



**MAX4249–MAX4257**

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## **UCSP, Single-Supply, Low-Noise, Low-Distortion, Rail-to-Rail Op Amps**

#### **General Description**

The MAX4249–MAX4257 low-noise, low-distortion operational amplifiers offer rail-to-rail outputs and single-supply operation down to 2.4V. They draw 400μA of quiescent supply current per amplifier while featuring ultra-low distortion (0.0002% THD), as well as low input voltagenoise density  $(7.9nV/\sqrt{Hz})$  and low input current-noise density (0.5fA/ $\sqrt{Hz}$ ). These features make the devices an ideal choice for portable/battery-powered applications that require low distortion and/or low noise.

For additional power conservation, the MAX4249/ MAX4251/MAX4253/MAX4256 offer a low-power shutdown mode that reduces supply current to 0.5μA and puts the amplifiers' outputs into a high-impedance state. The MAX4249-MAX4257's outputs swing rail-to-rail and their input common-mode voltage range includes ground. The MAX4250–MAX4254 are unity-gain stable with a gainbandwidth product of 3MHz. The MAX4249/MAX4255/ MAX4256/MAX4257 are internally compensated for gains of 10V/V or greater with a gain-bandwidth product of 22MHz. The single MAX4250/MAX4255 are available in space-saving 5-pin SOT23 packages. The MAX4252 is available in an 8-bump chip-scale package (UCSP™) and the MAX4253 is available in a 10-bump UCSP. The MAX4250AAUK comes in a 5-pin SOT23 package and is specified for operation over the automotive (-40°C to +125°C) temperature range.

#### **Applications**

- Wireless Communications Devices
- **PA Control**
- Portable/Battery-Powered Equipment
- Medical Instrumentation
- **ADC Buffers**
- 

### **Pin/Bump Configurations**

### **Features**

- Available in Space-Saving UCSP, SOT23, and µMAX® Packages
- Low Distortion: 0.0002% THD (1kΩ load)
- 400µA Quiescent Supply Current per Amplifier
- Single-Supply Operation from 2.4V to 5.5V
- Input Common-Mode Voltage Range Includes Ground
- Outputs Swing Within 8mV of Rails with a 10kΩ Load
- 3MHz GBW Product, Unity-Gain Stable (MAX4250–MAX4254)
	- 22MHz GBW Product, Stable with  $A_V \ge 10$ V/V (MAX4249/MAX4255/MAX4256/MAX4257)
- Excellent DC Characteristics
	- $V_{OS} = 70 \mu V$
	- $I<sub>BIAS</sub> = 1pA$
	- Large-Signal Voltage Gain = 116dB
- Low-Power Shutdown Mode
	- Reduces Supply Current to 0.5µA
	- Places Outputs in a High-Impedance State
- 400pF Capacitive-Load Handling Capability

### **Ordering Information**



*+Denotes a lead(Pb)-free/RoHS-compliant package. T = Tape and reel.*

ADC Builers<br>Digital Scales/Strain Gauges *Ordering Information continued at end of data sheet.***<br>
2. Listing Carlier and of data sheet.** *Selector Guide appears at end of data sheet.*



*UCSP is a trademark and μMAX is a registered trademark of Maxim Integrated Products, Inc.*

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#### **Absolute Maximum Ratings**

Power-Supply Voltage  $(V_{DD}$  to  $V_{SS})$ ......................+6.0V to -0.3V Analog Input Voltage (IN\_+, IN\_-). ( $V_{DD}$  + 0.3V) to ( $V_{SS}$  - 0.3V) SHDN Input Voltage ....................................6.0V to (VSS - 0.3V) Output Short-Circuit Duration to Either Supply ..........Continuous Continuous Power Dissipation  $(T_A = +70^{\circ}C)$ 





*Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

### **Electrical Characteristics**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = 0V, V<sub>OUT</sub> = V<sub>DD</sub>/2, R<sub>L</sub> connected to V<sub>DD</sub>/2, SHDN = V<sub>DD</sub>, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T $_{\mathsf{A}}$  = +25°C.) (Notes 2, 3)



### **Electrical Characteristics (continued)**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = 0V, V<sub>OUT</sub> = V<sub>DD</sub>/2, R<sub>L</sub> connected to V<sub>DD</sub>/2, SHDN = V<sub>DD</sub>, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T $_{\mathsf{A}}$  = +25°C.) (Notes 2, 3)



### **Electrical Characteristics (continued)**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = 0V, V<sub>OUT</sub> = V<sub>DD</sub>/2, R<sub>L</sub> connected to V<sub>DD</sub>/2,  $\overline{SHDN}$  = V<sub>DD</sub>, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at  $T_A$  = +25°C.) (Notes 2, 3)



**Note 2:** SHDN is available on the MAX4249/MAX4251/MAX4253/MAX4256 only.

**Note 3:** All device specifications are 100% tested at T<sub>A</sub> = +25°C. Limits over temperature are guaranteed by design.

**Note 4:** Guaranteed by the PSRR test.

**Note 5:** Offset voltage prior to reflow on the UCSP.

**Note 6:** Guaranteed by design.

**Note 7:** Lowpass-filter bandwidth is 22kHz for f = 1kHz and 80kHz for f = 20kHz. Noise floor of test equipment = 10nV/√Hz.

### **Typical Operating Characteristics**





### **Typical Operating Characteristics (continued)**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = V<sub>OUT</sub> = V<sub>DD</sub>/2, input noise floor of test equipment =10nV/ $\sqrt{Hz}$  for all distortion measurements,  $T_A$  = +25°C, unless otherwise noted.)

FREQUENCY (Hz)

#### **SUPPLY CURRENT AND SHUTDOWN LARGE-SIGNAL VOLTAGE GAIN LARGE-SIGNAL VOLTAGE GAIN SUPPLY CURRENT vs. TEMPERATURE vs. OUTPUT VOLTAGE SWING vs. TEMPERATURE** 125 460 150  $R_L = 200k\Omega$ <br>  $R_L = 20k\Omega$ <br>  $R_L = 2k\Omega$ <br>  $R_L = 2k\Omega$ <br>  $V_{DD} = 5V$ <br>  $R_L$  REFERENCED TO GND<br>
0 50 100 150 200 250<br>
250 MAX4249-57 TOC11 PER AMPLIFIER  $R_1 = 200k$ 140 440  $R_1 = 20k$ 120 130 R<sub>I</sub> REFERENCED TO V<sub>DD</sub>/2 SUPPLY CURRENT (µA) SUPPLY CURRENT (µA) 120 420  $V<sub>DD</sub> = 5V$  $R_L = 2k\Omega$ AV (dB) 115 110 AV (dB) 400 100  $R<sub>L</sub> = 100k\Omega$ 110 90  $V_{OUT} = 10$ m $V$ 380 TO 4.99mV 80  $\mathbf{I}$ 70 105  $R_1 = 1k\Omega$  $R_1 = 10k\Omega$ 360  $V_{OUT} = 150$ mV  $V_{OUIT} = 20mV$  $V<sub>DD</sub> = 5V$ 60 TO 4.975mV RL REFERENCED TO GND TO 4.75mV 340 50 100 -40 -20 0 20 40 60 80 VOUT SWING FROM EITHER SUPPLY (mV) TEMPERATURE (°C) **SUPPLY CURRENT AND SHUTDOWN SUPPLY CURRENT SUPPLY CURRENT vs. SUPPLY VOLTAGE vs. OUTPUT VOLTAGE** 180 440 MAX4249-57 TOC13 0.6 2000 MAX4249-57 TOC14 PER AMPLIFIER SHUTDOWN SUPPLY CURRENT (µA) 160 SHUTDOWN SUPPLY CURRENT (µA) 420 0.5 SUPPLY CURRENT (µA)<br>3UPPLY CURRENT (00  $\overline{\text{SHDN}} = \text{V}_{\text{DD}}$ 140 SUPPLY CURRENT (µA) SUPPLY CURRENT (µA 400 0.4  $V_{DD} = 5V$  $\overline{\text{SHDN}}$  =  $V_{SS}$ VOS (µV) 120 0.3 380 100 400 360 0.2 80  $3V$ 340 0.1 60 100  $320$  L<br>1.8  $\theta$ 40 1.8 2.3 2.8 3.3 3.8 4.3 4.8 5.3 5.5 1.8 2.3 2.8 3.3 3.8 4.3 4.8 5.3 0.001 0.01 0.1 1 5 SUPPLY VOLTAGE (V) OUTPUT VOLTAGE (V) **MAX4250–MAX4254 MAX4249/MAX4255/MAX4256/MAX4257 POWER-SUPPLY REJECTION RATIO GAIN AND PHASE vs. FREQUENCY GAIN AND PHASE vs. FREQUENCY** 60 MAX4249-57 TOC16 180 60 MAX4249-57 TOC17 0 180  $V_{DD}$  = 3V, 5V  $V_{DD} = 3V, 5V$  $V<sub>DD</sub> = 3V.5V$ -10 50 144 50 144  $R_L = 50k\Omega$ <br>C<sub>L</sub> = 20pF  $R_L = 50k\Omega$  $= 20pF$ Ш -20  $C_L = 20pF$ 108 40 40 108  $1000$  $1000$ **GAIN** -30 PHASE (DEGREES) PHASE (DEGREES) 30 30 72 72 (DEGREES) PHASE (DEGREES) **GAIN** -40 PSRR (dB)<br>-50<br>© 00 36 36 20 GAIN (dB) ⊕ 20<br>N<br>G<br>G 20 0 10  $\mathbf 0$ -60 PHASE 0 -36 0 -36 -70 -72 -10 PHASE -10 -72 -80 -108 PHASE -20 -20 -108 -90 -30 -144 -100 -30 -144 -110 -40 -180 -180 -40 1 10 100 1k 10k 100k 1M 10M 100 1k 10k 100k 1M 10M 100 1k 10k 100k 1M 10M



SUPPLY VOLTAGE (V)

**MAX4250–MAX4254** 

**vs. FREQUENCY**

PSRR+

FREQUENCY (Hz)

PSRR-

RL = 100kΩ

MAX4249-57 TOC18

0.376

SHUTDOWN SUPPLY CURRENT (µA)

SHUTDOWN SUPPLY CURRENT (µA)

MAX4249-57 TOC12

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FREQUENCY (Hz)

### **Typical Operating Characteristics (continued)**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = V<sub>OUT</sub> = V<sub>DD</sub>/2, input noise floor of test equipment =10nV/ $\sqrt{Hz}$  for all distortion measurements,  $T_A$  = +25°C, unless otherwise noted.)



### **Typical Operating Characteristics (continued)**

(V<sub>DD</sub> = 5V, V<sub>SS</sub> = 0V, V<sub>CM</sub> = V<sub>OUT</sub> = V<sub>DD</sub>/2, input noise floor of test equipment =10nV/ $\sqrt{Hz}$  for all distortion measurements,  $T_A$  = +25°C, unless otherwise noted.)



### **Pin/Bump Description**



#### **Detailed Description**

The MAX4249–MAX4257 single-supply operational amplifiers feature ultra-low noise and distortion while consuming very little power. Their low distortion and low noise make them ideal for use as preamplifiers in wide dynamic-range applications, such as 16-bit analog-todigital converters (see *Typical Operating Circuit*). Their high-input impedance and low noise are also useful for signal conditioning of high-impedance sources, such as piezoelectric transducers.

These devices have true rail-to-rail output operation, drive loads as low as 1kΩ while maintaining DC accuracy, and can drive capacitive loads up to 400pF without oscillation. The input common-mode voltage range extends from V<sub>DD</sub> - 1.1V to 200mV beyond the negative rail. The pushpull output stage maintains excellent DC characteristics, while delivering up to ±5mA of current.

The MAX4250–4254 are unity-gain stable, whereas, the MAX4249/MAX4255/MAX4256/MAX4257 have a higher slew rate and are stable for gains ≥ 10V/V. The MAX4249/ MAX4251/MAX4253/MAX4256 feature a low-power shutdown mode, which reduces the supply current to 0.5μA and disables the outputs.

The MAX4250AAUK is specified for operation over the automotive (-40°C to +125°C) temperature range.

#### **Low Distortion**

Many factors can affect the noise and distortion that the device contributes to the input signal. The following guidelines offer valuable information on the impact of design choices on Total Harmonic Distortion (THD).

Choosing proper feedback and gain resistor values for a particular application can be a very important factor in reducing THD. In general, the smaller the closedloop gain, the smaller the THD generated, especially when driving heavy resistive loads. Large-value feedback resistors can significantly improve distortion. The THD of the part normally increases at approximately 20dB per decade, as a function of frequency. Operating the device near or above the full-power bandwidth significantly degrades distortion.

Referencing the load to either supply also improves the part's distortion performance, because only one of the MOSFETs of the push-pull output stage drives the output. Referencing the load to midsupply increases the part's distortion for a given load and feedback setting. (See the Total Harmonic Distortion vs. Frequency graph in the *Typical Operating Characteristics*.)

For gains ≥ 10V/V, the decompensated devices MAX4249/ MAX4255/MAX4256/MAX4257 deliver the best distortion performance, since they have a higher slew rate and provide a higher amount of loop gain for a given closed-loop gain setting. Capacitive loads below 400pF, do not significantly affect distortion results. Distortion performance remains relatively constant over supply voltages.

#### **Low Noise**

The amplifier's input-referred, noise-voltage density is dominated by flicker noise at lower frequencies, and by thermal noise at higher frequencies. Because the thermal noise contribution is affected by the parallel combination of the feedback resistive network  $(R_F \parallel R_G, F_i)$  Figure 1), these resistors should be reduced in cases where the system bandwidth is large and thermal noise is dominant. This noise contribution factor decreases, however, with increasing gain settings.

For example, the input noise-voltage density of the circuit with R<sub>F</sub> = 100kΩ, R<sub>G</sub> = 11kΩ (A<sub>V</sub> = 10V/V) is e<sub>n</sub> = 15nV/ $\sqrt{Hz}$ , e<sub>n</sub> can be reduced to 9nV/ $\sqrt{Hz}$  by choosing  $R_F = 10k\Omega$ ,  $R_G = 1.1k\Omega$  (A<sub>V</sub> = 10V/V), at the expense of greater current consumption and potentially higher distortion. For a gain of 100V/V with  $R_F = 100 \text{k}\Omega$ ,  $R_G = 1.1 \text{k}\Omega$ , the e<sub>n</sub> is low (9nV/ $\sqrt{Hz}$ ).



*Figure 1. Adding Feed-Forward Compensation*



*Figure 2a. Pulse Response with No Feed-Forward Compensation*



*Figure 2b. Pulse Response with 10pF Feed-Forward Compensation*



*Figure 3. Overdriven Input Showing No Phase Reversal*



*Figure 4. Rail-to-Rail Output Operation*



*Figure 5. Capacitive-Load Driving Circuit*

#### **Using a Feed-Forward Compensation Capacitor, CZ**

The amplifier's input capacitance is 11pF. If the resistance seen by the inverting input is large (feedback network), this can introduce a pole within the amplifier's bandwidth, resulting in reduced phase margin. Compensate the reduced phase margin by introducing a feed-forward capacitor  $(C_7)$  between the inverting input and the output (Figure 1). This effectively cancels the pole from the inverting input of the amplifier. Choose the value of  $C<sub>7</sub>$  as follows:

$$
C_Z = 11 \times (R_F / R_G)
$$
 [pF]

In the unity-gain stable MAX4250–MAX4254, the use of a proper C<sub>7</sub> is most important for  $A_V = 2V/V$ , and  $A_V = -1V/V$ . In the decompensated MAX4249/MAX4255/MAX4256/ MAX4257,  $C_Z$  is most important for  $A_V$  = 10V/V. Figures 2a and 2b show transient response both with and without  $C_7$ .

Using a slightly smaller  $C<sub>7</sub>$  than suggested by the formula above achieves a higher bandwidth at the expense of reduced phase and gain margin. As a general guideline, consider using C<sub>7</sub> for cases where  $R_G \parallel R_F$  is greater than 20kΩ (MAX4250–MAX4254) or greater than 5kΩ (MAX4249/MAX4255/MAX4256/MAX4257).

### **Applications Information**

The MAX4249–MAX4257 combine good driving capability with ground-sensing input and rail-to-rail output operation. With their low distortion, low noise, and lowpower consumption, these devices are ideal for use in portable instrumentation systems and other low-power, noisesensitive applications.

#### **Ground-Sensing and Rail-to-Rail Outputs**

The common-mode input range of these devices extends below ground, and offers excellent commonmode rejection. These devices are guaranteed not to undergo phase reversal when the input is overdriven (Figure 3).

Figure 4 showcases the true rail-to-rail output operation of the amplifier, configured with  $A_V = 10V/V$ . The output swings to within 8mV of the supplies with a 10kΩ load, making the devices ideal in low-supply-voltage applications.

#### **Output Loading and Stability**

Even with their low quiescent current of 400μA, these amplifiers can drive 1kΩ loads while maintaining excellent DC accuracy. Stability while driving heavy capacitive loads is another key feature.



*Figure 6. Isolation Resistance vs. Capacitive Loading to Minimize Peaking (<2dB)*



*Figure 7. Peaking vs. Capacitive Load*



*Figure 8. MAX4250–MAX4254 Unity-Gain Bandwidth vs. Capacitive Load*

These devices maintain stability while driving loads up to 400pF. To drive higher capacitive loads, place a small isolation resistor in series between the output of the amplifier and the capacitive load (Figure 5). This resistor improves the amplifier's phase margin by isolating the capacitor from the op amp's output. Reference Figure 6 to select a resistance value that will ensure a load capacitance that limits peaking to <2dB (25%). For example, if the capacitive load is 1000pF, the corresponding isolation resistor is 150Ω. Figure 7 shows that peaking occurs without the isolation resistor. Figure 8 shows the unity-gain bandwidth vs. capacitive load for the MAX4250–MAX4254.

#### **Power Supplies and Layout**

The MAX4249–MAX4257 operate from a single 2.4V to 5.5V power supply or from dual supplies of ±1.20V to ±2.75V. For single-supply operation, bypass the power supply with a 0.1μF ceramic capacitor placed close to the  $V_{DD}$  pin. If operating from dual supplies, bypass each supply to ground.

Good layout improves performance by decreasing the amount of stray capacitance and noise at the op amp's inputs and output. To decrease stray capacitance, minimize PC board trace lengths and resistor leads, and place external components close to the op amp's pins.

## **Typical Operating Circuit**



### **Selector Guide**





## **Pin/Bump Configurations (continued)**

### **Ordering Information (continued)**



### **Package Information**

For the latest package outline information and land patterns (footprints), go to **[www.maximintegrated.com/packages](http://www.maximintegrated.com/packages)**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

