0.4	V
Vol(IRQ)	IRQ Output Low Voltage	ISINK = 3mA			0.4	V
VOL(SYNC_ OUT)	Sync Clock Output Low Voltage	ISINK = 1mA			0.4	V
VOH(SYNC _OUT)	Sync Clock Output High Voltage	ISOURCE = 1mA			Vdd-0.4	V
	Capacitive Load for Each Bus Line				400	pF

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Table 4. Logic Inputs/Outputs Characteristics

1. available on request, See Ordering Information on page 37

Table 5. I²C Timing Characteristics

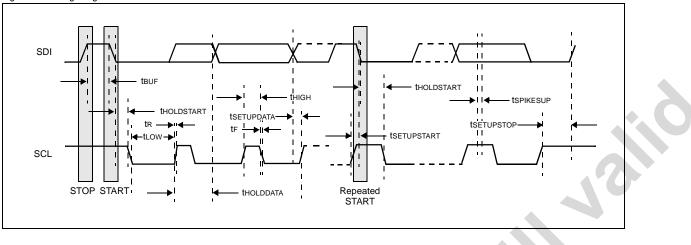
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
fscl	SCL Frequency		100		1000	kHz
tBUF	Bus Free Time Between STOP and START Conditions	XU	1.3			μs
tholdstart	Hold Time for Repeated START Condition		260			ns
tLOW	SCL Low Period		500			ns
thigh	SCL High Period		260			ns
tSETUPSTART	Setup Time for Repeated START Condition		260			ns
t SETUPDATA	Data Setup Time		100			ns
tholddata	Data Hold Time				70	ns
tRISE(SCL)	SCL Rise Time				120	ns
tRISE(SCL1)	SCL Rise Time after Repeated START Condition and After an ACK Bit				120	ns
tFALL(SCL)	SCL Fall Time				120	ns
tRISE(SDA)	SDA Rise Time				120	ns
tFALL(SDA)	SDA Fall Time				120	ns
tSETUPSTOP	STOP Condition Setup Time		260			ns
tSPIKESUP	Pulse Width of Spike Suppressed				6	ns

Note: The Min / Max values of the Timing Characteristics are guaranteed by design.

Datasheet - Electrical Characteristics



Figure 3. Timing Diagram

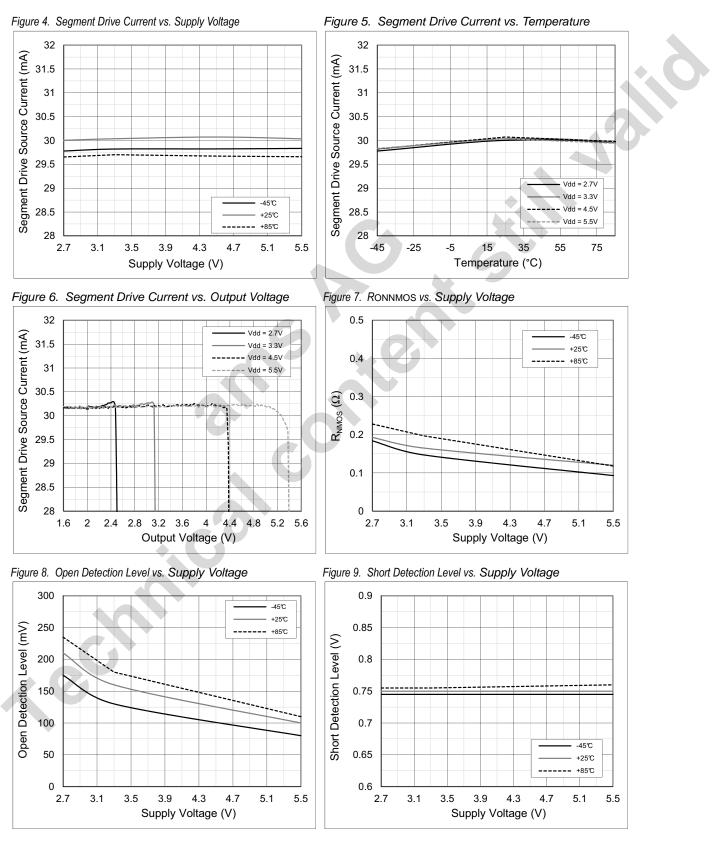


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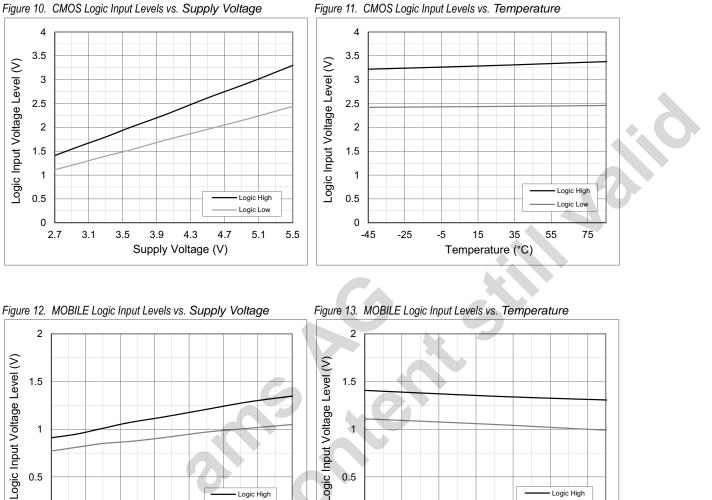
7 Typical Operating Characteristics



Logic Low

75

55



0

-45

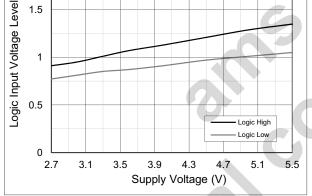
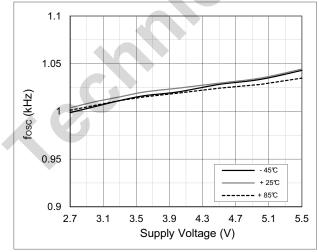
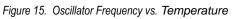


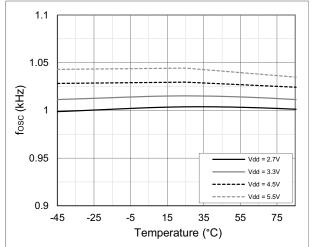
Figure 14. Oscillator Frequency vs. Supply Voltage





-5

-25

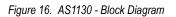


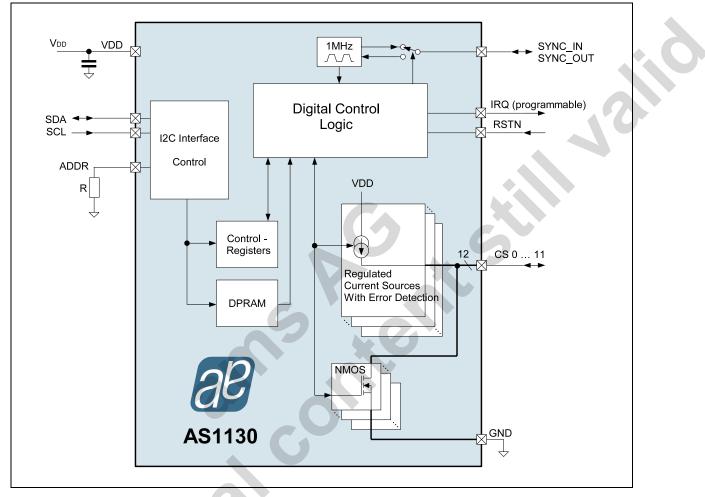
15

Temperature (°C)

35

8 Detailed Description





Cross-Plexing Theorem

The cross-plexing theorem is using the fact that a LED has a forward and backward direction. A LED will only glow if there is a current flowing in forward direction. A parallel LED in backward direction will block the current flow. This effect is used in a cross-plexed matrix of LED's.

Each CSx pin (CS0 to CS11) can be switched to VDD via the internal current source ("high"), to GND ("low") or not connected ("highZ").

The mode of operation which is controlled by an internal state machine looks like following. CS0 is switched to GND and all other CSx pins (CS1 to CS11) are controlled according to the settings in the On/Off Frame and Blink & PWM registers (see Table 7 on page 14).

Than CS1 is switched to GND and all other CSx pins (CS0 and CS2 to CS11) are controlled according to the settings in the On/Off Frame and Blink & PWM registers.

In this manner all LEDs in the matrix are scanned and turned on/off depending on the register settings.

I²C Interface

The AS1130 supports the I²C serial bus and data transmission protocol in fast mode at 1MHz. The AS1130 operates as a slave on the I²C bus. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates the START and STOP conditions. Connections to the bus are made via the open-drain I/O pins SCL and SDA.

Figure 17. I²C Interface Initialization

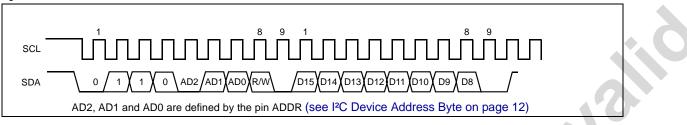
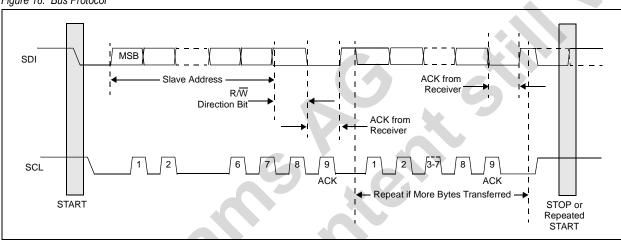


Figure 18. Bus Protocol



The bus protocol (as shown in Figure 18) is defined as:

- Data transfer may be initiated only when the bus is not busy.
- During data transfer, the data line must remain stable whenever the clock line is HIGH. Changes in the data line while the clock line is HIGH will be interpreted as control signals.

The bus conditions are defined as:

- Bus Not Busy. Data and clock lines remain HIGH.
- Start Data Transfer. A change in the state of the data line, from HIGH to LOW, while the clock is HIGH, defines a START condition.
- Stop Data Transfer. A change in the state of the data line, from LOW to HIGH, while the clock line is HIGH, defines the STOP condition.
- Data Valid. The state of the data line represents valid data, when, after a START condition, the data line is stable for the duration of the HIGH period of the clock signal. There is one clock pulse per bit of data. Each data transfer is initiated with a START condition and terminated with a STOP condition. The number of data bytes transferred between START and STOP conditions is not limited and is determined by the master device. The information is transferred byte-wise and each receiver acknowledges with a ninth-bit. Within the I²C bus specifications a high-speed mode (3.4MHz clock rate) is defined.
- Acknowledge: Each receiving device, when addressed, is obliged to generate an acknowledge after the reception of each byte. The master device must generate an extra clock pulse that is associated with this acknowledge bit. A device that acknowledges must pull down the SDA line during the acknowledge clock pulse in such a way that the SDA line is stable LOW during the HIGH period of the acknowledge clock pulse. Of course, setup and hold times must be taken into account. A master must signal an end of data to the slave by not generating an acknowledge bit on the last byte that has been clocked out of the slave. In this case, the slave must leave the data line HIGH to enable the master to generate the STOP condition.
- Figure 18 on page 10 details how data transfer is accomplished on the I²C bus. Depending upon the state of the R/W bit, two types of data transfer are possible:

- Master Transmitter to Slave Receiver. The first byte transmitted by the master is the slave address, followed by a number of data bytes. The slave returns an acknowledge bit after the slave address and each received byte.
- Slave Transmitter to Master Receiver. The first byte, the slave address, is transmitted by the master. The slave then returns an acknowledge bit. Next, a number of data bytes are transmitted by the slave to the master. The master returns an acknowledge bit after all received bytes other than the last byte. At the end of the last received byte, a not-acknowledge is returned. The master device generates all of the serial clock pulses and the START and STOP conditions. A transfer is ended with a STOP condition or a repeated START condition. Since a repeated START condition is also the beginning of the next serial transfer, the bus will not be released.

The AS1130 can operate in the following slave modes:

- Slave Receiver Mode. Serial data and clock are received through SDA and SCL. After each byte is received, an acknowledge bit is transmitted. START and STOP conditions are recognized as the beginning and end of a serial transfer. Address recognition is performed by hardware after reception of the slave address and direction bit.
- Slave Transmitter Mode. The first byte (the slave address) is received and handled as in the slave receiver mode. However, in this mode the direction bit will indicate that the transfer direction is reversed. Serial data is transmitted on SDA by the AS1130 while the serial clock is input on SCL. START and STOP conditions are recognized as the beginning and end of a serial transfer.

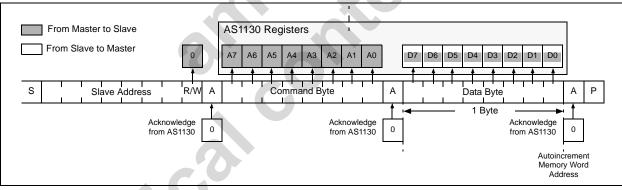
Command Byte

The AS1130 operation, (see Table 13 on page 20) is determined by a command byte (see Table 19).

Figure 19. Command Byte

A7 A6 A5 A4 A3 A2 A1 A0	MSB	6	5	4	3	2	1	LSB
	A7	A6	A5	A4	A3	A2	A1	A0

Figure 20. Command and Single Data Byte received by AS1130





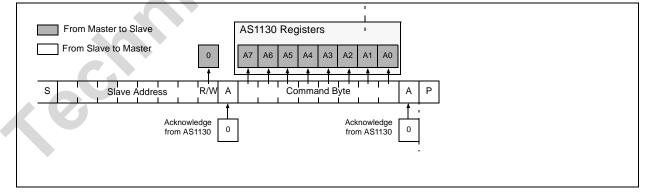
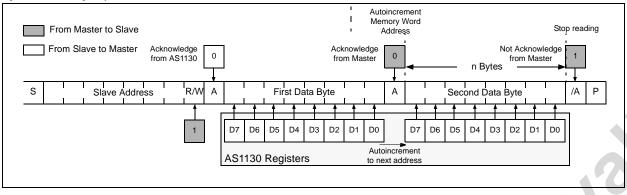




Figure 22. Reading n Bytes from AS1130



I²C Device Address Byte

The address byte (see Figure 23) is the first byte received following the START condition from the master device.

Figure 23. I²C Device Address Byte MSB 4 3 LSB 6 5 2 1 AD2 AD1 AD0 R/W 0 0* address: 1 1 *) can be factory set to 1

- The bit 1, 2 and 3 of the address byte are defined through the resistor @ the device select pin ADDR (see Table 6 on page 12). A maximum of 8 devices with the same pre-set code can be connected on the same bus at one time.
- The last bit of the address byte (R/W) define the operation to be performed. When set to a 1 a read operation is selected; when set to a 0 a write operation is selected.
- I²C Common address. All devices are responding on the address "0111111" if the function is enabled in the register AS1130 Config Register (0x06) on page 25.

Following the START condition, the AS1130 monitors the I²C bus, checking the device type identifier being transmitted. Upon receiving the address code, and the R/W bit, the slave device outputs an acknowledge signal on the SDA line.

Table 6. Device Address

				I2C Address
Bit	Bit Name	Default	Access	Description
3:1	i2c_addr	000	R	Defines the I ² C address of one device via an external resistor on pin ADDR 000: $1M\Omega$ or floating 001: $470k\Omega$ 010: $220k\Omega$ 011: $100k\Omega$ 100: $47k\Omega$ 101: $22k\Omega$ 110: $10k\Omega$ 111: $10k\Omega$ 111: $4.7k\Omega$ or GND

The pin ADDR is scanned after start up (POR) and defines the address for the device. The device reacts to this address until a hardware reset (low on pin RSTN) is performed or the power-on-reset (POR) triggers again.

Note: The internal address decoder needs 5ms to identify the address and to set up the device for this address.

Initial Power-Up

On initial power-up, the AS1130 registers are reset to their default values, the display is blanked, and the device goes into shutdown mode. At this time, all registers should be programmed for normal operation. To bring the device into normal operation the following sequence needs to be performed.

Start-up sequence:

- Power-up the AS1130 (connect VDD to a source), the devices is in shutdown;
- After 5ms the address of the AS1130 is valid and the first I²C command can be send.
- Define RAM Configuration; bit mem_conf in the AS1130 Config Register (see Table 20 on page 25)
 - On/Off Frames
 - Blink & PWM Sets
 - Dot Correction, if specified
- Define Control Register (see Table 13 on page 20)
 - Current Source
 - Display options
 - Display picture / play movie
- To light up the LEDs set the shdn bit to '1' for normal operation mode (see Table 23 on page 26).

Shutdown Mode

The AS1130 device features two different shutdown modes. A software shutdown via shutdown register (see Shutdown & Open/Short Register Format on page 26) and a hardware shutdown via the RSTN pin.

The software shutdown disables all LED's and stops the internal operation of the logic. A shutdown mode via the RSTN pin additionally powers down the power-on-reset (POR) of the device. In this shutdown mode the AS1130 consumes only 100nA (typ.).

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9 Register Description

Register Selection

Within this register the access to one of the RAM sections, the Dot Correction or to the Control register is selected. After one section is selected this section is valid as long as an other section is selected.

Register Section				Ad	dres	s				Data							Description			
Register Section	HEX	A7	A6	A5	A4	A3	A2	A1	A0	HEX	D7	D6	D5	D4	D3	D2	D1	D0	Description	
NOP										0x00	0	0	0	0	0	0	0	0	No operation	
On/Off Frame 0										0x01	0	0	0	0	0	0	0	1		
On/Off Frame 1											0x02	0	0	0	0	0	0	1	0	
On/Off Frame 2										0x03	0	0	0	0	0	0	1	1	On/Off Information for each Frame (up to 36	
																			Frames)	
On/Off Frame 34										0x23	0	0	1	0	0	0	1	1		
On/Off Frame 35										0x24	0	0	1	0	0	1	0	0		
Blink & PWM Set 0								•		0x40	0	1	0	0	0	0	0	0		
Blink & PWM Set 1	0xFD	1	1	1	1	1	1	0	1	0x41	0	1	0	0	0	0	0	1		
Blink & PWM Set 2										0x42	0	1	0	0	0	0	1	0	Blink & PWM Information Sets (up to	
Blink & PWM Set 3										0x43	0	1	0	0	0	0	1	1	6 sets)	
Blink & PWM Set 4									2	0x44	0	1	0	0	0	1	0	0		
Blink & PWM Set 5										0x45	0	1	0	0	0	1	0	1		
Dot Correction										0x80	1	0	0	0	0	0	0	0	Selection of Dot Correction Register	
Control Register								Ŧ		0xC0	1	1	0	0	0	0	0	0	Selection of Control Register	

Table 7. Register Selection Address Map

Data Definition of the single frames

One frame consists of 2 datasets, the On/Off dataset and the Blink & PWM dataset. Where more On/Off frames can be linked to one PWM set. Depending on the used PWM sets more or less On/Off frames can be stored inside the AS1130 (see Table 8).

Each On/Off Frame needs to define the used Blink & PWM dataset.

Table 8.	RAM Configuration
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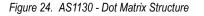
RAM Configuration	Blink & PWM Sets	On/Off Frames	On/Off Frames with Dot Correction
1	1	36	35
2	2	30	29
3	3	24	23
4	4	18	17
5	5	12	11
6	6	6	5

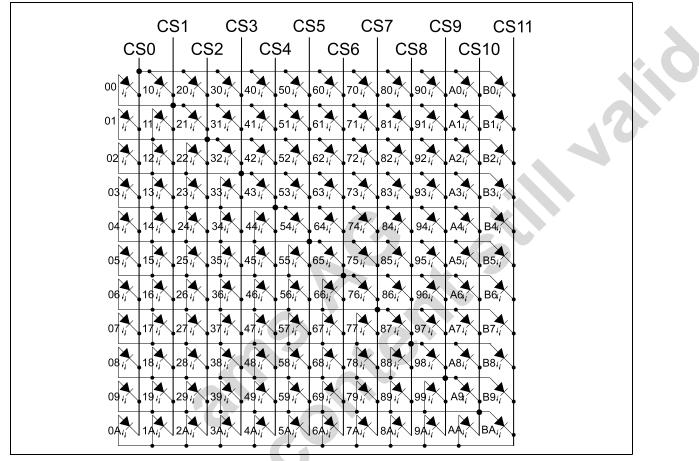
It's necessary to define the RAM configuration before data can be written to the frame datasets. The RAM configuration is defined in the AS1130 config register (see Table 20 on page 25) via bit 2:0 and bit 4 for Dot Correction.

Note: After a first write of data to the frames, the configuration is locked in the AS1130 config register and can be changed only after a reset of the device. A change of the RAM configuration requires to re-write the frame datasets.

12x11 LED Matrix

The AS1130 is configured to control one big LED matrix.





In Table 9 it's described which databit represents which LED in the matrix. Per default all databits are '0', meaning no LED is on. A '1' puts the LED on.

Each Current Segment of the LED Matrix consists of 11 LEDs, therefore 2 bytes of data are required for one Current Segment. CS0 is defined by the two bytes with address 0x00 and 0x01 and also includes the address of the used Blink & PWM dataset for this frame.

Sagmant	Data																
Segment	HEX	A7 (A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0
0	0x00	0	0	0	0	0	0	0	0	LED 07	LED 06	LED 05	LED 04	LED 03	LED 02	LED 01	LED 00
0	0x01	0	0	0	0	0	0	0	1	PWM [2]	PWM [1]	PWM [0]	Х	Х	LED 0A	LED 09	LED 08
1	0x02	0	0	0	0	0	0	1	0	LED 17	LED 16	LED 15	LED 14	LED 13	LED 12	LED 11	LED 10
	0x03	0	0	0	0	0	0	1	1	Х	Х	Х	Х	Х	LED 1A	LED 19	LED 18
2	0x04	0	0	0	0	0	1	0	0	LED 27	LED 26	LED 25	LED 24	LED 23	LED 22	LED 21	LED 20
2	0x05	0	0	0	0	0	1	0	1	Х	Х	Х	Х	Х	LED 2A	LED 29	LED 28

Table 9. LEDs On/Off Frame Register Format

Sagmart	Address									Data								
Segment	HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0	
3	0x06	0	0	0	0	0	1	1	0	LED 37	LED 36	LED 35	LED 34	LED 33	LED 32	LED 31	LED 30	
5	0x07	0	0	0	0	0	1	1	1	Х	Х	Х	Х	Х	LED 3A	LED 39	LED 38	
4	0x08	0	0	0	0	1	0	0	0	LED 47	LED 46	LED 45	LED 44	LED 43	LED 42	LED 41	LED 40	
4	0x09	0	0	0	0	1	0	0	1	Х	Х	Х	Х	Х	LED 4A	LED 49	LED 48	
5	0x0A	0	0	0	0	1	0	1	0	LED 57	LED 56	LED 55	LED 54	LED 53	LED 52	LED 51	LED 50	
3	0x0B	0	0	0	0	1	0	1	1	Х	Х	х	Х	Х	LED 5A	LED 59	LED 58	
6	0x0C	0	0	0	0	1	1	0	0	LED 67	LED 66	LED 65	LED 64	LED 63	LED 62	LED 61	LED 60	
U	0x0D	0	0	0	0	1	1	0	1	X	х	х	x	x	LED 6A	LED 69	LED 68	
7	0x0E	0	0	0	0	1	1	1	0	LED 77	LED 76	LED 75	LED 74	LED 73	LED 72	LED 71	LED 70	
1	0x0F	0	0	0	0	1	1	1	1	Х	х	x	x	x	LED 7A	LED 79	LED 78	
8	0x10	0	0	0	1	0	0	0	0	LED 87	LED 86	LED 85	LED 84	LED 83	LED 82	LED 81	LED 80	
0	0x11	0	0	0	1	0	0	0	1	×	x	X	х	Х	LED 8A	LED 89	LED 88	
9	0x12	0	0	0	1	0	0	1	0	LED 97	LED 96	LED 95	LED 94	LED 93	LED 92	LED 91	LED 90	
	0x13	0	0	0	1	0	0	1	1	x	Х	Х	Х	Х	LED 9A	LED 99	LED 98	
А	0x14	0	0	0	1	0	1	0	0	LED A7	LED A6	LED A5	LED A4	LED A3	LED A2	LED A1	LED A0	
//	0x15	0	0	0	1	0	Ţ	0	1	Х	Х	Х	Х	Х	LED AA	LED A9	LED A8	
В	0x16	0	0	0	1	0	1	1	0	LED B7	LED B6	LED B5	LED B4	LED B3	LED B2	LED B1	LED B0	
	0x17	0	0	0	1	0	1	1	1	Х	Х	Х	Х	Х	LED BA	LED B9	LED B8	

The Blink & PWM sets contain blink on/off and the digital PWM information for each LED in the matrix. The number of PWM datasets is flexible according to the defined RAM configuration (see Figure 8 on page 14).

In the blink register (see Table 10) every single LED can be set to blink. The blink period is set in the display option register (see Display Option Register Format on page 24).

Segment	C	Address										Data								
Segment	HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0			
0	0x00	0	0	0	0	0	0	0	0	LED 07	LED 06	LED 05	LED 04	LED 03	LED 02	LED 01	LED 00			
	0x01	0	0	0	0	0	0	0	1	Х	Х	Х	Х	Х	LED 0A	LED 09	LED 08			
1	0x02	0	0	0	0	0	0	1	0	LED 17	LED 16	LED 15	LED 14	LED 13	LED 12	LED 11	LED 10			
I	0x03	0	0	0	0	0	0	1	1	Х	Х	Х	Х	Х	LED 1A	LED 19	LED 18			

Table 10.	LEDs Blink Frame	Register Format
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egment HEX A7 A6 A5 A4 A3 A2 A1 A0 D7 D6 D5 D4 D2 D1 D0 2 0x04 0 0 0 0 0 1 0 0 LED
2 0x4 0 0 0 0 1 0 0 27 26 25 24 23 22 21 20 0x05 0 0 0 0 0 0 1 0 1 X X X X LED
0x05 0 0 0 1 0 1 X
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
4 0x09 0 0 0 1 0 0 1 X X X X X K
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
5 0x0B 0 0 0 1 0 1 1 X X X X X K
0x0C 0 0 0 1 1 0 0 LED LED <th< td=""></th<>
6 0x0D 0 0 0 1 1 0 1 X X X X X LED
0x0E 0 0 0 1 1 1 0 EP
1 0x0F 0 0 0 1 1 1 X
0x10 0 0 1 0 0 0 87 1ED 1ED <t< td=""></t<>
8 0x11 0 0 0 1 0 0 0 1 X
9 0x12 0 0 0 1 0 0 1 0 LED 1 0 1 1 0 1 0 1 1 1 0 1 0 1 1 1 0 1 <th1< td="" th<=""></th1<>
9 0x13 0 0 0 1 0 0 1 1 X X X X X X LED LED 99
0x14 0 0 0 1 0 1 0 <u>LED LED LED LED LED LED LED LED LED LED </u>
A 0x15 0 0 0 1 0 1 0 1 X X X X X X <u>LED LED LED A</u>
0x16 0 0 0 1 0 1 1 0 0 LED
B 0x17 0 0 0 1 0 1 1 1 X X X X X X <u>LED LED LED B</u> 8



In the PWM register (see Table 11) the brightness of every single LED can be set via a 8bit PWM (255 steps).

Table 11. LEDs PWM Register Format

Segment					Ad	dres	s							Dat	ta				
e e ginon		HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3 I	D2	D1	D0	
	LED00	0x18	0	0	0	1	1	0	0	0									
	LED01	0x19	0	0	0	1	1	0	0	1									
	LED02	0x1A	0	0	0	1	1	0	1	0									
	LED03	0x1B	0	0	0	1	1	0	1	1									
	LED04	0x1C	0	0	0	1	1	1	0	0									2
0	LED05	0x1D	0	0	0	1	1	1	0	1	2	55 ste	ps for	intensi	ty each	sing	le LED)	
	LED06	0x1E	0	0	0	1	1	1	1	0									
	LED07	0x1F	0	0	0	1	1	1	1	1									
	LED08	0x20	0	0	1	0	0	0	0	0	_								
	LED09	0x21	0	0	1	0	0	0	0	1	_								
	LED0A	0x22	0	0	1	0	0	0	1	0									
	LED10	0x23	0	0	1	0	0	0	1	1									
	LED11	0x24	0	0	1	0	0	1	0	0									
	LED12	0x25	0	0	1	0	0	1	0	1									
	LED13	0x26	0	0	1	0	0	1	1	0									
	LED14	0x27	0	0	1	0	0	1	1	1								_	
1	LED15	0x28	0	0	1	0	1	0	0	0	2	55 ste	ps for	intensi	ty each	sing	le LEL)	
	LED16	0x29	0	0	1	0	1	0	0	1									
	LED17	0x2A	0	0	1	0	1	0	1	0									
	LED18	0x2B	0	0	1	0	1	0	1	1									
	LED19	0x2C	0	0	1	0	1	1	0	0									
	LED1A	0x2D	0	0	1	0	1	1	0	1									
	LED20	0x2E	0	0	1	0	1	1	1	0	-								
	LED21 LED22	0x2F 0x30	0	0	1	0	1 0	0	0	0	-								
	LED22 LED23	0x30 0x31	0	0	1	1	0	0	0	1									
	LED23	0x31	0	0	1	1	0	0	1	0									
2	LED24 LED25	0x32	0	0	1	1	0	0	1	1	2	55 cto	ne for	intensi	hu opoh	cina		h	
2	LED25	0x34	0	0	1	1	0	1	0	0	2	00 310	p3 101	IIICIISI	ly each	Sing		,	
	LED20	0x35	0	0	1	1	0	1	0	1									
	LED27	0x36	0	0	1	1	0	1	1	0									
	LED20	0x37	0	0	1	1	0	1	1	1	_								
	LED20	0x38	0	0	1	1	1	0	0	0									
	LED30	0x39	0	0	1	1	1	0	0	1									
	LED31	0x3A	0	0	1	1	1	0	1	0	-								
	LED32	0x3B	0	0	1	1	1	0	1	1	-								
	LED33	0x3C	0	0	1	1	1	1	0	0	-								
	LED34	0x3D	0	0	1	1	1	1	0	1	-								
3	LED35	0x3E	0	0	1	1	1	1	1	0	2	55 ste	ps for	intensi	ty each	sina	le LE)	
	LED36	0x3F	0	0	1	1	1	1	1	1	1								
	LED37	0x40	0	1	0	0	0	0	0	0									
	LED38	0x41	0	1	0	0	0	0	0										
	LED39	0x42	0	1	0	0	0	0	1	0									
	LED3A	0x43	0	1	0	0	0	0	1										

Table 11. LEDs PWM Register Format

Segment					Ad	dres	s				Data
Geginent		HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7 D6 D5 D4 D3 D2 D1 D0
	LED40	0x44	0	1	0	0	0	1	0	0	
	LED41	0x45	0	1	0	0	0	1	0	1	
	LED42	0x46	0	1	0	0	0	1	1	0	
	LED43	0x47	0	1	0	0	0	1	1	1	
	LED44	0x48	0	1	0	0	1	0	0	0	
4	LED45	0x49	0	1	0	0	1	0	0	1	255 steps for intensity each single LED
	LED46	0x4A	0	1	0	0	1	0	1	0	
	LED47	0x4B	0	1	0	0	1	0	1	1	
LED48 0x4C 0 1 0 1 1 0 0 LED49 0x4D 0 1 0 1 1 0 1											
	LED49 LED4A	0x4D 0x4E	0	1	0	0	1	1	0	1 0	
	LED4A	0x4E	0	1	0	0	1	1	1	1	
	LED50	0x50	0	1	0	1	0	0	0	0	
	LED51	0x51	0	1	0	1	0	0	0	1	
	LED52	0x52	0	1	0	1	0	0	1	0	
	LED54	0x53	0	1	0	1	0	0	1	1	
5	LED55	0x54	0	1	0	1	0	1	0	0	255 steps for intensity each single LED
	LED56	0x55	0	1	0	1	0	1	0	1	
	LED57	0x56	0	1	0	1	0	1	1	0	
	LED58	0x57	0	1	0	1	0	1	1	1	
	LED59	0x58	0	1	0	1	1	0	0	0	
	LED5A	0x59	0	1	0	1	1	0	0	1	
	LEDA0	0x86	1	0	0	0	0	1	1	0	
	LEDA1	0x87	1	0	0	0	0	1	1	1	
	LEDA2	0x88	1	0	0	0	1	0	0	0	
	LEDA3	0x89	1	0	0	0	1	0	0	1	
	LEDA4	0x8A	1	0	0	0	1	0	1	0	
A	LEDA5	0x8B	1	0	0	0	1	0	1	1	255 steps for intensity each single LED
	LEDA6	0x8C	1	0	0	0	1	1	0	0	
	LEDA7	0x8D	1	0	0	0	1	1	0	1	
	LEDA8	0x8E	1	0	0	0	1	1	1	0	
	LEDA9	0x8F	1	0	0	0	1	1	1	1	
	LEDR0	0x90 0x91	1	0	0	1	0	0	0	0	
	LEDB0 LEDB1	0x91 0x92	1	0	0	1	0	0	0	1 0	
	LEDB1	0x92 0x93	1	0	0	1	0	0	1	0	
	LEDB2	0x93 0x94	1	0	0	1	0	0	0	0	
	LEDB3	0x94 0x95	1	0	0	1	0	1	0	1	
в	LEDB4	0x95 0x96	1	0	0	1	0	1	1	0	255 steps for intensity each single LED
	LEDB5	0x90 0x97	1	0	0	1	0	1		200 steps for intensity each single LED	
	LEDB0	0x97 0x98	1	0	0	1	1	0	0	0	
	LEDB7	0x98	1	0	0	1	1	0	0	1	
	LEDB0	0x99	1	0	0	1	1	0	1	0	
	LEDBS	0x9A 0x9B	1	0	0	1	1	0	1	1	
	LLUDA	0730		0	0			0			

Dot Correction Register

The AS1130 offers a feature to define a correction factor for the analog current for every segment. This correction factor is called Dot Correction and is defined in the Dot Correction register (see Table 12). The Dot Correction Register is selected via data 128 on addr 253.

Sagmont				Α	ddres	s				Data								
Segment	HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0	
0	0x00	0	0	0	0	0	0	0	0									
1	0x01	0	0	0	0	0	0	0	1									
2	0x02	0	0	0	0	0	0	1	0									
3	0x03	0	0	0	0	0	0	1	1	8 bit Dot Correction								
4	0x04	0	0	0	0	0	1	0	0									
5	0x05	0	0	0	0	0	1	0	1		8 bit Dot Correction							
6	0x06	0	0	0	0	0	1	1	0			8	bit Dot (Correcti	on			
7	0x07	0	0	0	0	0	1	1	1			8	bit Dot (Correcti	on			
8	0x08	0	0	0	0	1	0	0	0			8	bit Dot (Correcti	on			
9	0x09	0	0	0	0	1	0	0	1			8	bit Dot (Correcti	on			
А	0x0A	0	0	0	0	1	0	1	0			8	bit Dot (Correcti	on			
В	0x0B	0	0	0	0	1	0	1	1			8	bit Dot (Correcti	on			

Table 12. Dot Correction Register Format

Control-Registers

The AS1130 device contains 14 control-registers which are listed in Table 13. All registers are selected using a 8-bit address word, and communication is done via the serial interface. Select the Control Register via the Register Selection (see Table 7 on page 14).

The Control Register is selected via data 192 on addr 253.

Pagiotar Nama	HEX			R	egister	Addres	s			Register Data		
Register Name		A7	A6	A5	A4	A3	A2	A1	A0	D7:D0		
Picture	0x00	0	0	0	0	0	0	0	0	(see Table 14 on page 21)		
Movie	0x01	0	0	0	0	0	0	0	1	(see Table 15 on page 21)		
Movie Mode	0x02	0	0	0	0	0	0	1	0	(see Table 16 on page 22)		
Frame Time / Scroll	0x03	0	0	0	0	0	0	1	1	(see Table 17 on page 23)		
Display Option	0x04	0	0	0	0	0	1	0	0	(see Table 18 on page 24)		
Current Source	0x05	0	0	0	0	0	1	0	1	(see Table 19 on page 24)		
AS1130 Config	0x06	0	0	0	0	0	1	1	0	(see Table 20 on page 25)		
Interrupt Mask	0x07	0	0	0	0	0	1	1	1	(see Table 21 on page 25)		
Interrupt Frame Definition	0x08	0	0	0	0	1	0	0	0	(see Table 22 on page 26)		
Shutdown & Open/Short	0x09	0	0	0	0	1	0	0	1	(see Table 23 on page 26)		
I ² C Interface Monitoring	0x0A	0	0	0	0	1	0	1	0	(see Table 24 on page 27)		
CLK Synchronization	0x0B	0	0	0	0	1	0	1	1	(see Table 25 on page 27)		
Interrupt Status	0x0E	0	0	0	0	1	1	0	0	(see Table 26 on page 28)		
AS1130 Status	0x0F	0	0	0	0	1	1	0	1	(see Table 27 on page 29)		
	0x20	0	0	1	0	0	0	0	0			
Open LED										(see Table 28 on page 29)		
	0x37	0	0	1	1	0	1	1	1			

Table 13. Control Register Address Map

Picture Register (0x00)

In this register it must be set if a picture is to display on the LED matrix or not. Also the address of the picture which should be displayed must be set within this register. The default setting of this register is 0x00.

Table 14. Picture Register Format

			0x00	Picture Register	
Bit	Bit Name	Default	Access	Bit Description	
7	blink_pic	0	R/W	All LEDs in blink mode during display picture 0: no blink 1: all LEDs blink	
6	display_pic	0	R/W	Display Picture 0: no picture 1: display picture	
5:0	pic_addr	000000	R/W	Address of Picture 000000: Frame 0 000001: Frame 1 000010: Frame 2 000010: Frame 3 000100: Frame 4 000101: Frame 5 	

Note: The display_pic bit (bit 6 in Picture Register) has lower priority than the display_movie bit (bit 6 in Movie Register).

Movie Register (0x01)

In this register it must be set if a movie is to display on the LED matrix or not. Also the address of the first frame in the movie needs be set within this register. The default setting of this register is 0x00.

Table 15. Movie Register Format

			0x0 [.]	1 Movie Register
Bit	Bit Name	Default	Access	Bit Description
7	blink_movie	0	R/W	All LEDs in blink mode during play movie 0: no blink 1: all LEDs blink
6	display_movie	0	R/W	0: no movie 1: start movie
5:0	movie_addr	000000	R/W	Address of first Frame in Movie 000000: Frame 0 000001: Frame 1 000010: Frame 2 000010: Frame 3 000100: Frame 4 000101: Frame 5

Note: The display_movie bit (bit 6 in Movie Register) has higher priority than the display_pic bit (bit 6 in Picture Register).

Movie Mode Register (0x02)

Within this register two movie play options can be set. Per default this register is set to 0x00.

- In scroll mode a movie can stop with the last frame of the movie or scroll endless
- The number of frames to play in a movie

Table 16. Movie Mode Register Format

	0x02 Movie Mode Register						
Bit	Bit Name	Default	Access	Bit Description			
7	blink_en	0	R/W	LED blink option ¹ 0: enabled 1: disabled			
6	end_last	0	R/W	defines at which frame a movie stops in scroll mode 0: movie ends with 1st frame 1: movie ends with last frame			
5:0	movie_frames	000000	R/W	Number of frames played in a movie, starting at movie_addr defined in Movie Register 000000: Play 1 Frame 000001: Play 2 Frames 000010: Play 3 Frames 000010: Play 4 Frames 000101: Play 5 Frames 000101: Play 33 Frames 100000: Play 33 Frames 100001: Play 34 Frames 100011: Play 35 Frames 100011: Play 36 Frames			

1. Disable blink option overrides any blink definition in PWM data definition or global blink definition in picture register & movie register bit 7.

.uon in PWM data o

Frame Time/Scroll Register (0x03)

Every single frame in a movie is displayed for a certain time before the next frame is displayed. This time can be set within this register with 4 bits. The stated values in Table 17 are typical values.

Also the scroll options are set within this register. Per default this register is set to 0x00.

Table 17. Frame Time/Scroll Register Format

Bit Bit Name	Default	Access	Bit Description
7 frame_fad	0	R/W	Fade Frame Option (not available in 5 LED block configuration) 0: no fading 1: fading of a Frame
6 scroll_dir	0	R/W	Scroll Direction 0: scroll to right 1: scroll to left
5 block_size	0	R/W	Define block size for scrolling 0: scroll in full matrix 1: scroll in 5 LED blocks (current sources split in 2 sections, See Scroll Function on page 31)
4 Enable Scroll	0	R/W	Scroll digits at play movie 0: no scrolling 1: scrolling digits at play movie
3:0 frame_dela	0000	R/W	Delay between frame change in a movie 0000: play frame only one time 0001: 32.5ms 0010: 65ms 0011: 97.5ms 0100: 130ms 0101: 162.5ms 0110: 195ms 0111: 227.5ms 1000: 260ms 1001: 292.5ms 1010: 325ms 1011: 357.5ms 1101: 357.5ms 1101: 422.5ms 1110: 455ms 1111: 487.5ms

Display Option Register (0x04)

In this register the number of loops in a movie are defined. With the scan-limit it can be controlled how many digits are displayed in each matrix. When all 12 digits in the matrix are displayed, the display scan rate is 430Hz (typ.). If the number of digits to display is reduced, the update frequency is increased. Per default this register is set to 0x20.

Table 18. Display Option Register Format

	0x04 Display Option Register							
Bit	Bit Name	Default	Access	Bit Description				
7:5	loops	001	R/W	Number of loops played in one movie 000: not valid 001: 1 loop 010: 2 loops 011: 3 loops 100: 4 loops 101: 5 loops 110: 6 loops 111: play movie endless (needs to be reset to 0-6 to stop movie); for scroll endless set bit end_last = '0'				
4	blink_freq	0	R/W	Blink period 0: 1.5s 1: 3s				
3:0	scan_limit	0000	R/W	Number of displayed segments in one frame (scan-limit) 0000: CS0 0001: CS0 to CS1 0010: CS0 to CS2 0011: CS0 to CS3 0100: CS0 to CS4 0101: CS0 to CS5 0110: CS0 to CS5 0111: CS0 to CS6 0111: CS0 to CS7 1000: CS0 to CS8 1001: CS0 to CS9 1010: CS0 to CS10 1011: CS0 to CS11				

Note: To stop a movie in *play endless* mode, bits D7:D5 have to be set to a value between 000 to 110.

Current Source Register (0x05)

Within this registers the current for every single LED can be set from 0mA to 30mA in 255 steps (8 bits). Per default this register is set to 0x00.

Table 19. Current Source Register Format

	0x05 Current Source Register						
Bit	Bit Name	Default	Access	Bit Description			
7:0	current		R/W	0000000: 0mA			
	6	00000000		 11111111: 30mA			

AS1130 Config Register (0x06)

Per default this register is set to 0x00.

Table 20. AS1130 Config Register Format

0x06 AS1130 Config Register						
Bit	Bit Name	Default	Access	Bit Description		
7	low_vdd_rst	0	R/W	 0: at the end of a movie or a display picture the "low_VDD" flag is not changed 1: at the end of a movie or a display picture, the "low_VDD" flag is set to "0" 		
6	low_vdd_stat	0	R/W	This bit indicates the supply status 0: if low_VDD is detected, the Interrupt Status Register will be updated accordingly and pin IRQ is triggered. 1: the low_VDD bit is directly mapped to the pin IRQ. This can be used to control an external DC/DC Converter or Charge Pump. In this case pin IRQ can't be used for interrupt functionality, the Interrupt Status REgister will be updated accordingly.		
5	led_error_correction	0	R/W	This bit defines the LED open handling 0 : open LEDs which are detected at LED open test, are NOT disabled 1 : open LEDs which are detected at LED open test, are disabled		
4	dot_corr	0	R/W	Analog current DotCorrection ¹ 0: disabled 1: enabled		
3	common_addr	0	R/W	I ² C Common Address 0: disabled 1: enabled (all AS1130 are reacting on the same address "0111111")		
2:0	mem_conf	000	R/W	Define Memory Configuration ¹ (see Table 8 on page 14) 000: Invalid Configuration (default value) 001: RAM Configuration 1 010: RAM Configuration 2 011: RAM Configuration 3 100: RAM Configuration 4 101: RAM Configuration 5 110: RAM Configuration 6		

1. This configuration is locked after the first write access to ON/OFF, PWM od DotCorrection data section. Unlock can be performed only by a reset of the device.

Interrupt Mask Register (0x07)

Per default this register is set to 0x20.

Table 21. Interrupt Mask Register Format

	0x07 Interrupt Mask Register							
Bit	Bit Name	Default	Access	Bit Description				
7	selected_pic	0	R/W	IRQ pin triggers if defined Frame is displayed (see Interrupt Frame Definition Register (0x08) on page 26) 0: disabled 1: enabled				
6	watchdog	0	R/W	IRQ pin triggers if the I ² C watchdog triggers 0: disabled 1: enabled				
5	por	1	R/W	IRQ pin triggers if POR is active 0: disabled 1: enabled				

Table 21. Interrupt Mask Register Format

	0x07 Interrupt Mask Register							
Bit	Bit Name	Default	Access	Bit Description				
4	overtemp	0	R/W	IRQ pin triggers if the over temperature limit is reached 0 : disabled 1 : enabled				
3	low_vdd	0	R/W	IRQ pin triggers if VDD is to low for used LEDs (low_VDD flag) 0 : disabled 1 : enabled				
2	open_err	0	R/W	IRQ pin triggers if an error on the open test occurs 0 : disabled 1 : enabled				
1	short_err	0	R/W	IRQ pin triggers if an error on the short test occurs 0 : disabled 1 : enabled				
0	movie_fin	0	R/W	IRQ pin triggers if a movie is finished 0 : disabled 1 : enabled				

Interrupt Frame Definition Register (0x08)

Per default this register is set to 0x3F.

Table 22. Interrupt Frame Definition Register Format

	0x08 Interrupt Frame Definition Register							
Bit	Bit Name	Default	Access	Bit Description				
7:6	-	00	n/a					
5:0	last_frame	111111	RW	After this frame is displayed the last time (depending on the number of loops played in a movie) an interrupt will be triggered. 0000001: Frame 0 000001: Frame 1 000010: Frame 2 000011: Frame 3 000100: Frame 4 000101: Frame 5 				

Shutdown & Open/Short Register (0x09)

Per default this register is set to 0x02.

Table 23. Shutdown & Open/Short Register Format

	0x09 Shutdown & Open/Short Register						
Bit	Bit Name	Default	Access	Bit Description			
7:5	-	000	n/a				
4	test_all	0	R/W	The LED open/short test is performed on all LED locations 0: disabled 1: enabled			

0x09 Shutdown & Open/Short Register						
Bit	Bit Name	Default	Access	Bit Description		
3	auto_test	0	R/W	The LED open/short test is automatically started at display picture/frame 0: disabled 1: enabled		
2	manual_test	0	R/W	The LED open/short test is started manually 0: disabled 1: enabled		
1	init	1	R/W	0: initialise control logic (internal State machine is reset again) 1: normal operation		
0	shdn	0	R/W	 0: device is in shutdown mode (Outputs are turned off, internal State machine stops) 1: normal operation 		

Table 23. Shutdown & Open/Short Register Format

I²C Interface Monitoring Register (0x0A)

This register is used to monitor the activity on the I²C bus. If a deadlock situation occurs (e.g. the bus SDA pin is pulled to low and no communication is possible) the chip will reset the I²C interface and the master is able to start the communication again.

The time window for the reset of the interface of the AS1130 can bes set via 7 bits from 256µs to 33ms. The default setting of this register is 0xFF.

	0x0A I ² C Interface Monitoring Register							
Bit	Bit Name	Default	Access	Bit Description				
7	-	1	n/a					
6:1	Time out window	11111	R/W	Definition of the Time out window (0 to 127 => 1 to 128x256µs) 0000000: 256µs 1111111: 32.7ms				
0	i2c_monitor	1	R/W	0: I ² C monitoring off 1: I ² C monitoring on				

CLK Synchronization Register (0x0B)

The default setting of this register is 0x00.

	0x0B CLK Synchronization Register										
Bit	Bit Name	Default	Access	Bit Description							
7:4	-	0000	n/a								
3:2	clk_out	00	R/W	Adjustable clock out frequency 00: 1MHz 01: 500kHz 10: 125kHz 11: 32kHz							

Table 25.	CLK Synchronizatio	on Register Format
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0x0B CLK Synchronization Register					
Bit	Bit Name	Default	Access	Bit Description	
1	sync_out	0	R/W	The internal oscillator is used as system-clk. The selected clk frequency is available on pin D4 for synchronization. (Output) ¹ 0: disabled 1: enabled	
0	sync_in	0	R/W	The internal oscillator is disabled. Pin D4 is used as clk input for system-clk. 0: disabled 1: enabled	

Interrupt Status Register (0x0E)

This is a read only register. Within this register the cause of an interrupt can be read out. After power up or a reset the default setting of this register is 0x20. A read out command will set this register to default and the IRQ pin will be released again.

Bit	Bit Name	Default	Access	Bit Description
7	frame_int	0	R	0: no interrupt 1: defined Frame is displayed (see Interrupt Frame Definition Register (0x08) on page 26)
6	i2c_int	0	R	0: no interrupt 1: I ² C watchdog reports a deadlock on the interface
5	por_int 1 R 0: no interrupt 1: POR was trigger			0: no interrupt 1: POR was triggered
4	overtemp_int	0	R	0: no interrupt 1: over temperature limit is reached
3	low_vdd_int	0	R	0: no interrupt 1: VDD is too low to drive requested current through the LEDs
2	open_int	0	R	0: no interrupt 1: error on open test
1	short_int	0	R	0: no interrupt 1: error on short test
0	movie_int	0	R	0: no interrupt 1: play movie is finished
	Scyli			

Table 26. Interrupt Status Register Format

AS1130 Status Register (0x0F)

This is a read only register. From this register the actual status of the AS1130 can be read out. The default setting of this register is 0x00.

Table 27. AS1130 Status Register Format

			0x0F AS	1130 Status Register	
Bit	Bit Name	Default	Access	Bit Description	
7:2	frame_on	000000	R	Actual displayed frame 000000: Frame 0 000001: Frame 1 000010: Frame 2 000011: Frame 3 000100: Frame 4 000101: Frame 5 	
1	movie_on	0	R	0: no movie 1: movie playing	
0	test_on	0	R	0: no test is running 1: open/short test ongoing	

AS1130 Open LED Register (0x20 to 0x37)

This is a read only register. From this register the LED's which failed with an open error can be read out. A '1' indicates LED okay, a '0' stands for LED open. If a LED, which is physically not connected to the device is tested, the Open LED test will return a '0'.

Segment		Address								Data							
Segment	HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0
0	0x20	0	0	1	0	0	0	0	0	LED 07	LED 06	LED 05	LED 04	LED 03	LED 02	LED 01	LED 00
Ū	0x21	0	0	1	0	0	0	0	1	0	0	0	0	0	LED 0A	LED 09	LED 08
1	0x22	0	0	1	0	0	0	1	0	LED 17	LED 16	LED 15	LED 14	LED 13	LED 12	LED 11	LED 10
I	0x23	0	0	1	0	0	0	1	1	0	0	0	0	0	LED 1A	LED 19	LED 18
2	0x24	0	0	1	0	0	1	0	0	LED 27	LED 26	LED 25	LED 24	LED 23	LED 22	LED 21	LED 20
2	0x25	0	0	1	0	0	1	0	1	0	0	0	0	0	LED 2A	LED 29	LED 28
3	0x26	0	0	1	0	0	1	1	0	LED 37	LED 36	LED 35	LED 34	LED 33	LED 32	LED 31	LED 30
3	0x27	0	0	1	0	0	1	1	1	0	0	0	0	0	LED 3A	LED 39	LED 38
4	0x28	0	0	1	0	1	0	0	0	LED 47	LED 46	LED 45	LED 44	LED 43	LED 42	LED 41	LED 40
4	0x29	0	0	1	0	1	0	0	1	0	0	0	0	0	LED 4A	LED 49	LED 48

Table 28. Open LED Register Format

Segment		Address											ata			
	HEX	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1
5	0x2A	0	0	1	0	1	0	1	0	LED 57	LED 56	LED 55	LED 54	LED 53	LED 52	LED 51
Ū	0x2B	0	0	1	0	1	0	1	1	0	0	0	0	0	LED 5A	LED 59
<u>^</u>	0x2C	0	0	1	0	1	1	0	0	LED 67	LED 66	LED 65	LED 64	LED 63	LED 62	LEC 61
6	0x2D	0	0	1	0	1	1	0	1	0	0	0	0	0	LED 6A	LED 69
_	0x2E	0	0	1	0	1	1	1	0	LED 77	LED 76	LED 75	LED 74	LED 73	LED 72	LED 71
7	0x2F	0	0	1	0	1	1	1	1	0	0	0	0	0	LED 7A	LEC 79
	0x30	0	0	1	1	0	0	0	0	LED 87	LED 86	LED 85	LED 84	LED 83	LED 82	LEC 81
8	0x31	0	0	1	1	0	0	0	1	0	0	0	0	0	LED 8A	LED 89
0	0x32	0	0	1	1	0	0	1	0	LED 97	LED 96	LED 95	LED 94	LED 93	LED 92	LED 91
9	0x33	0	0	1	1	0	0	1	1	0	0	0	0	0	LED 9A	LEI 99
	0x34	0	0	1	1	0	1	0	0	LED A7	LED A6	LED A5	LED A4	LED A3	LED A2	LEI A1
A	0x35	0	0	1	1	0	1	0	1	0	0	0	0	0	LED AA	LEI A9
P	0x36	0	0	1	1	0	1	1	0	LED B7	LED B6	LED B5	LED B4	LED B3	LED B2	LEI B1
В	0x37	0	0	1	1	0	1	1	1	0	0	0	0	0	LED BA	LEI B9
							C									

10 Typical Application

Scroll Function

The AS1130 offers a feature for scrolling a picture through the matrix without the need of communication via a μ P. The scrolling can be done in the whole matrix (11x12) or optimized for a ticker in a 5x24 Matrix (see Figure 25).

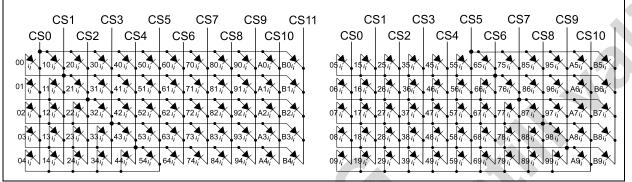


Figure 25. LED configuration for 5LED block scroll function

In the movie display mode the frame is shown in the matrix at once. On the contrary in the scroll function the frame is shifted through the matrix segment after segment (CS0 to CS1 to CS2 to CS3).



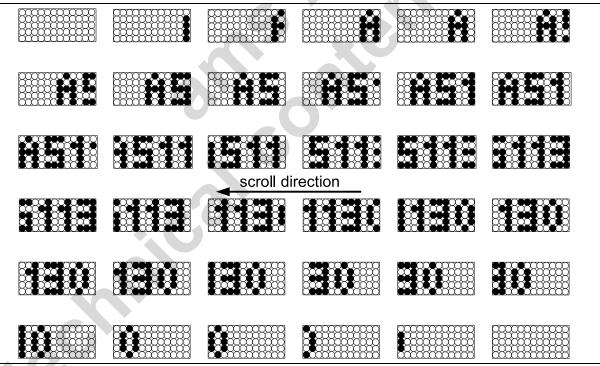
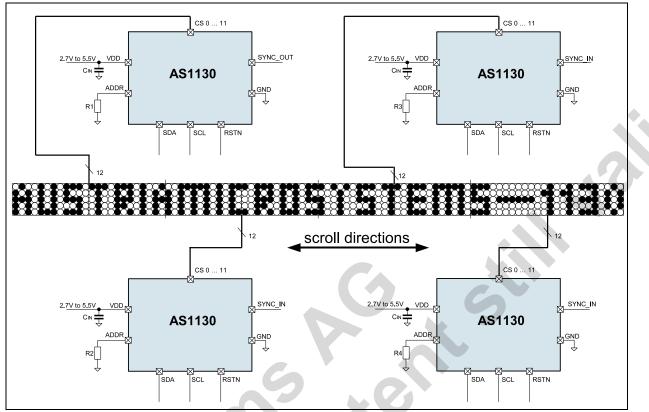


Figure 27. Ticker Application with 5x96 LED Matrix



(EQ 2)

LED Current Calculation

The current through a LED in the matrix is set via three registers (Current Source Register, Dot Correction and PWM). The resulting current through the single LED can be calculated as shown in the following.

First it's necessary to calculate the time how long one LED will be ON.

$$t_{LEDon} = \frac{PWM}{f_{OSC}} \tag{EQ 1}$$

Where:

 $t_{LEDon} \dots time$ where the LED is ON

PWM . . . value set in the register (0 - 256), (see Table 11 on page 18)

fOSC . . . frequency set in the CLK Synchronization Register, (see Table 25 on page 27)

The refresh rate is defined by the scan-limit and fOSC.

$$t_{REFRESH} = \frac{(scanlimit+1) \times 256}{f_{OSC}}$$

Where:

tREFRESH . . . time needed to refresh the matrix

scan-limit . . . is set via the Display Option Register (0 - 11), (see Table 18 on page 24)

fOSC . . . frequency set in the CLK Synchronization Register, (see Table 25 on page 27)

With the LED on-time and the refresh rate an average LED ON factor can be calculated.

$$LEDon_{avg} = \frac{t_{LEDon}}{t_{REFRESH}} = \frac{PWM}{(scanlimit+1) \times 256}$$
(EQ 3)

The resulting current is then the Segment Current (set in the Current Source Register) times the average LED ON factor.

$$I_{LEDavg} = I_{SEG} \times LEDon_{avg} = I_{SEG} \times \frac{PWM}{(scanlimit+1) \times 256}$$
(EQ 4)

Where:

ISEG ... Segment Current set via register (see Table 19 on page 24)

Example:

Assume that following conditions are set in the registers: PWM = 256, scan-limit = 5 (half filled matrix, 66 LEDs), ISEG = 30mA

$$I_{LEDavg} = 30mA \times \frac{256}{(5+1) \times 256} = 5mA$$
 (EQ 5)



11 Package Drawings and Markings

Figure 28. 20-pin WL-CSP Marking

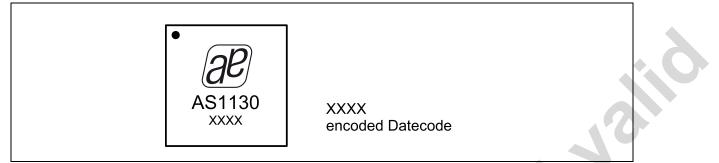


Figure 29. 28-pin SSOP Marking



Table 29. Packaging Code YYWWRZZ

Connie

YY	WW	R	ZZ
last two digits of the current year	manufacturing week	plant identifier	free choice / traceability code

Figure 30. 20-pin WL-CSP Package

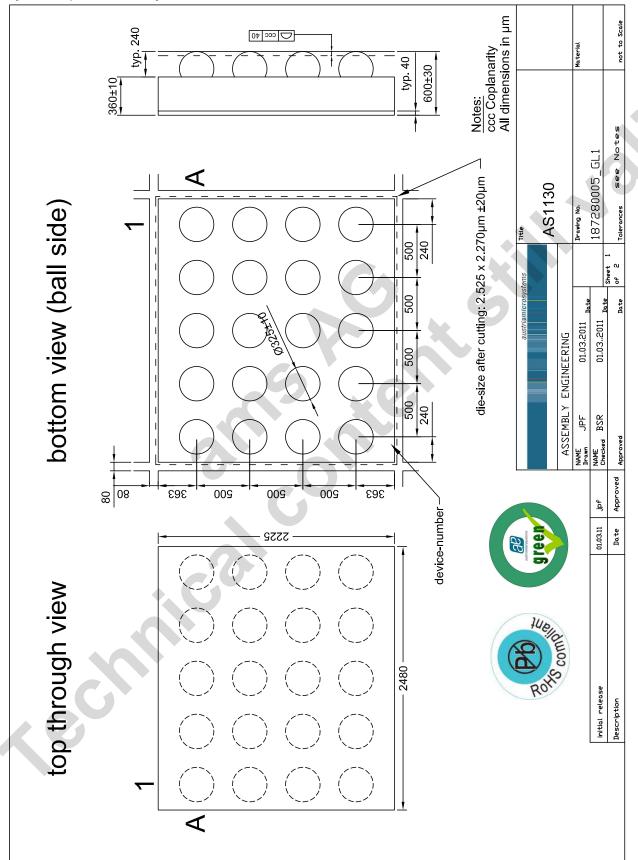
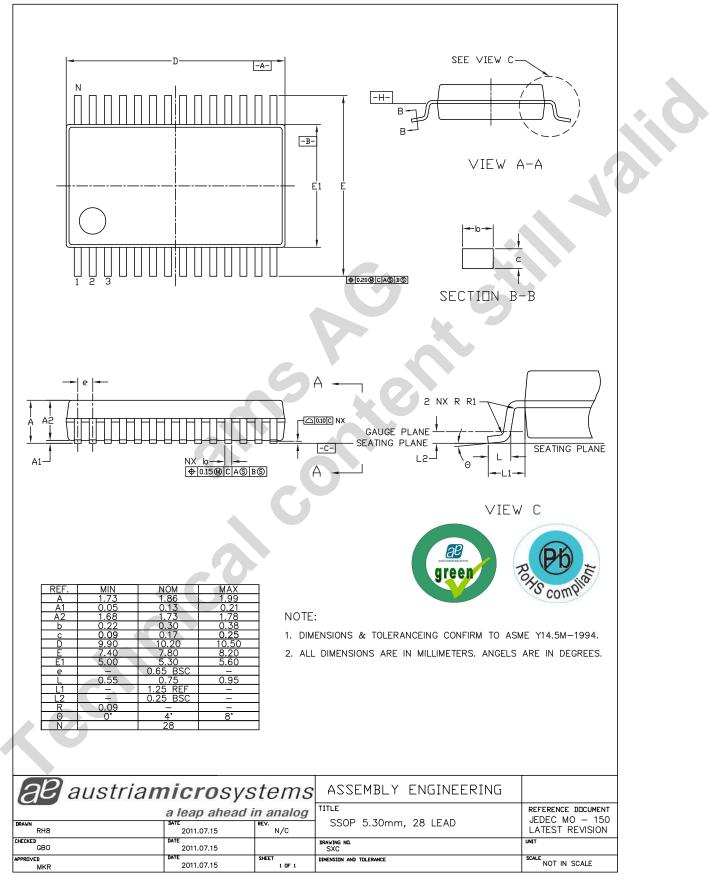


Figure 31. 28-pin SSOP Package



12 Ordering Information

The devices are available as the standard products shown in Table 30.

Table 30. Ordering Information

Ordering Code	Marking	Logic Levels	Address	Description	Delivery Form	Package
AS1130-BSST	AS1130	CMOS	0x30 - 0x37	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	
AS1130B-BSST*	AS1130B	Mobile	0830 - 0837	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	28-pin SSOP
AS1130C-BSST*	AS1130C	CMOS	0x38 - 0x3E	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	
AS1130D-BSST*	AS1130D	Mobile	0830 - 0832	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	
AS1130-BWLT	AS1130	CMOS	0x30 - 0x37	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	
AS1130B-BWLT*	AS1130B	Mobile	0x30 - 0x37	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	20-pin WL-CSP
AS1130C-BWLT*	tbd	CMOS	0x38 - 0x3E	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	
AS1130D-BWLT*	tbd	Mobile	0X30 - 0X3E	132-LED Cross-Plexing Driver with scrolling Function	Tape and Reel	

*) on request

Note: All products are RoHS compliant and austriamicrosystems green. Buy our products or get free samples online at ICdirect: http://www.austriamicrosystems.com/ICdirect

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