



## Features

- Incremental encoder / quadrature output
- Exceptionally long operating life
- Sturdy construction
- Bushing mount
- Available with PC board mounting bracket (optional)
- RoHS compliant\*

## ECW - Digital Contacting Encoder

### Electrical Characteristics

Output	2-bit quadrature code, Channel A leads Channel B by 90° electrically turning clockwise (CW)
Closed Circuit Resistance	5 ohms maximum
Open Circuit Resistance	100 K ohms minimum
Contact Rating	10 milliamp @ 10 VDC or 0.1 watt maximum
Insulation Resistance (500 VDC)	1,000 megohms minimum
Dielectric Withstanding Voltage (MIL-STD-202 Method 301)	
Sea Level	1,000 VAC minimum
Electrical Travel	Continuous
Contact Bounce (15 RPM)	5 milliseconds maximum
RPM (Operating)	120 maximum
Phase Tolerance (CH A to CH B)	90° ± 72°

### Environmental Characteristics

Operating Temperature Range	-40 °C to +85 °C (-40 °F to 185 °F)
Storage Temperature Range	-40 °C to +85 °C (-40 °F to +185 °F)
Humidity	MIL-STD-202, Method 103B, Condition B
Vibration	15 G
Contact Bounce	0.1 millisecond maximum
Shock	50 G
Contact Bounce	0.1 millisecond maximum
Rotational Life	200,000 shaft revolutions
IP Rating	IP 40

### Mechanical Characteristics

Mechanical Angle	Continuous
Running Torque (Detented)	0.5 to 1.5 N-cm (0.75 to 2.25 oz-in.)
Undetented Torque	0.17 to 1.0 N-cm (0.25 to 1.50 oz-in.)
Mounting Torque	79 N-cm (7 lb.-in.) maximum
Shaft Side Load (Static)	4.5 kg (10 lbs.) minimum
Weight	Approximately 21 gms. (0.75 oz.)
Terminals	PC pin or solder lug
Soldering Condition	
Manual Soldering	96.5Sn/3.0Ag/0.5Cu solid wire or no-clean rosin cored wire 370 °C (700 °F) max. for 3 seconds
Wave Soldering	96.5Sn/3.0Ag/0.5Cu solder with no-clean flux 260 °C (500 °F) max. for 5 seconds
Wash processes	Not recommended
Marking	Manufacturer's name and trademark, part number, and date code.
Hardware	One lockwasher and one mounting nut are shipped with each encoder, except where noted in the part number.

### Quadrature Output Table – This table is intended to show available outputs as currently defined.



### RECOMMENDED INCREMENTAL CONTROL DIAGRAM FOR USE WITH A DEBOUNCE CIRCUIT



\*RoHS Directive 2002/95/EC Jan. 27, 2003 including annex and RoHS Recast 2011/65/EU June 8, 2011.

Specifications are subject to change without notice.

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# ECW - Digital Contacting Encoder

# BOURNS®

## Dimensional Drawings

### BUSHING MOUNTED - HOUSING A Rear-Facing Terminals



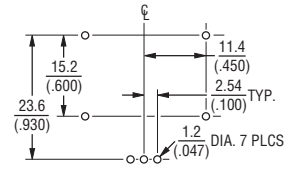
### PANEL HOLE DIMENSIONS Bushing Mounted



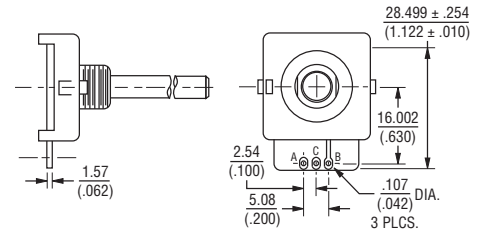
### PCB BRACKET MOUNTED - HOUSING B Dimensions not given are the same as Bushing Mounted.



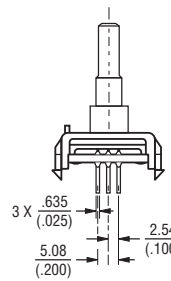
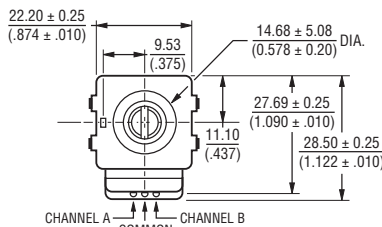
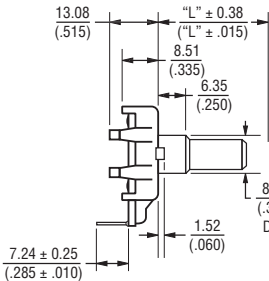
### PCB MOUNTING DIMENSIONS (Housing Styles B and E)



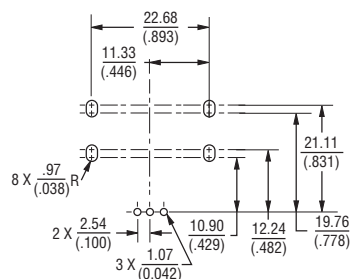
### SOLDER HOLES - HOUSING C Dimensions not given are the same as Bushing Mounted.



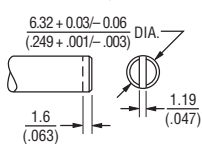
### SNAP-IN MOUNT - Housing G



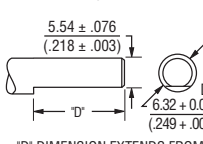
### PCB MOUNTING DIMENSIONS



### Shaft Style B

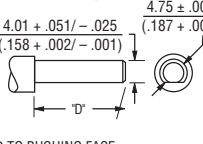


### Shaft Style C

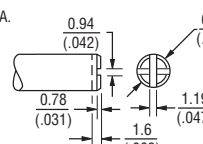


"D" DIMENSION EXTENDS FROM SHAFT END TO BUSHING FACE  
 "D" = (SHAFT LENGTH, FMS) - (BUSHING LENGTH)

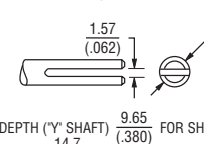
### Shaft Style J



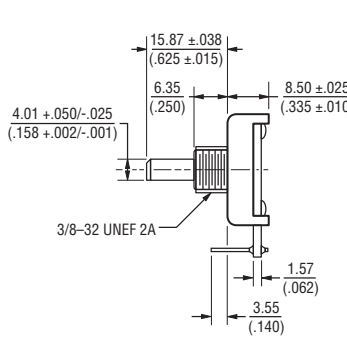
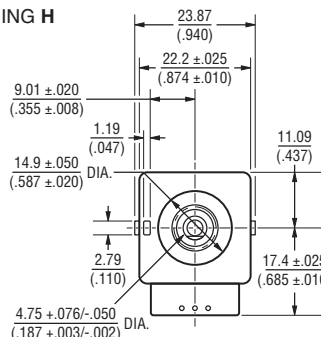
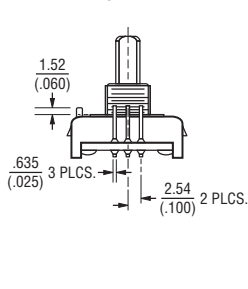
### Shaft Style R



### Shaft Style Y



### BUSHING MOUNTED - HOUSING H Front-Facing Terminals

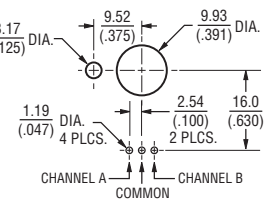


### FOR TOLERANCES NOT SHOWN

.XX ± .25  
 (.010) .XXX ± .13  
 (.005)

SHAFT DIMENSIONS ± 1/32"

DIMENSIONS: MM  
 (IN)



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