

LTC1661

FEATURES

- Tiny: Two 10-Bit DACs in an 8-Lead MSOP— Half the Board Space of an SO-8
- Micropower: 60µA per DAC Sleep Mode: 1µA for Extended Battery Life
- Rail-to-Rail Voltage Outputs Drive 1000pF
- Wide 2.7V to 5.5V Supply Range
- Double Buffered for Independent or Simultaneous DAC Updates
- Reference Range Includes Supply for Ratiometric 0V-to-V_{CC} Output
- Reference Input Has Constant Impedance over All Codes (260kΩ Typ)—Eliminates External Buffers
- 3-Wire Serial Interface with Schmitt Trigger Inputs
- Differential Nonlinearity: ≤±0.75LSB Max

APPLICATIONS

- Mobile Communications
- Digitally Controlled Amplifiers and Attenuators
- Portable Battery-Powered Instruments
- Automatic Calibration for Manufacturing
- Remote Industrial Devices

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Micropower Dual 10-Bit DAC in MSOP

DESCRIPTION

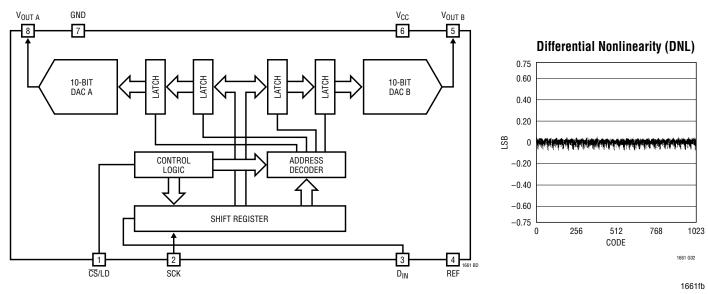
The LTC®1661 integrates two accurate, serially addressable, 10-bit digital-to-analog converters (DACs) in a single tiny MS8 package. Each buffered DAC draws just 60µA total supply current, yet is capable of supplying DC output currents in excess of 5mA and reliably driving capacitive loads up to 1000pF. Sleep mode further reduces total supply current to a negligible 1µA.

Linear Technology's proprietary, inherently monotonic voltage interpolation architecture provides excellent linearity while allowing for an exceptionally small external form factor. The double-buffered input logic provides simultaneous update capability and can be used to write to either DAC without interrupting sleep mode.

Ultralow supply current, power-saving sleep mode and extremely compact size make the LTC1661 ideal for battery-powered applications, while its straightforward usability, high performance and wide supply range make it an excellent choice as a general purpose converter.

For additional outputs and even greater board density, please refer to the LTC1660 micropower octal DAC for 10-bit applications. For 8-bit applications, please consult the LTC1665 micropower octal DAC.

BLOCK DIAGRAM



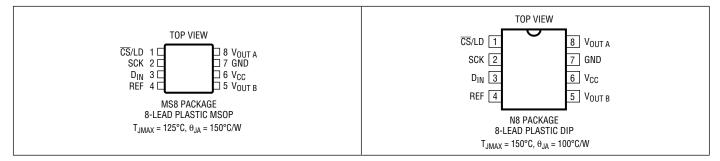


ABSOLUTE MAXIMUM RATINGS (Note 1)

Operating Temperature Range

LTC1661C	0°C to 70°C
LTC16611	. –40°C to 85°C
Lead Temperature (Soldering, 10 sec)	300°C

PIN CONFIGURATION



ORDER INFORMATION (http://www.linear.com/product/LTC1661#orderinfo)

Lead Free Finish

TUBE	TAPE AND REEL	PART MARKING	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC1661CMS8#PBF	LTC1661CMS8#TRPBF	LTDV	8-Lead Plastic MSOP	0°C to 70°C
LTC1661IMS8#PBF	LTC1661IMS8#TRPBF	LTDW	8-Lead Plastic MSOP	-40°C to 85°C
LTC1661CN8#PBF	LTC1661CN8#TRPBF	LTC1661CN8	8-Lead Plastic DIP	0°C to 70°C
LTC1661IN8#PBF	LTC1661IN8#TRPBF	LTC1661IN8	8-Lead Plastic DIP	-40°C to 85°C

Consult LTC Marketing for parts specified with wider operating temperature ranges.

For more information on lead free part marking, go to: http://www.linear.com/leadfree/

For more information on tape and reel specifications, go to: http://www.linear.com/tapeandreel/. Some packages are available in 500 unit reels through designated sales channels with #TRMPBF suffix.

ELECTRICAL CHARACTERISTICS The • denotes the specifications which apply over the full operating

temperature range, otherwise specifications are at $T_A = 25^{\circ}$ C. $V_{CC} = 2.7$ V to 5.5V, $V_{REF} \le V_{CC}$, V_{OUT} unloaded unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS					
Accuracy	icy										
	Resolution			10			Bits				
	Monotonicity	$1V \le V_{REF} \le V_{CC} - 0.1V$ (Note 2)	•	10			Bits				
DNL	Differential Nonlinearity	$1V \le V_{REF} \le V_{CC} - 0.1V$ (Note 2)	•		±0.1	±0.75	LSB				
INL	Integral Nonlinearity	$1V \le V_{REF} \le V_{CC} - 0.1V$ (Note 2)	•		±0.4	±2	LSB				
V _{OS}	Offset Error	Measured at Code 20	•		±5	±30	mV				
	V _{OS} Temperature Coefficient				±15		μV/°C				
FSE	Full-Scale Error	V _{CC} = 5V, V _{REF} = 4.096V	•		±1	±12	LSB				
	Full-Scale Error Temperature Coefficient			±30		μV/°C					



 $\label{eq:constraint} \begin{array}{l} \textbf{ELECTRICAL CHARACTERISTICS} \\ temperature range, otherwise specifications are at $T_A = 25^\circ C$. $V_{CC} = 2.7V$ to $5.5V$, $V_{REF} \leq V_{CC}$, V_{OUT} unloaded unless otherwise noted. \\ \end{array}$

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
PSR	Power Supply Rejection	V _{REF} = 2.5V			0.18		LSB/V
Reference	Input	I				Į	
	Input Voltage Range			0		V _{CC}	V
	Resistance	Active Mode	•	140	260		kΩ
	Capacitance				15		pF
I _{REF}	Reference Current	Sleep Mode			0.001	1	μA
Power Sup	ply					· · · ·	
V _{CC}	Positive Supply Voltage	For Specified Performance		2.7		5.5	V
I _{CC}	Supply Current	V _{CC} = 5V (Note 3) V _{CC} = 3V (Note 3) Sleep Mode (Note 3)		120 95 1	195 154 3	μΑ μΑ μΑ	
DC Perform	nance					· · ·	
	Short-Circuit Current Low	$V_{OUT} = 0V$, $V_{CC} = V_{REF} = 5V$, Code = 1023		10	25	100	mA
	Short-Circuit Current High	$V_{OUT} = V_{CC} = V_{REF} = 5V$, Code = 0		7	19	120	mA
AC Perform	nance						
	Voltage Output Slew Rate	Rising (Notes 4, 5) Falling (Notes 4, 5)			0.60 0.25		V/µs V/µs
	Voltage Output Settling Time	To ±0.5LSB (Notes 4, 5)			30		μs
	Capacitive Load Driving				1000		pF
Digital I/O		· ·				· · ·	
V _{IH}	Digital Input High Voltage	V _{CC} = 2.7V to 5.5V V _{CC} = 2.7V to 3.6V	•	2.4 2.0			V V
V _{IL}	Digital Input Low Voltage	V _{CC} = 4.5V to 5.5V V _{CC} = 2.7V to 5.5V	•			0.8 0.6	V V
I _{LK}	Digital Input Leakage	$V_{IN} = GND$ to V_{CC}	•			±10	μA
CIN	Digital Input Capacitance	(Note 6)				10	pF

TIMING CHARACTERISTICS range, otherwise specifications are at $T_A = 25^{\circ}C$. The \bullet denotes the specifications which apply over the full operating temperature

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{CC} = 4.5V	to 5.5V	I				· · ·	
t ₁	D _{IN} Valid to SCK Setup		•	40			ns
t ₂	D _{IN} Valid to SCK Hold		•	0			ns
t ₃	SCK High Time	(Note 6)	•	30	-		ns
t ₄	SCK Low Time	(Note 6)	•	30			ns
t ₅	CS/LD Pulse Width	(Note 6)	•	80			ns
t ₆	LSB SCK High to CS/LD High	(Note 6)	•	30			ns
t ₇	CS/LD Low to SCK High	(Note 6)	•	20			ns
t9	SCK Low to CS/LD Low	(Note 6)	•	0			ns
t ₁₁	CS/LD High to SCK Positive Edge	(Note 6)		20			ns
	SCK Frequency	Square Wave (Note 6)	•			16.7	MHz



TIMING CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$.

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{CC} = 2.7V	to 5.5V					I	
t ₁	D _{IN} Valid to SCK Setup	(Note 6)	•	60			ns
t ₂	D _{IN} Valid to SCK Hold	(Note 6)	•	0			ns
t ₃	SCK High Time	(Note 6)	•	50			ns
t ₄	SCK Low Time	(Note 6)	•	50			ns
t ₅	CS/LD Pulse Width	(Note 6)	•	100			ns
t ₆	LSB SCK High to CS/LD High	(Note 6)	•	50			ns
t ₇	CS/LD Low to SCK High	(Note 6)	•	30			ns
t ₉	SCK Low to CS/LD Low	(Note 6)	•	0			ns
t ₁₁	CS/LD High to SCK Positive Edge	(Note 6)	•	30			ns
	SCK Frequency	Square Wave (Note 6)	•			10	MHz

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: Nonlinearity and monotonicity are defined from code 20 to code 1023 (full scale). See Applications Information.

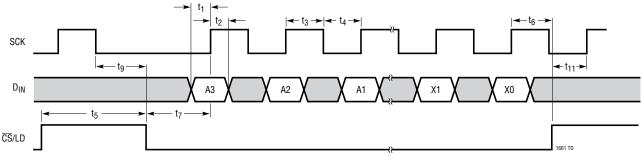
Note 3: Digital inputs at OV or V_{CC}.

Note 4: Load is $10k\Omega$ in parallel with 100pF.

Note 5: $V_{CC} = V_{REF} = 5V$. DAC switched between $0.1V_{FS}$ and $0.9V_{FS}$, i.e., codes k = 102 and k = 922.

Note 6: Guaranteed by design and not subject to test.

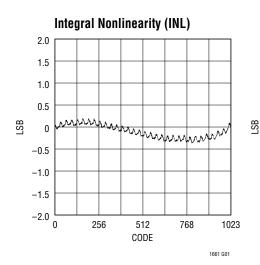
TIMING DIAGRAM

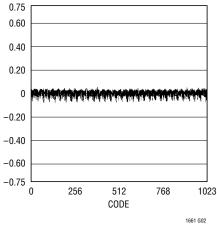




1661 G03

TYPICAL PERFORMANCE CHARACTERISTICS





Mid-Scale Output Voltage

vs Load Current

 $V_{REF} = V_{CC}$ CODE = 512

3.0

2.9

2.8

2.7

2.6

2.5

2.4

2.3

2.2

2.1

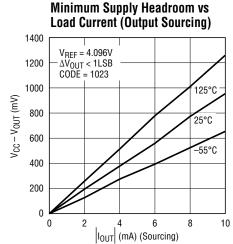
2.0

1661 G04

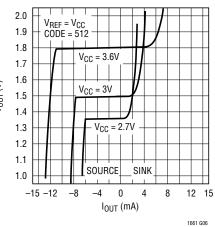
-30

-20

Differential Nonlinearity (DNL)



Mid-Scale Output Voltage vs Load Current

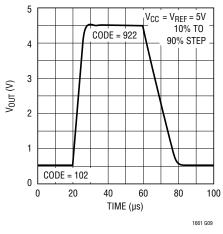


Vout (V)

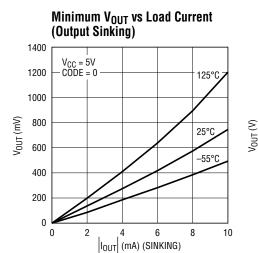
V_{CC} = 5.5V $V_{CC} = 5V$ $V_{CC} = 4.5V$ SOURCE SINK 20 -10 0 10 30 I_{OUT} (mA)

1661 G05

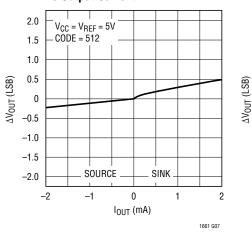
Large-Signal Step Response



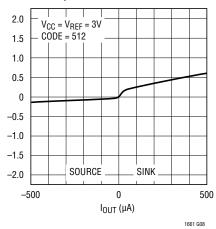
1661fb



Load Regulation vs Output Current



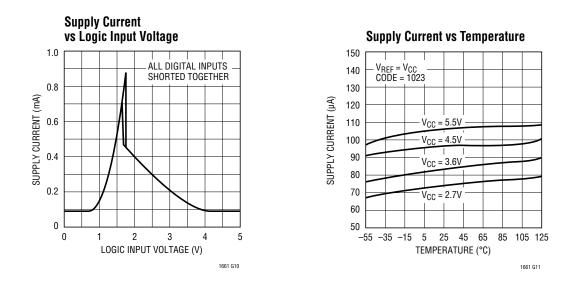








TYPICAL PERFORMANCE CHARACTERISTICS



PIN FUNCTIONS

CS/LD (Pin 1): Serial Interface Chip Select/Load Input. When \overline{CS}/LD is low, SCK is enabled for shifting data on D_{IN} into the register. When \overline{CS}/LD is pulled high, SCK is disabled and the operation(s) specified in the control code, A3-A0, is (are) performed. CMOS and TTL compatible.

SCK (Pin 2): Serial Interface Clock Input. CMOS and TTL compatible.

 D_{IN} (Pin 3): Serial Interface Data Input. Input word data on the D_{IN} pin is shifted into the 16-bit register on the rising edge of SCK. CMOS and TTL compatible.

REF (Pin 4): Reference Voltage Input. $0V \le V_{REF} \le V_{CC}$.

V_{OUT A}, **V_{OUT B}** (**Pin 8**, **Pin 5**): DAC Analog Voltage Outputs. The output range is

$$0 \le V_{\text{OUTA}}, V_{\text{OUTB}} \le V_{\text{REF}} \left(\frac{1023}{1024}\right)$$

V_{CC} (Pin 6): Supply Voltage Input. $2.7V \le V_{CC} \le 5.5V$. **GND (Pin 7):** System Ground.



DEFINITIONS

Differential Nonlinearity (DNL): The difference between the measured change and the ideal 1LSB change for any two adjacent codes. The DNL error between any two codes is calculated as follows:

$$\mathsf{DNL} = \frac{\Delta \mathsf{V}_{\mathsf{OUT}} - \mathsf{LSB}}{\mathsf{LSB}}$$

where ΔV_{OUT} is the measured voltage difference between two adjacent codes.

Full-Scale Error (FSE): The deviation of the actual full-scale voltage from ideal. FSE includes the effects of offset and gain errors (see Applications Information).

Integral Nonlinearity (INL): The deviation from a straight line passing through the endpoints of the DAC transfer curve (endpoint INL). Because the output cannot go below zero, the linearity is measured between full scale and the lowest code which guarantees the output will be greater than zero. The INL error at a given input code is calculated as follows:

$$INL = \frac{V_{OUT} - V_{OS} - (V_{FS} - V_{OS}) \left(\frac{Code}{1023}\right)}{LSB}$$

where $V_{\mbox{OUT}}$ is the output voltage of the DAC measured at the given input code.

Least Significant Bit (LSB): The ideal voltage difference between two successive codes.

$$LSB = \frac{V_{REF}}{1024}$$

Resolution (n): Defines the number of DAC output states (2n) that divide the full-scale range. Resolution does not imply linearity.

Voltage Offset Error (V_{OS}): Nominally, the voltage at the output when the DAC is loaded with all zeros. A single supply DAC can have a true negative offset, but the output cannot go below zero (see Applications Information).

For this reason, single supply DAC offset is measured at the lowest code that guarantees the output will be greater than zero.





OPERATION

Transfer Function

The transfer function for the LTC1661 is:

$$V_{OUT(DEAL)} = \left(\frac{k}{1024}\right) V_{REF}$$

where k is the decimal equivalent of the binary DAC input code D9-D0 and V_{REF} is the voltage at REF (Pin 6).

Power-On Reset

The LTC1661 positively clears the outputs to zero scale when power is first applied, making system initialization consistent and repeatable.

Power Supply Sequencing

The voltage at REF (Pin 4) must not ever exceed the voltage at V_{CC} (Pin 6) by more than 0.3V. Particular care should be taken in the power supply turn-on and turn-off sequences to assure that this limit is observed. See Absolute Maximum Ratings.

Serial Interface

See Table 1. The 16-bit Input word consists of the 4-bit Control code, the 10-bit Input code and two don't-care bits. **Table 1. LTC1661 Input Word**

_															
A3	A2	A1	A0	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	X1	X0
CONTROL CODE INPUT CODE											N'T RF				

After the Input word is loaded into the register (see Figure 1), it is internally converted from serial to parallel format. The parallel 10-bit-wide input code data path is then buffered by two latch registers.

The first of these, the input register, is used for loading new input codes. The second buffer, the DAC register, is used for updating the DAC outputs. Each DAC has its own 10-bit input register and 10-bit DAC register. By selecting the appropriate 4-bit control code (see Table 2) it is possible to perform single operations, such as loading one DAC or changing power-down status (sleep/wake). In addition, some Control codes perform two or more operations at the same time. For example, one such code loads DAC A, updates both outputs and wakes the part up. The DACs can be loaded separately or together, but the outputs are always updated together.

Register Loading Sequence

See Figure 1. With $\overline{\text{CS}}/\text{LD}$ held low, data on the D_{IN} input is shifted into the 16-bit shift register on the positive edge of SCK. The 4-bit control code, A3-A0, is loaded first, then the 10-bit Input code, D9-D0, ordered MSB-to-LSB in each case. Two don't-care bits, X1 and X0, are loaded last. When the full 16-bit Input word has been shifted in, $\overline{\text{CS}}/\text{LD}$ is pulled high, causing the system to respond according to Table 2. The clock is disabled internally when $\overline{\text{CS}}/\text{LD}$ is high. Note: SCK must be low when $\overline{\text{CS}}/\text{LD}$ is pulled low.

Sleep Mode

DAC control code 1110_b is reserved for the special sleep instruction (see Table 2). In this mode, the digital parts of the circuit stay active while the analog sections are disabled; static power consumption is greatly reduced. The reference input and analog outputs are set in a high impedance state and all DAC settings are retained in memory so that when Sleep mode is exited, the outputs of DACs not updated by the wake command are restored to their last active state.

Sleep mode is initiated by performing a load sequence using control code 1110_b (the DAC input code D9-D0 is ignored).

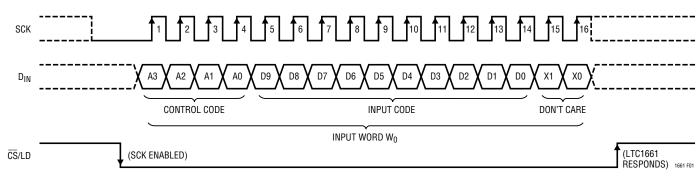
To save instruction cycles, the DACs may be prepared with new input codes during Sleep (control codes 0001_b and 0010_b); then, a single command (1000_b) can be used both to wake the part and to update the output values.



OPERATION

Table 2. DAC Control Functions

	CONTROL			INPUT REGISTER	DAC REGISTER	POWER-DOWN STATUS	
A3	A2	A1	AO	STATUS	STATUS	(SLEEP/WAKE)	COMMENTS
0	0	0	0	No Change	No Update	No Change	No Operation. Power-Down Status Unchanged (Part Stays in Wake or Sleep Mode)
0	0	0	1	Load DAC A	No Update	No Change	Load Input Register A with Data. DAC Outputs Unchanged. Power-Down Status Unchanged
0	0	1	0	Load DAC B	No Update	No Change	Load Input Register B with Data. DAC Outputs Unchanged. Power-Down Status Unchanged
0	0	1	1		Reserved		
0	1	0	0		Reserved		
0	1	0	1		Reserved		
0	1	1	0		Reserved		
0	1	1	1		Reserved		
1	0	0	0	No Change	Update Outputs	Wake	Load Both DAC Regs with Existing Contents of Input Regs. Outputs Update. Part Wakes Up
1	0	0	1	Load DAC A	Update Outputs	Wake	Load Input Reg A. Load DAC Regs with New Contents of Input Reg A and Existing Contents of Reg B. Outputs Update. Part Wakes Up
1	0	1	0	Load DAC B	Update Outputs	Wake	Load Input Reg B. Load DAC Regs with Existing Contents of Input Reg A and New Contents of Reg B. Outputs Update. Part Wakes Up
1	0	1	1		Reserved		
1	1	0	0		Reserved		
1	1	0	1	No Change	No Update	Wake	Part Wakes Up. Input and DAC Regs Unchanged. DAC Outputs Reflect Existing Contents of DAC Regs
1	1	1	0	No Change	No Update	Sleep	Part Goes to Sleep. Input and DAC Regs Unchanged. DAC Outputs Set to High Impedance State
1	1	1	1	Load DACs A, B with Same 10-Bit Code	Update Outputs	Wake	Load Both Input Regs. Load Both DAC Regs with New Contents of Input Regs. Outputs Update. Part Wakes Up







OPERATION

Voltage Outputs

Each of the rail-to-rail output amplifiers contained in the LTC1661 can typically source or sink up to 5mA ($V_{CC} = 5V$). The outputs swing to within a few millivolts of either supply when unloaded and have an equivalent output resistance of 85 Ω (typical) when driving a load to the rails. The output amplifiers are stable driving capacitive loads up to 1000pF.

A small resistor placed in series with the output can be used to achieve stability for any load capacitance. A 1 μ F load can be successfully driven by inserting a 20 Ω resistor in series with the V_{OUT} pin. A 2.2 μ F load needs only a 10 Ω resistor, and a 10 μ F electrolytic capacitor can be used without any resistor (the equivalent series resistance of the capacitor itself provides the required small resistance). In any of these cases, larger values of resistance, capacitance or both may be substituted for the values given.

Rail-to-Rail Output Considerations

In any rail-to-rail DAC, the output swing is limited to voltages within the supply range.

If the DAC offset is negative, the output for the lowest codes limits at OV as shown in Figure 2b.

Similarly, limiting can occur near full scale when the REF pin is tied to V_{CC}. If V_{REF} = V_{CC} and the DAC full-scale error (FSE) is positive, the output for the highest codes limits at V_{CC} as shown in Figure 2c. No full-scale limiting can occur if V_{REF} is less than V_{CC} – FSE.

Offset and linearity are defined and tested over the region of the DAC transfer function where no output limiting can occur.

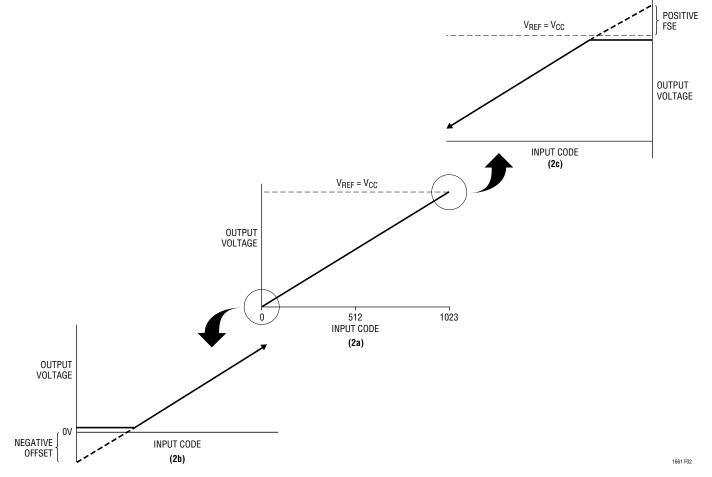
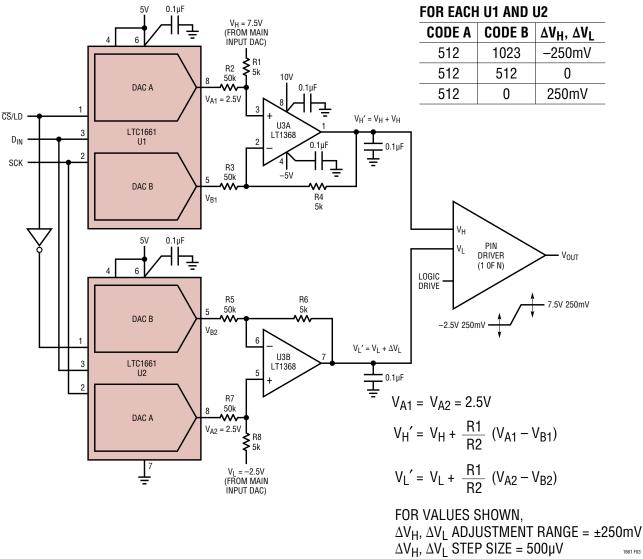


Figure 2. Effects of Rail-to-Rail Operation On a DAC Transfer Curve. (2a) Overall Transfer Function (2b) Effect of Negative Offset for Codes Near Zero Scale (2c) Effect of Positive Full-Scale Error for Input Codes Near Full Scale When $V_{REF} = V_{CC}$





TYPICAL APPLICATIONS





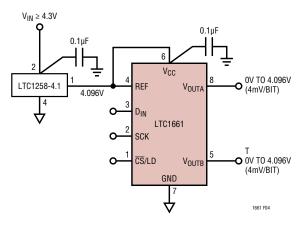
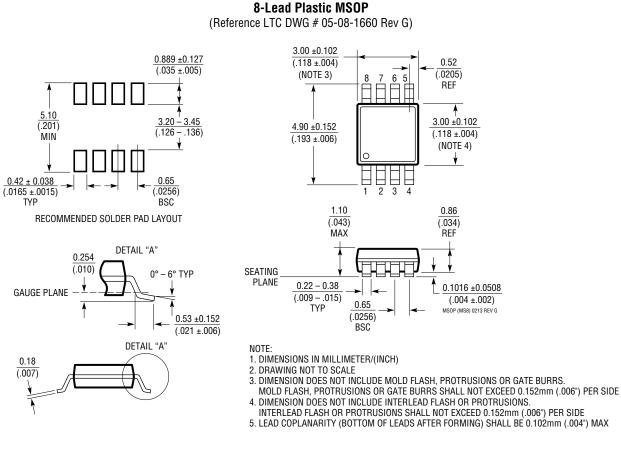


Figure 4. Using the LTC1258 and the LTC1661 In a Single Li-Ion Battery Application



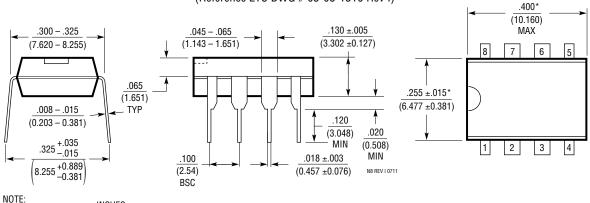
PACKAGE DESCRIPTION

Please refer to http://www.linear.com/product/LTC1661#packaging for the most recent package drawings.



MS8 Package

N Package 8-Lead PDIP (Narrow .300 Inch) (Reference LTC DWG # 05-08-1510 Rev I)



1. DIMENSIONS ARE <u>INCHES</u> MILLIMETERS

*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .010 INCH (0.254mm)



REVISION HISTORY

REV	DATE	DESCRIPTION	PAGE NUMBER
Α	11/10	Removed typical values from Timing Characteristics section	3, 4
В	4/16	Corrected typo for V _{CC} under Power Supply	3

