

FEATURES

Complete 16-channel, 12-bit/16-bit DACs 8 software-programmable output ranges: −20 V to 0 V, −16 V to 0 V, −10 V to 0 V, −10 V to +6 V, −12 V to +14 V, −16 V to +10 V, ±5 V and ±10 V Integrated DAC output buffers with ±20 mA output current capability 4 mm × 4 mm WLCSP package and 40-lead LFCSP package Integrated reference buffers 2 dither signal input pins Channel monitoring multiplexer 1.8 V logic compatibility Temperature range: −40°C to +105°C APPLICATIONS

Mach Zehnder modulator bias control Optical networking Instrumentation Industrial automation Data acquisition systems Analog output modules

GENERAL DESCRIPTION

The AD5766/AD5767 are 16-channel, 16-bit/12-bit, voltage output denseDAC® digital-to-analog converters (DACs).

The DACs generate output voltage ranges from an external 2.5 V reference. Depending on the voltage range selected, the midpoint of the output span can be adjusted, allowing a minimum output

16-Channel, 16-Bit/12-Bit Voltage Output denseDACs

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voltage as low as −20 V or a maximum output voltage of up to +14 V. Each of the 16 channels can be monitored with an integrated output voltage multiplexer.

The AD5766/AD5767 have integrated output buffers that can sink or source up to 20 mA. In conjunction with these buffers, a low frequency signal can be superimposed onto each DAC output via dedicated dither pins. These dedicated dither pins simplify the system design by reducing the number of external components required for a similar external implementation, like operational amplifiers or resistors. The reduction of external components makes the AD5766/AD5767 suitable for indium phosphide Mach Zehnder modulator (InP MZM) biasing applications.

The devices incorporate a power-on reset (POR) circuit that ensures that the DAC outputs are clamped to ground on power up and remain at this level until the output range of the DAC is configured. The outputs of all DACs are updated through register configuration, with the added functionality of user-selectable DAC channels to be simultaneously updated.

The AD5766/AD5767 use a versatile 4-wire serial interface that operates at clock rates of up to 50 MHz for write mode and is compatible with serial peripheral interface (SPI), QSPI™, MICROWIRE™, and DSP interface standards. The AD5766/ AD5767 also contain a V_{LOGIC} pin intended for 1.8 V/3.3 V/5 V logic.

The AD5766/AD5767 are available in a 4 mm \times 4 mm WLCSP package and a 40-lead LFCSP package. The AD5766/AD5767 operate at a temperature range of −40°C to +105°C.

FUNCTIONAL BLOCK DIAGRAM

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AD5766/AD5767

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REVISION HISTORY

10/2017—Rev. A to Rev. B

4/2017—Rev. 0 to Rev. A

1/2017—Revision 0: Initial Version

SPECIFICATIONS

 $AV_{CC} = 2.97$ V to 3.6 V, $V_{LOGIC} = 1.7$ V to 5.5 V, $AV_{DD} = 2.97$ V to 16 V, $AV_{SS} = -22$ V to -7 V, $AGND = DGND = 0$ V, $V_{REF} = 2.5$ V, output range = \pm 5 V, V_{OUT}x unloaded, all specifications T_{MIN} to T_{MAX}, typical specifications at T_A = 25°C, dither powered on, unless otherwise noted.

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¹ Output amplifier headroom requirement is 2 V minimum.

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 $AV_{CC} = 2.97$ V to 3.6 V, $V_{LOGIC} = 1.7$ V to 5.5 V, $AV_{DD} = 2.97$ V to 16 V, $AV_{SS} = -22$ V to -7 V, $AGND = DGND = 0$ V, $V_{REF} = 2.5$ V, output range = ±5 V, V_{OUT}x unloaded, all specifications T_{MIN} to T_{MAX}, typical specifications at T_A = 25°C, dither powered off, unless otherwise noted.

AC PERFORMANCE CHARACTERISTICS

 $AV_{CC} = 2.97$ V to 3.6 V, $V_{LOGIC} = 1.7$ V to 5.5 V, $AV_{DD} = 2.97$ V to 15 V, $AV_{SS} = -22$ V to -7 V, $AGND = DGND = 0$ V, $V_{REF} = 2.5$ V, output range = -10 V to 0 V, V_{OUT}x unloaded, all specifications T_{MIN} to T_{MAX}, typical specifications at T_A = 25°C, dither powered on, analog dither signals not applied, unless otherwise noted.

Table 3.

¹ DAC code = midscale. AV_{DD} = V_{OUT_MAX} + 2 V. AV_{SS} = V_{OUT_MIN} − 2 V. ² 0.1 Hz to 10 Hz. AV_{DD} = V_{OUT_MAX} + 2 V. AV_{SS} = V_{OUT_MIN} − 2 V.

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TIMING CHARACTERISTICS

All input signals are specified with $t_R = t_F = 1$ ns/V (10% to 90% of AV_{DD}) and timed from a voltage level of (V_{IL} + V_{IH})/2. See [Figure 2,](#page-8-1) [Figure 3,](#page-9-0) and [Figure 4.](#page-9-1) AV_{CC} = 2.97 V to 3.6 V, V_{LOGIC} = 1.7 V to 5.5 V, V_{REF} = 2.5 V, all specifications −40°C to +105°C, dither powered on, unless otherwise noted.

¹ Maximum SCLK frequency is 50 MHz for write mode and 10 MHz for readback mode.

² Minimum time between a reset and the subsequent successful write is typically 25 ns.

³ C_{L_SDO} is the capacitive load on the SDO output.

Timing Diagrams

Figure 2. Serial Interface Timing Diagram

Figure 4. Readback Timing Diagram

ABSOLUTE MAXIMUM RATINGS

 $T_A = 25$ °C, unless otherwise noted. Transient currents of up to 100 mA do not cause silicon controlled rectifier (SCR) latch-up.

Table 5.

¹ The digital inputs include RESET, SCLK, SYNC, and SDI.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.

 θ_{JA} is the natural convection junction to ambient thermal resistance measured in a one cubic foot sealed enclosure.

Table 6. Thermal Resistance

¹ Thermal impedance simulated values are based on JEDEC 2S2P thermal test board with 16 thermal vias. See JEDEC JESD51.

ESD CAUTION

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

NOTES
1. DINC = DO NOT CONNECT. DO NOT CONNECT TO THESE PINS
2. NIC = NO INTERNAL CONNECTION. THESE PINS SHOULD BE
1. ROUTED TO THERMAL VIAS ON THE PCB TO AID WITH HEAT
DISSIPATION. CONNECT THESE PINS TO GROUND. 15145-005 15145-005

Figure 5. WLCSP Package Pin Configuration

Table 7. 49-Ball WLCSP Pin Function Descriptions

Pin No.	Mnemonic	Description
Dither		
F ₁	N ₀	Dither Signal Input Pin 0. A signal connected to this pin can be added to the DAC outputs via register commands. If unused, connect this pin to ground. Refer to the Dither section for more information.
E ₁	N ₁	Dither Signal Input Pin 1. A signal connected to this pin can be added to the DAC outputs via register commands. If unused, connect this pin to ground. Refer to the Dither section for more information.
Logic Inputs and Outputs		
E7	SCLK	Serial Clock Input. Data is clocked into the input shift register on the falling edge of the serial clock input. Data can be transferred at rates of up to 50 MHz for write mode and 10 MHz for readback and daisy-chain mode.
F ₇	SYNC	Active Low Control Input. SYNC is the frame synchronization signal for the input data. When SYNC goes low, it powers on the SCLK and SDI buffers and enables the input shift register. Data is transferred in on the falling edges of the next 24 clocks. If $\overline{\text{SYNC}}$ is taken high before the 24 th falling edge, the rising edge of SYNC acts as an interrupt, and the write sequence is ignored by the device.
C ₇	SDI	Serial Data Input. This device has a 24-bit shift register. Data is clocked into the register on the falling edge of the serial clock input.
E ₆	SDO	Serial Data Output. This pin clocks data from the serial register in daisy-chain or readback mode. Data is clocked out on the rising edge of SCLK and is valid on the falling edge of SCLK.
B7	RESET	Active Low Reset Input. Asserting this pin logic low returns the AD5766/AD5767 to the default power-on state. After this pin returns to logic high, the device comes out of the reset mode and is ready to accept a new SPI command. This pin can be left floating, because there is a weak internal pull-up resistor.
Analog Outputs		
B ₃	$V_{\text{OUT}}0$	Analog Output Voltage from DAC 0.
A2	$V_{\text{OUT}}1$	Analog Output Voltage from DAC 1.
A ₃	V _{OUT} 2	Analog Output Voltage from DAC 2.
B4	V _{OUT} 3	Analog Output Voltage from DAC 3.
A4	V _{OUT} 4	Analog Output Voltage from DAC 4.
A ₅	V_{OUT}	Analog Output Voltage from DAC 5.
A ₆	Vout ₆	Analog Output Voltage from DAC 6.

No Internal Connection C2 to C4, D2 to D6,

E2 to E5

NIC No Internal Connection. Route these pins to thermal vias on the PCB to aid with heat

dissipation. Connect these pins to ground.

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Figure 6. LFCSP Package Pin Configuration

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TYPICAL PERFORMANCE CHARACTERISTICS

Figure 7. AD5766 INL Error vs. DAC Code (Unipolar Output)

Figure 8. AD5767 INL Error vs. DAC Code (Unipolar Output)

Figure 9. AD5766 INL Error vs. DAC Code (Bipolar Outputs)

Figure 10. AD5767 INL Error vs. DAC Code (Bipolar Outputs)

Figure 11. AD5766 DNL Error vs. DAC Code (Bipolar Outputs)

Figure 12. AD5767 DNL Error vs. DAC Code (Bipolar Outputs)

Figure 13. AD5766 DNL Error vs. DAC Code (Unipolar Outputs)

Figure 14. AD5767 DNL Error vs. DAC Code (Unipolar Outputs)

Figure 15. Total Unadjusted Error (TUE) vs. DAC Code (Unipolar Outputs)

Figure 16. Total Unadjusted Error (TUE) vs. DAC Code (Bipolar Outputs)

Figure 18. DNL Error vs. Temperature

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OUTPUT CURRENT (mA)

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4 \mathbf{I} **±5V RANGE 3 AVDD/AVSS = RANGE ± 2V 0x0000 TO 0xFFFF DITHER ON 2 LFCSP PACKAGE** V_{OUTX} (mV) **VOUTx (mV) 1 0 –1 –2 –3** 15145-237 15145-237 **0 10 20 30 40 50 60 70 80 TIME (µs)**

Figure 37. Analog Crosstalk for LFCSP Package (Dither Enabled)

Figure 38. Analog Crosstalk for WLCSP Package (Dither Disabled)

Figure 40. DAC-to-DAC Crosstalk for WLCSP Package (Dither Enabled)

Figure 41. DAC-to-DAC Crosstalk for LFCSP Package (Dither Enabled)

Figure 42. DAC-to-DAC Crosstalk for WLCSP Package (Dither Disabled)

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Figure 50. Supply Current (AI_{DD}) vs. Supply Voltage (AV_{DD})

Figure 54. Supply Current (AISS) vs. Code

Figure 55. Logic Current (ILOGIC) vs. Logic Input Voltage (VLOGIC)

Figure 56. Supply Current vs. Temperature

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DITHER CHARACTERISTICS

Figure 57. Transient on Dither Selected Channel (Dither Enabled)

Figure 58. Transient on Nondither Selected Channel (Dither Enabled)

Figure 59. Transient on Dither Selected Channel (Dither Disabled)

Figure 60. Transient on Nondither Selected Channel (Dither Disabled)

Figure 62. Dither Input to DAC Output Attenuation vs. Frequency (±5 V Range and −10 V to 0 V Range)

Figure 63. Dither Input to DAC Output Attenuation vs. Frequency (±10 V Range and −20 V to 0 V Range)

Figure 64. Dither Input to DAC Output Attenuation vs. Frequency (−10 V to +6 V Range and −16 V to 0 V Range)

Figure 65. Dither Input to DAC Output Attenuation vs. Frequency (−12 V to +14 V Range and −16 V to +10 V Range)

Figure 66. Total Harmonic Distortion (THD) vs. Frequency

Figure 67. Dither Input to DAC Output Phase Shift vs. Frequency

TERMINOLOGY

Total Unadjusted Error (TUE)

Total unadjusted error is a measure of the output error taking all the various errors into account, namely INL error, offset error, gain error, and output drift over supplies, temperature, and time. TUE is expressed in % FSR.

Relative Accuracy or Integral Nonlinearity (INL)

Relative accuracy or integral nonlinearity is a measurement of the maximum deviation, in LSBs, from a straight line passing through the endpoints of the DAC transfer function. Typical INL error vs. DAC code plots are shown i[n Figure 7](#page-15-1) and [Figure 10.](#page-15-2)

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between the measured change and the ideal 1 LSB change between any two adjacent codes. A specified differential nonlinearity of ±1 LSB maximum ensures monotonicity. This DAC is guaranteed monotonic by design. Typical DNL error vs. DAC code plots are shown in [Figure 12](#page-15-3) an[d Figure 14.](#page-16-0)

Zero-Scale Error

Zero-scale error is a measurement of the output error when zero code (0x0000) is loaded to the DAC register. Zero code error is expressed in mV.

Zero-Scale Error Temperature Coefficient

Zero code error drift is a measure of the change in zero code error with a change in temperature. It is expressed in μ V/°C.

Bipolar Zero Error

Bipolar zero error is the deviation of the analog output from the ideal half-scale output of 0 V when the DAC register is loaded with 0x2000.

Bipolar Zero Error Temperature Coefficient

Bipolar zero drift is a measure of the change in the bipolar zero error with a change in temperature. It is expressed in μ V/°C.

Gain Error

Gain error is a measure of the span error of the DAC. It is the deviation in slope of the DAC transfer characteristic from the ideal expressed as % FSR.

Gain Error Temperature Coefficient

Gain temperature coefficient is a measurement of the change in gain error with changes in temperature. It is expressed in ppm of FSR/°C.

Offset Error

Offset error is a measurement of the difference between V_{OUT} x (actual) and V_{OUTX} (ideal), expressed in mV, in the linear region of the transfer function. Offset error can be negative or positive.

Offset Error Drift

Offset error drift is a measurement of the change in offset error with a change in temperature. It is expressed in μ V/°C.

Dither DC Shift

Dither dc shift is a measurement of the dc voltage difference between V_{OUTX} (actual) and V_{OUTX} (ideal) due to the coupling of a dither tone to the analog output. It is expressed in LSB.

Dither Transient

Dither transient is the amplitude of the impulse injected into the analog outputs due to the enabling or disabling of the dither functionality on an output channel. The transients are measured the selected output channel and the other nonselected channels. It is specified in nV-sec.

DC Power Supply Rejection Ratio (PSRR)

PSRR indicates how the output of the DAC is affected by changes in the supply voltage. PSRR is the ratio of the change in V_{OUTX} to a change in AV_{DD} for a full-scale output of the DAC. It is measured in V/V.

Output Voltage Settling Time

Output voltage settling time is the amount of time it takes for the output of a DAC to settle to a specified level for a 1/4 to 3/4 full-scale input change and is measured from the rising edge of SYNC.

Digital-to-Analog Glitch Impulse

Digital-to-analog glitch impulse is the impulse injected into the analog output when the input code in the DAC register changes state. It is normally specified as the area of the glitch in nV-sec, and is measured when the digital input code is changed by 1 LSB at the major carry transition (0x7FFF to 0x800 for the AD5767 and 0x7FFF to 0x8000 for the AD5766).

Digital Feedthrough

Digital feedthrough is a measure of the impulse injected into the analog output of the DAC from the digital inputs of the DAC, but is measured when the DAC output is not updated. It is specified in nV-sec, and measured with a full-scale code change on the data bus, that is, from all 0s to all 1s and vice versa.

DC Crosstalk

DC crosstalk is the dc change in the output level of one DAC in response to a change in the output of another DAC. It is measured with a full-scale output change on one DAC (or power-down and power-up) while monitoring another DAC maintained at midscale. It is expressed in μV.

DC crosstalk due to load current change is a measure of the impact that a change in load current on one DAC has to another DAC kept at midscale. It is expressed in μV/mA.

Digital Crosstalk

Digital crosstalk is the glitch impulse transferred to the output of one DAC at midscale in response to a full-scale code change (all 0s to all 1s and vice versa) in the input register of another DAC. It is measured in standalone mode and is expressed in nV-sec.

Analog Crosstalk

Analog crosstalk is the glitch impulse transferred to the output of one DAC due to a change in the output of another DAC. It is measured by loading one of the input registers with a full-scale code change (all 0s to all 1s and vice versa), then executing a software LDAC command (se[e Table 21\)](#page-34-3), and monitoring the output of the DAC whose digital code was not changed. The area of the glitch is expressed in nV-sec.

DAC-to-DAC Crosstalk

DAC-to-DAC crosstalk is the glitch impulse transferred to the output of one DAC due to a digital code change and subsequent analog output change of another DAC. It is measured by loading the attack channel with a full-scale code change (all 0s to all 1s and vice versa), using the write to and update commands while monitoring the output of the victim channel that is at midscale. The energy of the glitch is expressed in nV-sec.

Output Noise Spectral Density

Output noise spectral density is a measurement of the internally generated random noise. Random noise is characterized as a spectral density (nV/ \forall Hz). It is measured by loading the DAC to midscale and measuring noise at the output. It is measured in nV/ \sqrt{Hz} .

THEORY OF OPERATION **DIGITAL-TO-ANALOG CONVERTER**

The AD5766/AD5767 are 16-channel, 16-bit/12-bit, serial input, voltage output DACs capable of providing multiple output ranges with ±20 mA output current capability. The available output voltage ranges are as follows:

- -20 V to 0 V
- −16 V to 0 V
- −10 V to 0 V
- -10 V to +6 V
- −12 V to +14 V
- -16 V to $+10$ V
- $±5 V$
- ± 10 V

The devices operate from four supply voltages: AV_{CC} , AV_{DD} , AV_{SS}, and V_{LOGIC}. AV_{CC} is the power supply input voltage for the DACs and other low voltage circuitry, whereas AV_{DD} and AVss are the positive and negative analog supplies for the output amplifiers. The output amplifiers require +2 V of headroom and −2 V of footroom to drive 20 mA with a minimum output voltage error of less than 1 LSB. [Table 9](#page-28-5) shows the power supply requirements for the selected output range. VLOGIC defines the logic levels for the digital input and output signals.

Table 9. Power Supply Requirements for the Selected Output Range

DAC ARCHITECTURE

The architecture of one DAC channel consists of a resistor string DAC followed by an output buffer amplifier. The voltage at the VREF pin provides the reference voltage for the all DAC channels[. Figure 68](#page-28-6) shows a block diagram of the DAC architecture.

Figure 68. DAC Architecture

The input coding to the DAC is straight binary, the ideal output voltage is given by

$$
V_{OUT} = \left(Span \times \frac{D}{N}\right) + V_{MIN}
$$

where:

Span is the full extent of the DAC output voltage range from the minimum to the maximum limit.

D is the decimal equivalent of the binary code that is loaded to the DAC register.

N is 4096 for the AD5767 (12-bit version), and 65536 for the AD5766 (16-bit version).

VMIN is the lowest voltage of the span.

RESISTOR STRING

The resistor string section is shown in [Figure 69.](#page-28-7) It is a simplified resistor string structure, each of Value R. The digital code loaded to the DAC register determines at which node on the string the voltage is connected to be fed into the output amplifier. The voltage is tapped off by closing one of the switches connecting the string to the amplifier. Because a string of resistors is used, the DAC is guaranteed to be monotonic.

POWER-ON RESET (POR)

The AD5766/AD5767 contain a POR circuit that controls the output voltage during power-up. The AD5766/AD5767 outputs are clamped to ground at power-up and remain powered up at this level until a valid write sequence is made to the span register to configure the output range of the DAC. At power-on, the dither functionality is also enabled.

A software executable reset function resets the DAC to the power-up state. Command 0111 is reserved for this reset function (see [Table 30\)](#page-36-2). A minimum time is required between a reset and a successful write (see the timing characteristics in [Table 4\)](#page-8-2). [Figure 70](#page-29-0) shows the programming sequence to follow to configure the AD5766/AD5767 upon power-on.

Figure 70. Programming Sequence to Write/Enable the AD5766/AD5767 Outputs

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DITHER

External dither signals can be coupled onto any DAC output by writing the appropriate value to the dither registers. The dither signals are applied to the N0 and N1 input pins (see [Figure 71\)](#page-30-3). If dither is not required, connect these pins to AGND. The dither signals amplitude have a maximum peak-to-peak voltage (ac voltage) of 0.25 V p-p, and the absolute input voltage (ac and dc voltage) must not exceed the range of 0 V to AV_{CC} . The dither signals can be attenuated and/or inverted internally on a per channel basis if required. Dither signals in the range of 10 kHz to 100 kHz can be applied to the dither input pins. Due to the nature of the internal dither circuitry, the dc value of the output can shift (se[e Table 1\)](#page-3-1) and the shift can be compensated for. For the recommended configuration of the dither functionality, see th[e Applications](#page-39-0) Information section.

DITHER POWER-DOWN MODE

The AD5766/AD5767 contain a dither block power-down mode per channel. Command 0101 is reserved for the powerdown function (se[e Table 10\)](#page-32-2). The power-down mode is software-programmable by setting four bits, Bit D19 to Bit D16, in the power control register. To address the dither block power-down per channel function, D19 to D16 must be set to 0001 (se[e Table 26\)](#page-35-3)[. Table 27](#page-35-4) shows how the state of the Bit D16 corresponds to the mode of operation of the device. The dither functionality of any or all DACs can be powered down to the selected mode by setting the corresponding 16 bits (D15 to D0) to 1.

Ensure that all channels are powered up before writing to the span register.

MONITOR MUX

The AD5766/AD5767 contain a channel monitor function that consists of an analog multiplexer addressed via the serial interface, allowing any channel output to be routed to the common MUX_OUT pin for external monitoring.

Because the MUX_OUT pin is not buffered, the amount of current drawn from this pin creates a voltage drop across the switches, which in turn leads to an error in the voltage being monitored. Therefore, the MUX_OUT pin must be connected to only high impedance inputs or externally buffered.

Figure 71. Dither Signal Generation

SERIAL INTERFACE

The AD5766/AD5767 4-wire (SYNC, SCLK, SDI, and SDO) interface is compatible with SPI, QSPI, and MICROWIRE interface standards as well as most digital signal processors (DSPs). The write sequence begins after bringing the SYNC line low, maintaining this line low until the complete data-word is loaded from the SDI pin. Data is loaded into the AD5766/AD5767 at the SCLK falling edge transition (see [Figure 2\)](#page-8-1). When a rising edge is detected on $\overline{\text{SYNC}}$, the serial data-word is decoded according to the instructions i[n Table 10.](#page-32-2) The command must be a multiple of 24; otherwise, the device ignores the command. The AD5766/AD5767 contain an SDO pin to allow the user to daisy-chain multiple devices together or to read back the contents of the status register.

Readback Operation

The contents of the status registers can be read back via the SDO pin[. Figure 4 s](#page-9-1)hows how the registers are decoded. After a register has been addressed for a read, the next 24 clock cycles clock the data out on the SDO pin. The clocks must be applied while SYNC is low. For a read of a single register, the no operation (NOP) function clocks out the data. Alternatively, if more than one register is to be read, the data of the first register to be addressed clocks out at the same time that the second register to be read is being addressed.

Daisy-Chain Operation

Daisy chaining minimizes the number of port pins required from the controlling IC. As shown in [Figure 72,](#page-31-1) the SDO pin of one package must be tied to the SDI pin of the next package. To enable daisy-chain mode, the DC_EN bit i[n Table 15](#page-34-4) must be high. When two AD5766/AD5767 devices are daisy-chained, 48 bits of data are required. The first 24 bits are assigned to U2, and the second 24 bits are assigned to U1, as shown i[n Figure 72.](#page-31-1) Keep the SYNC pin low until all 48 bits are clocked into their respective serial registers.

The $\overline{\text{SYNC}}$ pin is then pulled high to complete the operation.

To prevent data from mislocking (for example, due to noise) the device includes an internal counter; if the SCLK falling edges count is not a multiple of 24, the device ignores the command. A valid clock count is 24, 48, 72, and so on. The counter resets when SYNC returns high.

Daisy-chain mode is disabled by default and is enabled using the daisy-chain control register (see [Table 15\)](#page-34-4).

Figure 72. Daisy-Chain Block Diagram

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REGISTER DETAILS **INPUT SHIFT REGISTER**

The input shift register of the AD5766/AD5767 are 24 bits wide. Data is loaded MSB first (D23). The first four bits are the command bits, C3 to C0 (see [Figure 73\)](#page-32-3), followed by the 4-bit DAC address bits (se[e Table 11\)](#page-33-1), and finally the data bits. The 24-bit data-word is transferred to the input register on the 24 falling edges of SCLK and are updated on the rising edge of SYNC.

Table 10. Command Definitions1

¹ X means don't care.

² Se[e Table 11](#page-33-1) for the address bit setting.

[Table 11](#page-33-1) shows the DAC x address commands. For applications using the WLCSP package that do not require all 16 channels, do not use Channel 8 because it is more sensitive to crosstalk and digital feedthrough.

Table 11. DAC x Address Commands

MONITOR MUX CONTROL

The monitor mux control command determines whether one of the DAC outputs or none is switched out on the MUX_OUT pin depending on the desired D[4:0] value. To assert the no operation command, write all zeros to the D15 to D0 bits.

Table 12. Monitor Mux Control Register

Table 13. Output Voltage Selection from Mux

¹ X means don't care.

NO OPERATION

Writing all zeros does not vary the state of the device.

Table 14. No Operation Register

DAISY-CHAIN MODE

To use the daisy-chain mode, enable the DC_EN bit in the daisy-chain control register. This bit is linked to the internal SDO buffer. If the functionality is not required, set the DC_EN bit to 0 to save the power consumed by the SDO buffer.

Table 15. Daisy-Chain Control Register

Table 16. Daisy-Chain Enable/Disable Bit Description

WRITE AND UPDATE COMMANDS

Write to DAC x Input Register

This command allows the user to write to the dedicated input register of each DAC individually. The output of the DAC does not change its value until a write to the software LDAC register occurs with the appropriate bit set to include the addressed channel in the update.

Table 17. AD5766 Write to DAC x Input Register

Table 18. AD5767 Write to DAC x Input Register

Write to Input Register and DAC Register

This command writes directly to the selected DAC register and updates the output accordingly.

Table 19. AD5766 Write to DACx Input and DAC Register

Table 20. AD5767 Write to DACx Input and DAC Register

Software LDAC Register

This command copies data from the selected input registers to the corresponding DAC registers and the outputs update accordingly.

Table 21. Software LDAC Register

Table 22. LDAC Bit Description

SPAN REGISTER

This register selects the output span of the AD5766/AD5767. Se[e Table 24](#page-35-5) and [Table 25.](#page-35-6) Always issue a software reset before writing to the span register.

Table 23. Span Register

Table 24. Span Selection

Table 25. Power-Up Condition Selection

DITHER POWER CONTROL REGISTER

The dither power control register with D[19:16] = 0001 powers up or powers down the dither functionality of the individual DACs. It is recommended to power down the selected channel dither block during the first write to the AD5766/AD5767 if no dither tone is input on to the dither inputs N0 or N1.

Table 26. Dither Power Control Register

Table 27. Dither Power Control

WRITE INPUT DATA TO ALL DAC REGISTERS

This command writes the data in D[15:0] to the DAC register of all DACs and sets all DAC outputs to the same value. For the AD5766/AD5767, the data is written in D[15:0] for the 16-bit resolution DAC and in D[15:4] for the 12-bit resolution version.

Table 28. AD5766 Write Input Data to All DAC Registers

Table 29. AD5767 Write Input Data to All DAC Registers

SOFTWARE FULL RESET

Writing 0x1234 initiates a reset routine, which returns the AD5766/AD5767 to the power-on state.

SELECT REGISTER FOR READBACK

This command selects which registers to read back (se[e Table 31\)](#page-36-3). After issuing this command, the contents of the selected registers are clocked out on the SDO on the next 24-bit frame (se[e Table 32\)](#page-36-4).

Table 31. Initiate Readback Register

Table 32. Readback Data Register

Table 33. Readback Register Data Functions

APPLY N0 OR N1 DITHER SIGNAL TO DACs REGISTER

These commands determine which dither signal, N0 or N1, is applied to the selected DACs. Couple the dither signals to the AD5766/ AD5767 outputs after the dither signals are configured and the clamp to ground is removed by writing to the span register. Refer to the [Applications](#page-39-0) Information section for a more information.

Table 34. Apply N0 or N1 Dither Signal to DACs Register (DAC 7 to DAC 0)

Table 35. Apply N0 or N1 Dither Signal to DACs Register (DAC 15 to DAC 8)

[Table 36](#page-37-2) shows the dither scaling setting using Bits[D15:D14] as an example. To apply the N0 dither to DAC 7 (se[e Table 34\)](#page-37-3), set D15 to 0 and D14 to 1. The same dither selection settings apply to the other bits, Bits[D13:D12], Bits[D11:D10], Bits[D9:D8], Bits[D7:D6], Bits[D5:D4], Bits[D3:D2], and Bits[D1:D0] i[n Table 34](#page-37-3) an[d Table 35.](#page-37-4)

Table 36. Dither Selection for DAC x (DAC 0 to DAC 15)

DITHER SCALE

This command scales the dither before it is applied to the selected channel.

Table 37. Dither Scaling Register (DAC 7 to DAC 0)

Table 38. Dither Scaling Register (DAC 15 to DAC 8)

[Table 39](#page-37-5) shows the dither scaling setting using Bits[D15:D14] as an example. To apply 25% scaling to DAC 7 (se[e Table 37\)](#page-37-6), set D15 to 1 and D14 to 1. The same dither scaling settings apply to the other bits, Bits[D13:D12], Bits[D11:D10], Bits[D9:D8], Bits[D7:D6], Bits[D5:D4], Bits[D3:D2], and Bits[D1:D0] i[n Table 34](#page-37-3) an[d Table 35.](#page-37-4)

Table 39. Apply Dither Signal to DAC x (DAC 0 to DAC 15)

INVERT DITHER REGISTER

This command inverts the dither applied to the selected DACs when the appropriate bit is set to 0.

Table 40. Invert Dither Register

Table 41. Invert Dither

APPLICATIONS INFORMATION **DITHER CONFIGURATION**

The AD5766/AD5767 contain two dither input pins to allow dither tone signals to be coupled to any of the 16 DAC output channels.

Operate the AD5766/AD5767 using the dither functionality to minimize the transient amplitude seen on the DAC outputs when the dither functionality is enabled or disabled. The recommended configuration of the dither functionality is as follows:

- 1. After the AD5766/AD5767 power up, the input dither signals must be configured by writing to the dither scale register and the invert dither register if required.
- 2. Configure the AD5766/AD5767 in normal operating mode before applying dither by programming the span register.
- 3. Write to the apply N0 or N1 dither signal to DACs register to couple the N0/N1 input dither signals to any DAC output, V_{OUT} x.

Enabling the dither feature on a channel can increase its sensitivity to digital feedthrough.

THERMAL CONSIDERATIONS

Up to ±20 mA can be sourced from each channel on the AD5766/AD5767; thus, it is important to understand the effects of power dissipation on the package and its effects on junction temperature. The internal junction temperature must not exceed 150°C. The AD5766/AD5767 are packaged in a 49-ball, 4 mm \times 4mm WLCSP and a 40-lead 6 mm \times 6 mm LFCSP package. The thermal impedance, θ_{JA} , is specified in the [Absolute Maximum Ratings s](#page-10-0)ection. It is important that the device is not operated under conditions that cause the junction temperature to exceed the maximum temperature specified in the [Absolute Maximum Ratings s](#page-10-0)ection.

The [Thermal Calculation Example \(WLCSP\) s](#page-39-5)ection details how to calculate the die temperature and maximum permitted ambient temperature. The quiescent current of the AV_{DD}, AV_{SS}, AV_{CC} , and V_{LOGIC} pins must also be included in the calculation of the junction temperature. These calculations use the typical supply currents specified i[n Table 1.](#page-3-1)

Thermal Calculation Example (WLCSP)

For this thermal calculation example, all 16 channels are enabled with the ±10 V output voltage range used. Each channel is drawing 2 mA for a +1V output voltage.

$$
AVDD = Span + 2 V = 12 V
$$

$$
AVSS = Span - 2 V = -12 V
$$

$$
AVCC = VLOGIC = 3.3 V
$$

where *Span* is the output voltage range, ±10 V.

The current required to supply 16 channels (output power) is

 $2 \text{ mA} \times 16 = 32 \text{ mA}$

The power required on the AV_{DD} rail for the AD5766/AD5767 to supply the 16 channels and 6 mA typical supply current is

 $12 \text{ V} \times (32 \text{ mA} + 6 \text{ mA}) = 0.456 \text{ W}$

Next, add power dissipated by the AVss, AV_{CC}, and V_{LOGIC} rails (input power) as follows:

 0.456 W + (−12 V × −9 mA) + (3.3 V × 8.3 mA) + (3.3 V × $0.02 \mu A$ = 0.59 W

To calculate the power dissipated by the AD5766/AD5767, use the following equation:

PDISS = *Input Power* − *Output Power*

For example,

 $0.59 W - (32 mA \times 1 V) = 0.558 W$

Then, calculate the die temperature,

 $0.558 \text{ W} \times 53^{\circ} \text{C/W} = 29.57^{\circ} \text{C}$

Using the following equation to calculate the maximum permitted ambient temperature:

TA MAX = *TJ MAX* − *Die Temperature*

For example,

 150° C – 29.57° = 120°C

The θ_{JA} specification assumes that proper layout and grounding techniques are followed to minimize power dissipation, as outlined in the [Layout Guidelines](#page-40-0) section

MICROPROCESSOR INTERFACING

Microprocessor interfacing to the AD5766/AD5767 is via a serial bus that uses a standard protocol compatible with DSPs and microcontrollers. The communications channel requires a 4-wire serial interface consisting of a clock signal, a data input signal, a data output signal, and a synchronization signal. The device requires a 24-bit data-word with data valid on the falling edge of SCLK.

AD5766/AD5767 TO SPI INTERFACE

The SPI interface of the AD5766/AD5767 is designed to be easily connected to industry-standard DSPs and microcontrollers. [Figure 74](#page-39-6) shows the AD5766/AD5767 connected to the Analog Devices, Inc.[, ADSP-BF531](http://analog.com/ADSP-BF531?doc=AD5766-5767.pdf) Blackfin® DSP. The Blackfin has an integrated SPI port that can be connected directly to the SPI pins of the AD5766/AD5767.

Figure 74[. ADSP-BF531 S](http://analog.com/ADSP-BF531?doc=AD5766-5767.pdf)PI Interface

Data Sheet [AD5766](http://www.analog.com/AD5766?doc=AD5766-5767.pdf)[/AD5767](http://www.analog.com/AD5767?doc=AD5766-5767.pdf) Noted AD5766/AD5767 Noted AD5766/AD5767 Noted AD5766/AD5767

LAYOUT GUIDELINES

In any circuit where accuracy is important, careful consideration of the power supply and ground return layout helps to ensure the rated performance. The PCB on which the AD5766/AD5767 are mounted must be designed so that the AD5766/AD5767 lay on the analog plane. Ensure that the board has separate analog and digital sections. If the AD5766/AD5767 are in a system where other devices require an AGND to DGND connection, make the connection at one point only. Keep this ground point as close as possible to the AD5766/AD5767.

The AD5766/AD5767 must have ample supply bypassing of 10 μ F in parallel with 0.1μ F on each supply, located as close to the package as possible, ideally right up against the device. The 10 µF capacitors are the tantalum bead type. The 0.1 µF capacitor must have low effective series resistance (ESR) and low effective series inductance (ESI). Ceramic capacitors, for example, provide a low impedance path to ground at high frequencies to handle transient currents due to internal logic switching.

Ensure that the power supply line has as large a trace as possible to provide a low impedance path and reduce glitch effects on the supply line. Shield clocks and other fast switching digital signals from other parts of the board by using a digital ground. Avoid crossover of digital and analog signals if possible. When traces cross on opposite sides of the board, ensure that they run

at right angles to each other to reduce feedthrough effects through the board. The best board layout technique is the microstrip technique, where the component side of the board is dedicated to the ground plane only, and the signal traces are placed on the solder side. However, this technique is not always possible with a 2-layer board.

It is often useful to provide some heat sinking capability to allow the power to dissipate easily.

For the WLCSP package, heat is transferred through the solder balls to the PCB board. θ_{JA} thermal impedance is dependent on board construction. More copper layers enable heat to be removed more effectively.

The LFCSP package of the AD5766/AD5767 have an exposed pad beneath the device. Connect this pad to the AV_{SS} supply of the device. For optimum performance, use special consideration when designing the motherboard and mounting the package. For enhanced thermal, electrical, and board level performance, solder the exposed pad on the bottom of the package to the corresponding thermal land pad on the PCB. Design thermal vias into the PCB land pad area to improve heat dissipation further.

The AV_{SS} plane on the device can be increased (as shown in [Figure 75\)](#page-40-1) to provide a natural heat sinking effect.

Figure 75. Exposed Pad Connection to Board

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OUTLINE DIMENSIONS

