

AS22 Series Miniature Kit Encoder



Description

The Broadcom[®] AS22 Series kit encoder solution offers a compact size with an overall diameter of 22 mm and height of 10.9 mm for the space-constrained application.

To meet the growing demand for high-precision application, the AS22 Series offers a wide range of incremental resolution, ranging from 360 to 2048 counts per revolution (cpr).

The encoder provides A and B channel of incremental digital signal output, as well as a digital index pulse per revolution enabling the homing positioning operation. The three-channel solution comes with the optional RS422 compatible differential output offering the high transmission noise immunity for signal over cable.

To cater to a wide selection of industrial applications, this encoder is design to operate in a robust environment with the operating temperature ranging from -20°C to $+100^{\circ}\text{C}$.

The AS22 Series is designed for ease of use. The kit solution is engineered with the hassle-free installation, eliminating the need for a tedious alignment process.

Features

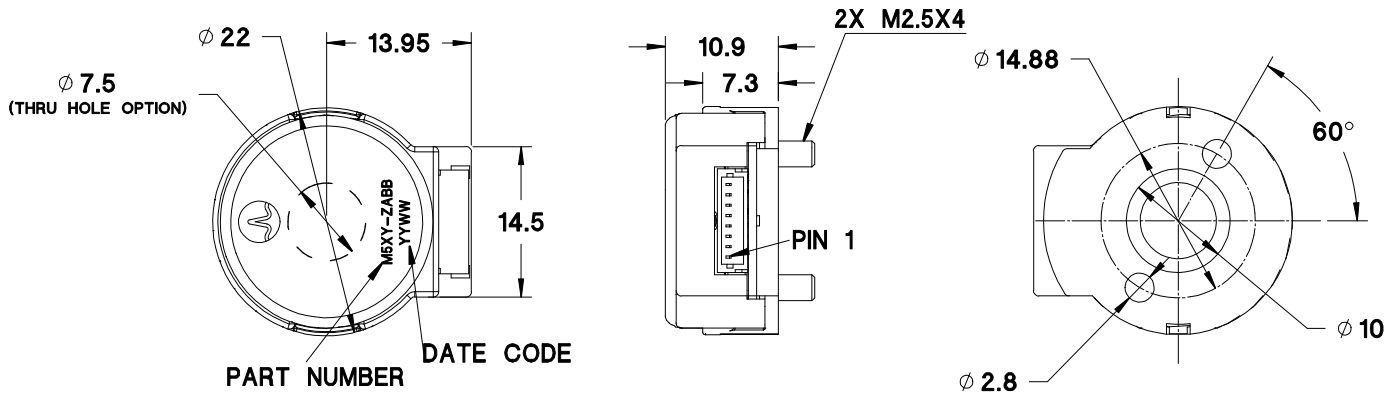
- Compact size $\text{Ø}22 \times 10.9$ mm
- 5V operating voltage
- -20°C to $+100^{\circ}\text{C}$ operating temperature
- Incremental A, B, and Index channels
- TTL and RS422 compatible differential output
- 360 cpr to 2048 cpr
- Shaft diameter from 2 mm up to $\frac{1}{4}$ "
- Spatial play tolerance of $\text{Ø}0.15$ mm
- Allows motor shaft axial play of ± 0.25 mm
- Hassles-free installation
- Rohs compliance

Applications

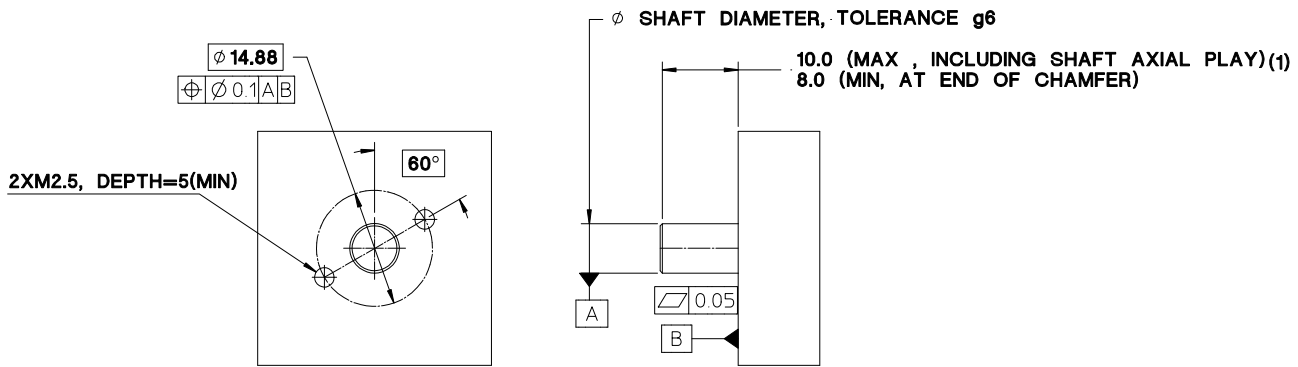
- Industrial automation and robotic
- Industrial sewing and textiles machinery
- Stepper/servo motor
- Factory automation

NOTE: This product is not specifically designed or manufactured for use in any specific device. Customers are solely responsible for determining the suitability of this product for its intended application and solely liable for all loss, damage, expense, or liability in connection with such use.

Package Dimensions



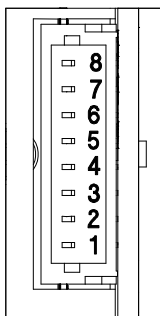
Mounting Considerations



All dimensions are in mm.

NOTE: 1. No maximum shaft length limit for cover with hole option.

Pin Configuration



| Pin | Differential | Single Ended (TTL) |
|----------------|--------------|--------------------|
| 1 | GND | GND |
| 2 | Ch A+ | Ch A+ |
| 3 | Ch A- | NA |
| 4 | Vcc | Vcc |
| 5 | Ch B+ | Ch B+ |
| 6 | Ch B- | NA |
| 7 ^a | Ch I+ | Ch I+ |
| 8 ^a | Ch I- | NA |

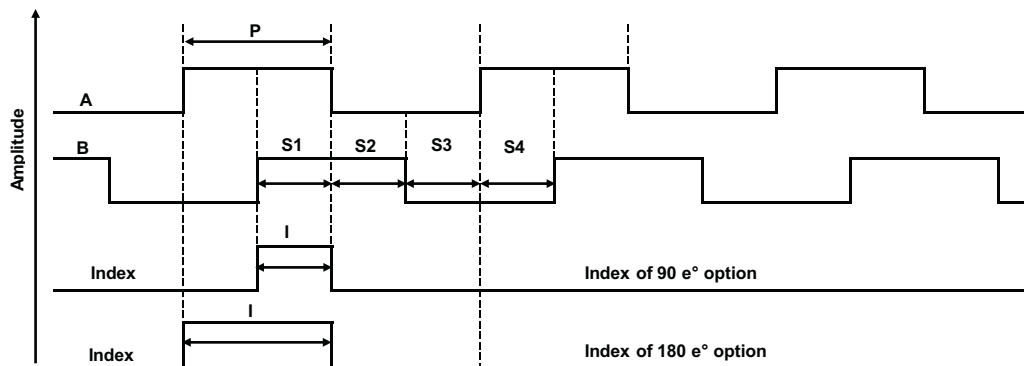
a. Only applicable to 3 channel options.

NOTE: Mating connector is JST Socket 08SR-3S, wire AWG #30 or JST SHR-08V-S-B/SHR-08V-S with contact SSH-003T-P0.2-H for wire AWG#32~28 .

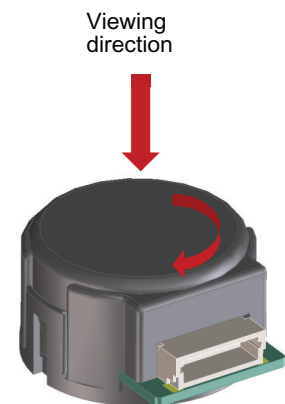
Absolute Maximum Ratings

| Parameter | |
|---|--|
| Storage Temperature, T_S | -40°C to +100°C |
| Operating Temperature, T_A | -20°C to +100°C |
| Supply Voltage, V_{CC} | -0.5V to +7V |
| Output Voltage, V_O | -0.5V to V_{CC} |
| Output Current per Channel, I_{OUT} (single ended) | ±1.5 mA |
| Output Current per Channel, I_{OUT} (differential line drivers) | ±20 mA |
| Vibration (JEDEC JESD22-B103) | 20G, 20 Hz to 2000 Hz |
| Mechanical Shock (JEDEC JESD22-B110) | 1500G (peak), 0.5-ms pulse duration, half sine |
| Relative Humidity | 60°C, 90%RH |
| ESD, IEC 61000-4-2, Air discharge (TTL and differential) | ±15 kV |

Output Waveform



Ch A leads Ch B for clockwise direction, viewed from cover side of the encoder



Recommended Operating Conditions

| Parameter | Sym. | Min. | Typ. | Max. | Unit | Notes |
|---------------------|----------|------|------|------------|------|-----------------------|
| Ambient Temperature | T_A | -20 | — | +100 | °C | |
| Supply Voltage | V_{CC} | 4.5 | 5.0 | 5.5 | V | Ripple < 100 mVp-p |
| Max RPM | | — | — | 4800k/cpr | | 360 cpr to 512 cpr |
| | | | | 9600k/cpr | | 1000 cpr and 1024 cpr |
| | | | | 19200k/cpr | | 2000 cpr and 2048 cpr |

Encoding Characteristics

Encoding characteristics over recommended operating range and recommended mounting tolerances unless otherwise specified.

| Parameter | Sym. | Min. | Typ. | Max. | Unit | Notes |
|-------------------------|------------|------|------|------|------|-----------------------|
| Pulse Width Error | ΔP | — | 10 | 20 | °e | 360 cpr to 512 cpr |
| | | — | 15 | 25 | °e | 1000 cpr and 1024 cpr |
| | | — | 20 | 45 | °e | 2000 cpr and 2048 cpr |
| Logic State Width Error | ΔS | — | 5 | 15 | °e | 360 cpr to 512 cpr |
| | | — | 10 | 25 | °e | 1000 cpr and 1024 cpr |
| | | — | 15 | 40 | °e | 2000 cpr and 2048 cpr |
| Index Width Error | ΔI | — | 5 | 40 | °e | 180°e index |
| | | — | 5 | 15 | °e | 90°e index |

Single-Ended Electrical Characteristics

Electrical characteristics over recommended operating condition at 25°C.

| Parameter | Sym. | Min. | Typ. | Max. | Unit | Notes |
|----------------------------|----------|------|------|------|------|---------------------|
| Supply Current | I_{CC} | — | 23 | 35 | mA | No load |
| High Level Output Voltage | V_{OH} | 2.4 | — | — | V | $I_{OH} = -1.5mA$ |
| Low Level Output Voltage | V_{OL} | — | — | 0.4 | V | $I_{OL} = +1.5mA$ |
| Output Current per Channel | I_O | — | — | 1.5 | mA | |
| Rise Time | t_r | — | <100 | — | ns | $C_L = 25 pF$ |
| Fall Time | t_f | — | <100 | — | ns | $R_L = 2.7 k\Omega$ |
| Rise Time | t_r | — | <65 | — | ns | No load |
| Fall Time | t_f | — | <90 | — | ns | |

Differential Electrical Characteristics

Electrical characteristics over recommended operating condition at 25°C.

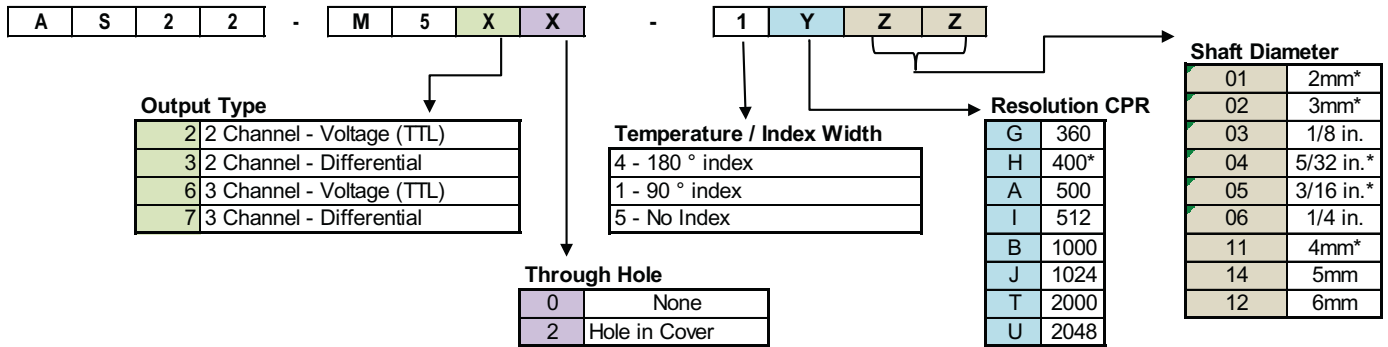
| Parameter | Sym. | Min. | Typ. | Max. | Unit | Notes |
|----------------------------|----------|------|------|------|------|------------------------|
| Supply Current | I_{CC} | — | 35 | 60 | mA | No load |
| High Level Output Voltage | V_{OH} | 2.4 | — | — | V | $I_{OH} = -20$ mA |
| Low Level Output Voltage | V_{OL} | — | — | 0.4 | V | $I_{OL} = +20$ mA |
| Output Current per Channel | I_O | — | — | 20 | mA | |
| Rise Time | t_r | — | <220 | — | ns | $C_L = 14$ pF |
| Fall Time | t_f | — | <150 | — | ns | $R_L = 2.7$ k Ω |
| Rise Time | t_r | — | <35 | — | ns | No load |
| Fall Time | t_f | — | <25 | — | ns | |

Mechanical Characteristics

| Parameter | Remark | Dimension | Tolerance | Unit |
|---|----------------------------|----------------------|----------------------------|-------------------|
| Code Wheel Shaft Diameter | | 2, 3, 4, 5, 6 | g6 | mm |
| | | 1/8, 5/32, 3/16, 1/4 | | in. |
| Max Shaft Length ^a | Including shaft axial play | 10(0.395) | — | mm |
| Min Shaft Length | End of shaft chamfer | 8.0(0.315) | — | mm |
| Shaft Axial Play | | — | ± 0.25 (± 0.01) | mm (in.) |
| Radial Play Including Shaft TIR | | — | $\varnothing 0.15$ (0.006) | mm (in.) |
| Max Moment of Inertia for Code Wheel Assembly | | 81.5 | — | g.mm ² |
| Hub Set Screw Torque | | 0.10 to 0.13 | — | N.m |
| Mounting Screw Torque (2x M2.5) | | 0.10 to 0.23 | — | N.m |

a. No limit for hole in cover option.

Ordering Information



* Check with Factory for availability