

100MHz to 70GHz Linear-in-dB RMS Power Detector with 35dB Dynamic Range **DESCRIPTION**

FEATURES

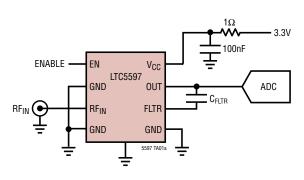
- Ultra Wide Matched Input Frequency Range: 100MHz to 70GHz
- 35dB Linear Dynamic Range (< ±1dB Error)</p>
- 28.5mV/dB Logarithmic Slope
- ±2dB Flat Response from 100MHz to 60GHz
- Accurate RMS Power Measurement of High Crest Factors (Up to 12dB) Modulated Waveforms
- Low Power Shutdown Mode
- Low Supply Current: 33mA at 3.3V (Typical)
- Small 2mm × 2mm Plastic DFN8 Package
- I-Grade: -40°C to 105°C Rated
 H-Grade: -40°C to 125°C Rated
 with Guaranteed Log-Slope and Log-Intercept
- ESD Rating: 2500V HBM, 1500V CDM

APPLICATIONS

- Point-to-Point Microwave Links
- SATCOM
- Instrumentation and Measurement Equipment
- Military Radios
- 5G, LTE, WiFi, Wireless Networks
- RMS Power Measurement
- Receive and Transmit Gain Control
- RF PA Transmit Power Control

TYPICAL APPLICATION

100MHz to 70GHz RMS Power Detector



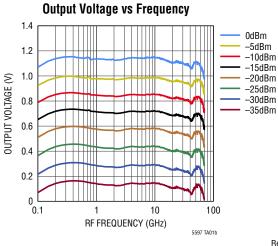
The LTC[®]5597 is a high accuracy RMS power detector that provides a very wide RF input bandwidth, from 100MHz up to 70GHz. This makes the device suitable for a wide range of RF and microwave applications, such as point-to-point microwave links, instrumentation and power control applications.

The DC output voltage of the detector is an accurate representation of the average signal power applied to the RF input. The response is linear-in-dB with 28.5mV/dB logarithmic slope over a 35dB dynamic range with typically better than $\pm 1dB$ accuracy. The detector is particularly suited for measurement of waveforms with crest factor (CF) as high as 12dB, and waveforms that exhibit a significant variation of the crest factor during measurement.

To achieve higher accuracy and lower output ripple, the averaging bandwidth can be externally adjusted by a capacitor connected between the FLTR and OUT pins.

The enable interface switches the device between active measurement mode and a low power shutdown mode.

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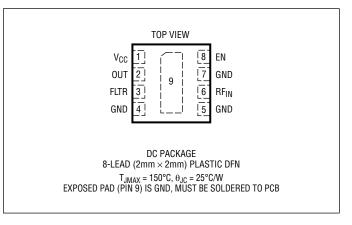


ABSOLUTE MAXIMUM RATINGS

(Note 1)

Supply Voltage (V _{CC})	
RF _{IN} Input Signal Power - Average	
RF _{IN} Input Signal Power - Peak (Note 2).	20dBm
DC Voltage at RF _{IN}	–0.3V to 1V
DC Voltage at FLTR	–0.3V to 0.4V
DC Voltage at EN	0.3V to 3.8V
Т _{ЈМАХ}	150°C
Case Operating Temperature Range (T _C):	
I-Grade (Note 3)	–40°C to 105°C
H-Grade (Note 4)	-40°C to 125°C
Storage Temperature Range	–65°C to 150°C

PIN CONFIGURATION



ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC5597IDC#PBF	LTC5597IDC#TRPBF	LHKF	8-Lead 2mm × 2mm Plastic DFN	-40°C to 105°C
LTC5597HDC#PBF	LTC5597HDC#TRPBF	LHKF	8-Lead 2mm x 2mm Plastic DFN	-40°C to 125°C

Contact the factory for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container.

Tape and reel specifications. Some packages are available in 500 unit reels through designated sales channels with #TRMPBF suffix.

ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T_C = 25°C. V_{CC} = 3.3V, EN = 3.3V. CW, 50 Ω source at RF_{IN}, f_{RF} = 2.7GHz, test circuit is shown in Figure 1.

		- I	-GRADE (NOTE	3)	H-GRADE (NOTE 4)			
PARAMETER	CONDITIONS	MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
RF Input	·	···						
Input Frequency Range			0.1 to 70			0.1 to 70		GHz
Input Impedance			50 50			50 50		Ω fF
Detector Response (RF _{IN} to OUT)					_			
RF Input Power Range, T _C = 25°C ±1dB LOG-Linearity Error (Note 5, 6)	$f_{RF} = 100MHz \\ f_{RF} = 500MHz \\ f_{RF} = 1GHz \\ f_{RF} = 1GHz \\ f_{RF} = 5.8GHz \\ f_{RF} = 10GHz \\ f_{RF} = 15GHz \\ f_{RF} = 15GHz \\ f_{RF} = 24GHz \\ f_{RF} = 24GHz \\ f_{RF} = 30GHz \\ f_{RF} = 30GHz \\ f_{RF} = 30GHz \\ f_{RF} = 50GHz \\ f_{RF} = 52GHz \\ f_{RF} = 52GHz \\ f_{RF} = 60GHz \\ f_{RF} = 67GHz \\ f_{RF} = 70GHz \\ f_{$		$\begin{array}{c} -38.2 \ \text{to} \ 4.5 \\ -41.7 \ \text{to} \ 3.2 \\ -40.8 \ \text{to} \ 3.5 \\ -40.1 \ \text{to} \ 3.5 \\ -40.6 \ \text{to} \ 3.3 \\ -41.1 \ \text{to} \ 3.0 \\ -40.2 \ \text{to} \ 3.7 \\ -40.0 \ \text{to} \ 3.6 \\ -39.3 \ \text{to} \ 4.3 \\ -38.7 \ \text{to} \ 4.7 \\ -38.0 \ \text{to} \ 5.2 \\ -38.1 \ \text{to} \ 5.0 \\ -40.0 \ \text{to} \ 3.0 \\ -39.4 \ \text{to} \ 1.5 \\ -38.3 \ \text{to} \ 0.2 \\ -36.1 \ \text{to} \ 1.9 \end{array}$			-38.2 to 4.5 -41.7 to 3.2 -40.8 to 3.5 -40.1 to 3.5 -40.6 to 3.3 -41.1 to 3.0 -40.2 to 3.7 -40.0 to 3.6 -39.3 to 4.3 -38.7 to 4.7 -38.0 to 5.2 -38.1 to 5.0 -40.0 to 3.0 -40.0 to 2.8 -39.4 to 1.5 -38.3 to 0.2 -36.1 to 1.9		dBm dBm dBm dBm dBm dBm dBm dBm dBm dBm

ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T_C = 25°C. V_{CC} = 3.3V, EN = 3.3V. CW, 50 Ω source at RF_{IN}, f_{RF} = 2.7GHz, test circuit is shown in Figure 1.

			I-GRADE (NOTE	3)		H-GRADE (NOTE 4)		
PARAMETER	CONDITIONS		MIN TYP	MAX	MIN	ТҮР	MAX	UNITS
RF Input Power Range Over Operating	1.10	•	-38.1 to 3.3			-37.1 to 1.2		dBm
Temperature Range	$f_{RF} = 500 MHz$		-38.4 to -0.6			-36.1 to -0.6		dBm
±1dB LOG-Linearity Error (Note 5, 6)	f _{RF} = 1GHz	•	-38.5 to -0.3			-36.7 to -0.3		dBm
	$f_{RF} = 2.7 GHz$		-40.1 to 0.2			-36.6 to 0.2		dBm
	$f_{RF} = 5.8 GHz$		-39.6 to -0.3			-37.0 to -0.3		dBm
	f _{RF} = 10GHz f _{RF} = 15GHz		–39.0 to –0.9 –38.6 to –0.1			-37.0 to -0.9 -36.2 to 0.1		dBm dBm
	$f_{RF} = 13GHZ$		-38.6 to -0.1 -40.0 to 0.3			-36.4 to 0.3		dBm
	$f_{RF} = 24GHz$		-40.0 to 0.3			-36.6 to 0.1		dBm
	$f_{RF} = 28GHz$		-39.2 to 0.8			-36.0 to 0.8		dBm
	f _{RF} = 30GHz		-38.7 to 1.7			-37.2 to 1.7		dBm
	f _{RF} = 39GHz		-37.9 to 3.0			-36.7 to 2.1		dBm
	f _{BF} = 42GHz		-38.1 to 2.0			-38.1 to 1.2		dBm
	f _{BF} = 50GHz		-40.0 to -0.2			-36.3 to -2.9		dBm
	f _{BF} = 52GHz		-39.4 to -0.8			-35.4 to -4.0		dBm
±2dB LOG-Linearity Error (Note 5, 6)	f _{BF} = 60GHz		-40.0 to -0.9			-34.9 to -3.7		dBm
±3dB LOG-Linearity Error (Note 5, 6)	f _{RF} = 67GHz		-40.1 to -0.2			-31.1 to -4.3		dBm
±3dB LOG-Linearity Error (Note 5, 6)	f _{RF} = 70GHz		–36.1 to –0.1					dBm
±3.5dB LOG-Linearity Error (Note 5, 6)	f _{RF} = 70GHz	•				-27.6 to -3.2		dBm
Linear Dynamic Range, T _C = 25°C	f _{RF} = 100MHz		42.7			42.7		dB
(Note 6)	$f_{RF} = 500 MHz$		44.8			44.8		dB
	$f_{RF} = 1GHz$		44.3			44.3		dB
	$f_{RF} = 2.7 GHz$		43.7			43.7		dB
	$f_{RF} = 5.8 GHz$		43.9			43.9		dB
	f _{RF} = 10GHz		44.0			44.0		dB
	$f_{RF} = 15GHz$		43.8			43.8		dB
	$f_{RF} = 18GHz$		43.6 43.7			43.6		dB
	f _{RF} = 24GHz f _{RF} = 28GHz		43.7			43.7 43.6		dB dB
	$f_{RF} = 30GHz$		43.5			43.5		dB
	$f_{RF} = 39GHz$		43.3			43.3		dB
	$f_{RF} = 42GHz$		43.2			43.2		dB
	f _{RF} = 50GHz		43.0			43.0		dB
	f _{BF} = 52GHz		42.8			42.8		dB
	f _{RF} = 60GHz		40.9			40.9		dB
	f _{BF} = 67GHz		38.4			38.4		dB
	f _{RF} = 70GHz		38.0			38.0		dB
Linear Dynamic Range Over Operating	f _{RF} = 100MHz	•	41.5			38.3		dB
Temperature Range			37.8			35.5		dB
±1dB LOG-Linearity Error (Note 6)			38.2			36.5		dB
	$f_{RF} = 2.7 GHz$		40.3			36.8		dB
	1 10		39.3			36.7		dB
	1.10		38.1			36.1		dB
	f _{RF} = 15GHz	•	38.5			36.3		dB
	$f_{RF} = 18GHz$		40.4			36.8		dB
			40.2			36.8		dB
	$f_{RF} = 28GHz$		40.1			36.9		dB
	$f_{RF} = 30GHz$		40.4			38.9		dB dP
	f _{RF} = 39GHz f _{RF} = 42GHz		40.9 40.1			38.8 39.3		dB dB
	$f_{RF} = 42GHZ$ $f_{RF} = 50GHZ$		39.8			39.3 33.4		dB
			39.0 38.6			33.4 31.4		dB
±2dB LOG-Linearity Error (Note 5, 6)	$f_{RF} = 60GHz$		30.0 39.1			31.4		dB
±3dB LOG-Linearity Error (Note 5, 6)	07011		39.9			26.8		dB
±3dB LOG-Linearity Error (Note 5, 6)	1 ····		36.1			20.0		dB
±3.5dB LOG-Linearity Error (Note 5, 6)	f _{RF} = 70GHz		00.1			24.4		dB
	111	-				=		

ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at T_C = 25°C. V_{CC} = 3.3V, EN = 3.3V. CW, 50 Ω source at RF_{IN}, f_{RF} = 2.7GHz, test circuit is shown in Figure 1.

		I-(GRADE (NOTE	3)	H-GRADE (NOTE 4)			
PARAMETER	CONDITIONS	MIN	ΤΥΡ	MAX	MIN	ТҮР	MAX	UNITS
Logarithmic Slope, T _C = 25°C (Note 7)	$ \begin{split} f_{RF} &= 100MHz \\ f_{RF} &= 500MHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 5.8GHz \\ f_{RF} &= 10GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 18GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 39GHz \\ f_{RF} &= 50GHz \\ f_{RF} &= 52GHz \\ f_{RF} &= 60GHz \\ f_{RF} &= 67GHz \\ f_{RF} &= 70GHz \\ \end{split} $		28.6 27.7 28.0 28.5 28.3 28.2 28.4 28.5 28.5 28.6 28.6 28.6 28.7 28.7 28.7 28.3 28.3 28.3 28.3 28.3 28.3		27.1	28.6 27.7 28.0 28.5 28.3 28.2 28.4 28.5 28.5 28.6 28.6 28.6 28.7 28.7 28.7 28.3 28.3 28.3 28.3 28.3 28.3	29.5	mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB
Logarithmic Slope Over Operating Temperature Range (Note 7)	$ \begin{split} f_{RF} &= 100MHz \\ f_{RF} &= 500MHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 2.7GHz \\ f_{RF} &= 5.8GHz \\ f_{RF} &= 10GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 18GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 28GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 50GHz \\ f_{RF} &= 52GHz \\ f_{RF} &= 60GHz \\ f_{RF} &= 67GHz \\ f_{RF} &= 70GHz \\ \end{split} $		27.9 to 29.2 26.9 to 28.4 27.3 to 28.7 27.8 to 29.1 27.6 to 28.9 27.7 to 29.0 27.8 to 29.1 27.8 to 29.1 27.8 to 29.1 27.9 to 29.2 27.9 to 29.3 28.0 to 29.3 28.0 to 29.3 27.7 to 28.9 27.7 to 28.9 27.6 to 28.7 27.6 to 28.7 27.6 to 28.7 27.6 to 28.7 27.2 to 28.0		26.4	27.9 to 29.2 26.9 to 28.4 27.3 to 28.7 27.8 to 29.1 27.6 to 28.9 27.5 to 28.8 27.7 to 29.0 27.8 to 29.1 27.8 to 29.1 27.9 to 29.2 27.9 to 29.3 28.0 to 29.3 28.0 to 29.3 27.7 to 28.9 27.7 to 28.9 27.6 to 28.9 27.6 to 28.7 26.6 to 28.0	30.4	mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB mV/dB
Logarithmic Intercept, T _C = 25°C (Note 8)	$ \begin{split} f_{RF} &= 100MHz \\ f_{RF} &= 500MHz \\ f_{RF} &= 500MHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 1GHz \\ f_{RF} &= 5.8GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 15GHz \\ f_{RF} &= 18GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 24GHz \\ f_{RF} &= 28GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 30GHz \\ f_{RF} &= 50GHz \\ f_{RF} &= 52GHz \\ f_{RF} &= 60GHz \\ f_{RF} &= 67GHz \\ f_{RF} &= 70GHz \\ \end{split} $		$\begin{array}{c} -37.2 \\ -40.7 \\ -39.9 \\ -39.2 \\ -39.7 \\ -40.1 \\ -39.2 \\ -39.1 \\ -39.1 \\ -39.1 \\ -38.3 \\ -37.8 \\ -37.1 \\ -37.2 \\ -39.1 \\ -37.2 \\ -39.1 \\ -39.0 \\ -38.4 \\ -37.3 \\ -35.2 \end{array}$		-40.6	$\begin{array}{r} -37.2 \\ -40.7 \\ -39.9 \\ -39.2 \\ -39.7 \\ -40.1 \\ -39.2 \\ -39.1 \\ -39.1 \\ -39.1 \\ -38.3 \\ -37.8 \\ -37.8 \\ -37.1 \\ -37.2 \\ -39.1 \\ -39.0 \\ -38.4 \\ -37.3 \\ -35.2 \end{array}$	-38.0	dBm dBm dBm dBm dBm dBm dBm dBm dBm dBm

ELECTRICAL CHARACTERISTICS The • denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_C = 25^{\circ}C$. $V_{CC} = 3.3V$, EN = 3.3V. CW, 50 Ω source at RF_{IN}, $f_{RF} = 2.7$ GHz, test circuit is shown in Figure 1.

				I-GRADE (NOTE	3)	H-GRADE (NOTE 4)			
PARAMETER	CONDITIONS		MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
Logarithmic Intercept Over Operating	f _{RF} = 100MHz	•		–37.6 to –36.6			-37.6 to -36.4		dBm
Temperature Range (Note 8)	f _{RF} = 500MHz	•		-41.3 to -39.9			-41.3 to -39.7		dBm
	$f_{RF} = 1 GHz$			-40.3 to -39.0		44.0	-40.3 to -38.8	07.0	dBm
	$f_{RF} = 2.7 GHz$			-39.6 to -38.4		-41.6	-39.6 to -38.2	-37.2	dBm
	$f_{RF} = 5.8 GHz$			-40.1 to -38.9			-40.1 to -38.7		dBm
	f _{RF} = 10GHz f _{BF} = 15GHz			-40.6 to -39.3 -39.7 to -38.4			–40.6 to –39.1 –39.7 to –38.1		dBm dBm
	$f_{RF} = 18GHz$			-39.7 to $-38.4-39.5$ to -38.3			-39.5 to -38.0		dBm
	$f_{RF} = 24GHz$			-39.5 to -38.3			-39.5 to -38.1		dBm
	$f_{RF} = 28GHz$			-38.7 to -37.5			-38.7 to -37.2		dBm
	$f_{\rm RF} = 30 {\rm GHz}$			-38.2 to -37.0			-38.2 to -36.8		dBm
	f _{RF} = 39GHz			-37.4 to -36.4			-37.4 to -36.2		dBm
	$f_{\rm RF} = 42 \rm GHz$			-37.4 to -36.6			-37.4 to -36.4		dBm
	f _{BF} = 50GHz			–39.4 to –38.3			-39.4 to -38.0		dBm
	f _{RF} = 52GHz			–39.3 to –38.2			-39.3 to -37.8		dBm
	f _{RF} = 60GHz			–39.5 to –36.7			–39.5 to –36.3		dBm
	f _{RF} = 67GHz			–38.3 to –35.0			–38.3 to –34.5		dBm
	f _{RF} = 70GHz	•		–36.9 to –33.2			-36.9 to -32.7		dBm
RF Input Power Range for Various	CDMA 9Ch fwd			-40.1 to 2.3			-40.1 to 2.3		dBm
Modulation Formats (Note 9)	CDMA 32Ch fwd			-40.0 to 2.3			-40.0 to 2.3		dBm
	CDMA 64Ch fwd			-39.8 to 2.3			-39.8 to 2.3		dBm
	CDMA 3 Carriers			-40.8 to 1.8			-40.8 to 1.8		dBm
	CDMA 4 Carriers			-40.6 to 2.6			-40.6 to 2.6		dBm
	WCDMA 1Ch Up WCDMA 1Ch Down			-40.2 to 2.8 -40.1 to 2.8			-40.2 to 2.8 -40.1 to 2.8		dBm dBm
	WCDMA 2 Carriers			-40.1 to 2.8			-40.1 to 2.8		dBm
	WCDMA 3 Carriers			-40.2 to 1.0			-40.2 to 1.0		dBm
	WCDMA 4 Carriers			-40.8 to 1.8			-40.8 to 1.8		dBm
	AWGN 5MHz BW			-40.6 to 1.9			-40.6 to 1.9		dBm
	AWGN 10MHz BW			-40.4 to 2.6			-40.4 to 2.6		dBm
	AWGN 15MHz BW			-40.3 to 2.7			-40.3 to 2.7		dBm
Propagation Delay (Note 10)	P _{IN} from –55dBm to 0dBm			1.2			1.2		μs
OUT Interface									
Output DC Voltage	No RF Signal Present EN = 1.1V			1.0	5.0		1.0	5.0	mV
	P _{IN} = 10dBm EN = 1.1V		1.150	1.2	1.250	1.150	1.2	1.250	V
Output Voltage Droop	25mA Sourcing 25mA Sinking		-35	6 30	20	-35	6 30	20	mV mV
Integrated Output Noise	1kHz to 6.5kHz P _{IN} = 0dBm			22			22		μV _{RMS}
Rise Time (Note 11)	50Ω Load at OUT			2.9			2.9		μs
Fall Time (Note 12)	50 Ω Load at OUT			8.1			8.1		μs

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ELECTRICAL CHARACTERISTICS The • denotes the specifications which apply over the full operating

temperature range, otherwise specifications are at $T_c = 25^{\circ}C$. $V_{CC} = 3.3V$, EN = 3.3V. CW, 50 Ω source at RF_{IN} , $f_{RF} = 2.7GHz$, test circuit is shown in Figure 1.

				I-GRADE (NO	FE 3)	H	I-GRADE (NOTE 4)		
PARAMETER	CONDITIONS		MIN	ТҮР	MAX	MIN	ТҮР	MAX	UNITS
Enable (EN) Low = Off, High = On	·								
EN Input High Voltage (On)		•	1.1			1.1			V
EN Input Low Voltage (Off)		٠			0.6			0.6	V
EN Pin Input Current				50	500		50	500	nA
Turn ON Time (Note 13)	50Ω Load at OUT			8			8		μs
Turn OFF Time (Note 14)	50 Ω Load at OUT 1M Ω 11 pF Load at OUT			45 100			45 100		ns µs
Power Supply			•						
Supply Voltage		•	2.7	3.3	3.6	2.7	3.3	3.6	V
Active Supply Current	EN = 3.3V		29.8	33.5	37.3	29.8	33.5	37.3	mA
Shutdown Supply Current	EN = 0V			50	500		50	500	nA

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime. The voltage on all pins should not exceed 3.8V, V_{CC} + 0.3V or be less than -0.3V, otherwise damage to the ESD diodes may occur.

Note 2: Not production tested. Guaranteed by design and correlation to production tested parameters.

Note 3: The LTC5597IDC is guaranteed functional over the case temperature range -40° C to 105° C. All limits at -40° C and 105° C are guaranteed by design and production sample testing.

Note 4: The LTC5597HDC is guaranteed functional over the case temperature range –40°C to 125°C. All limits at –40°C and 125°C are guaranteed by 100% production testing.

Note 5: LOG-Linearity Error is the input-referred power measurement error relative to the best fit straight line (output voltage vs input power in dBm) obtained by linear regression at $T_C = 25^{\circ}C$. The input power range used for the linear regression is from -37dBm to -5dBm for all frequencies. An offset of 0.5dB is added to the LOG-intercept for all frequencies to center the errors over the full temperature range. See also the Application Section for an explanation of measurement error metrics.

Note 6: Range for which the LOG-Linearity Error is within ±1dB.

Note 7: Slope of the best fit straight line obtained by linear regression. **Note 8:** Extrapolated input power level (straight line obtained by linear regression) where the voltage at OUT equals OV.

Note 9: Power range for which LOG-Linearity Error is within ± 1 dB, relative to best fit straight line for CW data (see Note 5).

Note 10: Delay from 50% change in RF_{IN} to 50% change in output voltage. Note 11: Time required to change voltage at OUT pin from 10% to 90% of

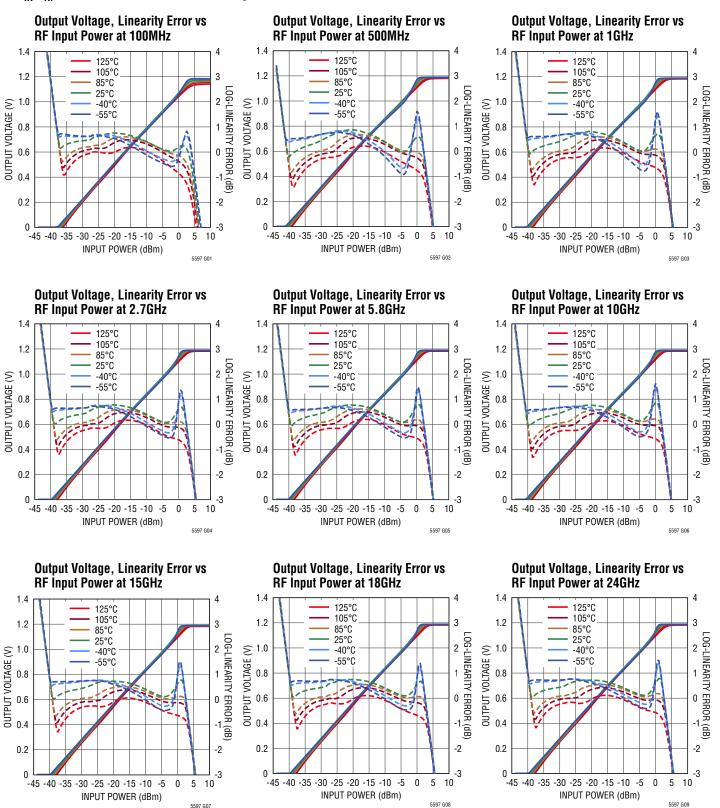
final value. Input power stepped from –55dBm to 0dBm. **Note 12:** Time required to change voltage at OUT pin from 90% to 10% of

Note 12: Time required to change voltage at OUT pin from 90% to 10% of initial value. Input power stepped from 0dBm to –55dBm.

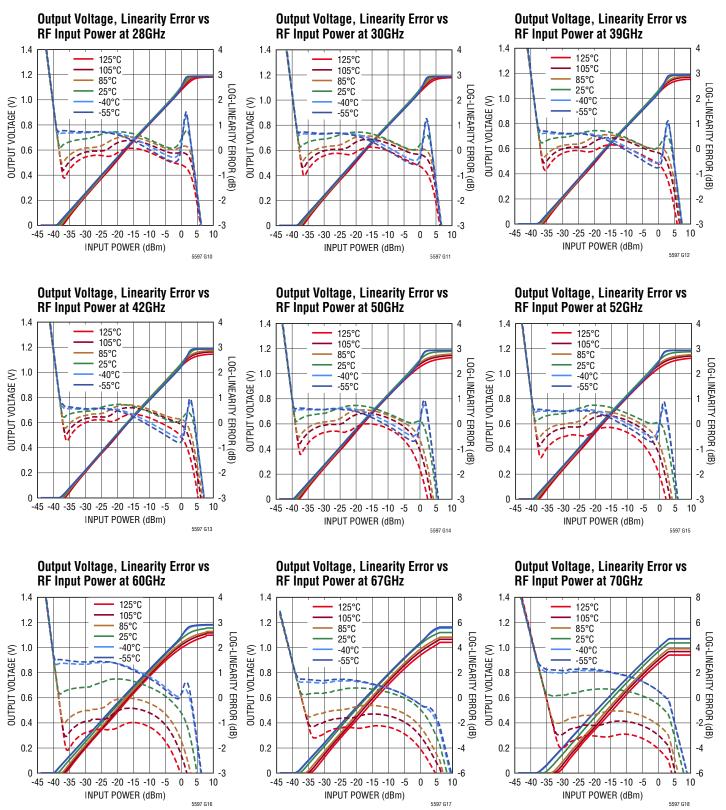
Note 13: Time required to change voltage at OUT pin to 90% of final value. Input power 0dBm.

Note 14: Time required to change voltage at OUT pin to 10% of initial value. Input power 0dBm. For higher load impedance the turn-off time will be (much) larger as the OUT interface is high impedance in shutdown mode.

TYPICAL PERFORMANCE CHARACTERISTICS $V_{CC} = 3.3V$, EN = 3.3V, T_C= 25°C. CW, 50 Ω Source at RF_{IN}, f_{RF} = 2.7GHz, test circuit is shown in Figure 1.



TYPICAL PERFORMANCE CHARACTERISTICS $V_{CC} = 3.3V$, EN = 3.3V, $T_{C} = 25^{\circ}C$. CW, 50 Ω Source at RF_{IN}, $f_{RF} = 2.7$ GHz, test circuit is shown in Figure 1.



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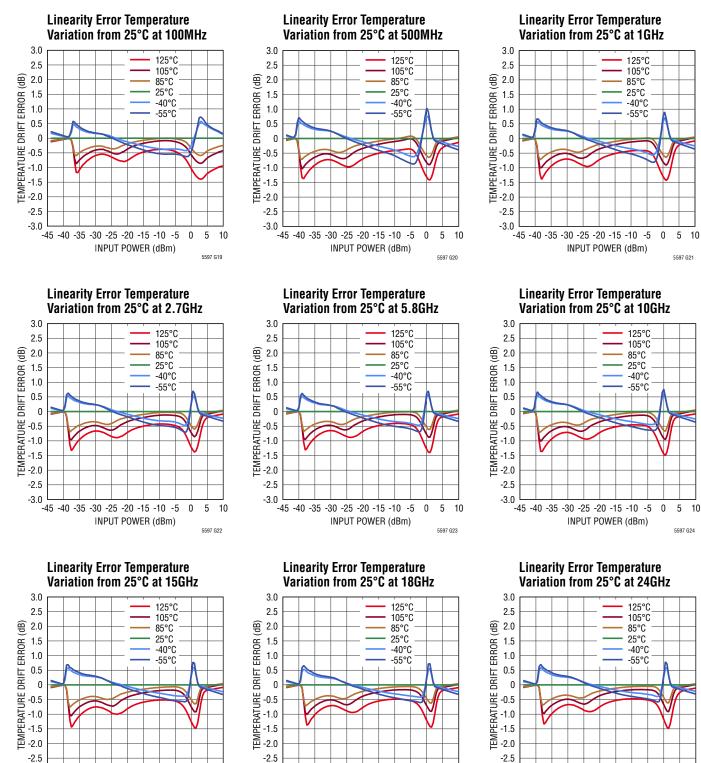
-3.0

-45 -40 -35 -30 -25 -20 -15 -10 -5

INPUT POWER (dBm)

0 5 10

5597 G25



5597 G27

0 5 10

-45 -40 -35 -30 -25 -20 -15 -10 -5

INPUT POWER (dBm)

0 5 10

5597 G26

-3.0

-45 -40 -35 -30 -25 -20 -15 -10 -5

INPUT POWER (dBm)

-3.0

-2.5

-3.0

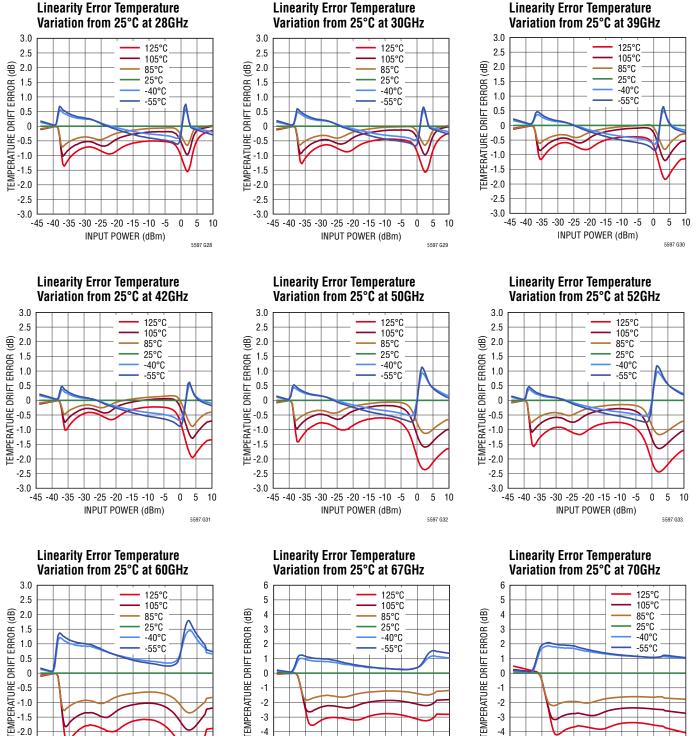
-45 -40 -35 -30 -25 -20 -15 -10 -5

INPUT POWER (dBm)

0 5 10

5597 634

TYPICAL PERFORMANCE CHARACTERISTICS $V_{CC} = 3.3V$, EN = 3.3V, $T_{C} = 25^{\circ}C$. CW, 50 Ω Source at RF_{IN}, $f_{RF} = 2.7$ GHz, test circuit is shown in Figure 1.



-45 -40 -35 -30 -25 -20 -15 -10 -5 0 5 10 INPUT POWER (dBm) 5597 636

-3

-4

-5

-6

-45 -40 -35 -30 -25 -20 -15 -10

INPUT POWER (dBm)

-5 0 5 10

5597 G35

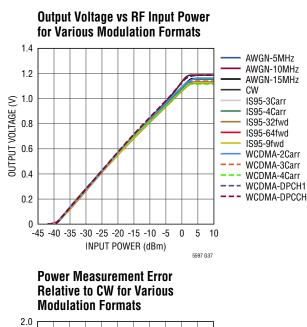
-3

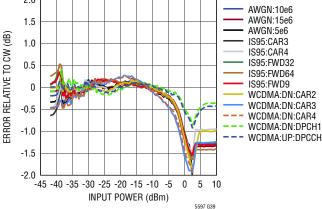
-4

-5

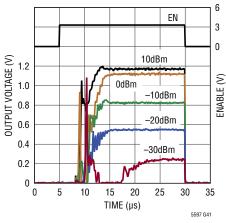
-6

TYPICAL PERFORMANCE CHARACTERISTICS $V_{CC} = 3.3V$, EN = 3.3V, T_C= 25°C. CW, 50 Ω Source at RF_{IN}, f_{RF} = 2.7GHz, test circuit is shown in Figure 1.

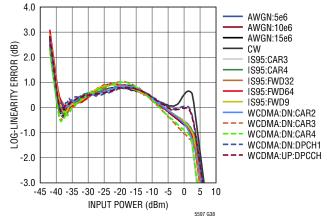




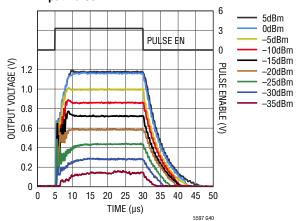




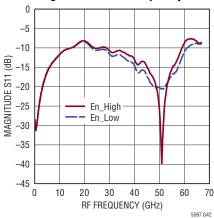
Linearity Error vs RF Input Power for Various Modulation Formats, Regression **Using CW Slope and Intercept Values**



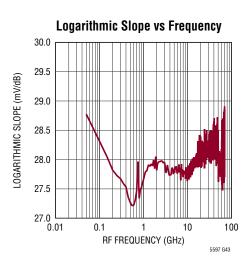
Output Transient Response to RF Input Pulse

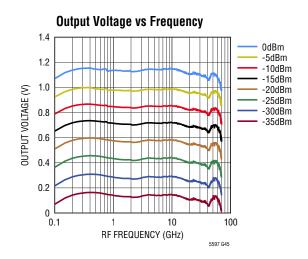


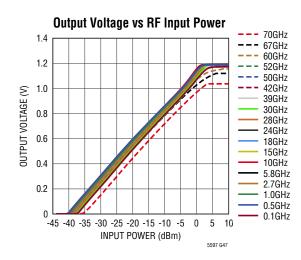


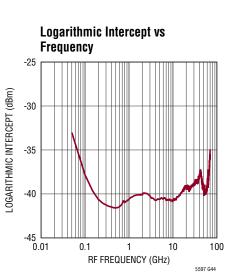


TYPICAL PERFORMANCE CHARACTERISTICS at RF_{IN} , $f_{RF} = 2.7GHz$, test circuit is shown in Figure 1. V_{CC} = 3.3V, EN = 3.3V, T_{C} = 25°C. CW, 50 Ω Source

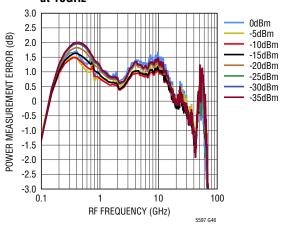




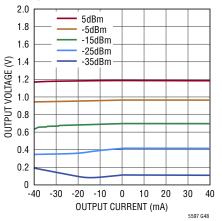




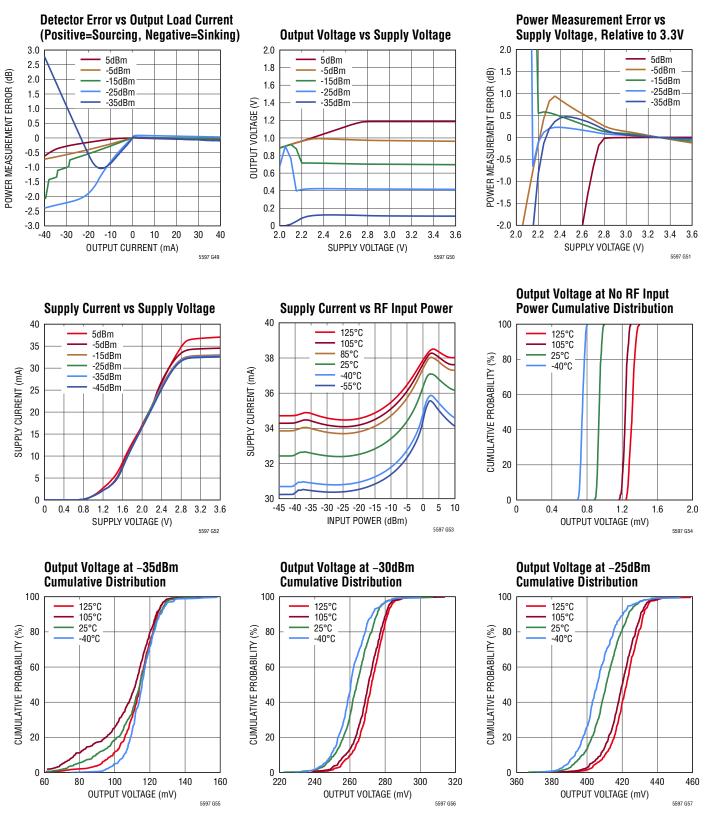
Power Measurement Error vs Frequency, Relative to Response at 18GHz



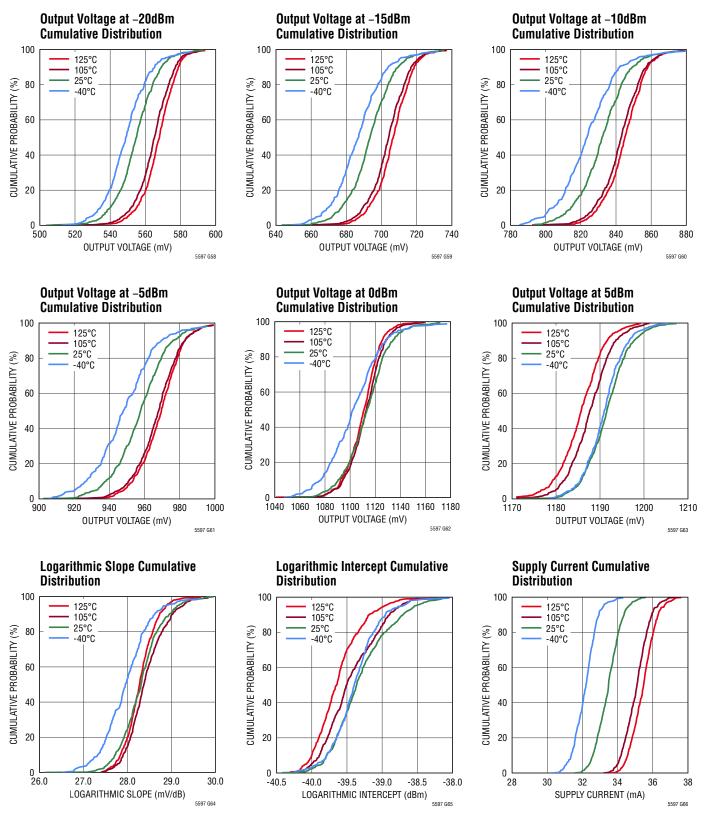
Output Voltage vs Output Current (Positive=Sourcing, Negative=Sinking)



TYPICAL PERFORMANCE CHARACTERISTICS $V_{CC} = 3.3V$, EN = 3.3V, $T_C = 25^{\circ}C$. CW, 50 Ω Source at RF_{IN}, $f_{RF} = 2.7$ GHz, test circuit is shown in Figure 1.



TYPICAL PERFORMANCE CHARACTERISTICS at RF_{IN} , $f_{RF} = 2.7GHz$, test circuit is shown in Figure 1. V_{CC} = 3.3V, EN = 3.3V, T_C= 25°C. CW, 50 Ω Source



Rev. 0

PIN FUNCTIONS

V_{CC} (Pin 1): Power Supply Pin. Typical current consumption is 33mA at room temperature. This pin should be externally bypassed with a 100nF capacitor.

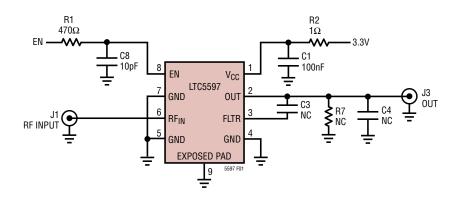
OUT(Pin 2): Detector Output. The DC voltage at this pin varies linearly with the RF input power level in dBm. This output is able to drive a 50 Ω load. To avoid permanent damage, do not short to V_{CC} or GND. In shutdown mode (EN = Low), this interface becomes high impedance, to avoid discharge of capacitors in an external ripple filter.

FLTR (Pin 3): An optional capacitor connected between FLTR and OUT (Pin 2) reduces the detector ripple averaging bandwidth. This will also increase the rise and fall times of the detector. To avoid permanent damage to the circuit, the DC voltage at this pin should not exceed 0.4V.

GND (Pins 4, 5, 7, Exposed Pad Pin 9): Circuit Ground. All ground pins are internally connected together. Pins 5 and 7 should be used as RF return ground and connected to the transmission line interfacing to RF_{IN} (pin 6). $\mathbf{RF_{IN}}$ (Pin 6): RF Input. This pin is internally DC-coupled to GND through a 50 Ω termination resistor. To avoid damage to the internal circuit, the DC voltage applied to this pin should not exceed 1V. The ground-signal-ground arrangement of pins 5 through 7 support termination of pin 6 by a high frequency transmission line, such as a grounded co-planar waveguide (GCPW). No external decoupling capacitor is necessary as long as the DC voltage on pin 6 is kept below 1V.

EN (Pin 8): Chip Enable. A voltage above 1.1V applied to this pin will bring the device into normal operating mode. A voltage below 0.6V will bring the device into a low power shutdown mode. Do not float this pin.

TEST CIRCUIT



REF DES	VALUE	SIZE	PART NUMBER	
C1	100nF	0402	MURATA 935152424610-T3N	
C3, C4	NC	0402		
C8	10pF	0402	MURATA GRM155C1H100JA01D	
R1	470Ω	0402	VISHAY CRCW0402470RFKED	
R2	1Ω	0402	VISHAY CRCW04021R00FNED	
R7	NC	0402		
J1	1.85mm JACK to EDGE- LAUNCH, DC-67GHz		SOUTHWEST MICROWAVE 1892-03A-6	
J3	SMA 50Ω EDGE-LAUNCH		E.F. JOHNSON, 142-0701-851	

Figure 1. Test Schematic Optimized for 100MHz to 70 GHz

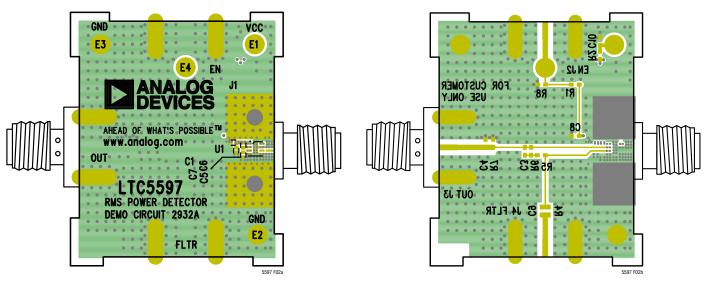


Figure 2a. Top Side of Evaluation Board

Figure 2b. Bottom Side of Evaluation Board

The LTC5597 is a true RMS RF power detector, capable of measuring an RF signal over the frequency range from 100MHz to 70GHz, independent of input waveforms with different crest factors such as CW, WCDMA, OFDM (LTE and WiFi) signals. Up to 35dB dynamic range is achieved with a very stable output within the full case temperature range.

RF Input

The single-ended RF input is internally matched to 50Ω , both in active mode and the low power shutdown mode. The DC voltage applied to this pin should be kept below 1V, to avoid damage to the internal circuitry, depicted in Figure 3.

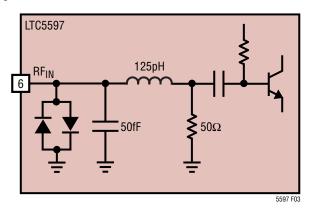


Figure 3. Simplified Schematic of the $\mathrm{RF}_{\mathrm{IN}}$ Interface

Together with GND Pin 5 and Pin 7, RF_{IN} (Pin 6) forms a ground-signal-ground configuration that can interface directly with a co-planar waveguide on the PCB. The recommended design is depicted in Figure 4.

To minimize reflections at high frequencies, the center strip has been chosen the same width as the ${\sf RF}_{\sf IN}$ package pin (10mils).

The LTC5597 evaluation board uses a 5mils thick layer of Rogers RO3003 material for the top substrate to achieve low dielectric losses up to 70GHz. The other two substrates on the board are regular FR-4 material. Using this configuration, a 50 Ω characteristic impedance is obtained for a 9mils gap width between the center strip and the two ground return conductors. Vias connecting the top ground conductors with the second metal ground plane should be placed along the edge of the GCPW top ground

conductors. Via dimensions should be kept as small as possible. The evaluation board uses vias with a diameter of 6mils or 8mils including the metal edge ring (donut).

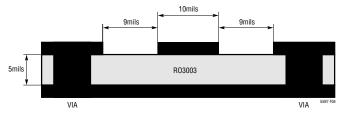


Figure 4. Grounded Co-Planar Waveguide (GCPW) to Interface $\mathrm{RF}_{\mathrm{IN}}$

FLTR Interface (Pin 3):

This pin enables additional suppression of high frequency ripple in the detector output signal, at the expense of a slower detector response (longer rise time, fall time and propagation delay). As depicted in Figure 1, an external capacitor C3 connected between FLTR and OUT enlarges the amount of feedback capacitance across the output amplifier, and reduces the output filter bandwidth without affecting the current drive capability of the LTC5597. Suitable capacitance values are in the range from 10pF up to 1nF, but the total of feedback and load capacitance (from OUT to signal ground) should not exceed 1nF. Larger capacitance values may result in instability of the output driver.

To avoid permanent damage to the chip, the DC voltage at the FLTR pin should not exceed 0.4V. Similarly, it is not recommended to supply a DC bias current to this pin in excess of about 100μ A.

OUT Interface (Pin 2):

The OUT interface, depicted in Figure 5, is a class-AB CMOS output stage that can source and sink over 20mA of load current.

It is able to drive a load resistance of 50Ω (or higher) over the full output voltage range. Short-circuiting the OUT interface should be avoided though, as this can lead to permanent damage of the device. The output driver is stable for capacitive loads up to at least 1nF. This includes any external feedback capacitance between OUT and FLTR, which is essentially experienced as a load by the driver amplifier.

Additional ripple filtering using larger capacitances can be achieved by connecting a series-RC low pass filter to OUT. This however reduces the current drive capability of the output signal, since the filter resistor is placed in series with OUT.

In general, the rise time of the LTC5597 is much shorter than the fall time. An external feedback capacitor between FLTR and OUT increases both rise and fall time, while an RC filter connected in series with OUT will primarily increase the rise time (as long as the time constant is smaller than the fall time).

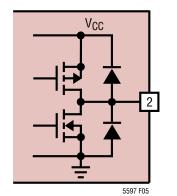


Figure 5. Simplified Schematic of the OUT Interface

The OUT interface becomes high impedance when the device is put into shutdown mode (EN = Low). This prevents discharge of capacitors in a ripple filter connected to the OUT interface. The fall time of the voltage at the OUT interface when the device is turned off (high to low transition of EN) is therefore dependent on the load impedance. Figure 6 shows the output voltage transient when the device is turned off for a 1M Ω load impedance and a 50 Ω load impedance.

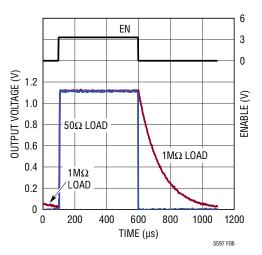


Figure 6. Output Voltage Turn-Off Transient for $1M\Omega\|11pF$ and 50Ω Load Impedance. Input Power OdBm, Input Frequency 2700MHz.

Enable Interface (Pin 8)

A simplified schematic of the EN pin interface is shown in Figure 7. The CMOS logic brings the device in its active operating mode for input voltages above 1.1V. Input voltages below 0.6V bring it into a low power shutdown mode. The voltage applied to the EN pin should never exceed V_{CC} by more than 0.3V, and never decrease below GND by 0.3V. Otherwise, permanent damage to the ESD diodes may occur. Placing an external resistor of at least several hundred Ω in series with the EN interface is an effective way to avoid such damage, by limiting the current flowing through the ESD diodes (see Figure 1).

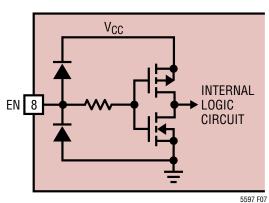


Figure 7. Simplified Schematic of the EN Interface

Supply Voltage Ramping

Fast ramping of the supply voltage can cause a current glitch in the internal ESD protection circuits. Depending on the supply inductance, this could result in a supply voltage overshooting at the initial transient that exceeds the maximum rating. A supply voltage ramp time of greater than 1ms is recommended. In case this voltage ramp time is not controllable, a small series resistor should be inserted in between the V_{CC} pin and the supply voltage source to mitigate the problem and self protect the IC. The 1 Ω resistor R2 and capacitor C1 shown in Figure 1 serve this purpose.

High Accuracy Power Measurement

The power measurement accuracy achieved using a power detector is not only determined by the performance of the power detector device itself, but also by the approach/ methods used to interpret the DC power detector output signal. This can be understood by considering Figure 8.

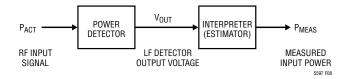


Figure 8. Power Measurement Concept

Systems for accurate power level measurements on RF signals can conceptually be thought to consist of two elements:

- A high accuracy power detector (like the LTC5597), converting the power level of an RF signal into a DC voltage or current;
- An interpreter (also called an estimator), translating the DC output voltage or current of the power detector back to a power level.

In Figure 8, P_{MEAS} represents the power level measured by the system, i.e. the power level the system thinks is present at its input, while P_{ACT} represents the actual power level present at the detector input. The power measurement error thus equals the difference:

 $\mathsf{P}_{\mathsf{ERR}} = \mathsf{P}_{\mathsf{MEAS}} - \mathsf{P}_{\mathsf{ACT}}.$

The more the interpreter knows about the operating conditions and transfer of the detector, the smaller the measurement error that can be achieved. For example, the interpreter may assume that the detector response is perfectly linear in dB, such that the relationship between input power and output voltage is a straight line:

 $V_{OUT} = SLOPE \bullet (P_{MEAS} - P_{INTERCEPT})$

This results in a power measurement error equal to:

LOG-Linearity Error = V_{OUT}/SLOPE + P_{INTERCEPT} - P_{ACT}

The parameters SLOPE and P_{INTERCEPT}, the LOG-slope and LOG-intercept, are best obtained from the actual detector response using linear regression over a suitable power range (where the detector response is close to linear). Better accuracy/smaller errors are obtained if SLOPE and P_{INTERCEPT} are determined for:

- Each detector device individually
- Each operating temperature
- Each operating frequency

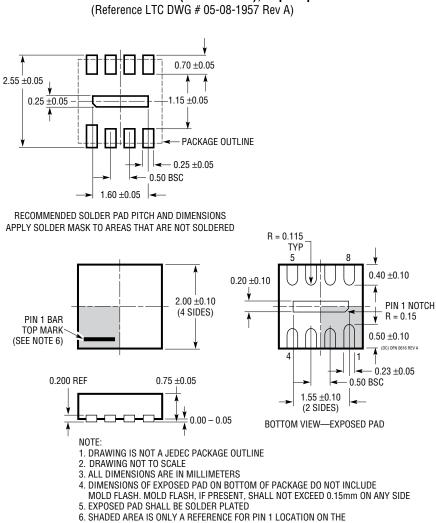
To achieve the best accuracy, it is recommended to determine SLOPE and $P_{INTERCEPT}$ for each individual unit, requiring a 2-point factory calibration. When temperature drift effects are to be included, SLOPE and $P_{INTERCEPT}$ need to be determined at different operating temperatures and the system needs to incorporate a temperature sensor to determine which parameter values to use for the current operating temperature.

The LOG-linearity error curves in the Typical Performance Characteristics section were obtained using linear regression, applied to the response of the individual detector devices at T = 25°C. For all frequencies, the input power range from -37dBm to -5dBm was used. The resulting LOG-linearity error tends to have larger negative values than positive values. To center the error curves within the ±1dB range, an additional 0.5dB was added to the P_{INTERCEPT} parameter. This slightly increases the measurement error at T = 25°C, but results in a smaller error over the full temperature range. The calculated LOG-slope and LOG-intercept numbers are displayed in the tables on page 4 and 5. A better measurement accuracy is achieved if the interpreter uses the actual detector response at T = 25°C as model for the detector, instead of the perfect linear-in-dB response described above. The resulting measurement error, the temperature drift error, equals:

Temperature Drift Error = $[V_{OUT}(T) - V_{OUT}(25^{\circ}C)]/SLOPE$

A system that achieves this measurement error should store the full output voltage vs input power response of the detector with suitable resolution. The error curves displayed on page 9 and 10 represent the achieved power measurement accuracy using this configuration.

PACKAGE DESCRIPTION



DC Package 8-Lead Plastic DFN (2mm × 2mm), Flip Chip

TOP AND BOTTOM OF PACKAGE