

HEF4528-Q100B

Dual monostable multivibrator

Rev. 2 — 4 March 2022

Product data sheet

1. General description

The HEF4528B-Q100 is a dual retriggerable-resettable monostable multivibrator. Each multivibrator has an active LOW input ($n\bar{A}$), and active HIGH input (nB), an active LOW clear direct input ($n\bar{C}\bar{D}$), an output (nQ) and its complement ($n\bar{Q}$), and two external timing component connecting pins (nC_{EXT} , always connected to ground, and nR_{EXT}/C_{EXT}).

An external timing capacitor (C_{EXT}) must be connected between nC_{EXT} and nR_{EXT}/C_{EXT} and an external resistor (R_{EXT}) must be connected between nR_{EXT}/C_{EXT} and V_{DD} . The output pulse duration is determined by the external timing components C_{EXT} and R_{EXT} . A HIGH-to-LOW transition on $n\bar{A}$ when nB is LOW or a LOW-to-HIGH transition on nB when $n\bar{A}$ is HIGH produces a positive pulse (LOW-HIGH-LOW) on nQ and a negative pulse (HIGH-LOW-HIGH) on $n\bar{Q}$ if the $n\bar{C}\bar{D}$ is HIGH. A LOW on $n\bar{C}\bar{D}$ forces nQ LOW, $n\bar{Q}$ HIGH and inhibits any further pulses until $n\bar{C}\bar{D}$ is HIGH.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
 - Specified from -40 °C to +85 °C
- Fully static operation
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
 - MIL-STD-883, method 3015 exceeds 2000 V
 - HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V ($C = 200$ pF, $R = 0$ Ω)
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1. Ordering information

| Type number | Package | | | |
|----------------|-------------------|------|--|----------|
| | Temperature range | Name | Description | Version |
| HEF4528BT-Q100 | 40 °C to +85 °C | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |

4. Functional diagram

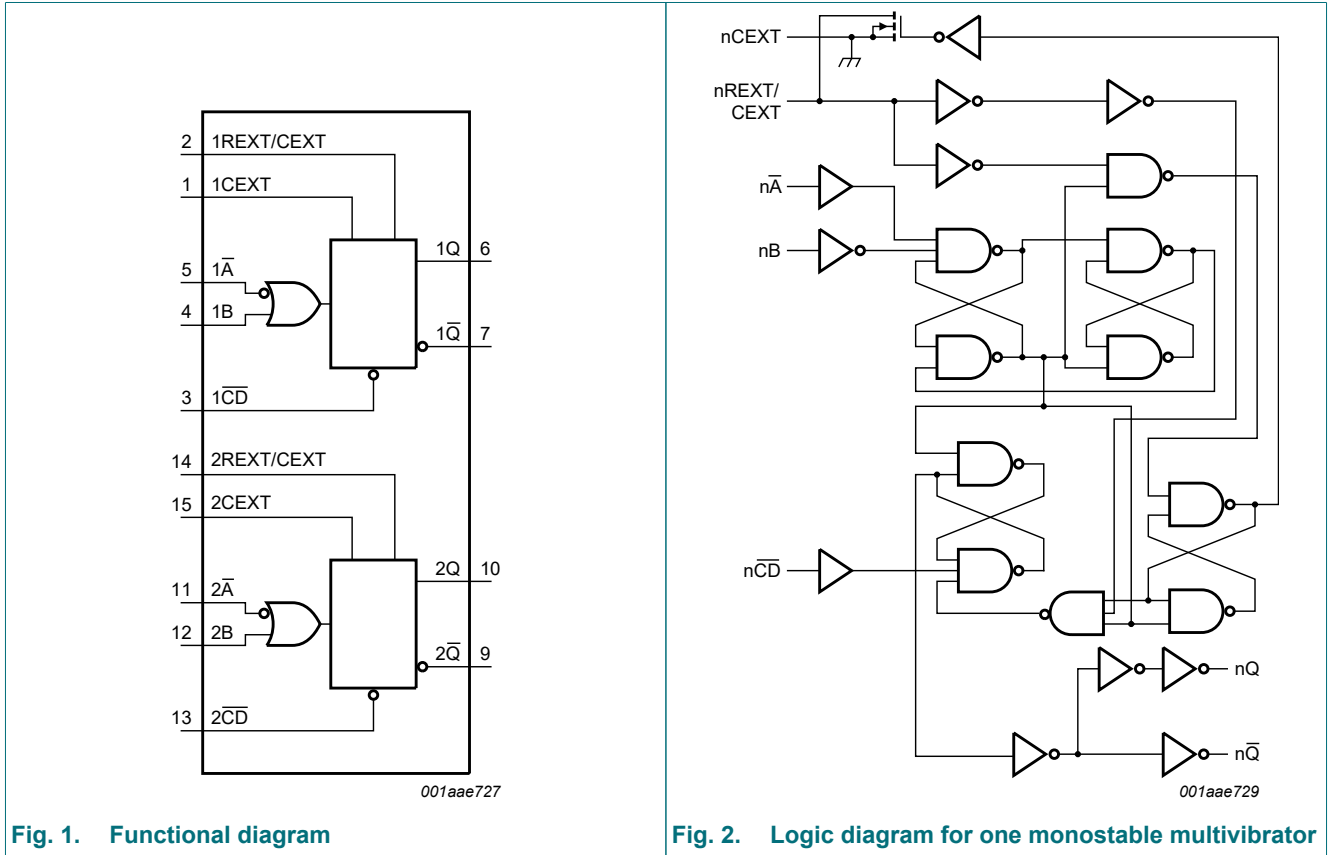


Fig. 1. Functional diagram

Fig. 2. Logic diagram for one monostable multivibrator

5. Pinning information

5.1. Pinning

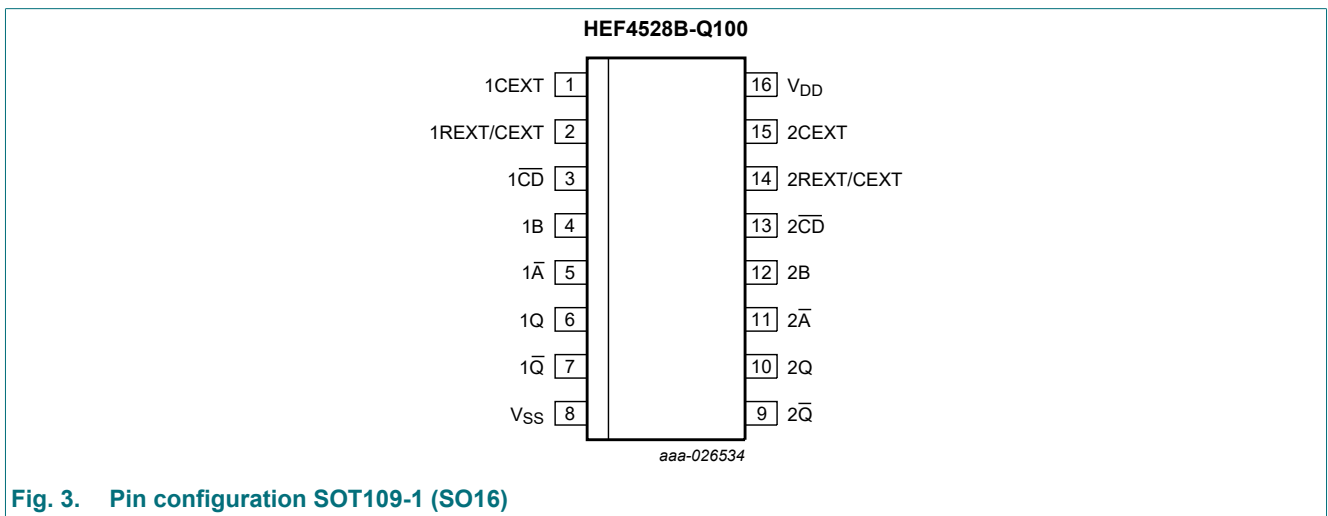


Fig. 3. Pin configuration SOT109-1 (SO16)

5.2. Pin description

Table 2. Pin description


| Symbol | Pin | Description |
|---------------------------------------|-------|--|
| 1CEXT, 2CEXT | 1, 15 | external capacitor connection (always connected to ground) |
| 1REXT/CEXT, 2REXT/CEXT | 2, 14 | external capacitor/resistor connection |
| 1 \overline{CD} , 2 \overline{CD} | 3, 13 | clear direct input (active LOW) |
| 1B, 2B | 4, 12 | input (LOW-to-HIGH triggered) |
| 1 \overline{A} , 2 \overline{A} | 5, 11 | input (HIGH-to-LOW triggered) |
| 1Q, 2Q | 6, 10 | output |
| 1 \overline{Q} , 2 \overline{Q} | 7, 9 | complementary output (active LOW) |
| V _{SS} | 8 | ground supply voltage |
| V _{DD} | 16 | supply voltage |


6. Functional description





Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care;

↑ = positive-going transition; ↓ = negative-going transition;

 = one HIGH level output pulse, with the pulse width determined by C_{EXT} and R_{EXT};

 = one LOW level output pulse, with the pulse width determined by C_{EXT} and R_{EXT}.

| Inputs | | | Outputs | |
|--------|---|----|---|---|
| A | B | CD | Q | \overline{Q} |
| ↓ | L | H |  |  |
| H | ↑ | H |  |  |
| X | X | L | L | H |

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to V_{SS} = 0 V (ground).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------|---|------|-----------------------|------|
| V _{DD} | supply voltage | | -0.5 | +18 | V |
| I _{IK} | input clamping current | V _I < -0.5 V or V _I > V _{DD} + 0.5 V | - | ±10 | mA |
| V _I | input voltage | | -0.5 | V _{DD} + 0.5 | V |
| I _{OK} | output clamping current | V _O < -0.5 V or V _O > V _{DD} + 0.5 V | - | ±10 | mA |
| I _{I/O} | input/output current | | - | ±10 | mA |
| I _{DD} | supply current | | - | 50 | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| T _{amb} | ambient temperature | | -40 | +85 | °C |
| P _{tot} | total power dissipation | T _{amb} = -40 °C to +85 °C | - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | 15 | V |
| V_I | input voltage | | 0 | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} , unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ °C}$ | | $T_{amb} = 25\text{ °C}$ | | $T_{amb} = 85\text{ °C}$ | | Unit |
|----------|---------------------------|---|----------|---------------------------|-----------|--------------------------|-----------|--------------------------|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | all valid input combinations; $I_O = 0\text{ A}$ | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | 7.5 | - | - | pF | |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; unless otherwise specified; for waveforms see Fig. 4 to Fig. 6; for test circuit see Fig. 7.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula [1] | Min | Typ | Max | Unit |
|---|-------------------------------|---|-----------------|-------------------------------------|-----|---------|-----|------|
| t _{PHL} | HIGH to LOW propagation delay | n \bar{A} or nB to n \bar{Q} ; see Fig. 5 | 5 V | 113 ns + (0.55 ns/pF)C _L | - | 140 | 280 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 100 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF)C _L | - | 35 | 70 | ns |
| | | n $\bar{C}\bar{D}$ to nQ; see Fig. 5 | 5 V | 78 ns + (0.55 ns/pF)C _L | - | 105 | 210 | ns |
| | | | 10 V | 29 ns + (0.23 ns/pF)C _L | - | 40 | 85 | ns |
| | | | 15 V | 22 ns + (0.16 ns/pF)C _L | - | 30 | 60 | ns |
| t _{PLH} | LOW to HIGH propagation delay | n \bar{A} or nB to nQ; see Fig. 5 | 5 V | 128 ns + (0.55 ns/pF)C _L | - | 155 | 305 | ns |
| | | | 10 V | 49 ns + (0.23 ns/pF)C _L | - | 60 | 115 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| | | n $\bar{C}\bar{D}$ to n \bar{Q} ; see Fig. 5 | 5 V | 93 ns + (0.55 ns/pF)C _L | - | 120 | 240 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 105 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF)C _L | - | 35 | 70 | ns |
| t _t | transition time | nQ, n \bar{Q} ; see Fig. 5 | 5 V [2] | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |
| t _{rec} | recovery time | n $\bar{C}\bar{D}$ to n \bar{A} or nB; see Fig. 6 | 5 V | | 0 | -75 | - | ns |
| | | | 10 V | | 0 | -30 | - | ns |
| | | | 15 V | | 0 | -25 | - | ns |
| t _{su} | set-up time | n $\bar{C}\bar{D}$ to n \bar{A} or nB; see Fig. 6 | 5 V | | 0 | -105 | - | ns |
| | | | 10 V | | 0 | -40 | - | ns |
| | | | 15 V | | 0 | -25 | - | ns |
| t _w | pulse width | n \bar{A} LOW; minimum width; see Fig. 6 | 5 V | | 50 | 25 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 20 | 10 | - | ns |
| | | nB HIGH; minimum width; see Fig. 6 | 5 V | | 50 | 25 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 20 | 10 | - | ns |
| | | n $\bar{C}\bar{D}$ LOW; minimum width; see Fig. 6 | 5 V | | 60 | 30 | - | ns |
| | | | 10 V | | 35 | 15 | - | ns |
| | | | 15 V | | 25 | 10 | - | ns |
| | | nQ or n \bar{Q} ; R _{EXT} = 5 k Ω ; C _{EXT} = 15 pF; see Fig. 6 | 5 V [3] | | - | 235 | - | ns |
| | | | 10 V | | - | 155 | - | ns |
| | | | 15 V | | - | 140 | - | ns |
| nQ or n \bar{Q} ; R _{EXT} = 10 k Ω ; C _{EXT} = 1 nF; see Fig. 6 | 5 V [4] | | - | 5.45 | - | μ s | | |
| | 10 V | | - | 4.95 | - | μ s | | |
| | 15 V | | - | 4.85 | - | μ s | | |

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula [1] | Min | Typ | Max | Unit |
|------------------|---------------------------|--|-----------------|---------------------------|-----------|-----|-----|------|
| Δt _W | pulse width variation | nQ output variation over temperature range | 5 V [5] | | - | ±3 | - | % |
| | | | 10 V | | - | ±2 | - | % |
| | | | 15 V | | - | ±2 | - | % |
| | | nQ output variation over voltage range V _{DD} ± 5 % | 5 V | | - | ±2 | - | % |
| | | | 10 V | | - | ±1 | - | % |
| | | | 15 V | | - | ±1 | - | % |
| R _{EXT} | external timing resistor | see Fig. 4 | 5 V | | 5 | - | 2 | MΩ |
| | | | 10 V | | 5 | - | 2 | MΩ |
| | | | 15 V | | 5 | - | 2 | MΩ |
| C _{EXT} | external timing capacitor | see Fig. 4 | 5 V | | no limits | | | |
| | | | 10 V | | no limits | | | |
| | | | 15 V | | no limits | | | |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

[2] t_i is the same as t_{THL} and t_{TLH}.

[3] For other R_{EXT}, C_{EXT} combinations and C_{EXT} < 0.01 μF see Fig. 4.

[4] For other R_{EXT}, C_{EXT} combinations and C_{EXT} > 0.01 μF use formula t_W = K × R_{EXT} × C_{EXT}.

where: t_W = output pulse width (s);

R_{EXT} = external timing resistor (Ω);

C_{EXT} = external timing capacitor (F);

K = 0.42 for V_{DD} = 5 V;

K = 0.32 for V_{DD} = 10 V;

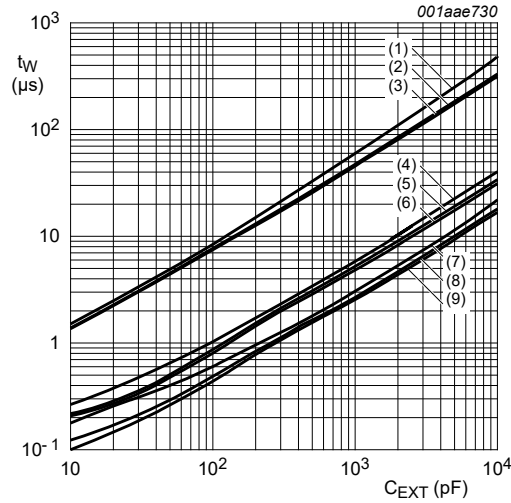
K = 0.30 for V_{DD} = 15 V.

[5] T_{amb} = -40 °C to +85 °C; Δt_W is referenced to t_W at T_{amb} = 25 °C.

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. V_{SS} = 0 V; t_r = t_f ≤ 20 ns; T_{amb} = 25 °C.

| Symbol | Parameter | V _{DD} | Typical formula for P _D (μW) | where: |
|----------------|---------------------------|-----------------|---|---|
| P _D | dynamic power dissipation | 5 V | $P_D = 4000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _i = input frequency in MHz; f _o = output frequency in MHz; C _L = output load capacitance in pF; V _{DD} = supply voltage in V; Σ(f _o × C _L) = sum of the outputs. |
| | | 10 V | $P_D = 20000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |
| | | 15 V | $P_D = 59000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |



- (1) $R_{EXT} = 100\text{ k}\Omega$, $V_{DD} = 5\text{ V}$.
- (2) $R_{EXT} = 100\text{ k}\Omega$, $V_{DD} = 10\text{ V}$.
- (3) $R_{EXT} = 100\text{ k}\Omega$, $V_{DD} = 15\text{ V}$.
- (4) $R_{EXT} = 10\text{ k}\Omega$, $V_{DD} = 5\text{ V}$.
- (5) $R_{EXT} = 10\text{ k}\Omega$, $V_{DD} = 10\text{ V}$.
- (6) $R_{EXT} = 10\text{ k}\Omega$, $V_{DD} = 15\text{ V}$.
- (7) $R_{EXT} = 5\text{ k}\Omega$, $V_{DD} = 5\text{ V}$.
- (8) $R_{EXT} = 5\text{ k}\Omega$, $V_{DD} = 10\text{ V}$.
- (9) $R_{EXT} = 5\text{ k}\Omega$, $V_{DD} = 15\text{ V}$.

Fig. 4. Output pulse width (t_w) as a function of external timing capacitor (C_{EXT})

10.1. Waveforms and test circuit

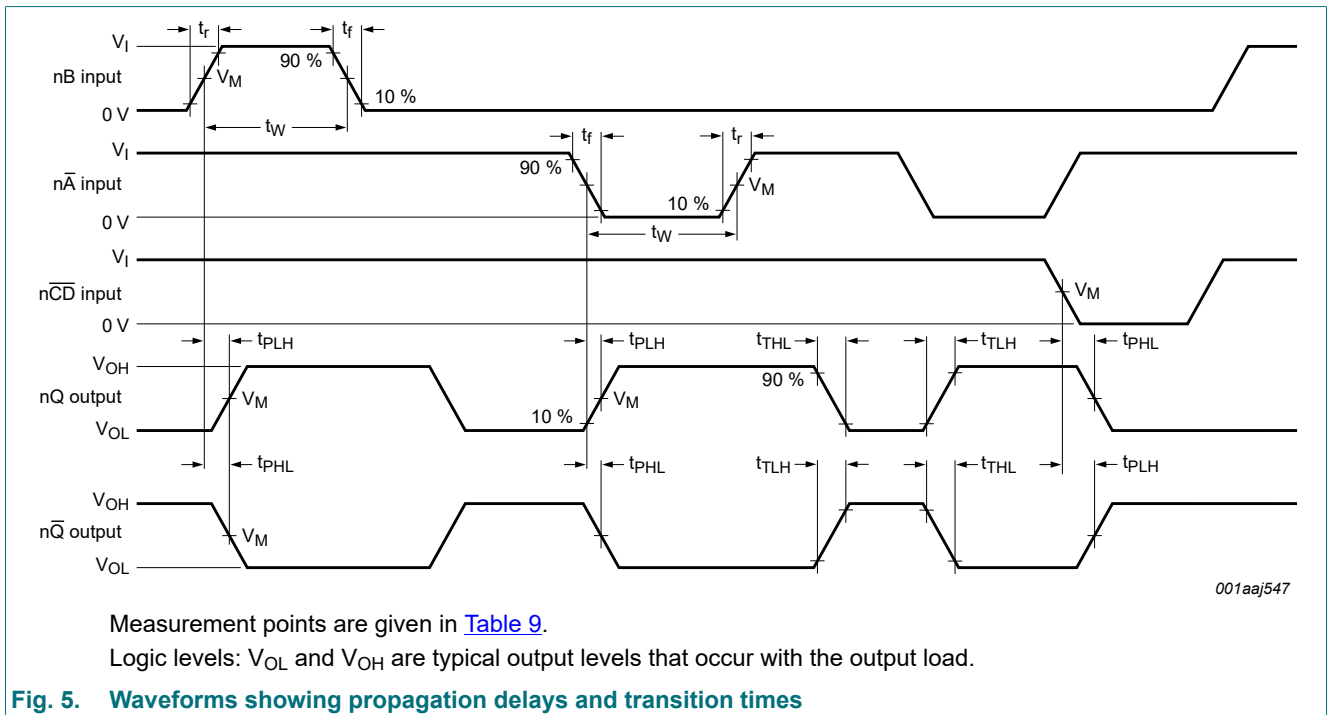


Fig. 5. Waveforms showing propagation delays and transition times

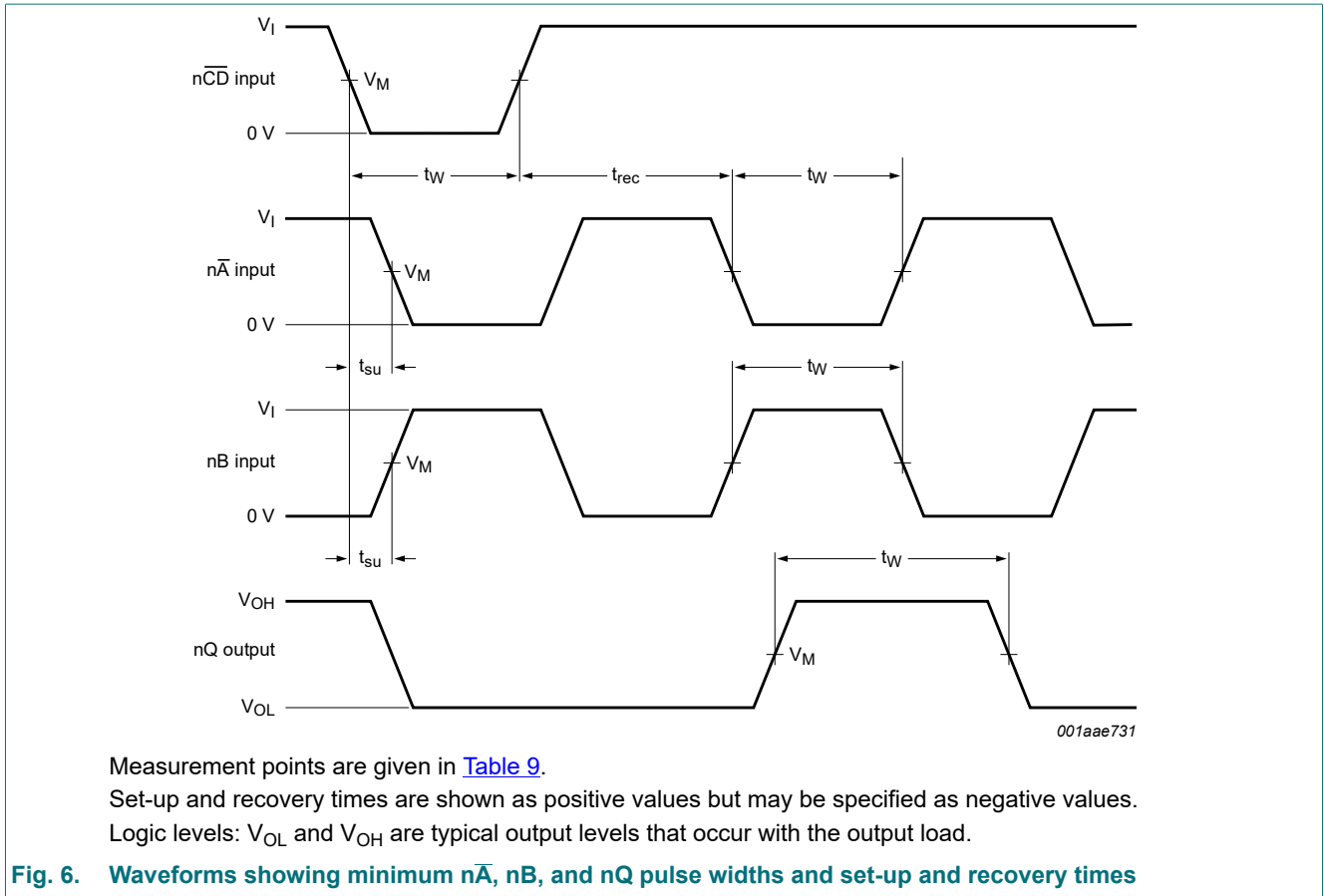
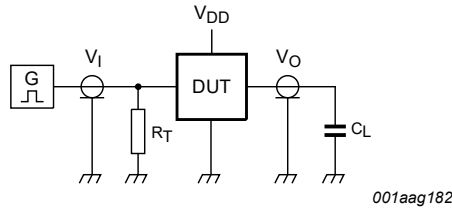


Table 9. Measurement points

| Supply voltage | Input | Output |
|----------------|---------------------|---------------------|
| V_{DD} | V_M | V_M |
| 5 V to 15 V | $0.5 \times V_{DD}$ | $0.5 \times V_{DD}$ |



Test data is given in [Table 10](#).

Definitions for test circuit:

C_L = load capacitance including jig and probe capacitance;

R_T = termination resistance should be equal to the output impedance Z_o of the pulse generator.

Fig. 7. Test circuit for measuring switching times

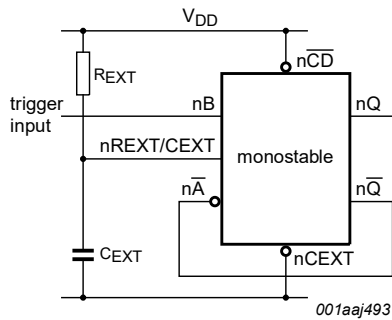
Table 10. Test data

| Supply voltage | Input | | Load |
|----------------|----------------------|--------------|-------|
| V_{DD} | V_I | t_r, t_f | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | 50 pF |

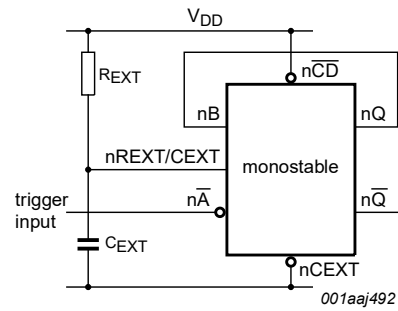
11. Application information

An example of a HEF4528B-Q100 application is:

- Non-retriggerable monostable multivibrator



a. Rising edge triggered



b. Falling edge triggered

Fig. 8. Non-retriggerable applications

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

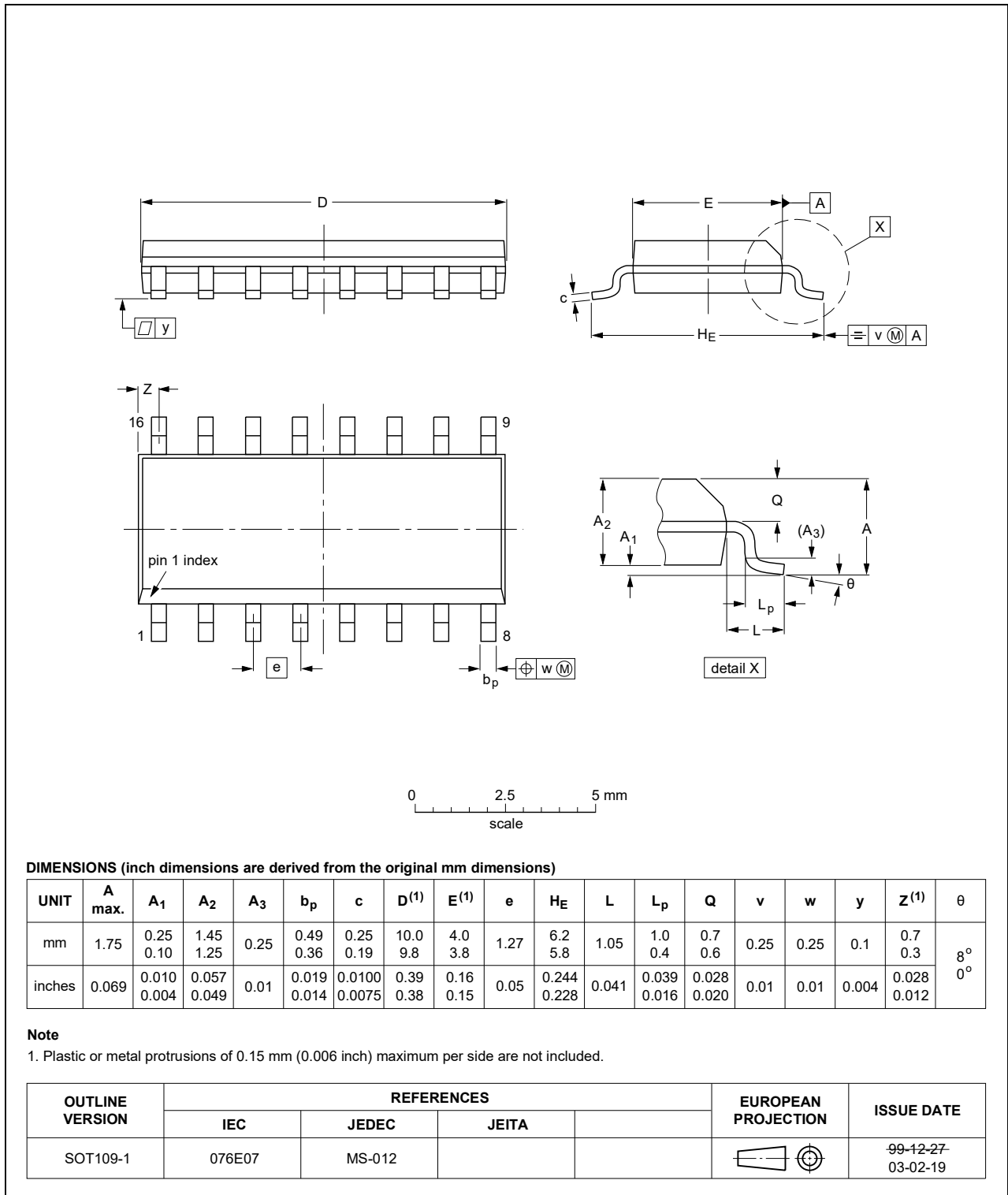


Fig. 9. Package outline SOT109-1 (SO16)

13. Abbreviations

Table 11. Abbreviations

| Acronym | Description |
|---------|-------------------------|
| CDM | Charged Device Model |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| MIL | Military |
| MM | Machine Model |

14. Revision history

Table 12. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|-------------------|--------------------------------------|--------------------|---------------|-------------------|
| HEF4528B_Q100 v.2 | 20220304 | Product data sheet | - | HEF4528B_Q100 v.1 |
| Modifications | • Section 2 updated. | | | |
| HEF4528B_Q100 v.1 | 20170314 | Product data sheet | - | - |

15. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|--------------------------------|--------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

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