To: OurPCB Tech. Ltd.

Issue No.

: RV-V-EVE-0087

Date of Issue: 13th. Apr .2020

Classification

■New □ Change

Product Description:

: 11mm GS ENCODER

Product Part Number

: Panasonic Part Number EVEUPCAH508B

Country of Origin

: VIETNAM (Indicated on the packing label in English)

Applications

Provisional Product Specification

Panasonic Industrial Devices Vietnam

Prepared by

: Technical Section

Co.,Ltd.

Plot J1-J2, Thang Long Industrial Park, Kim Chung commune, Dong Anh District, Hanoi,

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REVISION'S CAREER SHEET

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| ISSUE | PAGE | REVISIONS | DATE | DESIGN | CHECK | APPROVAL |
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1. Notification items.

1.1 Information of Chemical Substance and Environmental Hazardous Substances.

-This product has not been manufactured with ozone depleting chemical controlled under the Montoreal

—This product complies with the RoHs Directive (Restriction of the use of certain Hazadous Substance in

electrical and electronic equipment (DIRECTIVE 2011/65/EU as amended by EU2015/863). The material used in product contain only the substances listed in the List of existing Chemical Substances specified in 'Act on the Evaluation of Chemical Substances and regulation of Their Manufacture, etc'.

1.2 Limitation of Application

- This product has been designed and manufactured for general electronic devices, such as home electronics, office equipment, information devices and communication devices. In an event that this product is used for more sophisticated applications requiring higher safety and reliability and its failure or malfunction of this product may impose damage to human life or property, agreement on product specifications for approval suitable for such applications are required.

Such applications shall include the following:

Aircraft equipment, aerospace equipment, disaster prevention / crime prevention equipment, medical equipment, transportation equipment (vehicles, trains, ships, etc.), information processing equipment that are highly publicized, and other equivalent equipment

. Regardless of its applications, in an event that this product is used for the equipment requiring high safety levels, place protective circuits or redundant circuits and perform safety tests to

improve your products' safety.

1.3 Export control
When going through export procedures, please comply with laws and regulations related to export control such as Foreign Exchange and Foreign Trade Law.

1.4 Handling of provisional specification

Since the contents of this reference specification are subject to change without prior notifications. Please request us a formal specification again for your investigation before using.

1.5 Manufacturing sites Production country

Viet Nam

Production factory : Panasonic Industrial Devices Vietnam Co.,Itd Address factory : Plot J1, J2 Thang Long Industrial Pack, Dong Anh District, Hanoi, VietNam

2.1 This specification applied to rotary encoder used in electronic equipment.

- 2.2 This specification is a constituent document of contact for business concluded between your company and Panasonic Corporation.
- 2.3 Item not particularly specified in this specification shall be in conformance with JIS Standards.

2. Application Notes:

- 1. Avoid storing the products in a placeat high temperature and high humidity and in corrosive gases.
- 2. The encoder's pulse count method should be designed with taking operating speed, sampling time, and the design of the microcomputer software, etc. into consideration.

3. Prohibited items on fire and smoking

Absolutely avoid use of a product beyond its rated range because doing so may cause a

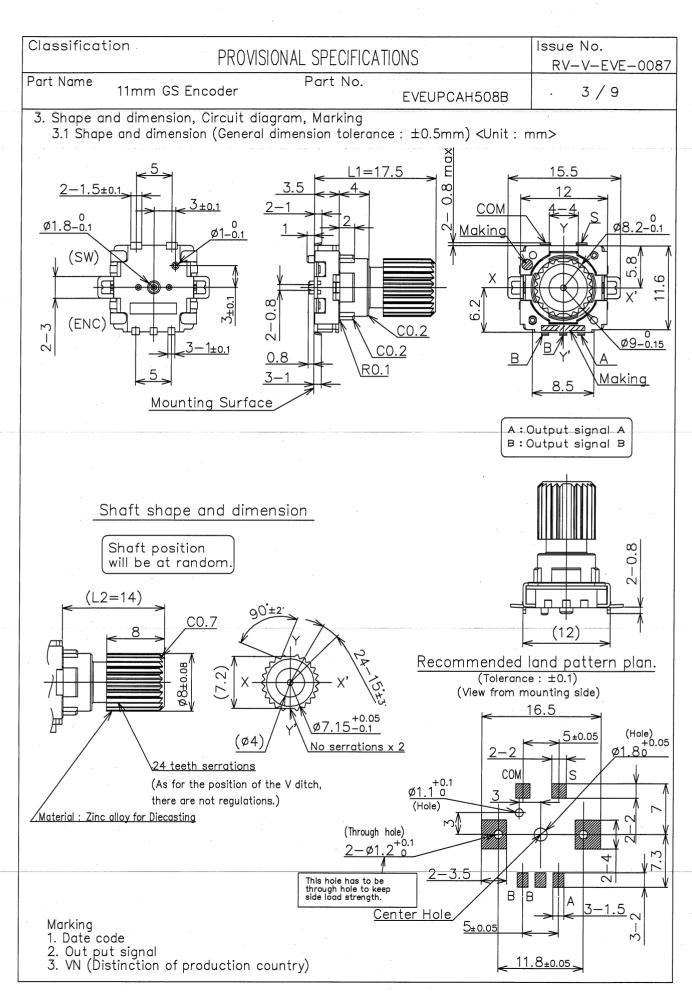
If misuse or abnormal use may result in conditions in whith the encoder is used out of its rated range, take proper measures such sa current interruption using a protective circuit.

Please do not use the product in any location or circumstances where spreading fire may occur, or necessary measure against spreading fire if use in such locations or circumstances

4. For use in equipment for which safty requested

Although care is taken to encoder quality, inferior characteristics, short circuits, open circuits are some problems that might be generated. To design a set which places maximam emphasis on safety, review the affect of any single fault of a encoder in advance and perform virtually fail—safe design to ensure maximum safety by:

-Preparing a protective circuit or a protective device to improve system safety, and -Preparing a redundant circuit to improve system safety so that the signal fault of a product. Encoder dose not cause a dangerous situation.



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4.General

4.1 Standard atmospheric conditions : Unless otherwise specified. The standard range

of atmospheric conditions for making measurements

and tests is as follows.

Ambient temperature : $15 \,^{\circ}\text{C} \sim 35 \,^{\circ}\text{C}$ Relative humidity : $25\% \sim 75\%$

Air pressure : 86kPa ~ 106kPa

4.2 Operating temperature range : $-40^{\circ}\text{C} \sim +85^{\circ}\text{C}$ 4.3 Storage temperature range : $-40^{\circ}\text{C} \sim +85^{\circ}\text{C}$

4.4 Rated voltage : Encoder D.C 10V

Switch D.C 16V

4.5 Rated current : Encoder D.C 1mA

Switch D.C 20mA

5.Performance

5.1 Mechanical performance(Encoder part)

| | ltem | | Conditions | | Specifications |
|---|-------|-----------------------------------|---|-------------|--|
| Ī | 5.1.1 | Rotation angle | | | 360° (Endless) |
| | 5.1.2 | Detent points | | | |
| | 5.1.3 | Each detent angle | | | 22.5*±3* |
| | 5.1.4 | Rotation torque | Operating temperature | 5°C~85°C | Before soldering 14.0mNm ± 8.0mNm After soldering 12.0mNm ± 7.0mNm |
| | | (Detent torque) (Avarage torque) | · · · · · · · · · · | _20°C~5°C | 40 mN·m max. |
| | | (,) | | -40°C~-20°C | 50 mN m max. |
| | 5.1.5 | Shaft pull—push strength | Pull and push static load of 100N shall be applied to the shaft in the axial direction for 10 second. | | Without damage or excessive play in shaft. No excessive abnormality in rotational feeling. And electrical characteristics shall be satisfied. |
| | 5.1.6 | Shaft side—load strength | the point 5mm from the tip of the shaft in a direction perpendicular to the axis of shaft for 10 second. | | Without excessive play or bending in shaft. No excessive abnormality in rotational feeling. And electrical characteristics shall be satisfied. |
| | 5.1.7 | Shaft wobble | A momentary load of 50 mNm shall be applied at the point 2mm from the tip of the shaft in a direction perpendicular to the axis of shaft. | | 0.35×L/30 mm(P-P)max. L=Distance between mounting surface and measuring point on the shaft. |
| | 5.1.8 | Shaft play in rotational wobble | Measure with jig for rotational | Langle. | 2' max. |

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5.2 Mechanical performance(Switch part)

| | ltem | Conditions | Specifications |
|-------|------------------------|--|--|
| 5.2.1 | Switch type | | Push type S.P.S.T. |
| 5.2.2 | Switch operation force | Measure the max.load until switch turned on when pressing the center of shaft to the operation direction of push SW. | 6.0 N ± 2.5 N |
| 5.2.3 | Push stroke | Measure the distance until switch turned on when pressing the center of shaft to the operation direction of push SW. | |
| | | | 0.3 mm ^{+0.25} mm (Travel to ON) |

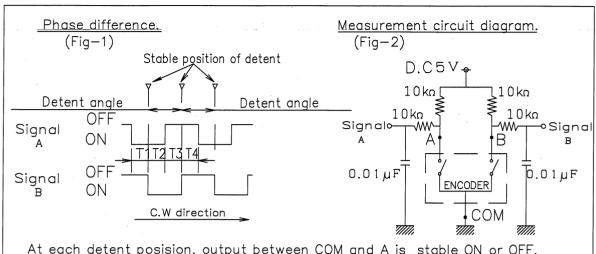
5.3 Electrical performance (Encoder part)

| Item | | Conditions | Specifications |
|-------|-----------------------|---|-------------------------------------|
| 5.3.1 | Output signal | (Output of phase difference Fig—1) | A,B 2 signals. |
| 5.3.2 | Output resolution | Number of pulses in 360° rotation. | 8 Pulse / 360° |
| 5.3.3 | Contact resistance | Measurement shall be stable condition which a output signal is ON condition. | 1n max. |
| 5.3.4 | Bouncing | Measurement circuit diagram.(Fig-2) At rotational speed 60 min-1 <phase (fig-3)="" t1,t3=""> (Passing time between 3.5V and 1.5V)</phase> | t1,t3: 5 ms max. |
| 5.3.5 | Sliding noise phase | Take sliding noise as time in the code—on area between bouncing(t1,t3) and voltage change exceed 1.5V.(Fig—3) Rotate shaft at speed 60±3 min=1 and measure. | t2: 3 ms max. |
| 5.3.6 | Phase-difference | Measurement shall be made under the condition which the shaft is rotated at 60 min–1. | T1, T2, T3, T4 (Fig—1) 4 ms min. |
| 5.3.7 | Insulation resistance | Measurement shall be made under the condition which a voltage of 250V D.C. is applied between individual terminals and a shaft. | 50MΩ min. |
| 5.3.8 | Withstand voltage | A voltage of 300V A.C. shall be applied for 1min. between individual terminals and a shaft. | Without arcing or breakdown. |

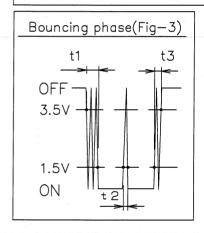
5.4 Electrical performance (Switch part)

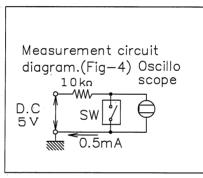
| ltem | Conditions | | Specifications | |
|-------|-----------------------|---|-----------------------------|--|
| 5.4.1 | Bouncing | Measurement circuit diagram.(Fig−4) At operation speed 3~4 times/s <phase (fig−5)="" ±4,±5=""> (Passing time between 3.5V and 1.5V)</phase> | t4,t5:10 ms max. | |
| 5.4.2 | Contact resistance | Measurement the contact resistance between COM and SW when push SW is ON. Applying force: 8.5N | 100mΩ max. | |
| 5.4.3 | Insulation resistance | Measurement shall be made under the condition which a voltage of 250V D.C. is applied between individual terminals and a shaft. | _50MΩ min. | |
| 5.4.4 | Withstand voltage | A voltage of 300V A.C. shall be applied for 1min. between individual terminals and a shaft. | Without arcing or breakdown | |

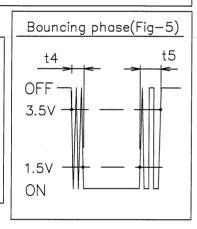
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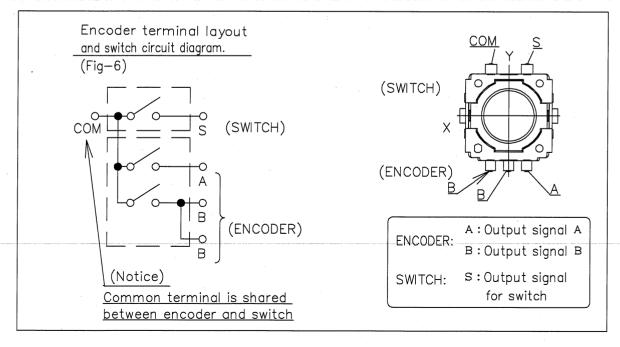


At each detent posision, output between COM and A is stable ON or OFF. (Output between COM and B is not specified.)





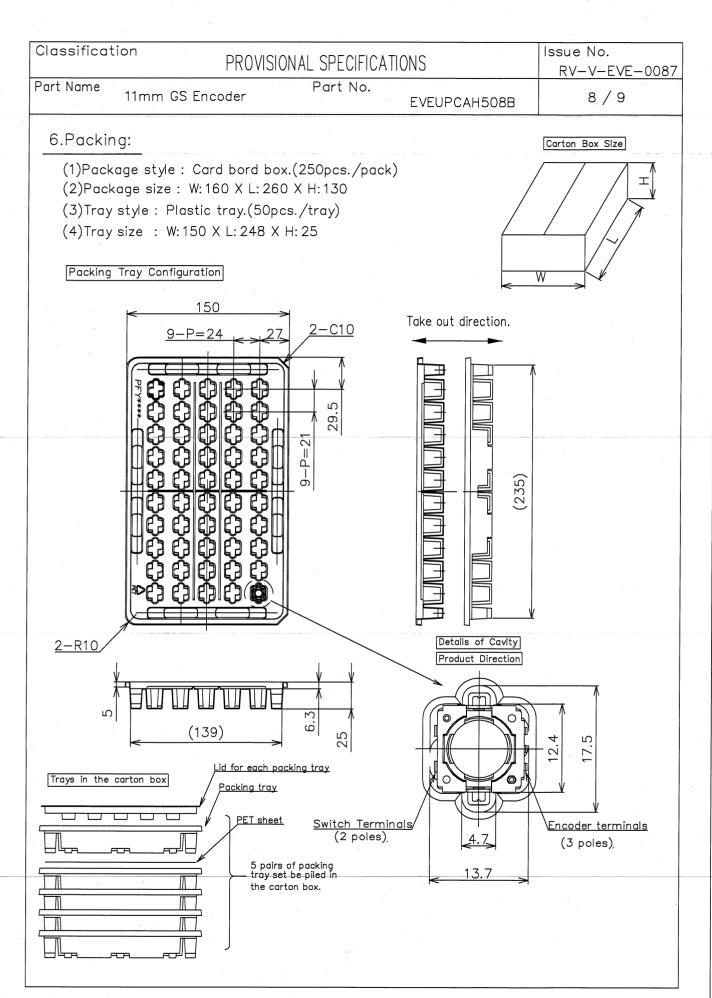




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5.5 Durability performance

| | Item | Conditions | Specifications | |
|-------|---------------------------------|--|---|--|
| 5.5.1 | Rotation life (Encoder) | The shaft of encoder shall be rotated to 30,000 cycles at a speed of 600 to 1000 cycles/h in room temp(15°C to 35°C) without electrical load after which measurements shall be made. | Rotation torque:Initial torque $\pm 80\%$ Phase—difference: 2.5 ms min. Contact resistance: 100Ω max. Clause 5.3.4, 5.3.5, 5.3.7, 5.3.8 be conformed | |
| 5.5.2 | Push operating life (Switch) | Apply 8.5N push strength to shaft to the switch operating direction. The shaft of encoder shall be pushed to 30,000 times at a speed of 2500 times/h in room temp(15°C to 35°C) without electrical load after which measurements shall be made. | Operation force: Initial operation force ±50% Contact resistance: 200mΩ max. Clause 5.2.3, 5.4.1, 5.4.3, 5.4.4 be conformed | |
| 5.5.3 | Heat temperature | The encoder shall be stored at a temperature of 85±3°C for 240±10h in a thermostatic chamber. And then the encoder shall be subjected to standard atmospheric conditions for 1.5h after which measurements shall be made. (Without electrical load) | Contact resistance: 100 Ω max. | |
| 5.5.4 | Humidity | The encoder shall be stored at a temperature of 60±3°C with relative humidity of 90% to 95% for 240±10h in a thermostatic chamber. And then the encoder shall be subjected to standard atmospheric conditions for 1.5h after which measurements shall be made. (Without electrical load) | Contact resistance: 100 Ω max. SW Contact resistance: 200 mΩmax. Clause 5.1.4, 5.2.2, 5.3.4 to 5.3.8, 5.4.1, 5.4.3, 5.4.4 be conformed | |
| 5.5.5 | Low temperature | The encoder shall be stored at a temperature of -40 ± 3 °C for 240±10h in a thermostatic chamber. And then the encoder shall be sub—jected to standard atmospheric conditions for 1.5h after which measurements shall be made. (Without electrical load) | | |



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