

HEF4020B-Q100

14-stage binary counter

Rev. 3 — 7 December 2021

Product data sheet

1. General description

The HEF4020B is a 14-stage binary ripple counter with a clock input (\overline{CP}), an overriding asynchronous master reset input (MR) and 12 buffered parallel outputs (Q0, and Q3 to Q13). The counter advances on the HIGH-to-LOW transition of \overline{CP} . A HIGH on MR clears all counter stages and forces all outputs LOW, independent of the state of \overline{CP} . Each counter stage is a static toggle flip-flop. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V_{DD} .

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
 - Specified from -40 °C to +85 °C
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- High speed operation
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
 - MIL-STD-883, method 3015 exceeds 2000 V
 - HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1. Ordering information

| Type number | Package | | | |
|----------------|-------------------|------|--|----------|
| | Temperature range | Name | Description | Version |
| HEF4020BT-Q100 | -40 °C to +85 °C | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |

4. Functional diagram

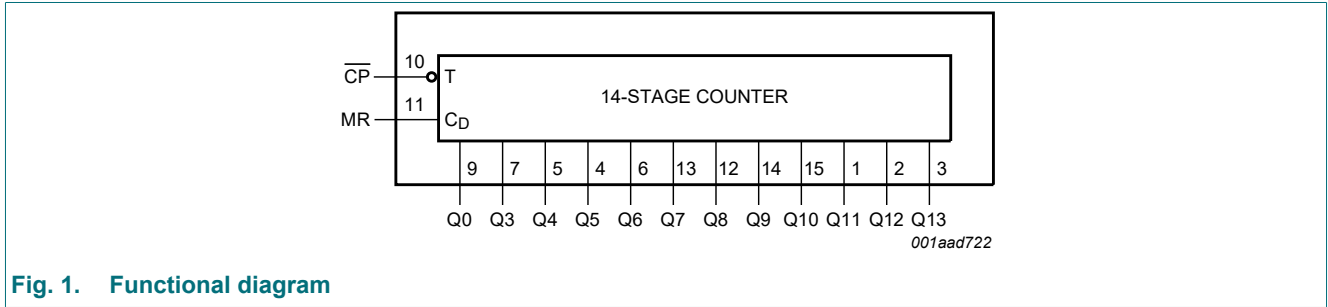


Fig. 1. Functional diagram

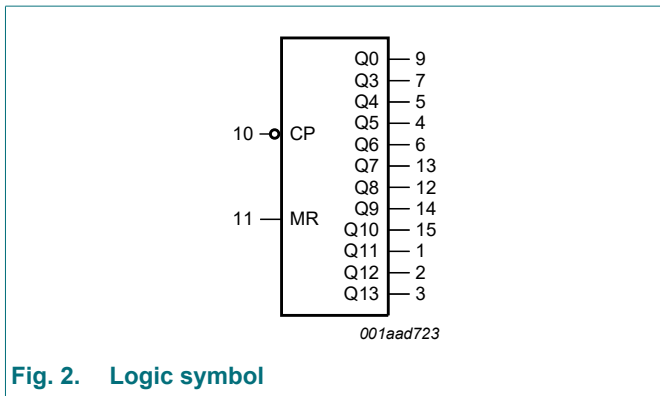


Fig. 2. Logic symbol

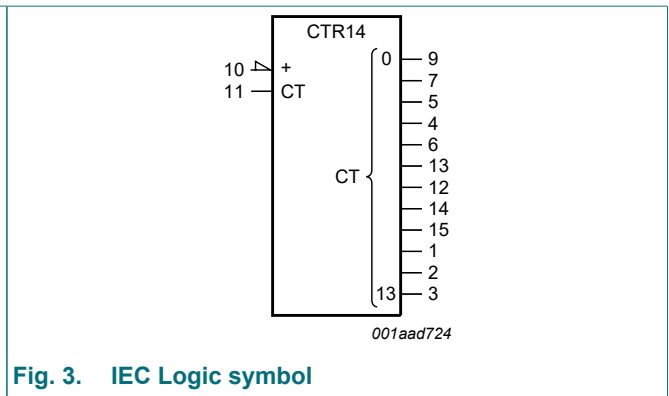


Fig. 3. IEC Logic symbol

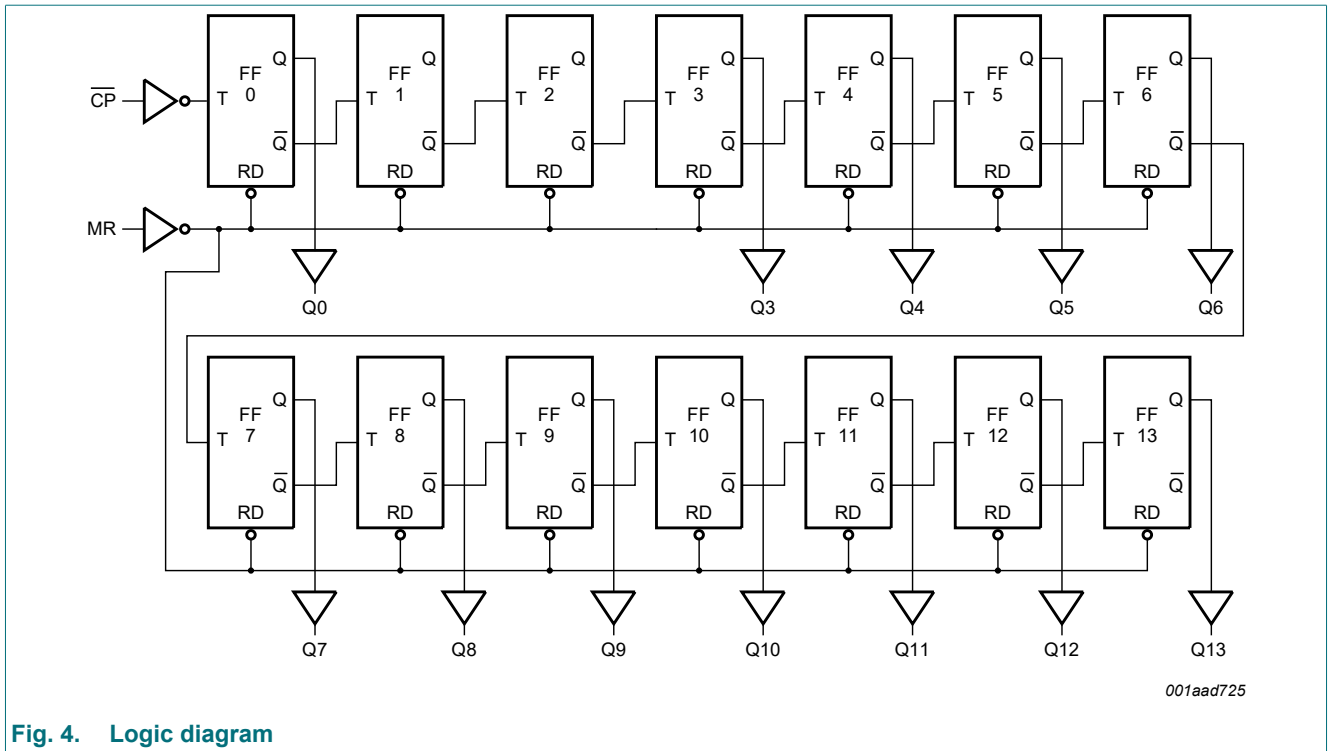


Fig. 4. Logic diagram

5. Pinning information

5.1. Pinning

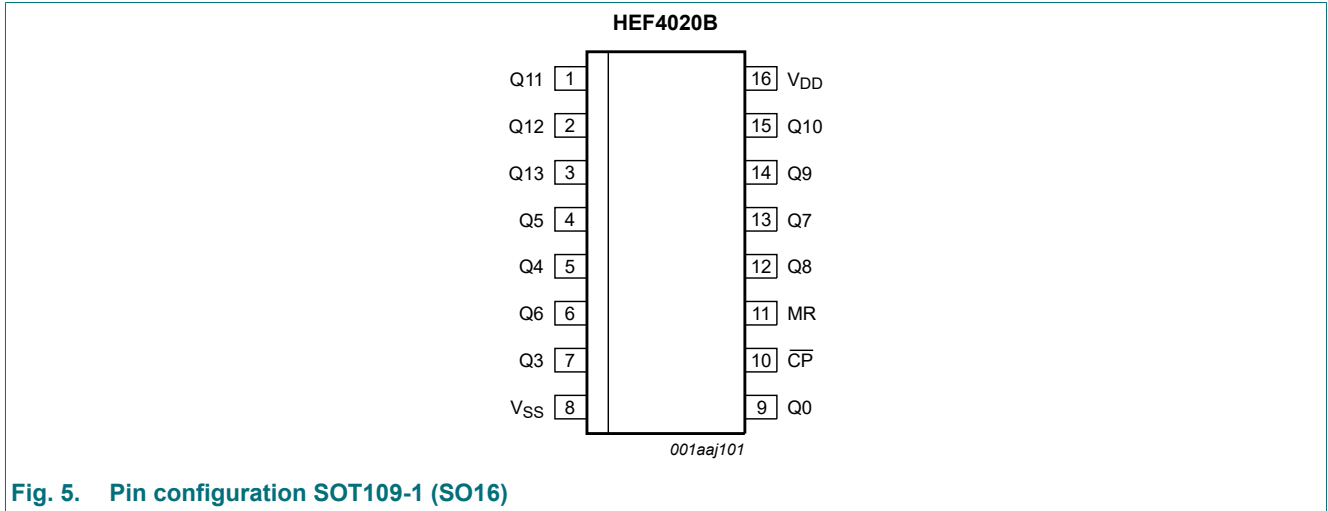


Fig. 5. Pin configuration SOT109-1 (SO16)

5.2. Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|--|-------------------------------------|--|
| Q3, Q4, Q5, Q6, Q7, Q8, Q9, Q10, Q11, Q12, Q13 | 7, 5, 4, 6, 13, 12, 14, 15, 1, 2, 3 | parallel output (Q3 to Q13) |
| V _{SS} | 8 | ground supply voltage |
| Q0 | 9 | parallel output |
| CP | 10 | clock input (HIGH-to-LOW edge triggered) |
| MR | 11 | master reset input (active HIGH) |
| V _{DD} | 16 | supply voltage |

6. Functional description

Table 3. Functional table

H = HIGH voltage level; L = LOW voltage level; X = don't care; ↑ = positive-going transition; ↓ = negative-going transition.

| Input | | Output |
|-------|----|---------------|
| CP | MR | Q0, Q3 to Q13 |
| ↑ | L | no change |
| ↓ | L | count |
| X | H | L |

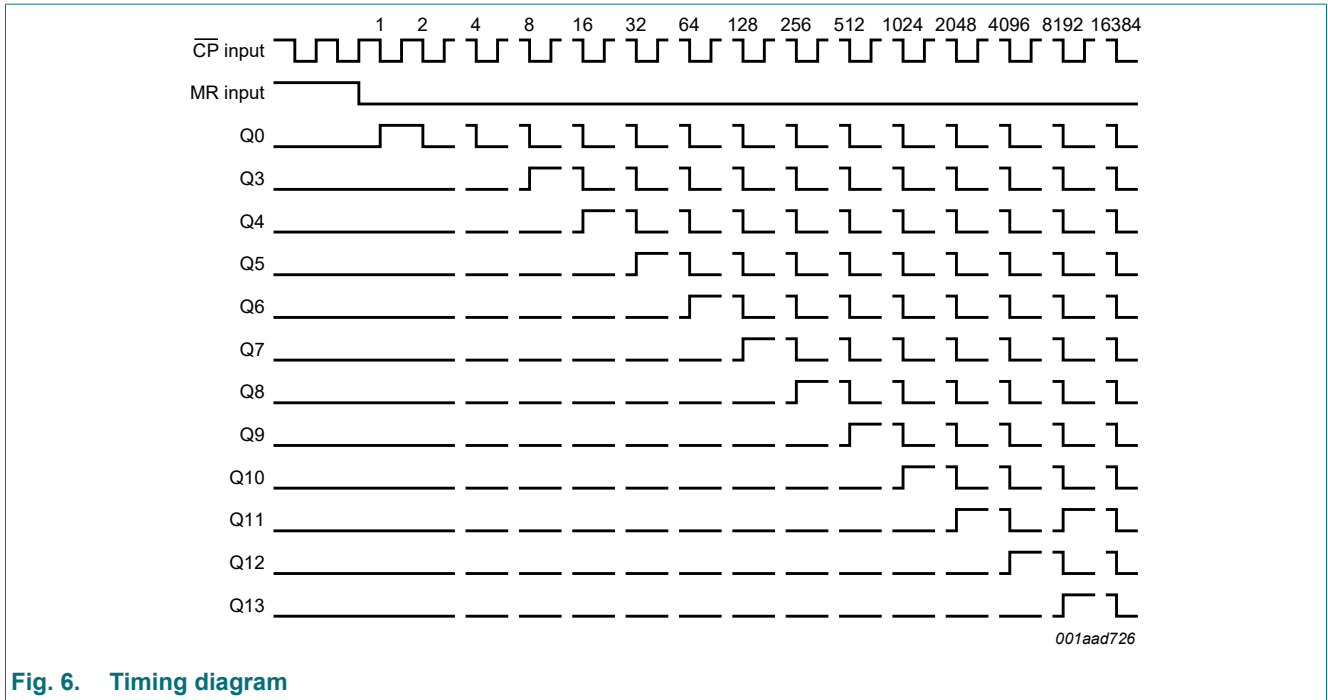


Fig. 6. Timing diagram

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|------|----------------|------|
| V_{DD} | supply voltage | | -0.5 | +18 | V |
| I_{IK} | input clamping current | $V_I < -0.5\text{ V}$ or $V_I > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| V_I | input voltage | | -0.5 | $V_{DD} + 0.5$ | V |
| I_{OK} | output clamping current | $V_O < -0.5\text{ V}$ or $V_O > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| $I_{I/O}$ | input/output current | | - | ± 10 | mA |
| I_{DD} | supply current | | - | 50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| T_{amb} | ambient temperature | | -40 | +85 | °C |
| P_{tot} | total power dissipation | $T_{amb} -40\text{ °C}$ to $+85\text{ °C}$ | - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics
 $V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} ; unless otherwise specified.

| Symbol | Parameter | Conditions | V _{DD} | T _{amb} = -40 °C | | T _{amb} = +25 °C | | T _{amb} = +85 °C | | Unit |
|-----------------|---------------------------|-------------------------|-----------------|---------------------------|-------|---------------------------|-------|---------------------------|-------|------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V _{IH} | HIGH-level input voltage | I _O < 1 μA | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V _{IL} | LOW-level input voltage | I _O < 1 μA | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V _{OH} | HIGH-level output voltage | I _O < 1 μA | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V _{OL} | LOW-level output voltage | I _O < 1 μA | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I _{OH} | HIGH-level output current | V _O = 2.5 V | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | V _O = 4.6 V | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | V _O = 9.5 V | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | V _O = 13.5 V | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I _{OL} | LOW-level output current | V _O = 0.4 V | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | V _O = 0.5 V | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | V _O = 1.5 V | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I _I | input leakage current | | 15 V | - | ±0.3 | - | ±0.3 | - | ±1.0 | μA |
| I _{DD} | supply current | I _O = 0 A | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C _I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; for test circuit see Fig. 8.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula [1] | Min | Typ | Max | Unit |
|------------------|-------------------------------|--|-----------------|-------------------------------------|-----|-----|-----|------|
| t _{PHL} | HIGH to LOW propagation delay | CP to Q0; see Fig. 7 | 5 V | 78 ns + (0.55 ns/pF)C _L | - | 105 | 210 | ns |
| | | | 10 V | 34 ns + (0.23 ns/pF)C _L | - | 45 | 90 | ns |
| | | | 15 V | 22 ns + (0.16 ns/pF)C _L | - | 30 | 65 | ns |
| | | Qn to Qn + 1 | 5 V | 53 ns + (0.55 ns/pF)C _L | - | 80 | 160 | ns |
| | | | 10 V | 19 ns + (0.23 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 12 ns + (0.16 ns/pF)C _L | - | 20 | 40 | ns |
| | | MR to Qn; see Fig. 7 | 5 V | 153 ns + (0.55 ns/pF)C _L | - | 180 | 360 | ns |
| | | | 10 V | 79 ns + (0.23 ns/pF)C _L | - | 90 | 180 | ns |
| | | | 15 V | 62 ns + (0.16 ns/pF)C _L | - | 70 | 140 | ns |
| t _{PLH} | LOW to HIGH propagation delay | CP to Q0; see Fig. 7 | 5 V | 78 ns + (0.55 ns/pF)C _L | - | 105 | 210 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 95 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF)C _L | - | 35 | 70 | ns |
| | | Qn to Qn + 1 | 5 V | 43 ns + (0.55 ns/pF)C _L | - | 70 | 140 | ns |
| | | | 10 V | 14 ns + (0.23 ns/pF)C _L | - | 25 | 50 | ns |
| | | | 15 V | 12 ns + (0.16 ns/pF)C _L | - | 20 | 40 | ns |
| t _t | transition time | see Fig. 7 | 5 V | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |
| t _w | pulse width | CP = HIGH; minimum width; see Fig. 7 | 5 V | | 50 | 25 | - | ns |
| | | | 10 V | | 25 | 15 | - | ns |
| | | | 15 V | | 20 | 10 | - | ns |
| | | MR = HIGH; minimum width; see Fig. 7 | 5 V | | 130 | 65 | - | ns |
| | | | 10 V | | 95 | 50 | - | ns |
| | | | 15 V | | 90 | 45 | - | ns |
| t _{rec} | recovery time | MR input; see Fig. 7 | 5 V | | 115 | 60 | - | ns |
| | | | 10 V | | 65 | 35 | - | ns |
| | | | 15 V | | 55 | 25 | - | ns |
| f _{max} | maximum frequency | see Fig. 7 | 5 V | | 5 | 10 | - | MHz |
| | | | 10 V | | 13 | 25 | - | MHz |
| | | | 15 V | | 18 | 35 | - | MHz |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0\text{ V}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ °C}$.

| Symbol | Parameter | V _{DD} | Typical formula for P _D (μW) | where: |
|----------------|---------------------------|-----------------|--|---|
| P _D | dynamic power dissipation | 5 V | $P_D = 600 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ | f _i = input frequency in MHz, f _o = output frequency in MHz, C _L = output load capacitance in pF, V _{DD} = supply voltage in V, ∑(f _o × C _L) = sum of the outputs. |
| | | 10 V | $P_D = 2800 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ | |
| | | 15 V | $P_D = 8200 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ | |

10.1. Waveforms and test circuit

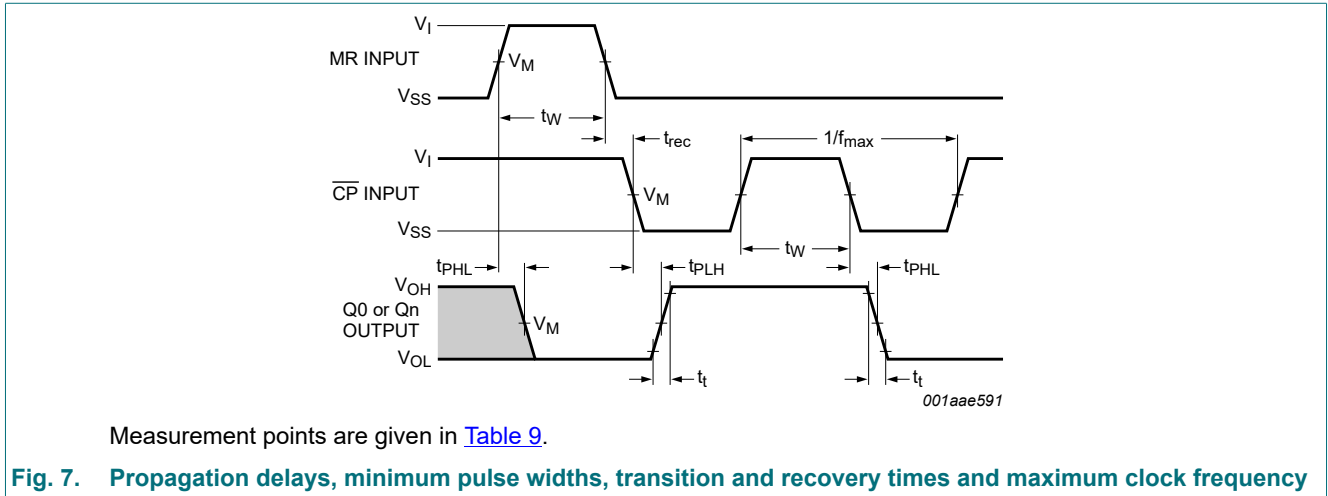


Table 9. Measurement points

| Supply voltage | Input | Output |
|----------------|-------------|-------------|
| V_{DD} | V_M | V_M |
| 5 V to 15 V | $0.5V_{DD}$ | $0.5V_{DD}$ |

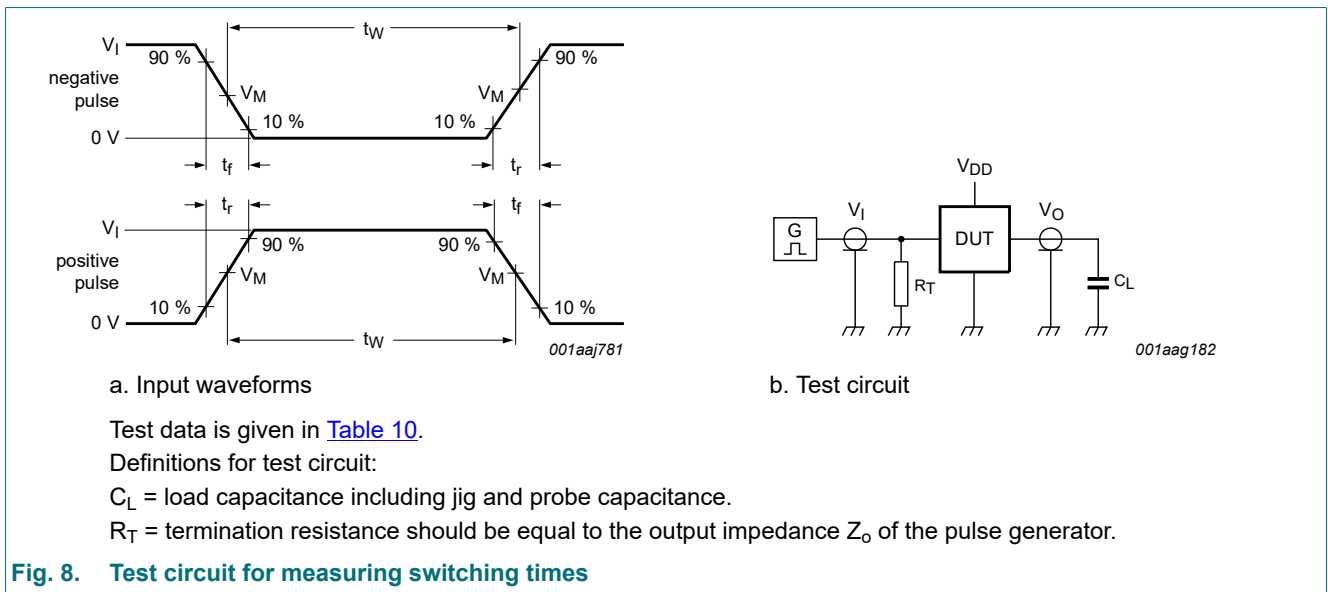


Table 10. Test data

| Supply voltage | Input | Load |
|----------------|----------------------|--------------|
| V_{DD} | V_I | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns |

11. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

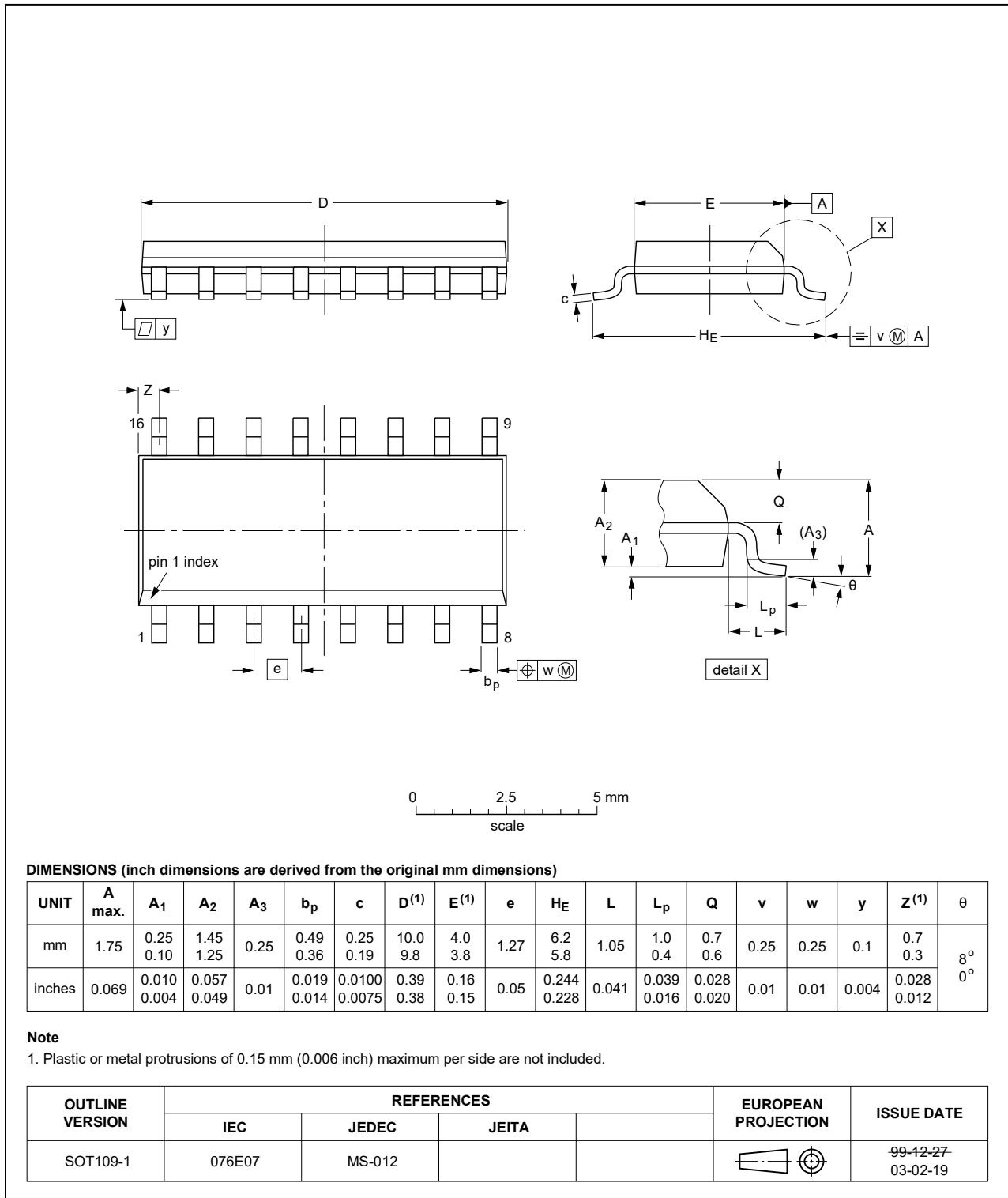


Fig. 9. Package outline SOT109-1 (SO16)

12. Abbreviations

Table 11. Abbreviations

| Acronym | Description |
|---------|---|
| CMOS | Complementary Metal-Oxide Semiconductor |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| MIL | Military |
| MM | Machine Model |

13. Revision history

Table 12. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|-------------------|---|--------------------|---------------|-------------------|
| HEF4020B_Q100 v.3 | 20211207 | Product data sheet | - | HEF4020B_Q100 v.2 |
| Modifications: | <ul style="list-style-type: none"> Section 1 and Section 2 updated. | | | |
| HEF4020B_Q100 v.2 | 20181018 | Product data sheet | - | HEF4020B_Q100 v.1 |
| Modifications: | <ul style="list-style-type: none"> The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia. Legal texts have been adapted to the new company name where appropriate. | | | |
| HEF4020B_Q100 v.1 | 20140604 | Product data sheet | - | - |

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| Document status [1][2] | Product status [3] | Definition |
|--------------------------------|--------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

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- [2] The term 'short data sheet' is explained in section "Definitions".
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