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Ultra-Low Quiescent Current PMIC with SIMO Buck-Boost for Wearable Applications



General Description

The MAX20310 is a compact power management integrated circuit (PMIC) for space-constrained, battery-powered applications where size and efficiency are critical. The device combines two single inductor, multiple output (SIMO) buck-boosted outputs with two LDOs and other system power management features like a push-button monitor and sequencing controller.

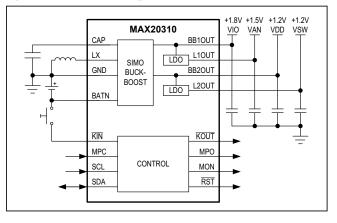
The device includes a SIMO buck-boost switching regulator that provides two programmable voltage rails using a single inductor, minimizing solution footprint. The MAX20310 operates with battery voltages down to 0.7V for use with Zinc Air, Silver Oxide, or Alkaline batteries. The architecture allows for output voltages above or below the battery voltage.

Additionally, the MAX20310 has two programmable lowdropout (LDO) linear regulators. The linear regulators can also operate as power switches that can disconnect the quiescent load of system peripherals.

The MAX20310 includes a programmable power controller that allows the device to be configured for use in applications that require a true off state or for always-on applications. This controller provides a delayed reset signal, voltage sequencing, and customized button timing for on/off control and recovery hard reset.

The device also features a multiplexer for monitoring the power inputs and outputs of each function. The MAX20310 is available in a 16-bump 0.4mm pitch 1.63mm x 1.63mm wafer-level package (WLP) and operates over the -40°C to +85°C extended temperature range.

Typical Operating Circuit



Benefits and Features

- Extend System Battery Use Time
 - Single Inductor, Multiple Output (SIMO) Ultra-Low I_Q Buck-Boost Regulator
 - Battery Input Voltage from 0.7V to 2.0V
 - Output Voltage Programmable From 0.9V to 4.05V
 - 250mW Maximum Total Input Power
 - Incremental CAP Quiescent Current 1µA per channel
 - 84% Efficiency for 1.8V, 10mA Output
 - Input Current Limited
 - Dual Ultra-Low IQ 50mA LDO
 - Inputs Supplied by Dual Buck-Boost Outputs
 - Output Programmable from 0.5V to 3.65V
 - Quiescent Current 1.1µA per LDO / 600nA per Load Switch
 - Configurable as Load Switch
- Extend Product Shelf-Life
 - Battery Seal Mode
 10nA Battery Current (typ)
 - Minimize Board Area
 - 1.63mm x 1.63mm WLP
- Easy-to-Implement System Control
- Voltage Monitor Multiplexer
 - 1% Accurate Battery Inverter (±10mV at 1.0V)
- Power Button Monitor
- Buffered Output
- Power Sequencing
- Reset Output
- I²C Control Interface

Applications

- Wearable Medical Devices
- Wearable Fitness Devices
- Portable Medical Devices

Ordering Information appears at end of data sheet.

19-8611; Rev 3; 12/21

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Absolute Maximum Ratings

Voltages reference to GND unless otherwise noted)
CAP, BB1OUT, BB2OUT, L1OUT, L2OUT
MPC, SDA, SCL, RST, KOUT to GND, BATN0.3V to +6V
KIN (BATN – 0.3V) to (GND + 0.3V)
_X to BATN0.3V to +6V
MPO, MON to BATIN0.3V to +6V
GND to BATN0.3V to +2.2V
Continuous Current into LX, BATN+0.5A

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

PACKAGE TYPE: 16 WLP							
Package Code	W161F1+1						
Outline Number	<u>21-0491</u>						
Land Pattern Number	Refer to Application Note 1891						
THERMAL RESISTANCE, FOUR-LAYER BOARI)						
Junction to Ambient (θ_{JA})	58°C/W						

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

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Electrical Characteristics

 $(V_{BAT} = +1.2V, V_{BB1OUT} = +1.8V, V_{BB2OUT} = +1.2V, V_{L1OUT} = +1.5V, V_{L2OUT} = +1.0V, I_{BB1OUT} = I_{BB2OUT} = I_{L1OUT} = I_{L2OUT} = 0A, T_A = -40^{\circ}C$ to +85°C, all registers in their default state, unless otherwise noted. Typical values are at T_A = +25°C) (Note 1) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
SUPPLY CURRENT	1						
Seal Input Current	I _{SEAL}	Seal mode, all functions disabled, T _A = +25°C		0.01	0.2	μA	
KIN Pullup Resistor to GND	KIN _{PULLUP}			465		kΩ	
		Buck-boost 1 enabled		4		μA	
CAP Quiescent Current		Buck-boost 1 and 2 enabled		5		μA	
CAP Quiescent Current	IQ_CAP	Buck-boost 1 and 2 and LDO 1 enabled		5.25		μA	
		Buck-boost 1 and 2 and LDO 1 and 2 enabled		5.5		μA	
POWER SEQUENCE	1	F					
Reset Time Accuracy	t _{RST}		-10		+10	%	
BUCK-BOOST REGULA	TOR						
Input Voltage	V _{BAT}	Operating	0.7		2	v	
	- DAI	Startup	0.8		2		
Output Voltage Range	V _{OUT}	50mV steps, (Note 3)	0.9		4.05	V	
Quiescent Supply Current From CAP	I _{Q_BB}	Burst mode, no switching, V_{BB_OUT} = +1.8V		1		μA	
		T _A = +25°C	-1		1		
Output Accuracy	V _{OUT_ACC_BB_OUT}	$T_A = 0^{\circ}C$ to +85°C	-1.8		+1.8	%	
		$T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$	-3		+3		
Power Supply Rejection Ratio	PSRR	C _{BB_OUT} = 10µF		40		dB	
Maximum Input Power	P _{IN}	(Note 5)	250			mW	
Maximum Input Current	1	$V_{BB_OUT} = +1.8V$		200		mA	
Maximum Input Current	I _{IN}	V _{BB_OUT} = +3.3V		244		mA	
Short-Circuit Current Limit	I _{LIM}	Maximum programmable current setting		0.6		A	
Passive Discharge Resistance	R _{PAS_BB_OUT}			10		kΩ	
LDO							
Quiescent Supply		LDO UVLO enabled		1.1	2		
Current	IQ_LDO	Switch mode, V _{BB_OUT} = +1.8V		0.4		μA	
Quiescent supply Current in Dropout	IQ_LDO_D	V _{BB_OUT} = V _{LDO_SET} – 0.1V		1.7	3.5	μA	
Maximum Output Current	I _{MAX_LDO}	(Note 4)	50			mA	
Output Voltage	VOUT LDO	50mV steps	0.5		3.65	V	

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Electrical Characteristics (continued)

 $(V_{BAT} = +1.2V, V_{BB1OUT} = +1.8V, V_{BB2OUT} = +1.2V, V_{L1OUT} = +1.5V, V_{L2OUT} = +1.0V, I_{BB1OUT} = I_{BB2OUT} = I_{L1OUT} = I_{L2OUT} = 0A, T_A = -40^{\circ}C$ to +85°C, all registers in their default state, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$) (Note 1) (Note 2)

PARAMETER	SYMBOL	CO	NDITIONS	MIN	TYP	MAX	UNITS
Output Accuracy	VOUT_ACC_LDO	V _{BB_OUT} = (V _{LDO_SET} +	$T_A = 0^{\circ}C$ to +85°C	-3		3	%
,	·001_ACC_EDO	0.5V) or higher, I _{LOAD} = 1mA	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	-3.5		+3.5	
Dropout Voltage	V _{DROP_LDO}	V _{BB_OUT} = V _{LDC} I _{LOAD} = 50mA)_SET = +1.8V,			100	mV
Line Regulation	LINEREG _{LDO}	V _{BB_OUT} = (V _{LD} +4.05V	0_SET + 0.5V) to	-1		1	%/V
Load Regulation	LOADREG _{LDO}	$I_{LOAD} = 50 \mu A \text{ to}$	50mA		0.003		%/mA
Passive Discharge Resistance	R _{PAS_LDO}				10		kΩ
Power Switch Mode Resistance	R _{ON_LS}	V _{BB_OUT} = +1.2	/			1	Ω
T 0 T		I _{LDO_OUT} = 0mA			0.7		
Turn-On Time	^t ON_SLOPE	I _{LDO_OUT} = 0mA	. Switch mode.		2.8		V/µs
Thermal Shutdown Threshold	T _{SD}	T _J rising			150		°C
Thermal Shutdown Hysteresis	T _{HYS}				21		°C
MONITOR MULTIPLEXE	R	·					
MON Impedance	R _{MON}	Sense pin voltage	e > +0.5V			500	Ω
Battery Voltage Buffer Precision	V _{BAT_OFF}			-10		10	mV
DIGITAL SIGNALS							
SDA, SCL, MPC Input Logic-High	V _{IH}			1.4			V
SDA, SCL, MPC Input Logic-Low	V _{IL}					0.5	V
SDA, RST, KOUT Output Logic-Low	V _{OL}	I _{OL} = 4mA				0.4	V
MPO Output Logic Low	Max	I _{OL} = 4mA to GN	D			0.4	v
MPO Output Logic-Low	V _{OL_MPO}	I _{OL} = 4mA to BA	I _{OL} = 4mA to BATN			0.4	
SCL Clock Frequency	f _{SCL}	(Note 5)		0		400	kHz
Bus Free Time Between a STOP and START Condition	^t BUF			1.3			μs

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Electrical Characteristics (continued)

 $(V_{BAT} = +1.2V, V_{BB1OUT} = +1.8V, V_{BB2OUT} = +1.2V, V_{L1OUT} = +1.5V, V_{L2OUT} = +1.0V, I_{BB1OUT} = I_{BB2OUT} = I_{L1OUT} = I_{L2OUT} = 0A, T_A = -40^{\circ}C$ to +85°C, all registers in their default state, unless otherwise noted. Typical values are at T_A = +25°C) (Note 1) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
START Condition (Repeated) Hold Time	^t HD:STA	(Note 6)	0.6			μs
Low Period of SCL Clock	tLOW		1.3			μs
High Period of SCL Clock	^t HIGH		0.6			μs
Setup Time for a Repeated START	^t SU:STA		0.6	0.6		μs
Condition						μs
Data Hold Time	thd:dat	(Notes 7, 8)	0			μs
Data Setup Time	^t SU:DAT	(Note 7)	100			ns
Setup Time for STOP Condition	^t su:sto		0.6			μs

Note 1: All devices are 100% production tested at $T_A = +25^{\circ}C$. Limits over the operating temperature range are guaranteed by design.

Note 2: V_{BAT} refers to the voltage across the battery terminals; $V_{BAT} = V_{GND} - V_{BATN}$. **Note 3:** Output voltage must not exceed $V_{BB_OUT} - V_{BATN} = 5.0V$.

Note 4: Actual value may be limited by the lower of the capability of the source (battery) or the maximum input power of the MAX20310.

Note 5: Timing must be fast enough to prevent the device from entering sleep mode due to bus low for period > t_{SLEEP}.

Note 6: f_{SCI} must meet the minimum clock low time plus the rise/fall times.

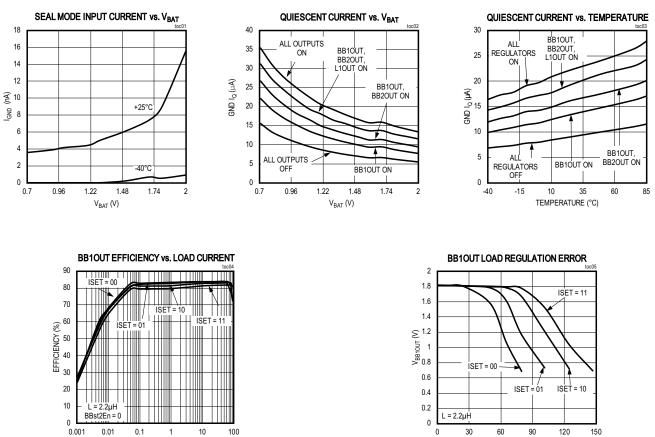
Note 7: The maximum t_{HD:DAT} has to be met only if the device does not stretch the low period (t_{LOW}) of the SCL signal.

Note 8: The device internally provides a hold time of at least 100ns for the SDA signal (referred to the VIH MIN of the SCL signal) to bridge the undefined region of the falling edge of SCL.

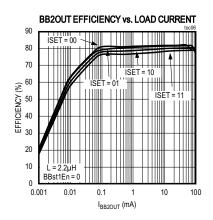
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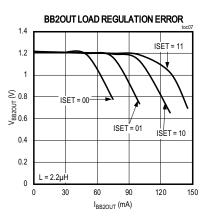
Typical Operating Characteristics

 $(V_{BAT} = 1.2V, V_{BB1OUT} = 1.8V, V_{BB2OUT} = 1.2V, V_{L1OUT} = 1.5V, V_{L2OUT} = 1.0V, L = 1.5\mu$ H, $C_{BB_OUT} = 10\mu$ F (effective), $C_{CAP} = 1\mu$ F (effective), $C_{LDO} = 2.2\mu$ F (effective) no load on any rail, $T_A = +25^{\circ}$ C, unless otherwise noted.)



I_{BB1OUT} (mA)



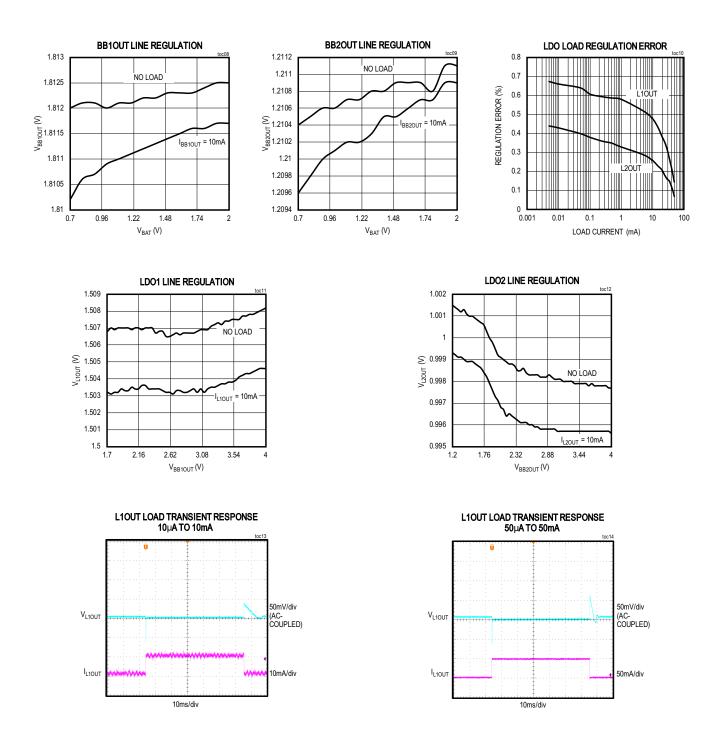


I_{BB1OUT} (mA)

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Typical Operating Characteristics (continued)

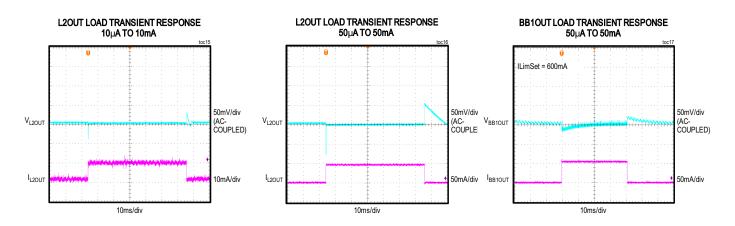
 $(V_{BAT} = 1.2V, V_{BB1OUT} = 1.8V, V_{BB2OUT} = 1.2V, V_{L1OUT} = 1.5V, V_{L2OUT} = 1.0V, L = 1.5\mu$ H, $C_{BB_OUT} = 10\mu$ F (effective), $C_{CAP} = 1\mu$ F (effective), $C_{LDO} = 2.2\mu$ F (effective) no load on any rail, $T_A = +25^{\circ}$ C, unless otherwise noted.)

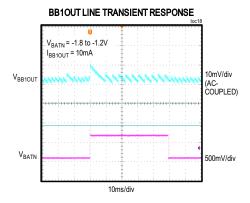


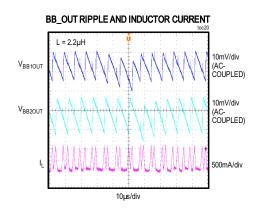
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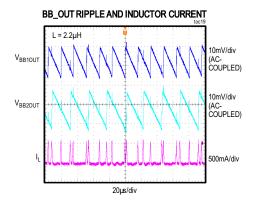
Typical Operating Characteristics (continued)

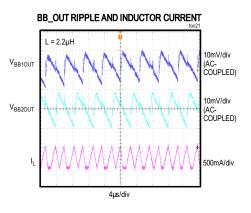
 $(V_{BAT} = 1.2V, V_{BB1OUT} = 1.8V, V_{BB2OUT} = 1.2V, V_{L1OUT} = 1.5V, V_{L2OUT} = 1.0V, L = 1.5\mu$ H, $C_{BB_OUT} = 10\mu$ F (effective), $C_{CAP} = 1\mu$ F (effective), $C_{LDO} = 2.2\mu$ F (effective) no load on any rail, $T_A = +25^{\circ}$ C, unless otherwise noted.)





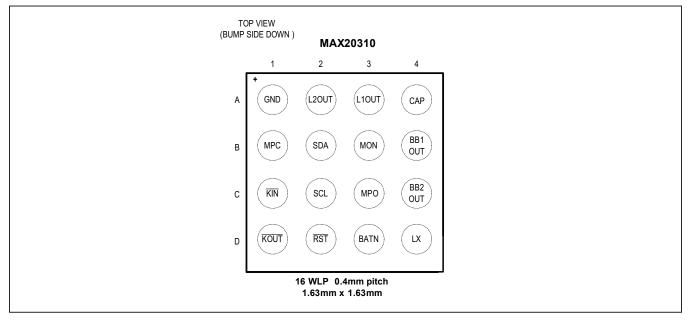






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Bump Configuration

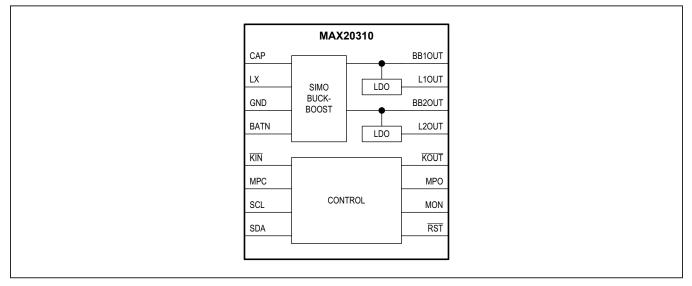


Bump Description

BUMP	NAME	FUNCTION
A1	GND	Ground/Battery Positive Terminal
A2	L2OUT	LDO/Switch 2 Output
A3	L1OUT	LDO/Switch 1 Output
A4	CAP	Internal Supply Decoupling. Connect a minimum 1µF of capacitance to GND.
B1	MPC	Multipurpose Control Input
B2	SDA	I ² C Serial Data
B3	MON	Monitor Multiplexer Output
B4	BB1OUT	Buck-Boost 1 Output
C1	KIN	Key Input, Internally Pulled to GND. To signal active, short KIN to BATN.
C2	SCL	I ² C Serial Clock
C3	MPO	Multipurpose Output. Level shifted digital output for controlling devices referenced to the negative battery terminal.
C4	BB2OUT	Buck-Boost 2 Output
D1	KOUT	Key Output. Active-low, level-shifted button status output.
D2	RST	Reset Output. Active-low, open-drain output indicates completion of sequencer.
D3	BATN	Battery Negative Terminal
D4	LX	Inductor Switch Connection

Ultra-Low Quiescent Current PMIC with SIMO Buck-Boost for Wearable Applications

Functional Block Diagram



Detailed Description

Power Regulation

The MAX20310 features an ultra-low I_Q SIMO buck-boost switching regulator that provides two programmable voltagle rails and two low- I_Q LDOs. The regulators minimize quiescent current and operate on low input voltages. This makes the MAX20310 ideal for applications powered by singe-cell Alkaline, Zinc Air, or Silver Oxide batteries. All regulator outputs are capable of being discharged through a resistive load (passive discharge) when turned off. The discharge mode is set by the PDsc bits in each regulator's configuration register.

Switching Regulator

In order to maximize efficiency, the switching regulator is implemented with an inverting buck-boost topology. Referencing the battery's positive terminal to ground configures the battery as a negative supply and the switching regulator output is positive. The switching regulator operates at supplies from -2.0V down to -0.7V, but requires -0.8V to start up. The outputs are independently configurable in 50mV increments.

LDO

For applications that require lower noise supplies, or simply need additional regulated voltages, the MAX20310 includes two LDO regulators. In normal operation, each LDO can source up to 50mA. The LDO inputs are supplied by the buck-boost outputs. As such, an LDO cannot be enabled unless its corresponding switching regulator output is active. The LDOs can be used as switches to disconnect the quiescent loads of peripheral systems, increasing battery life. The LDO outputs are configurable from 0.5 to 3.65V in 50mV increments.

Voltage Monitor Multiplexer

In addition to the four regulator outputs, the MAX20310 includes a voltage monitor multiplexer. The I²C controlled multiplexer connects the MON pin to any one of the regulator outputs or to BATN. This provides access to the different voltage rails in the device for ADC measurements. An inverting amplifier buffers the BATN channel in order to allow a positive, single-ended ADC to measure the voltage.

Multipurpose Control Input

The MAX20310 includes a multipurpose control (MPC) pin that can control various functions inside the part based on the buck-boost and LDO configuration and sequence register settings. For devices with at least one BBst_Seq[2:0] or LDO_Seq[2:0] field set by the factory to 101 (enabled by MPC, active-low) or 110 (enabled by MPC, active-high) according to Table 19, the MPC pin can be configured to control the multipurpose output (MPO) pin for level-shifting to the battery voltage. See the *Multipurpose Output* section below for details. If the MPC pin is unused, it must be tied to GND.

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Multipurpose Output

In addition to the MPC pin, the MAX20310 also features a multipurpose output (MPO). The MPO pin can be configured to pull down to BATN, to pull up to GND, to pullup/down (push/pull), or be disabled (no pull). On devices with at least one BBst_Seq[2:0] or LDO_Seq[2:0] field set by the factory to 101 (enabled by MPC, activelow) or 110 (enabled by MPC, active-high), as detailed in table 19, the MPOCfg register allows the state of the MPO pin to be controlled either by I²C command or by the MPC pin, regardless of polarity. <u>Table 1</u> below shows the truth table associated with such devices. Devices with none of the one BBst_Seq[2:0] or LDO_Seq[2:0] fields set by the factory to 101 (enabled by MPC, active-low) or 110 (enabled by MPC, active-high) allow the MPO output to be controlled by I²C command only. <u>Table 2</u> below shows the truth table associated with such devices. An example implementation is included in Figure 1 to show how to use this pin to control an external regulator powered directly from the battery.

Table 1. MPO Truth Table for Devices with One or More BBst_Seq[2:0]/LDO_Seq[2:0] Field Set to 101 or 110 by the Factory

MPOP	ull[1:0]	MPOE	in[1:0]	MPC	OUTPUT STATE
0	0	Х	Х	Х	High-Impedance
0	1	0	0	Х	High-Impedance
0	1	0	1	Х	Pulled to BATN
0	1	1	0	0	Pulled to BATN
0	1	1	0	1	High-Impedance
0	1	1	1	0	High-Impedance
0	1	1	1	1	Pulled to BATN
1	0	0	0	Х	Pulled to GND
1	0	0	1	Х	High-Impedance
1	0	1	0	0	High-Impedance
1	0	1	0	1	Pulled to GND
1	0	1	1	0	Pulled to GND
1	0	1	1	1	High-Impedance
1	1	0	0	Х	Pulled to GND
1	1	0	1	Х	Pulled to BATN
1	1	1	0	0	Pulled to BATN
1	1	1	0	1	Pulled to GND
1	1	1	1	0	Pulled to GND
1	1	1	1	1	Pulled to BATN

Table 2. MPO Truth Table for Devices with None of the BBst_Seq[2:0]/LDO_Seq[2:0] Fields Set to 101 or 110 by the Factory

МРОР	ull[1:0]	MPOE	in[1:0]	MPC	OUTPUT STATE
0	0	Х	Х	Х	High-Impedance
0	1	0	0	Х	High-Impedance
0	1	0	1	Х	Pulled to BATN
1	0	0	0	Х	Pulled to GND
1	0	0	1	Х	High-Impedance
1	1	0	0	Х	Pulled to GND
1	1	0 1		Х	Pulled to BATN

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Power On/Off and Reset Control

The MAX20310 is intended for use in small batterypowered applications. It includes an off mode to minimize drain on the battery. In the off mode, all outputs are disabled and the part waits until the KIN input goes active to wake the device. The KIN input is internally pulled to GND and needs to be shorted to BATN to wake the device. An open-drain buffered copy of the state of KIN is available at KOUT allowing the system to monitor the status of the button. When the device is powered on, each function can be automatically enabled by a sequencing controller or remain off until an I²C command enables it. This behavior is determined by the factory settings. A button monitor is present on the MAX20310 and can produce different actions for long or short button presses. The list of settings and corresponding actions is shown in <u>Table 18</u>. A button press always wakes up the device, and the factory configuration determines other behavior.

Reverse Battery Protection

Some applications use batteries like AAA's that do not have mechanical reverse installation protection. In such applications, an optional external nMOSFET and resistor connected as shown in Figure 2 provide reverse battery protection for the system. In normal operation, the 100 Ω resistor slows the charging of C_{IN} at startup until V_{CAP}-V_{BATN} exceeds the threshold of the external MOSFET. Thereafter, the circuit functions nominally. In the case of battery reversal, the 100 Ω resistor limits the current from the battery and protects the downstream system.

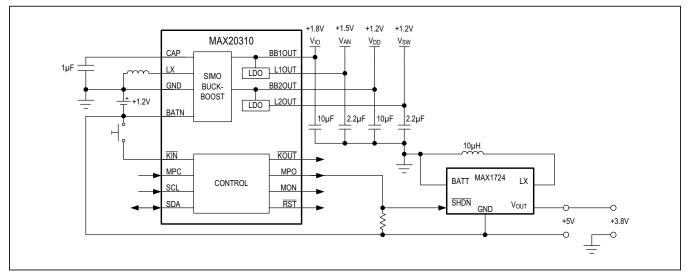


Figure 1. Controlling an External Regulator with MPO

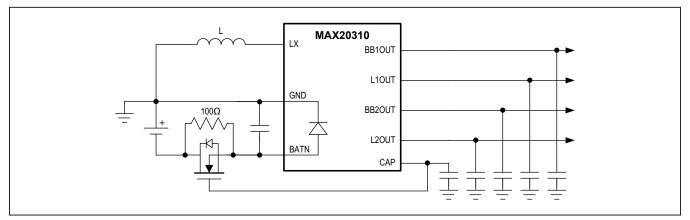


Figure 2. Reverse Battery Protection Using an External MOSFET

Ultra-Low Quiescent Current PMIC with SIMO Buck-Boost for Wearable Applications

Power Sequencing

The sequencing of the voltage regulators during power-on is configurable. Regulators can be configured to turn on at one of four points during the power on process. The four points are: 100ms after the power-on event, after the RST signal is released, or at two points in between. The two points are fixed proportionally to the duration of the Power-On Reset (POR) process, but the overall time of the reset delay is configurable (refer to PwrCfg register). The timing relationship is presented graphically in Figure 3. Additionally, the regulators are controllable by the sequencer, an input pin, or I²C command after reset is released. Note that the LDOs will not turn on until the associated switching output is also enabled.

I²C Interface

The MAX20310 uses the two-wire I^2C interface to communicate with a host microcontroller. The configuration settings and status information provided through this interface are detailed in the register descriptions. The slave address is 0x50 for writes and 0x51 for reads.

Applications Information

Always-On Devices

Due to its low power consumption, the MAX20310 is ideal for always-on applications. Products targeting these always-on, buttonless applications should select a version of the MAX20310 with PwrCfgMd[1:0] = 00 and connect the KIN input to BATN as shown in Figure 4. This PwrCfgMd setting configures a KIN press to only turn on the device. When a fresh battery is inserted, or when a battery tab used during product shelf life is removed, KIN is pulled to BATN and the device turns on.

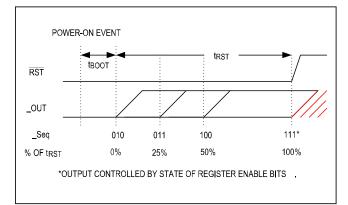


Figure 3. Reset Sequence Programming

Additional Voltage Regulators

In applications with additional voltage regulators operating directly from the battery, careful consideration must be given to battery and system power domains. Due to the negative battery implementation of the MAX20310, the common node for the system power domain (GND) is connected to the positive terminal of the battery.

Regulators using the battery as a positive supply should connect BATN as the local ground and GND as the input supply. However, the output must always be referenced to the positive terminal of the battery (GND). This causes the output voltage of the regulator, referenced to GND, to equal $V_{OUT} - V_{BAT}$. As the battery discharges, this voltage might change over time.

For example, in Figure 1, the external MAX1724 stepup converter produces 5V with respect to the regulator ground (BATN). Because the battery voltage is 1.2V, the output voltage in the system power domain is 3.8V. Due to the relative flatness of the discharge curves for Silver-Oxide, Zinc-Air, and other common coin cell batteries, the challenges associated with a changing reference node are reduced. However, designs should account for some variation of the BATN node.

I²C Interface

The MAX20310 contains an I^2C -compatible interface for data communication with a host controller (SCL and SDA). The interface supports a clock frequency of up to 400kHz. SCL and SDA require pullup resistors that are connected to a positive supply.

Start, Stop, and Repeated Start Conditions

When writing to the MAX20310 using I^2C , the master sends a START condition (S) followed by the MAX20310

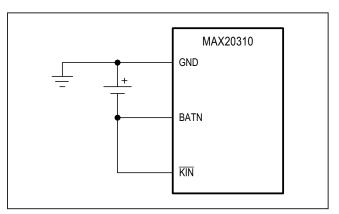


Figure 4. KIN Connected to BATN for Always-On Applications

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I²C address. After the address, the master sends the register address of the register that is to be programmed. The master then ends communication by issuing a

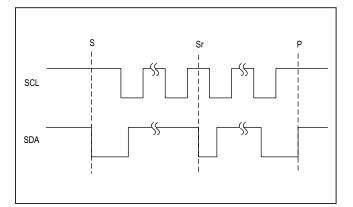


Figure 5. I²C START, STOP and REPEATED START Conditions

STOP condition (P) to relinquish control of the bus, or a REPEATED START condition (Sr) to communicate to another I^2C slave. See Figure 5.

Slave Address

Set the Read/Write bit high to configure the MAX20310 to read mode. Set the Read/Write bit low to configure the MAX20310 to write mode. The address is the first byte of information sent to the MAX20310 after the START condition.

Bit Transfer

One data bit is transferred on the rising edge of each SCL clock cycle. The data on SDA must remain stable during the high period of the SCL clock pulse. Changes in SDA while SCL is high and stable are considered control signals (see the START, STOP and REPEATED START Conditions section). Both SDA and SCL remain high when the bus is not active.

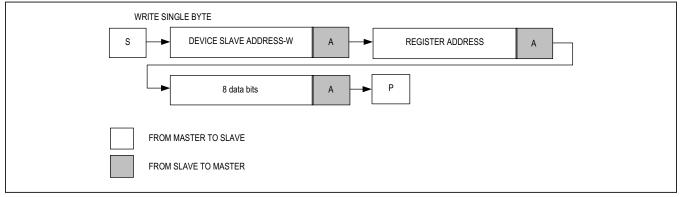


Figure 6. Write Byte Sequence

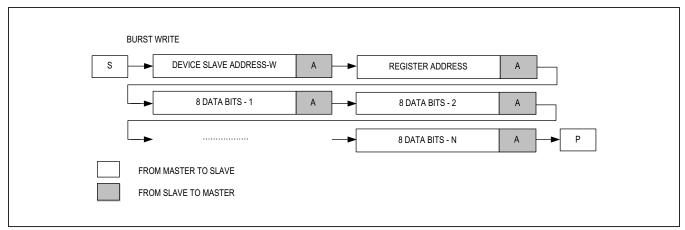


Figure 7. Burst Write Sequence

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Single-Byte Write

In this operation, the master sends an address and two data bytes to the slave device (Figure 6). The following procedure describes the single byte write operation:

The master sends a START condition

The master sends the 7-bit slave address plus a write bit (low)

The addressed slave asserts an ACK on the data line

The master sends the 8-bit register address

The slave asserts an ACK on the data line only if the address is valid (NAK if not)

The master sends 8 data bits

The slave asserts an ACK on the data line

The master generates a STOP condition

Burst Write

In this operation, the master sends an address and multiple data bytes to the slave device (Figure 7). The slave device automatically increments the register address after each data byte is sent, unless the register being accessed is 0x00, in which case the register address remains the same. The following procedure describes the burst write operation:

The master sends a START condition

The master sends the 7-bit slave address plus a write bit (low)

The addressed slave asserts an ACK on the data line

The master sends the 8-bit register address

The slave asserts an ACK on the data line only if the address is valid (NAK if not)

The master sends 8 data bits

The slave asserts an ACK on the data line

Repeat 6 and 7 N-1 times

The master generates a STOP condition

Single-Byte Read

In this operation, the master sends an address plus two data bytes and receives one data byte from the slave device (Figure 8). The following procedure describes the single byte read operation:

The master sends a START condition

The master sends the 7-bit slave address plus a write bit (low)

The addressed slave asserts an ACK on the data line

The master sends the 8-bit register address

The slave asserts an ACK on the data line only if the address is valid (NAK if not)

The master sends a REPEATED START condition

The master sends the 7-bit slave address plus a read bit (high)

The addressed slave asserts an ACK on the data line

The slave sends 8 data bits

The master asserts a NACK on the data line

The master generates a STOP condition

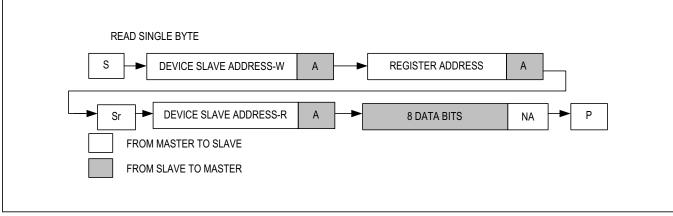


Figure 8. Read Byte Sequence

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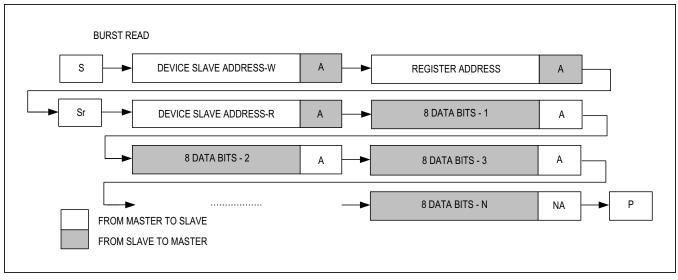


Figure 9. Burst Read Sequence

Burst Read

In this operation, the master sends an address plus two data bytes and receives multiple data bytes from the slave device (Figure 9). The following procedure describes the burst byte read operation:

The master sends a START condition

The master sends the 7-bit slave address plus a write bit (low)

The addressed slave asserts an ACK on the data line

The master sends the 8-bit register address

The slave asserts an ACK on the data line only if the address is valid (NAK if not)

The master sends a REPEATED START condition

The master sends the 7-bit slave address plus a read bit (high)

The slave asserts an ACK on the data line

The slave sends 8 data bits

The master asserts an ACK on the data line

Repeat 9 and 10 N-2 times

The slave sends the last 8 data bits

The master asserts a NACK on the data line

The master generates a STOP condition

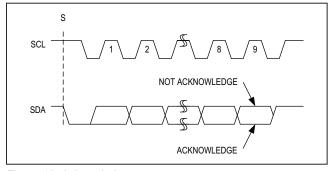


Figure 10. Acknowledge

Acknowledge Bits

Data transfers are acknowledged with an acknowledge bit (ACK) or a not-acknowledge bit (NACK). Both the master and the MAX20310 generate ACK bits. To generate an ACK, pull SDA low before the rising edge of the ninth clock pulse and hold it low during the high period of the ninth clock pulse (see Figure 10). To generate a NACK, leave SDA high before the rising edge of the ninth clock pulse and leave it high for the duration of the ninth clock pulse. Monitoring for NACK bits allows for detection of unsuccessful data transfers.

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	B0	ChipId[0]	ChipRev[0]	FetScale[0]		BBst1VSet[0]		BBst2VSet[0]		LDO1VSet[0]	LDO1Mode	LDO2VSet[0]	LDO2Mode	MonSel[0]	MPOPull[0]	PwrCmd[0]	MPCSts	BootDly[0]	BBst1Seq[0]	LD01Seq[0]
	8	ChipId[1]	ChipRev[1]	FetScale[1]	Ι	BBst1VSet[1]	Ι	BBst2VSet[1]	Ι	LD01VSet[1]	Ι	LD02VSet[1]	Ι	MonSel[1]	MPOPul[1]	PwrCmd[1]	KINSts	BootDly[1]	BBst1Seq[1]	LD01Seq[1]
	B2	Chipld[2]	ChipRev[2]	ILimSet[0]		BBst1VSet[2]		BBst2VSet[2]		LDO1VSet[2]		LDO2VSet[2]		MonSel[2]		PwrCmd[2]	LDO1CrMd		BBst1Seq[2]	LDO1Seq[2]
	B3	ChipId[3]	ChipRev[3]	ILimSet[1]		BBst1VSet[3]	BBst1RmpDis	BBst2VSet[3]	BBst2RmpDis	LDO1VSet[3]		LDO2VSet[3]		MonHiZ		PwrCmd[3]	LDO2CrMd			I
	B4	ChipId[4]	ChipRev[4]			BBst1VSet[4]	BBst1ADsc	BBst2VSet[4]	BBst2ADsc	LDO1VSet[4]	LD01ADsc	LDO2VSet[4]	LDO2ADsc			PwrCmd[4]	LDO1Thm		BBst2Seq[0]	LDO2Seq[0]
	B5	ChipId[5]	ChipRev[5]			BBst1VSet[5]	BBst1PDsc	BBst2VSet[5]	BBst2PDsc	LDO1VSet[5]	LDO1PDsc	LDO2VSet[5]	LD02PDsc			PwrCmd[5]	LDO2Thm	GPasDsc	BBst2Seq[1]	LDO2Seq[1]
	B6	ChipId[6]	ChipRev[6]	Ι		Ι	BBst1En[0]		BBst2En[0]	Ι	LDO1En[0]	Ι	LDO2En[0]		MPOEn[0]	PwrCmd[6]	LD01UVL0	PwrCfgMd[0]	BBst2Seq[2]	LDO2Seq[2]
	B7	ChipId[7]	ChipRev[7]	BBstDmpEn	Ι	Ι	BBst1En[1]	Ι	BBst2En[1]	Ι	LDO1En[1]	Ι	LDO2En[1]	I	MPOEn[1]	PwrCmd[7]	LDO2UVLO	PwrCfgMd[1]	I	Ι
	R/W	Ж	Я	RW		RW	RW	RW	RW	RW	RW	RW	RW	RW	RW	RW	Ж	R	R	Ж
I ² C Register Map	REGISTER NAME	Chipld	ChipRev	BBstCfg	Reserved	BBst1VSet	BBst1VCfg	BBst2VSet	BBst2VCfg	LD01Vset	LDO1Cfg	LDO2Vset	LDO2Cfg	MonCfg	MPOCfg	PwrCmd	Status	PwrCfg	BBstSeq	LDOSeq
I ² C Regi	REGISTER ADDRESS	00X0	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	60x0	0x0A	0x0B	0x0C	0x0D	0x0E	0x0F	0x10	0x11	0x12

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I²C Register Descriptions Table 3. ChipId Register (0x00)

ADDRESS	0x00 (Read-Only)									
BIT	7	7 6 5 4 3 2 1 0								
NAME		Chipld[7:0]								
Chipld[7:0]	ChipId[7:0] b	ChipId[7:0] bits show information about the version of the MAX20310								

Table 4. ChipRev Register (0x01)

ADDRESS	0x01 (Read-Only)									
BIT	7	7 6 5 4 3 2 1 0								
NAME		ChipRev[7:0]								
ChipRev[7:0]	ChipRev sho	ChipRev shows information about the revision of the MAX20310 silicon								

Table 5. BBstCfg Register (0x02)

ADDRESS	0x02 (Read, Wr	0x02 (Read, Write)										
BIT	7	6	5	4	3	2	1	0				
NAME	BBstDmpEn	-	-	-	ILimS	Set[1:0]	FetSc	ale[1:0]				
BBstDmpEn	This enables a 0: Switch disabl	Buck-Boost Dump Enable This enables a dump switch to reduce LX oscillations): Switch disabled): Switch enabled										
ILimSet[1:0]		01: 400mA 10: 500mA										
FetScale[1:0]	FetScale Scales the switching FETs to optimize efficiency at a given load 00: 28% 01: 60% 10: 80% 11: 100%											

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Table 6. BBst1VSet Register (0x04)

ADDRESS	0x04 (Read,	0x04 (Read, Write)									
BIT	7	6	5 4 3 2 1 0								
NAME	-	-		BBst1VSet[5:0]							
BBst1VSet[5:0]		95V 0V		nents							

Table 7. BBst1Cfg Register (0x05)

ADDRESS	0x05 (Read,	0x05 (Read, Write)									
BIT	7	6	5	4	3	2	1	0			
NAME	BBst1Er	BBst1En[1:0] BBst1PDsc — BBst1RmpDis — — —									
BBst1En[1:0]	00: Disabled 01: Enabled 10: Controlle	Buck-Boost 1 Enable 00: Disabled 01: Enabled 10: Controlled by MPC (active low) 11: Controlled by MPC (active high)									
BBst1PDsc	0: Disabled	Buck-Boost 1 Passive Discharge 0: Disabled 1: Enabled when output is off									
BBst1RmpDis	applied to th 1: Immedia	Disable the ramped output of Buck-Boost output 1. If disabled, the BBst1VSet value is immediately applied to the output. 1: Immediate transition to set value 0: Ramp to set value mode									

Table 8. BBst2VSet Register (0x06)

ADDRESS	0x06 (Rea	0x06 (Read, Write)								
BIT	7	6	5 4 3 2 1 0							
NAME	-	-		BBst2VSet[5:0]						
BBst2VSet[5:0]		0.95∨ .00∨		ements						

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Table 9. BBst2Cfg Register (0x07)

ADDRESS	0x07 (Rea	0x07 (Read, Write)									
BIT	7	6	5	4	3	2	1	0			
NAME	BBst2	BBst2En[1:0] BBst2PDsc - BBst2RmpDis									
BBst2En[1:0]	00: Disable 01: Enable 10: Contro	Buck-Boost 2 Output Enable 00: Disabled 01: Enabled 10: Controlled by MPC (active-low) 11: Controlled by MPC (active-high)									
BBst2PDsc	0: Disabled	Buck-Boost 2 Passive Discharge 0: Disabled 1: Enabled when output is off									
BBst2RmpDis	the output. 1: Immedi	Disable the ramped output of Buck-Boost output 2. If disabled, the BBst2VSet value is immediately applied to the output. 1: Immediate transition to set value 0: Ramp to set value mode									

Table 10. LDO1VSet Register (0x08)

ADDRESS	0x08 (Rea	0x08 (Read, Write)								
BIT	7	7 6 5 4 3 2 1 0								
NAME	—	—	LDO1VSet[5:0]							
LDO1VSet[5:0]		0.55V 9.60V								

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Table 11. LDO1Cfg Register (0x09)

ADDRESS	0x09 (Read	0x09 (Read, Write)									
BIT	7	7 6 5 4 3 2 1 0									
NAME	LDO1E	En[1:0]	LDO1PDsc	LDO1ADsc	—	—	—	LDO1Mode			
LDO1En[1:0]	00: Disabled 01: Enabled 10: Controll										
LDO1PDsc	0: Disabled	_DO 1 Passive Discharge): Disabled 1: Enabled when output is off									
LDO1Mode	Configure L 0: LDO	LDO 1 Mode Configure LDO1 as an LDO or a load switch 0: LDO 1: Load Switch									

Table 12. LDO2VSet Register (0x0A)

ADDRESS	0x0A (Rea	0x0A (Read, Write)								
BIT	7	6	5 4 3 2 1 0							
NAME		—		LDO2VSet[5:0]						
LDO2VSet[5:0]		0.55V 6.60V								

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Table 13. LDO2Cfg Register (0x0B)

ADDRESS	0x0B (Rea	0x0B (Read, Write)									
BIT	7	6	5	4	3	2	1	0			
NAME	LDO2E	En[1:0]	LDO2PDsc	—	—	—	—	LDO2Mode			
LDO2En[1:0]	00: Disabl 01: Enable 10: Contro	LDO 2 Output Enable 00: Disabled 01: Enabled 10: Controlled by MPC (active-low) 11: Controlled by MPC (active-high)									
LDO2PDsc	0: Disable	LDO 2 Passive Discharge D: Disabled 1: Enabled when output is off									
LDO2Mode	Configure 0: LDO	LDO 2 Mode Configure LDO2 as an LDO or a load switch									

Table 14. MonCfg Register (0x0C)

ADDRESS	0x0C (Read, Write)									
BIT	7	6	5	4	3	2 1 0				
NAME	—	_	—	—	MonHiZ		MonSel[2:0]			
MonHiZ	Monitor Off Mode Condition 0: 100kΩ pulldown when disabled 1: High impedance when disabled									
MonSel[2:0]	000: Disab 001: BB1C 010: BB2C 011: L1OU	DUT selected DUT selected IT selected IT selected N selected selected	ction							

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Table 15. MPOCfg Register (0x0D)

ADDRESS	0x0D (Read, Write)										
BIT	7	7 6 5 4 3 2 1 0									
NAME	MPO	En[1:0]	—	_	—	—	MPOP	ull[1:0]			
MPOEn[1:0]	00: Pull up 01: Pull do 10: Pull up	Multipurpose Output Enable 00: Pull up (to GND) 01: Pull down (to BATN) 10: Pull up when MPC high, pull down when MPC low 11: Pull up when MPC low, pull down when MPC high									
MPOPull[1:0]	Multipurpose Output Pull Mode 00: Disabled 01: Pull down (to BATN) 10: Pull up (to GND) 11: Pull up/down (Push/Pull)										

Table 16. PwrCmd Register (0x0E)

ADDRESS	0x0E (Read, Write)									
BIT	7	6	5	4	3	2	1	0		
NAME		PwrCmd[7:0]								
PwrCmd[7:0]	10110010: 11000011:	mmand Registe Power Off - Tu Hard Reset - Soft Reset - P	urn off and stay	turn back on						

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Table 17. Status Register (0x0F)

ADDRESS	0x0F (Read-Or	0x0F (Read-Only)										
BIT	7	6	5	4	3	2	1	0				
NAME	LDO2UVLO	LDO1UVLO	LDO2Thm	LDO1Thm	LDO2CrMd	LDO1CrMd	KINSts	MPCSts				
LDO2UVLO	0: Normal	DO 2 Undervoltage Lockout Status : Normal : Undervoltage										
LDO1UVLO	LDO 1 Undervo 0: Normal 1: Undervoltage	bltage Lockout \$ e	Status									
LDO2Thm	LDO 2 Therma 0: Normal 1: Thermal shu											
LDO1Thm	LDO 1 Therma 0: Normal 1: Thermal shu											
LDO2CrMd	LDO 2 Current 0: LDO 1: Switch	Mode										
LDO1CrMd	LDO 1 Current 0: LDO 1: Switch	Mode										
KINSts	KIN Status 0: Low 1: High	0: Low										
MPCSts	Multi-Purpose Control Status 0: Low 1: High											

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Table 18. PwrCfg Register (0x10)

ADDRESS	0x10 (Read-Only)							
BIT	7	6	5	4	3	2	1	0
NAME	PwrCf	gMd[1:0]	GPasDsc	—	—	—	BootD	ly[1:0]
PwrCfgMd[1:0]	Power Configuration Mode A short button press will always wake the device from the off state. 00: Button only wakes device (can be turned off by I ² C command) 01: Long button press generates reset pulse 10: Long button press power cycles and reboots device 11: Long button press turns device off							
GPasDsc	Global Passive Discharge 0: Passive discharge disabled in off state 1: Passive discharged enabled in off state							
BootDly[1:0]	Boot Sequence Delay (t _{RST}) 00: 80ms 01: 120ms 10: 160ms 11: 200ms							

Table 19. BBstSeq Register (0x11)

ADDRESS	0x11 (Read-Only)							
BIT	7	6	5	4	3	2	1	0
NAME	—	— BBst2Seq[2:0] — BBst1Seq[2:0]						
BBst2Seq[2:0]	Buck-Boost 2 Sequencing Configuration 000: Disabled 001: Reserved 010: Enabled at 0% of power on delay 011: Enabled at 25% of power on delay 100: Enabled at 50% of power on delay 101: Enabled by MPC (active low) 110: Enabled by MPC (active high) 111: Controlled by BBst2En[1:0] after 100% of power on delay							
BBst1Seq[2:0]	Buck-Boost 2 Sequencing Configuration 000: Disabled 001: Reserved 010: Enabled at 0% of power on delay 011: Enabled at 25% of power on delay 100: Enabled at 50% of power on delay 101: Enabled by MPC (active low) 110: Enabled by MPC (active high) 111: Controlled by BBst1En[1:0] after 100% of power on delay							

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Table 20. LDOSeq Register (0x12)

ADDRESS	0x12 (Read-Only)							
BIT	7	6	5	4	3	2	1	0
NAME	_	LDO2Seq[2:0] — LDO1Seq[2:0]]
LDO2Seq[2:0]	LDO 2 Sequencing Configuration 000: Disabled 001: Reserved 010: Enabled at 0% of power on delay 011: Enabled at 25% of power on delay 100: Enabled at 50% of power on delay 101: Enabled by MPC (active low) 110: Enabled by MPC (active high) 111: Controlled by LDO2En[1:0] after 100% of power on delay							
LDO1Seq[2:0]	LDO 1 Sequencing Configuration 000: Disabled 001: Reserved 010: Enabled at 0% of power on delay 011: Enabled at 25% of power on delay 100: Enabled at 50% of power on delay 101: Enabled by MPC (active low) 110: Enabled by MPC (active high) 111: Controlled by LDO1En[1:0] after 100% of power on delay							

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REGISTER BITS	MAX20310A	MAX20310B	MAX20310C	MAX20310D	MAX20310E
ILimSet[1:0]	400mA	600mA	300mA	300mA	300mA
FetScale[1:0]	100%	100%	80%	80%	80%
LDO1En[1:0]	Disabled	Disabled	Disabled	Disabled	Disabled
LDO1VSet[5:0]	1.5V	0.5V	1.5V	3.0V	1.2V
LDO2En[1:0]	Disabled	Disabled	Disabled	Disabled	Disabled
LDO2VSet[5:0]	1.0V	1.8V	1.0V	1.2V	1.0V
BBst1En[1:0]	Disabled	Disabled	Enabled	Enabled	Enabled
BBst1VSet[5:0]	1.8V	3.0V	2.5V	3.3V	1.8V
BBst2En[1:0]	Disabled	Disabled	Disabled	Disabled	Disabled
BBst2VSet[5:0]	1.2V	2.1V	1.2V	1.5V	1.2V
BBstDmpEn	Disabled	Disabled	Disabled	Disabled	Disabled
LDO2Mode	Switch	LDO	LDO	LDO	LDO
LDO1Mode	LDO	Switch	LDO	LDO	LDO
MPOEn[1:0]	GND	GND	GND	GND	GND
PullMode[1:0]	Disabled	Disabled	Disabled	Disabled	Disabled
PwrCfgMd[1:0]	ON/off	ON	Hard Reset	Soft Reset	On/Off
GPasDsc	Disabled	Disabled	Enabled	Enabled	Enabled
BootDly[1:0]	120ms	80ms	200ms	160ms	80ms
BBst2Seq[2:0]	0% boot	25% boot	l ² C after 100% boot	l ² C after 100% boot	l ² C after 100% boot
BBst1Seq[2:0]	0% boot	0% boot	I ² C after 100% boot	l ² C after 100% boot	l ² C after 100% boot
LDO2Seq[2:0]	l ² C after 100% boot	50% boot	I ² C after 100% boot	l ² C after 100% boot	I ² C after 100% boot
LDO1Seq[2:0]	l ² C after 100% boot	I ² C after 100% boot	I ² C after 100% boot	l ² C after 100% boot	I ² C after 100% boot

Table 21. Register Bit Default Values

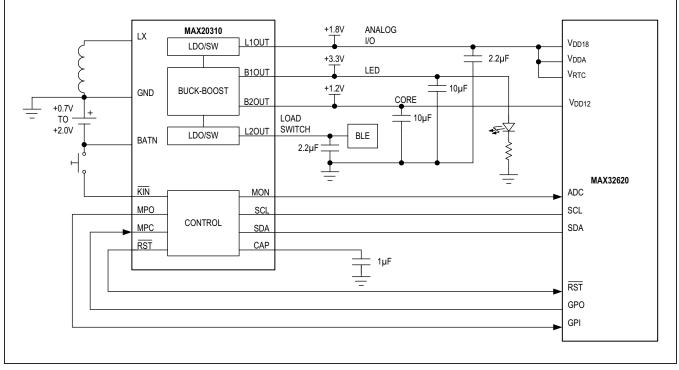
Ultra-Low Quiescent Current PMIC with SIMO Buck-Boost for Wearable Applications

REGISTER	REGISTER	DEFAULT VALUES						
ADDRESS	NAME	MAX20310A	MAX20310B	MAX20310C	MAX20310D	MAX20310E		
0x00	Chipld	0x00	0x00	0x00	0x00	0x00		
0x01	ChipRev	0x00	0x00	0x00	0x00	0x00		
0x02	BBstCfg	0x07	0x0F	0x02	0x02	0x02		
0x04	BBst1VSet	0x12	0x2A	0x20	0x30	0x12		
0x05	BBst1VCfg	0x20	0x10	0x60	0x60	0x60		
0x06	BBst2VSet	0x06	0x18	0x06	0x0C	0x06		
0x07	BBst2VCfg	0x20	0x10	0x20	0x20	0x20		
0x08	LDO1Vset	0x14	0x00	0x14	0x32	0x0E		
0x09	LDO1Cfg	0x20	0x11	0x20	0x20	0x20		
0x0A	LDO2Vset	0x0A	0x1A	0x0A	0x0E	0x0A		
0x0B	LDO2Cfg	0x21	0x10	0x20	0x20	0x20		
0x0D	MPOCfg	0x00	0x00	0x00	0x00	0x00		
0x10	PwrCfg	0xE1	0x10	0xA3	0x62	0xE0		
0x11	BBstSeq	0x22	0x32	0x77	0x77	0x77		
0x12	LDOSeq	0x77	0x47	0x77	0x77	0x77		

Table 22. Register Default Values

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Typical Application Circuit



Note: The capacitor values shown reflect an effective capacitance. Derate capacitors appropriately according to specific application requirements.

Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	TOP MARK
MAX20310AEWE+	-40°C to +85°C	16 WLP	AAK
MAX20310AEWE+T	-40°C to +85°C	16 WLP	AAK
MAX20310BEWE+	-40°C to +85°C	16 WLP	AAK
MAX20310BEWE+T	-40°C to +85°C	16 WLP	AAK
MAX20310CEWE+	-40°C to +85°C	16 WLP	AAK
MAX20310CEWE+T	-40°C to +85°C	16 WLP	AAK
MAX20310DEWE+	-40°C to +85°C	16 WLP	AAK
MAX20310DEWE+T	-40°C to +85°C	16 WLP	AAK
MAX20310EEWE+	-40°C to +85°C	16 WLP	AAK
MAX20310EEWE+T	-40°C to +85°C	16 WLP	AAK

+ Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

Chip Information

PROCESS: BICMOS