HEF4017B

5-stage Johnson decade counter

Rev. 9 — 8 April 2016

Product data sheet

1. General description

The HEF4017B is a 5-stage Johnson decade counter with ten spike-free decoded active HIGH outputs (Q0 to Q9), an active LOW carry output from the most significant flip-flop (Q5-9), active HIGH and active LOW clock inputs (CP0, CP1) and an overriding asynchronous master reset input (MR).

The counter is advanced by either a LOW-to-HIGH transition at CP0 while $\overline{\text{CP}}1$ is LOW or a HIGH-to-LOW transition at $\overline{\text{CP}}1$ while CP0 is HIGH (see Table 3).

When cascading counters, the $\overline{Q}5$ -9 output, which is LOW while the counter is in states 5, 6, 7, 8, and 9, can be used to drive the CP0 input of the next counter. A HIGH on MR resets the counter to zero (Q0 = $\overline{Q}5$ -9 = HIGH; Q1 to Q9 = LOW) independent of the clock inputs (CP0, $\overline{CP}1$).

Automatic counter code correction is provided by an internal circuit: following any illegal code the counter returns to a proper counting mode within 11 clock pulses.

Schmitt trigger action makes the clock inputs highly tolerant of slower rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Automatic counter correction
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1. Ordering information

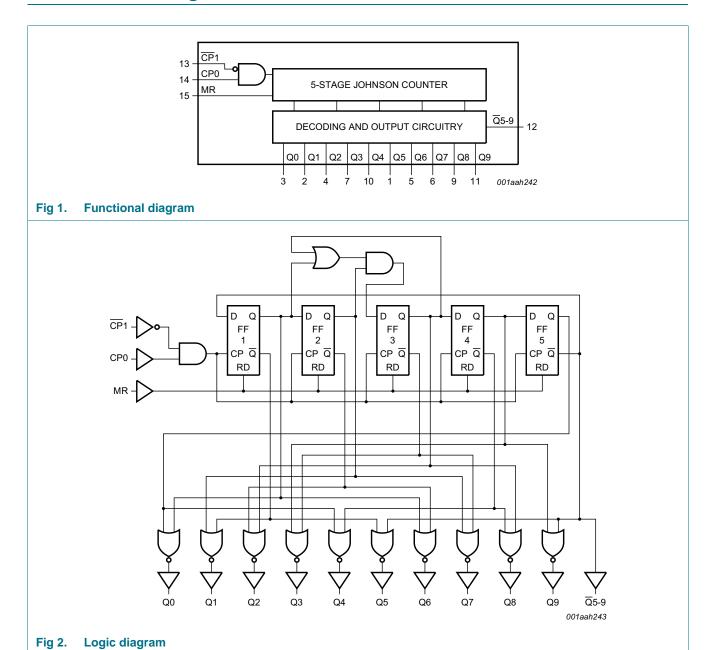
All types operate from -40~% to +125~%

Type number	Package		
	Name	Description	Version
HEF4017BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

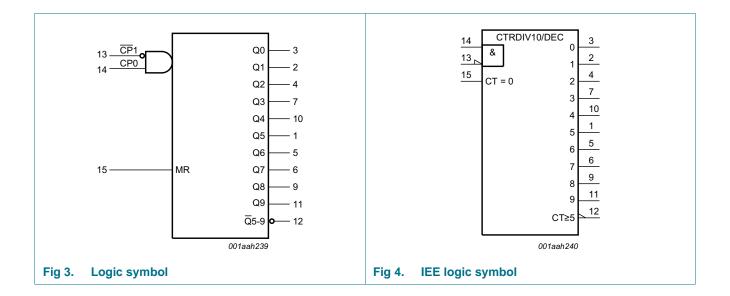


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4. Functional diagram



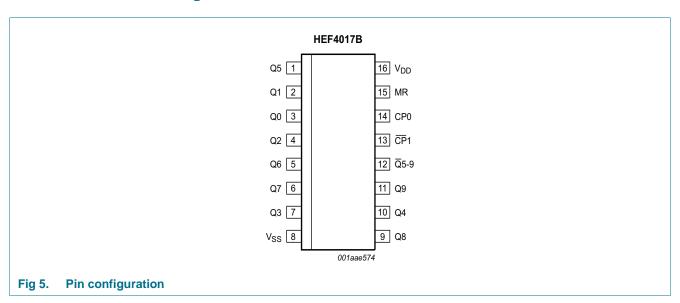
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5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
Q0 to Q9	3, 2, 4, 7, 10, 1, 5, 6, 9, 11	decoded output
V _{SS}	8	ground supply voltage
Q 5-9	12	carry output (active LOW)
CP1	13	clock input (HIGH-to-LOW edge-triggered)
CP0	14	clock input (LOW-to-HIGH edge-triggered)
MR	15	master reset input
V_{DD}	16	supply voltage

6. Functional description

Table 3. Function table [1]

MR	CP0	CP1	Operation
Н	X	X	$Q0 = \overline{Q}5-9 = H$; Q1 to Q9 = L
L	Н	\	counter advances
L	\uparrow	L	counter advances
L	L	X	no change
L	X	Н	no change
L	Н	\uparrow	no change
L	↓	L	no change

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care;

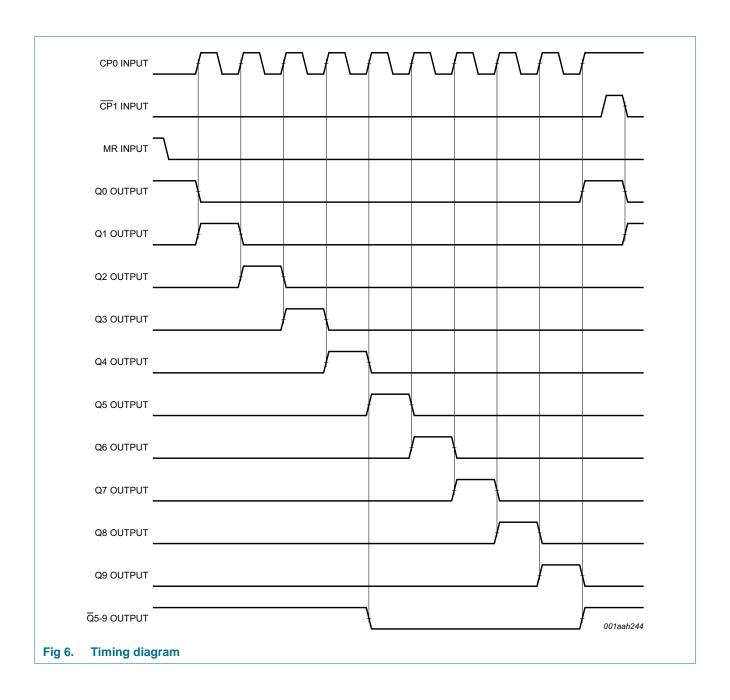
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 $[\]uparrow$ = positive-going transition; \downarrow = negative-going transition.

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7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}$			
		SO16 package	-	500	mW
Р	power dissipation	per output	-	100	mW

^[1] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V_{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	V _{DD} = 5 V	-	-	3.75	μs/V
		V _{DD} = 10 V	-	-	0.5	μs/V
		V _{DD} = 15 V	-	-	0.08	μs/V

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9. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	–40 °C	T _{amb} =	25 °C	T _{amb} =	85 °C	T _{amb} = 125 °C		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V _{IH}	HIGH-level	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V_{IL}	LOW-level	$ I_{O} < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V _{OH}	HIGH-level	$ I_O < 1 \mu A;$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage	$V_I = V_{SS}$ or V_{DD}	10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V_{OL}	LOW-level	$ I_O < 1 \mu A;$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage	$V_I = V_{SS}$ or V_{DD}	10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
	output current	V _O = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		V _O = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I _{OL}	LOW-level	V _O = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	V _O = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
lı	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I_{DD}	supply current	$I_{O} = 0 A;$	5 V	-	5	-	5	-	150	-	150	μΑ
		$V_I = V_{SS}$ or V_{DD}	10 V	-	10	-	10	-	300	-	300	μΑ
			15 V	-	20	-	20	-	600	-	600	μΑ
Cı	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

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10. Dynamic characteristics

Table 7. Dynamic characteristics

 $T_{amb} = 25$ °C; $V_{SS} = 0$ V; for test circuit see <u>Figure 10</u>

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula[1]	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	CP0, $\overline{CP1} \rightarrow Q0$ to Q9;	5 V	113 ns + (0.55 ns/pF)C _L	-	140	280	ns
	propagation delay	see Figure 7	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
	CP0, $\overline{\text{CP}}1 \rightarrow \overline{\text{Q}}5-9$;	5 V	118 ns + (0.55 ns/pF)C _L	-	145	290	ns	
		see Figure 7	10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		$MR \rightarrow Q1 \text{ to } Q9;$	5 V	88 ns + (0.55 ns/pF)C _L	-	115	230	ns
		see Figure 8	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	27 ns + (0.16 ns/pF)C _L	-	35	70	ns
t _{PLH}	LOW to HIGH	CP0, $\overline{CP}1 \rightarrow Q0$ to Q9;	5 V	98 ns + (0.55 ns/pF)C _L	-	125	250	ns
	propagation delay	see Figure 7	10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		CP0, $\overline{CP1} \rightarrow \overline{Q5-9}$; see Figure 7	5 V	98 ns + (0.55 ns/pF)C _L	-	125	250	ns
			10 V	39 ns + (0.23 ns/pF)C _L	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	80	ns
		$MR \rightarrow \overline{Q}5-9;$ see Figure 8	5 V	83 ns + (0.55 ns/pF)C _L	-	110	220	ns
			10 V	34 ns + (0.23 ns/pF)C _L	-	45	90	ns
			15 V	27 ns + (0.16 ns/pF)C _L	-	35	70	ns
		$MR \rightarrow Q0;$	5 V	103 ns + (0.55 ns/pF)C _L	-	130	260	ns
		see Figure 8	10 V	44 ns + (0.23 ns/pF)C _L	-	55	105	ns
			15 V	32 ns + (0.16 ns/pF)C _L	-	40	75	ns
t _t	transition time	see Figure 7	5 V [2]	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _h	hold time	$CP0 \rightarrow \overline{CP}1;$	5 V		90	45	-	ns
		see Figure 9	10 V		40	20	-	ns
			15 V		20	10	-	ns
		$\overline{CP}1 \to CP0;$	5 V		80	40	-	ns
		see Figure 9	10 V		40	20	-	ns
			15 V		30	10	-	ns

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 Table 7.
 Dynamic characteristics ...continued

 $T_{amb} = 25$ °C; $V_{SS} = 0$ V; for test circuit see <u>Figure 10</u>

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula[1]	Min	Тур	Max	Unit
t _W puls	pulse width	CP0 input LOW;	5 V		80	40	-	ns
		minimum width; see Figure 8	10 V		40	20	-	ns
		see <u>Figure o</u>	15 V		30	15	-	ns
		CP1 input HIGH;	5 V		80	40	-	ns
		minimum width;	10 V		40	20	-	ns
		see <u>Figure 8</u>	15 V		30	15	-	ns
		MR input HIGH;	5 V		50	25	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Figure 8</u>	15 V		20	10	-	ns
t _{rec}	recovery time	MR input;	5 V		60	30	-	ns
		see Figure 8	10 V		30	15	-	ns
			15 V		20	10	-	ns
f _{max}	maximum	see Figure 8	5 V		6	12	-	MHz
	frequency	uency	10 V		12	30	-	MHz
			15 V		15	30	-	MHz

^[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

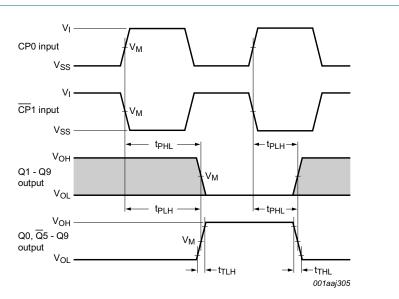
 P_D can be calculated from the formulas shown. $V_{SS} = 0 \text{ V}$; $t_r = t_f \le 20 \text{ ns}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$.

Symbol	Parameter	V_{DD}	Typical formula for P _D (μW)	where:
P_D	dynamic power	5 V	$P_D = 500 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$	f_i = input frequency in MHz;
	dissipation	10 V	$P_D = 2200 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	f _o = output frequency in MHz;
		15 V	$P_D = 6000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	C _L = output load capacitance in pF;
				V _{DD} = supply voltage in V;
				$\Sigma(C_L \times f_0)$ = sum of the outputs.

^[2] t_t is the same as t_{THL} and t_{TLH} .

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11. Waveforms

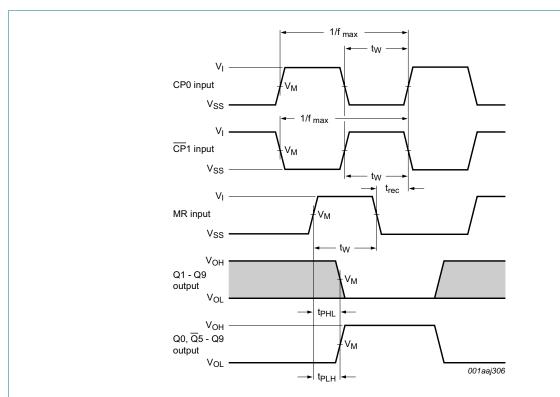


Conditions: $\overline{CP1}$ = LOW, while CP0 triggers on a LOW-to-HIGH transition. $\overline{CP1}$ triggers on a HIGH-to-LOW transition; The shaded areas indicate where the output state is set by the input count.

Measurement points given in Table 9.

Fig 7. Waveforms showing the propagation delays for CP0, $\overline{\text{CP}}1$ to Qn, $\overline{\text{Q}}5$ -9 outputs and the output transition times

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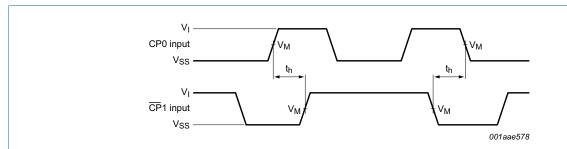


 $\overline{\text{CP}}$ 1 = LOW, while CP0 triggers on a LOW-to-HIGH transition, t_W and t_{rec} are measured when CP0 = HIGH and $\overline{\text{CP}}$ 1 triggers on a HIGH-to-LOW transition.

The shaded areas indicate where the output state is set by the input count.

Measurement points given in Table 9.

Fig 8. Waveforms showing the minimum pulse width for CP0, CP1 and MR input; the maximum frequency for CP0 and CP1 input; the recovery time for MR and the MR input to Qn and Q5-9 output propagation delays



Hold times are shown as positive values, but may be specified as negative values;

Measurement points given in Table 9.

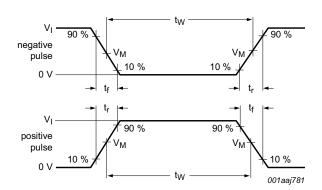
Fig 9. Waveforms showing hold times for CP0 to CP1 and CP1 to CP0

Table 9. Measurement points

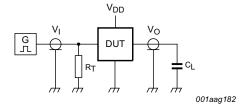
Supply voltage	Input	Output
V_{DD}	V _M	V _M
5 V to 15 V	0.5V _{DD}	0.5V _{DD}

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a. Input waveforms



b. Test circuit

Test data is given in Table 10.

Definitions for test circuit:

DUT = Device Under Test;

 C_L = load capacitance including jig and probe capacitance;

 R_T = termination resistance should be equal to the output impedance Z_0 of the pulse generator.

Fig 10. Test circuit for measuring switching times

Table 10. Test data

Supply voltage	Input	Load	
V_{DD}	VI	t _r , t _f	C _L
5 V to 15 V	V _{SS} or V _{DD}	≤ 20 ns	50 pF

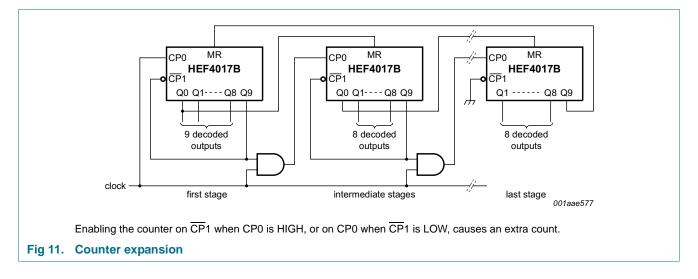
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12. Application information

Some examples of applications for the HEF4017B are:

- · Decade counter with decimal decoding
- 1 out of n decoding counter (when cascaded)
- Sequential controller
- Timer

<u>Figure 11</u> shows a technique for extending the number of decoded output states for the HEF4017B. Decoded outputs are sequential within each stage and from stage to stage, with no dead time (except propagation delay).

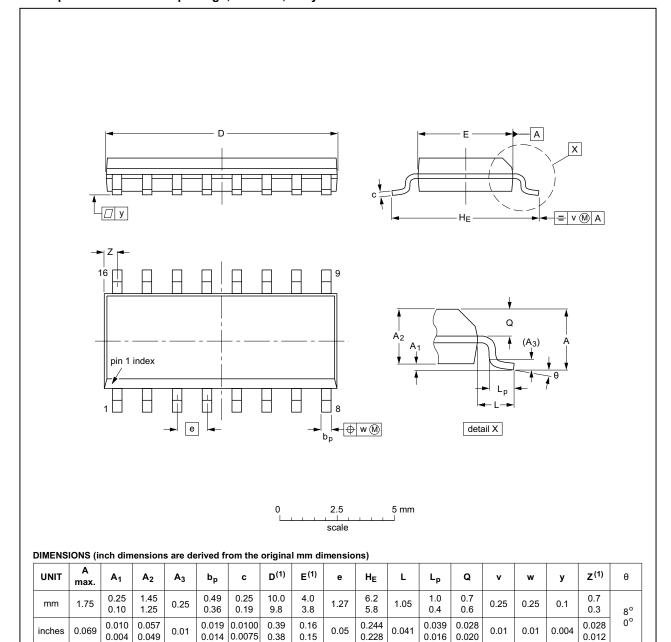


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13. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE	
SOT109-1	076E07	MS-012			99-12-27 03-02-19	

Fig 12. Package outline SOT109-1 (SO16)

HEF4017E

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14. Revision history

Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4017B v.9	20160408	Product data sheet	-	HEF4017B v.8
Modifications:	Type number HEF4017BP (SOT38-4) removed.			
HEF4017B v.8	20111118	Product data sheet	-	HEF4017B v.7
Modifications:	Legal pages updated.			
	 Changes in "General description" and "Features and benefits". 			
	 Section "Applications" removed. 			
HEF4017B v.7	20110914	Product data sheet	-	HEF4017B v.6
HEF4017B v.6	20091105	Product data sheet	-	HEF4017B v.5
HEF4017B v.5	20090709	Product data sheet	-	HEF4017B v.4
HEF4017B v.4	20081209	Product data sheet	-	HEF4017B_CNV v.3
HEF4017B_CNV v.3	19950101	Product specification	-	HEF4017B_CNV v.2
HEF4017B_CNV v.2	19950101	Product specification	-	-

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15. Legal information

15.1 Data sheet status

Document status[1][2]	Product status[3]	Definition	
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.	
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.	
Product [short] data sheet	Production	This document contains the product specification.	

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

16. Contact information

For more information, please visit: http://www.nexperia.com

For sales office addresses, please send an email to: salesaddresses@nexperia.com