

ISL97536

Monolithic 1A Step-Down Regulator with Low Quiescent Current

FN6279  
Rev 1.00  
November 2, 2007

The ISL97536 is a synchronous, integrated FET 1A step-down regulator with internal compensation. It operates with an input voltage range from 2.5V to 6V, which accommodates supplies of 3.3V, 5V, or a Li-ion battery source. The output can be externally set from 0.8V to  $V_{IN}$  with a resistive divider.

The ISL97536 features PWM control with a 1.4MHz typical switching frequency. The typical no load quiescent current is only 500µA. Additional features include a 100ms Power-On-Reset output, <1µA shutdown current, short-circuit protection, and over-temperature protection.

The ISL97536 is available in the 10 Ld MSOP package, making the entire converter occupy less than 0.15in<sup>2</sup> of PCB area with components on one side only. The 10 Ld MSOP package is specified for operation over the full -40°C to +85°C temperature range.

Ordering Information

| PART NUMBER (Note) | PART MARKING | PACKAGE (Pb-Free)           | PKG. DWG. # |
|--------------------|--------------|-----------------------------|-------------|
| ISL97536IUZ        | 7536Z        | 10 Ld MSOP                  | MDP0043     |
| ISL97536IUZ-TK*    | 7536Z        | 10 Ld MSOP<br>Tape and Reel | MDP0043     |
| ISL97536IUZ-T*     | 7536Z        | 10 Ld MSOP<br>Tape and Reel | MDP0043     |

\*Please refer to TB347 for details on reel specifications.

NOTE: These Intersil Pb-free plastic packaged products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate PLUS ANNEAL - e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

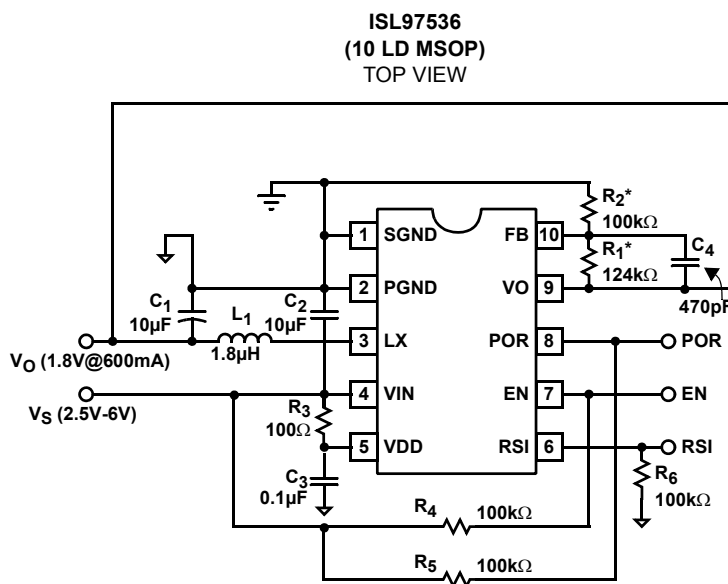
Features

- Less than 0.15in<sup>2</sup> footprint for the complete 1A converter
- Components on one side of PCB
- Max height 1.1mm MSOP10
- 100ms Power-On-Reset output (POR)
- Internally-compensated voltage mode controller
- Up to 95% efficiency
- <1µA shutdown current
- 500µA quiescent current
- Hiccup mode overcurrent and over-temperature protection
- Pb-free (RoHS compliant)

Applications

- PDA and pocket PC computers
- Bar code readers
- Cellular phones
- Portable test equipment
- Li-ion battery powered devices
- Small form factor (SFP) modules

Pinout and Typical Application Diagram



\*  $V_O = 0.8V * (1 + R_1/R_2)$

**Absolute Maximum Ratings** ( $T_A = +25^\circ\text{C}$ )

|                               |                                     |
|-------------------------------|-------------------------------------|
| $V_{IN}, V_{DD}$ , PG to SGND | -0.3V to +6.5V                      |
| LX to PGND                    | -0.3V to ( $V_{IN} + 0.3\text{V}$ ) |
| SYNC, EN, $V_O$ , FB to SGND  | -0.3V to ( $V_{IN} + 0.3\text{V}$ ) |
| PGND to SGND                  | -0.3V to +0.3V                      |
| Continuous Output Current     | 1A                                  |

**Thermal Information**

|                                      |   |
|--------------------------------------|---|
| Thermal Resistance (Typical, Note 1) | $\theta_{JA}$ ( $^\circ\text{C}/\text{W}$ )   |
| 10 Ld MSOP Package                   | 130   |
| Operating Ambient Temperature        | -40 $^\circ\text{C}$ to +85 $^\circ\text{C}$  |
| Storage Temperature                  | -65 $^\circ\text{C}$ to +150 $^\circ\text{C}$   |
| Junction Temperature                 | +125 $^\circ\text{C}$   |
| Pb-free reflow profile               | see link below  |
|                                      | <a href="http://www.intersil.com/pbfree/Pb-FreeReflow.asp">http://www.intersil.com/pbfree/Pb-FreeReflow.asp</a> |

**CAUTION:** Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

**NOTE:**

- $\theta_{JA}$  is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief TB379 for details.

**IMPORTANT NOTE:** All parameters having Min/Max specifications are guaranteed. Typ values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore:  $T_J = T_C = T_A$

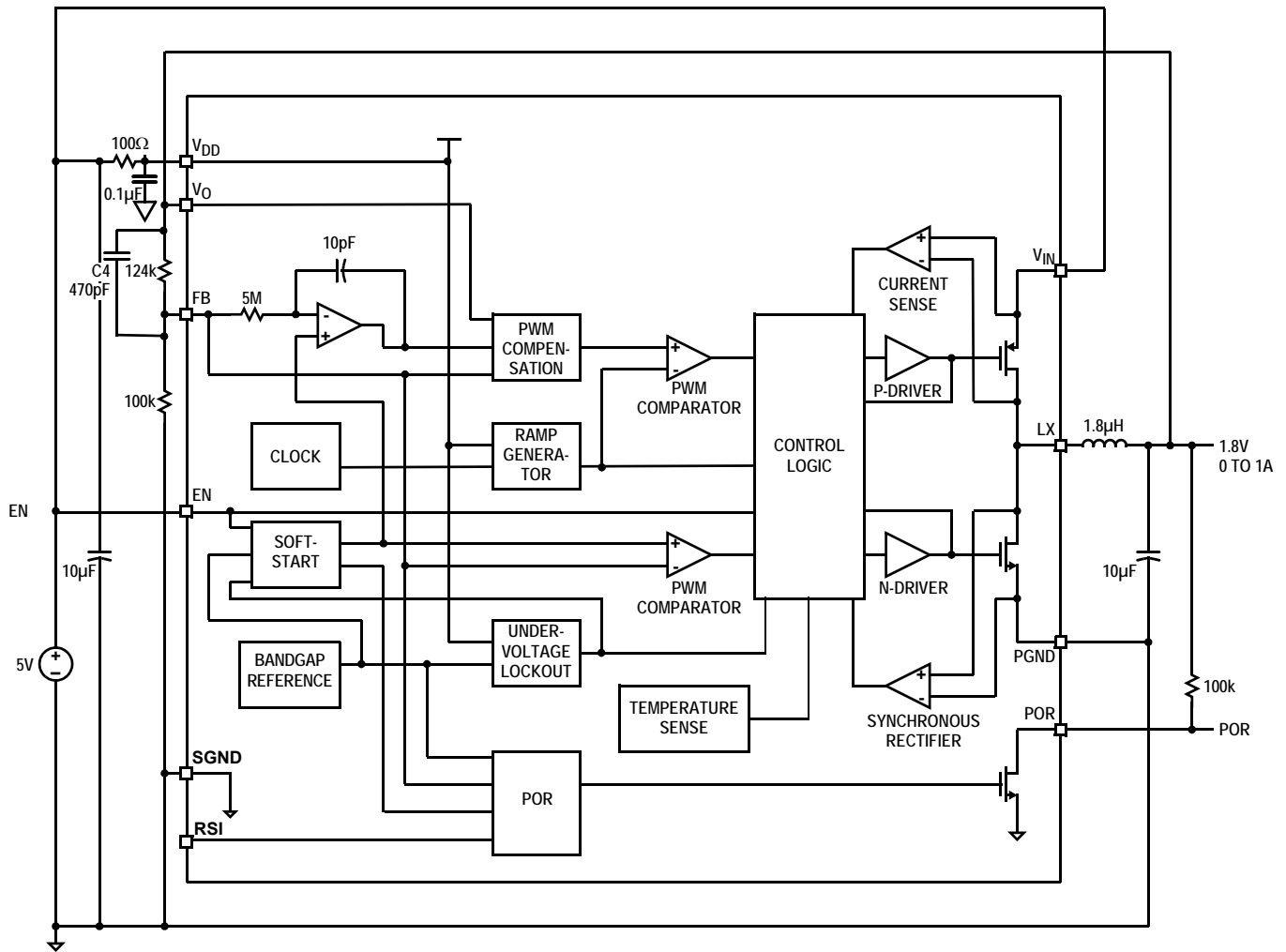
**Electrical Specifications**  $V_{DD} = V_{IN} = V_{EN} = 3.3\text{V}$ ,  $C_1 = C_2 = 10\mu\text{F}$ ,  $L = 1.8\mu\text{H}$ ,  $V_O = 1.8\text{V}$  (as shown in "Pinout and Typical Application Diagram" on page 1),  $T_A = -40^\circ\text{C}$  to +85 $^\circ\text{C}$  unless otherwise specified.

| PARAMETER                 | DESCRIPTION   | CONDITIONS                                       | MIN  | TYP | MAX | UNIT             |
|---------------------------|---|--|------|-----|-----|------------------|
| <b>DC CHARACTERISTICS</b> |   |  |      |     |     |                  |
| $V_{FB}$                  | Feedback Input Voltage                                |  | 790  | 800 | 810 | mV               |
| $I_{FB}$                  | Feedback Input Current                                |  |      |     | 250 | nA               |
| $V_{IN}, V_{DD}$          | Input Voltage   |  | 2.5  |     | 6   | V                |
| $V_{IN,OFF}$              | Minimum Voltage for Shutdown                          | $V_{IN}$ falling, $T_A = +25^\circ\text{C}$ only | 2    |     | 2.2 | V                |
| $V_{IN,ON}$               | Maximum Voltage for Start-up                          | $V_{IN}$ rising, $T_A = +25^\circ\text{C}$ only  | 2.2  |     | 2.4 | V                |
| $I_{DD}$                  | Supply Current  | $V_{IN} = V_{DD} = 5\text{V}$                    |      | 400 | 500 | $\mu\text{A}$    |
|                           |   | $EN = 0, V_{IN} = V_{DD} = 5\text{V}$            |      | 0.1 | 3   | $\mu\text{A}$    |
| $r_{DS(ON)-PMOS}$         | PMOS FET Resistance                                   | $V_{DD} = 5\text{V}, T_A = +25^\circ\text{C}$    |      | 70  |     | $\text{m}\Omega$ |
| $r_{DS(ON)-NMOS}$         | NMOS FET Resistance                                   | $V_{DD} = 5\text{V}, T_A = +25^\circ\text{C}$    |      | 45  |     | $\text{m}\Omega$ |
| $I_{LMAX}$                | Current Limit   |  |      | 1.5 |     | A                |
| $T_{OT,OFF}$              | Over-temperature Threshold                            | T rising   |      | 145 |     | $^\circ\text{C}$ |
| $T_{OT,ON}$               | Over-temperature Hysteresis                           | T falling  |      | 130 |     | $^\circ\text{C}$ |
| $I_{EN}, I_{RSI}$         | EN, RSI Current                                       | $V_{EN}, V_{RSI} = 0\text{V}$ and 3.3V           | -1   |     | 1   | $\mu\text{A}$    |
| $V_{EN1}, V_{RSI1}$       | EN, RSI Rising Threshold                              | $V_{DD} = 3.3\text{V}$                           |      |     | 2.4 | V                |
| $V_{EN2}, V_{RSI2}$       | EN, RSI Falling Threshold                             | $V_{DD} = 3.3\text{V}$                           | 0.8  |     |     | V                |
| $V_{POR}$                 | Minimum $V_{FB}$ for POR, WRT Targeted $V_{FB}$ Value | $V_{FB}$ rising                                  |      |     | 95  | %                |
|                           |   | $V_{FB}$ falling                                 | 86   |     |     | %                |
| $V_{OLPOR}$               | POR Voltage Drop                                      | $I_{SINK} = 3.3\text{mA}$                        |      | 35  | 70  | mV               |
| <b>AC CHARACTERISTICS</b> |   |  |      |     |     |                  |
| $F_{PWM}$                 | PWM Switching Frequency                               |  | 1.25 | 1.4 | 1.6 | MHz              |
| $t_{RSI}$                 | Minimum RSI Pulse Width                               | Guaranteed by design                             |      | 25  | 50  | ns               |
| $t_{SS}$                  | Soft-Start Time                                       |  |      | 650 |     | $\mu\text{s}$    |
| $t_{POR}$                 | Power On Reset Delay Time                             |  | 80   | 100 | 120 | ms               |

**Pin Descriptions**

| PIN NUMBER | PIN NAME | PIN FUNCTION   |
|------------|----------|--|
| 1          | SGND     | Negative supply for the controller stage   |
| 2          | PGND     | Negative supply for the power stage  |
| 3          | LX       | Inductor drive pin; high current digital output with average voltage equal to the regulator output voltage   |
| 4          | VIN      | Positive supply for the power stage  |
| 5          | VDD      | Power supply for the controller stage  |
| 6          | RSI      | Resets POR timer   |
| 7          | EN       | Enable   |
| 8          | POR      | Power on reset open drain output   |
| 9          | VO       | Output voltage sense   |
| 10         | FB       | Voltage feedback input; connected to an external resistor divider between $V_O$ and SGND for variable output |

**Block Diagram**



## Performance Curves and Waveforms

All waveforms are taken at  $V_{IN} = 3.3V$ ,  $V_O = 1.8V$ ,  $I_O = 600mA$  with component values shown on page 1 at room ambient temperature, unless otherwise noted.

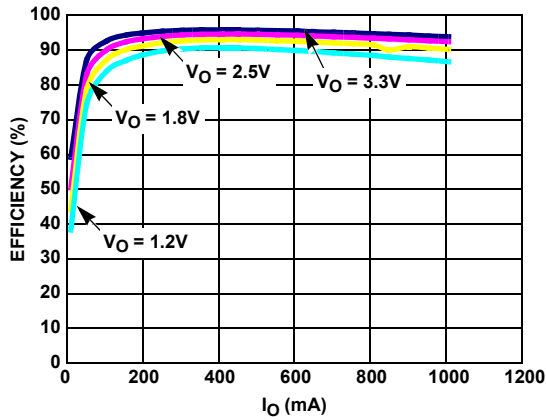


FIGURE 1. EFFICIENCY vs  $I_O$  AT 5V  $V_{IN}$

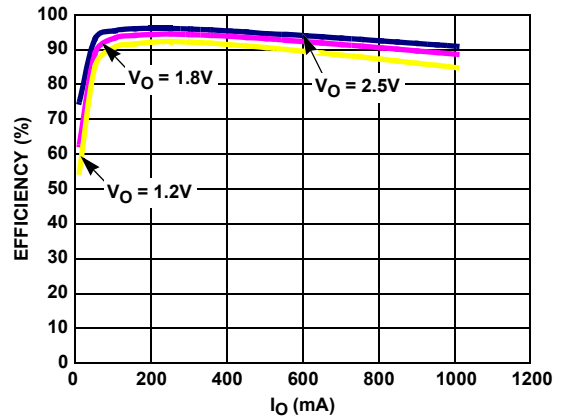


FIGURE 2. EFFICIENCY vs  $I_O$  AT 3.3V  $V_{IN}$

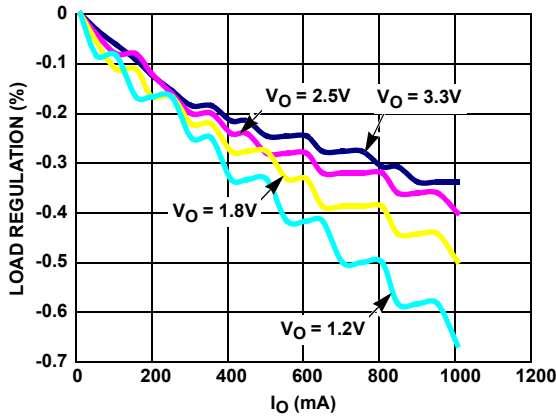


FIGURE 3. LOAD REGULATION vs  $I_O$  AT 5V  $V_{IN}$

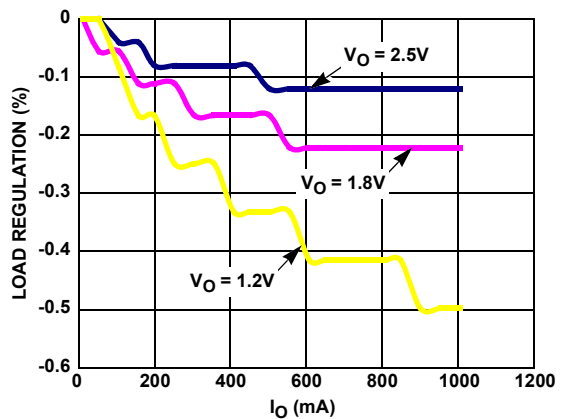


FIGURE 4. LOAD REGULATION vs  $I_O$  AT 3.3V  $V_{IN}$

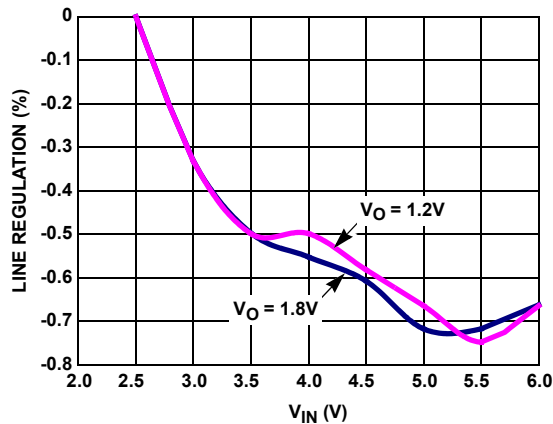


FIGURE 5. LINE REGULATION vs  $V_{IN}$

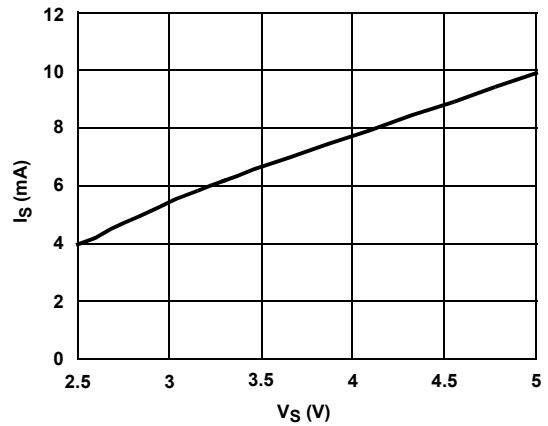


FIGURE 6. NO LOAD QUIESCIENT CURRENT

**Performance Curves and Waveforms** (Continued)

All waveforms are taken at  $V_{IN} = 3.3V$ ,  $V_O = 1.8V$ ,  $I_O = 600mA$  with component values shown on page 1 at room ambient temperature, unless otherwise noted.

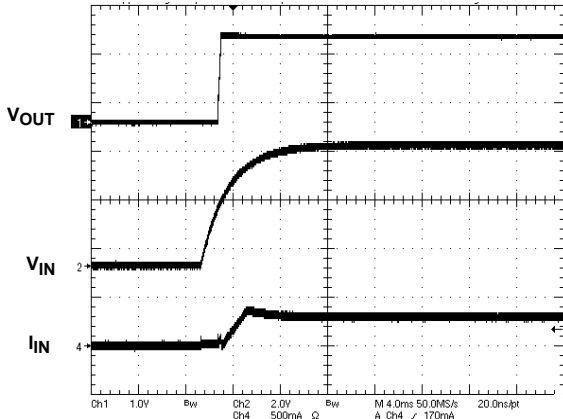


FIGURE 7. START-UP AT  $I_O = 600mA$

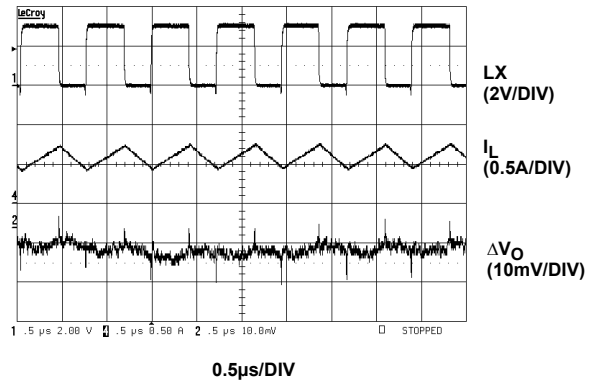


FIGURE 8. PWM STEADY-STATE OPERATION ( $I_O = 600mA$ )

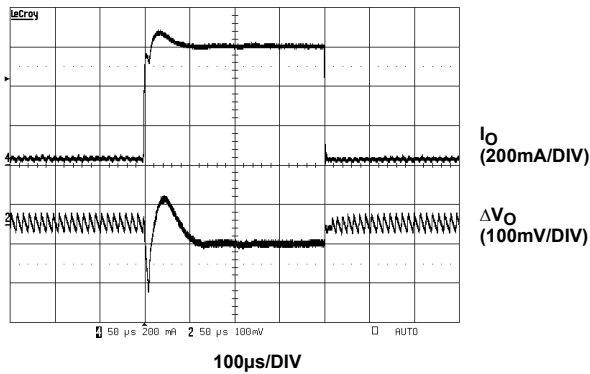


FIGURE 9. LOAD TRANSIENT RESPONSE (22mA TO 600mA)

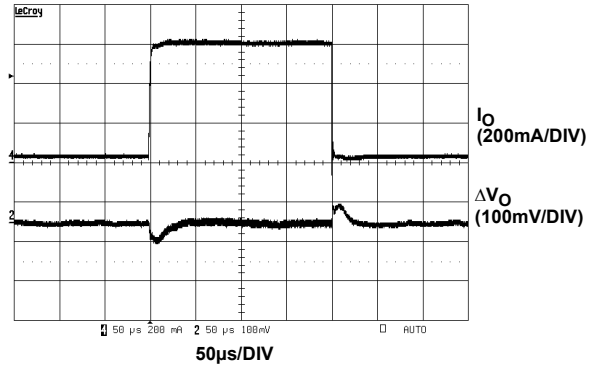


FIGURE 10. LOAD TRANSIENT RESPONSE (30mA TO 600mA)

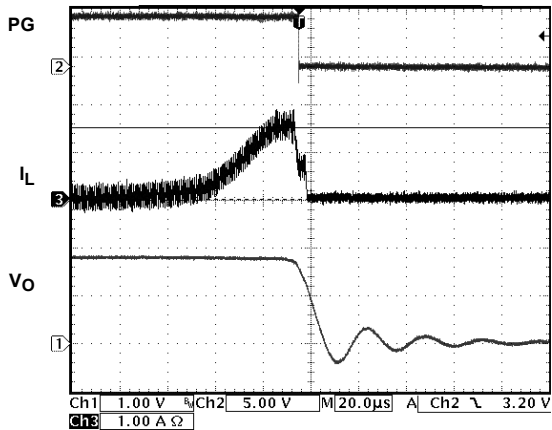


FIGURE 11. OVERCURRENT SHUTDOWN

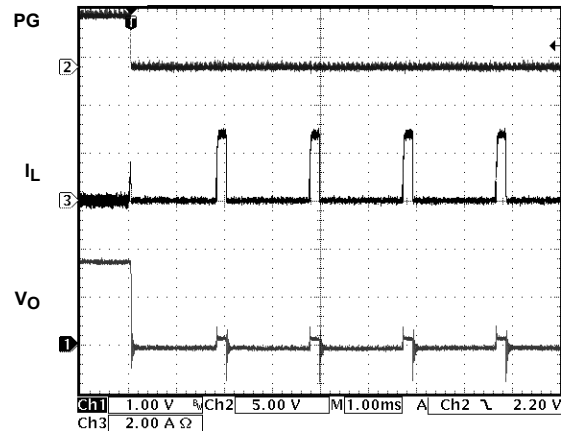


FIGURE 12. OVERCURRENT HICCUP MODE

## Applications Information

### Product Description

The ISL97536 is a synchronous, integrated FET 1A step-down regulator which operates from an input of 2.5V to 6V. The output voltage is user-adjustable with a pair of external resistors.

The internally-compensated controller makes it possible to use only two ceramic capacitors and one inductor to form a complete, very small footprint 1A DC/DC converter.

### PWM Operation

In PWM switching mode, the P-Channel MOSFET and N-Channel MOSFET always operate complementary. When the P-Channel MOSFET is on and the N-Channel MOSFET off, the inductor current increases linearly. The input energy is transferred to the output and also stored in the inductor. When the P-Channel MOSFET is off and the N-Channel MOSFET on, the inductor current decreases linearly, and energy is transferred from the inductor to the output. Hence, the average current through the inductor is the output current. Since the inductor and the output capacitor act as a low pass filter, the duty cycle ratio is approximately equal to  $V_O$  divided by  $V_{IN}$ .

The output LC filter has a second order effect. To maintain the stability of the converter, the overall controller must be compensated. This is done with the fixed internally compensated error amplifier and the PWM compensator. Because the compensations are fixed, the values of input and output capacitors are 10 $\mu$ F to 40 $\mu$ F ceramic and inductor is 1.5 $\mu$ H to 2.2 $\mu$ H.

### Start-Up and Shutdown

When the EN pin is tied to  $V_{IN}$ , and  $V_{IN}$  reaches approximately 2.4V, the regulator begins to switch. The inductor current limit is gradually increased to ensure proper soft-start operation.

When the EN pin is connected to a logic low, the ISL97536 is in the shutdown mode. All the control circuitry and both MOSFETs are off, and  $V_{OUT}$  falls to zero. In this mode, the total input current is less than 1 $\mu$ A.

When the EN reaches logic HI, the regulator repeats the start-up procedure, including the soft-start function.

### Current Limit and Short-Circuit Protection

The current limit is set at about 1.5A for the PMOS. When a short-circuit occurs in the load, the preset current limit restricts the amount of current available to the output, which causes the output voltage to drop as load demand increases. When the output voltage drops 30mV below the reference voltage, the converter will shutdown for a period of time, approximated by Equation 1, and then restart. If the overcurrent condition still exists, it will repeat the shutdown-wait-restart event. This is called a “hiccup” event. The average power dissipation is reduced, thereby reducing

the likelihood of damage current and thermal conditions in the IC as shown in Equation 1.

$$t_{\text{HICCUP}} \approx \left( \frac{700\mu \cdot V_{IN}}{3} + 216\mu \right) \quad (\text{EQ. 1})$$

### Thermal Shutdown

Once the junction reaches about +145°C, the regulator shuts down. Both the P-Channel and the N-Channel MOSFETs turn off. The output voltage will drop to zero. With the output MOSFETs turned off, the regulator will cool down. Once the junction temperature drops to about +130°C, the regulator will perform a normal restart.

### Thermal Performance

The ISL97536 is available in a fused-lead MSOP10. Compared with regular MSOP10 package, the fused-lead package provides lower thermal resistance. The  $\theta_{JA}$  is +100°C/W on a 4-layer board and +125°C/W on 2-layer board. Maximizing the copper area around the pins will further improve the thermal performance.

### RSI/POR Function

When powering up, the open-collector Power-On-Reset output holds low for about 100ms after  $V_O$  reaches the preset voltage. When the active-HI reset signal RSI is issued, POR goes to low immediately and holds for the same period of time after RSI comes back to LOW. The output voltage is unaffected. (Please refer to the timing diagram). When the function is not used, connect RSI to ground and leave open the pull-up resistor  $R_4$  at POR pin.

The POR output also serves as a 100ms delayed Power Good signal when the pull-up resistor  $R_4$  is installed. The RSI pin needs to be directly (or indirectly through a resistor  $R_6$ ) connected to Ground for this to function properly.

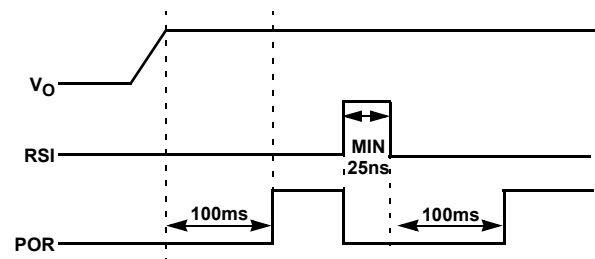


FIGURE 13. RSI AND POR TIMING DIAGRAM

### Output Voltage Selection

Users can set the output voltage of the variable version with a resistor divider, which can be chosen based on Equation 2:

$$V_O = 0.8 \times \left( 1 + \frac{R_1}{R_2} \right) \quad (\text{EQ. 2})$$

### Component Selection

Because of the fixed internal compensation, the component choice is relatively narrow. For a regulator with fixed output voltage, only two capacitors and one inductor are required. Capacitors must be chosen in the range of 10 $\mu$ F to 40 $\mu$ F, multilayer ceramic capacitors with X5R or X7R rating for both the input and output capacitors, and inductors in the range of 1.5 $\mu$ H to 2.2 $\mu$ H.

The RMS current present at the input capacitor is decided by Equation 3:

$$I_{INRMS} = \frac{\sqrt{V_O \times (V_{IN} - V_O)}}{V_{IN}} \times I_O \quad (\text{EQ. 3})$$

This is about half of the output current  $I_O$  for all the  $V_O$ . This input capacitor must be able to handle this current.

The inductor peak-to-peak ripple current is given as shown in Equation 4:

$$\Delta I_{IL} = \frac{(V_{IN} - V_O) \times V_O}{L \times V_{IN} \times f_S} \quad (\text{EQ. 4})$$

$L$  is the inductance

$f_S$  the switching frequency (nominally 1.4MHz)

The inductor must be able to handle  $I_O$  for the RMS load current, and to assure that the inductor is reliable, it must handle the 2A surge current that can occur during a current limit condition.

In addition to decoupling capacitors and inductor value, it is important to properly size the phase-lead capacitor  $C_4$  (Refer to the "Pinout and Typical Application Diagram" on page 1). The phase-lead capacitor creates additional phase margin in the control loop by generating a zero and a pole in the transfer function. As a general rule of thumb,  $C_4$  should be sized to start the phase-lead at a frequency of ~2.5kHz. The zero will always appear at lower frequency than the pole and follow Equation 5:

$$f_Z = \frac{1}{2\pi R_2 C_4} \quad (\text{EQ. 5})$$

Over a normal range of  $R_2$  (~10k to 100k),  $C_4$  will range from ~470pF to 4700pF. The pole frequency cannot be set once the zero frequency is chosen as it is dictated by the ratio of  $R_1$  and  $R_2$ , which is solely determined by the desired output set point. Equation 6 shows the pole frequency relationship:

$$f_P = \frac{1}{2\pi(R_1 || R_2)C_4} \quad (\text{EQ. 6})$$

### Layout Considerations

The layout is very important for the converter to function properly. The following PC layout guidelines should be followed:

1. Separate the Power Ground (  $\downarrow$  ) and Signal Ground (  $\frac{\perp}{\perp}$  ); connect them only at one point right at the pins
2. Place the input capacitor as close to  $V_{IN}$  and PGND pins as possible
3. Make the following PC traces as small as possible:
  - from LX pin to L
  - from  $C_O$  to PGND
4. If used, connect the trace from the FB pin to  $R_1$  and  $R_2$  as close as possible
5. Maximize the copper area around the PGND pin
6. Place several via holes under the chip to additional ground plane to improve heat dissipation

The demo board is a good example of layout based on this outline.