19-3067; Rev 1; 2/06

### EVALUATION KIT ///XI/// AVAILABLE 32-Tap, Nonvolatile, Linear-Taper Digital **Potentiometers in SOT23**

### **General Description**

The MAX5471/MAX5472/MAX5474/MAX5475 lineartaper digital potentiometers function as mechanical potentiometers, but replace the mechanics with a simple 3-wire up/down digital interface. These digital potentiometers feature nonvolatile memory (EEPROM) to return the wiper to its previously stored position upon power-up.

The MAX5471/MAX5472 are 2-terminal, variable resistors in 6-pin SOT23 packages. The MAX5474/MAX5475 are 3-terminal potentiometers in 8-pin SOT23 packages.

The MAX5471/MAX5474 have an end-to-end resistance of 50k $\Omega$ , and the MAX5472/MAX5475 have an endto-end resistance of  $100k\Omega$ . All of these devices have 32 wiper positions, a low ratiometric temperature coefficient (5ppm/°C), and all operate from a single +2.7V to +5.25V supply. Each device is guaranteed over the extended -40°C to +85°C temperature range.

### Applications

Mechanical Potentiometer Replacement

Liquid-Crystal-Display (LCD) Screen Adjustment Audio Volume Control

Programmable Filters

#### TOP VIEW CS 1 6 V<sub>DD</sub> CS 1 8 L GND 2 5 H V<sub>DD</sub> 2 7 W /IXI// 4 INC GND 3 U/D 3 6 H MAX5471 ////X//// MAX5472 MAX5474 U/D 4 5 INC SOT23-6 MAX5475 SOT23-8

### **Pin Configurations**

### M/XI/M

Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

### Features

- Wiper Position Stored in Nonvolatile Memory and **Recalled Upon Power-Up**
- Tiny SOT23 Package
- ♦ 35ppm/°C End-to-End Resistance Temperature Coefficient
- 5ppm/°C Ratiometric Temperature Coefficient
- 32 Tap Positions
- Voltage-Divider or Variable-Resistor **Potentiometer Configuration**
- 50kΩ and 100kΩ End-to-End Resistance Values
- 1µA (max) Static Supply Current
- 2.7V to 5.25V Single-Supply Operation
- 200,000 Wiper Store Cycles
- 50-Year Wiper Data Retention

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE	PKG CODE
MAX5471EZT-T	-40°C to +85°C	6 Thin SOT23-6	Z6-1
MAX5472EZT-T	-40°C to +85°C	6 Thin SOT23-6	Z6-1
MAX5474EKA-T	-40°C to +85°C	8 SOT23-8	K8S-3
MAX5475EKA-T	-40°C to +85°C	8 SOT23-8	K8S-3

### **Selector Guide**

PART	END-TO-END RESISTANCE (kΩ)	TOP MARK
MAX5471EZT	50	ABQN
MAX5472EZT	100	ABQM
MAX5474EKA	50	AEIZ
MAX5475EKA	100	AEIY

#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to GND0.3V to +0	6.0V
All Other Pins to GND0.3V to the lower of $(V_{DD} + 0.3V)$ or +1	6 01/
Maximum Continuous Current into H. L. and W	J.0V
MAX5471/MAX5474±1.3	3mA
MAX5472/MAX5475±0.6	ЗmА

Continuous Power Dissipation (T<sub>A</sub> = +70°C) 6-Pin SOT23 (derate 9.1mW/°C above +70°C)......727mW 8-Pin SOT23 (derate 8.9mW/°C above +70°C)......714mW Operating Temperature Range .....-40°C to +85°C Junction Temperature ......+150°C Storage Temperature Range ......-60°C to +150°C Lead Temperature (soldering, 10s).....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C, \text{ unless otherwise noted.}$  (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS	
DC PERFORMANCE	•	•				•	
Resolution	Ν		32			Тар	
		MAX5471/MAX5474	37.5	50	62.5	kΩ	
End-to-End Resistance		MAX5472/MAX5475	75	100	125	κΩ	
End-to-End Resistance Temperature Coefficient	TCR			35		ppm/°C	
Ratiometric Resistance Temperature Coefficient				5		ppm/°C	
		Variable-resistor mode (Note 2)		±0.5	±1.0		
Integral Nonlinearity	INL	Voltage-divider mode (MAX5474/MAX5475) (Note 3)		±0.1	±0.5	LSB	
	DNL	Variable-resistor mode (Note 2)		±0.5	±1.0		
Differential Nonlinearity		Voltage-divider mode (MAX5474/MAX5475) (Note 3)		±0.1	±0.5	LSB	
Full-Scale Error		MAX5474/MAX5475			-0.5	LSB	
Zero-Scale Error		MAX5474/MAX5475			+0.5	LSB	
Wiper Resistance	Rw	MAX5474/MAX5475 (Note 4)		600	1200	Ω	
DIGITAL INPUTS ( $\overline{CS}$ , U/ $\overline{D}$ , $\overline{INC}$ )	(Note 5)						
Input Ligh Voltage	VIH	V <sub>DD</sub> < 3.6V	0.7 x V <sub>DD</sub>			V	
Input High Voltage		$V_{DD} \ge 3.6V$	2.4				
Input Low Voltage	VIL	V <sub>DD</sub> < 3.6V		0.3 x V <sub>DD</sub>		V	
Input Low Voltage		$V_{DD} \ge 3.6V$			0.8		
Input Current	lın			±0.1	±1	μA	
DYNAMIC CHARACTERISTICS			_				
Wiper -3dB Bandwidth (Note 6)		MAX5471/MAX5474		400		kHz	
wiper -oub bandwidth (Note 0)		MAX5472/MAX5475		200		KIIZ	

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C, \text{ unless otherwise noted.})$  (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP MA	X UNITS
TIMING CHARACTERISTICS (	igure 1, Note 7	)			
CS to INC Setup	tCI		50		ns
INC High to U/D Change	tid		0		ns
$U/\overline{D}$ to $\overline{INC}$ Setup	t <sub>DI</sub>		100		ns
INC Low Period	tı∟		50		ns
INC High Period	tıH		50		ns
INC Cycle Time	tcyc		100		ns
INC Inactive to CS Inactive	tıC		100		ns
INC Active to CS Inactive	tıĸ		100		ns
CS Deselect Time (Store)	tCPH		100		ns
Wiper Settling Time	t <sub>IW</sub>	(Note 8)		1	μs
Power-Up to Wiper Stable	tpu			1	μs
Wiper Store Cycle	twsc		12		ms
NONVOLATILE MEMORY REL	IABILITY				
Data Retention		$T_{A} = +85^{\circ}C$		50	Year
		$T_A = +25^{\circ}C$		200,000	Chara
Endurance		$T_{A} = +85^{\circ}C$		50,000	Store
POWER SUPPLY					
Supply Voltage	V <sub>DD</sub>		2.70	5.2	5 V
Supply Current	I <sub>DD</sub>	Write to memory		400	) μΑ
Static Supply Current	I <sub>SD</sub>	$T_{A} = +25^{\circ}C$ (Note 9)		0.35 1	μA

**Note 1:** All devices are production tested at  $T_A = +25^{\circ}C$  and are guaranteed by design and characterization for  $-40^{\circ}C < T_A < +85^{\circ}C$ .

**Note 2:** The DNL and INL are measured with the potentiometer configured as a variable resistor. For the 3-terminal potentiometers (MAX5474/MAX5475), H is unconnected and L = GND. At  $V_{DD}$  = 5.25V, W is driven with a source current of 80µA for the 50k $\Omega$  configuration, and 40µA for the 100k $\Omega$  configuration. At  $V_{DD}$  = 2.7V, the wiper terminal is driven with a source current of 40µA for the 50k $\Omega$  configuration, and 20µA for the 100k $\Omega$  configuration.

**Note 3:** The DNL and INL are measured with the potentiometer configured as a voltage-divider with H = V<sub>DD</sub> and L = GND (MAX5474/MAX5475 only). The wiper terminal is unloaded.

Note 4: The wiper resistance is the worst value measured by injecting the currents given in Note 2 into W with L = GND.  $R_W = (V_W - V_H) / I_W.$ 

**Note 5:** The device draws higher supply current when digital inputs are driven with voltages between 0.3V x V<sub>DD</sub> and 0.7 x V<sub>DD</sub>. Drive the digital inputs as close as possible to V<sub>DD</sub> or GND. (See the *Typical Operating Characteristics* for the Supply Current vs. Digital Input Voltage graph.)

Note 6: Wiper at midscale with a 10pF load.

Note 7: Digital timing is guaranteed by design and characterization, and is not production tested.

**Note 8:** Wiper settling time is the worst-case 0% to 50% rise time measured between consecutive wiper positions. H = V<sub>DD</sub>, L = GND, and the wiper terminal is unloaded and measured with a 10pF oscilloscope probe (see the *Typical Operating Characteristics* for the Tap-to-Tap Switching Transient).

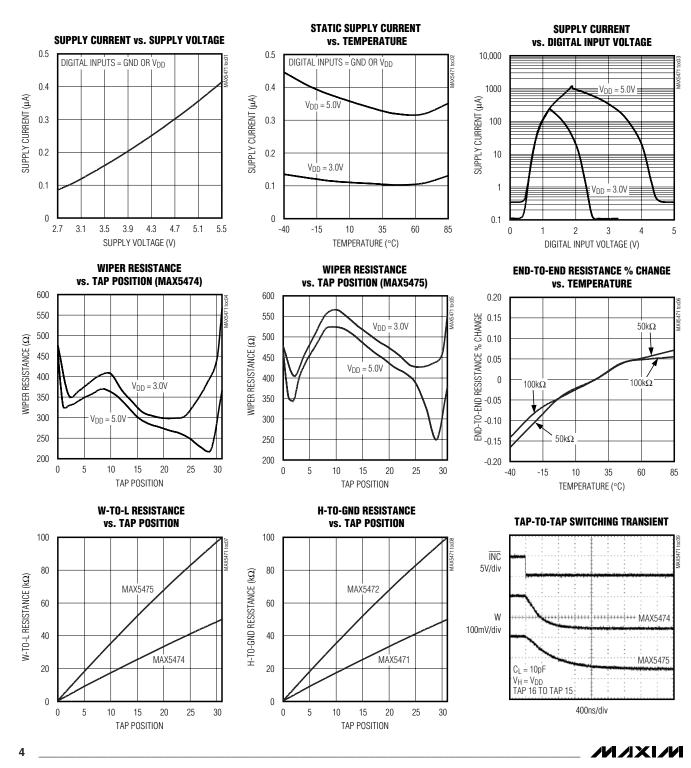
**Note 9:** Digital inputs CS, U/D, and INC are connected to GND or V<sub>DD</sub>. See the *Typical Operating Characteristics* for the Static Supply Current vs. Temperature graph.

### 

**MAX5471/MAX5472/MAX5474/MAX5475** 

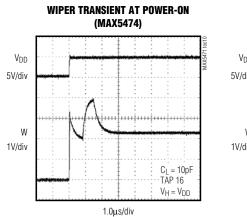
 $(V_{DD} = 5.0V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

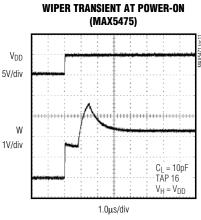
#### **Typical Operating Characteristics**

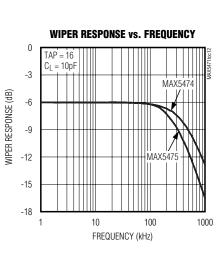


### **Typical Operating Characteristics (continued)**

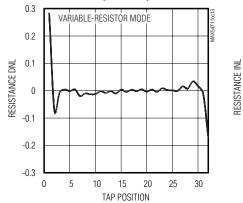
 $(V_{DD} = 5.0V, T_A = +25^{\circ}C, unless otherwise noted.)$ 



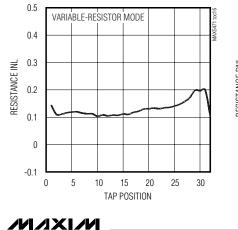




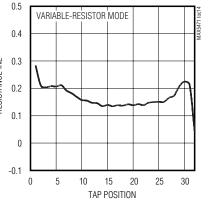
RESISTANCE DNL vs. TAP POSITION (MAX5471)



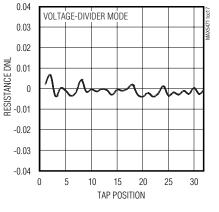
RESISTANCE INL vs. TAP POSITION (MAX5472)



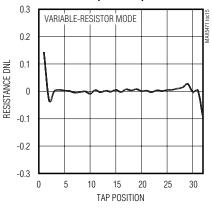
RESISTANCE INL vs. TAP POSITION (MAX5471)



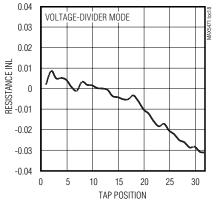
RESISTANCE DNL vs. TAP POSITION (MAX5474)



RESISTANCE DNL vs. TAP POSITION (MAX5472)

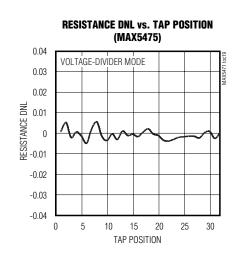


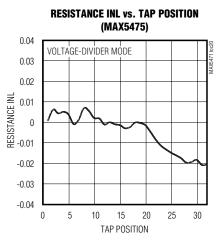
RESISTANCE INL vs. TAP POSITION (MAX5474)



### Typical Operating Characteristics (continued)

 $(V_{DD} = 5.0V, T_A = +25^{\circ}C, unless otherwise noted.)$ 





### Pin Description

P	N				
MAX5471/ MAX5474/ NAME MAX5472 MAX5475		NAME	FUNCTION		
1	1	CS	Chip-Select Input. Drive low to change wiper position (W) through $\overline{INC}$ and $U/\overline{D}$ . A low-to-high transition with $\overline{INC}$ high stores the wiper position in nonvolatile memory.		
2	3	GND	Ground		
3	4	U/D	Up/Down Control Input. With U/ $\overline{D}$ low, a high-to-low $\overline{INC}$ transition decrements the wiper position. With U/ $\overline{D}$ high, a high-to-low $\overline{INC}$ transition increments the wiper position.		
4	5	INC	Wiper Increment Control Input. With $\overline{CS}$ low, the wiper position moves in the direction determined by the state of U/ $\overline{D}$ on a high-to-low transition.		
5	6	Н	High Terminal of Resistor. The voltage at H can be greater than or less than the voltage at L. Current can flow into or out of H.		
6	2	V <sub>DD</sub>	Power Supply		
_	7	W	Wiper Terminal of Resistor		
_	8	L	Low Terminal of Resistor. The voltage at L can be greater than or less than the voltage at H. Current can flow into or out of L.		

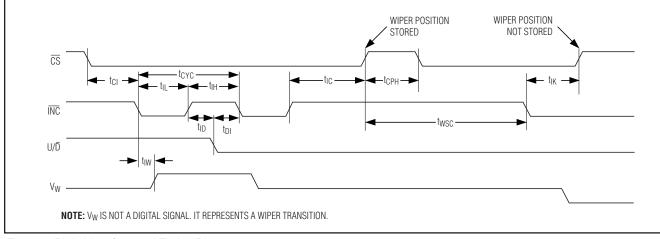


Figure 1. Digital Interface and Timing Diagram

#### **Detailed Description**

The MAX5471/MAX5472/MAX5474/MAX5475 contain a resistor array with 31 resistive elements (Figures 2 and 3). The MAX5471/MAX5474 have a total end-to-end resistance of 50k $\Omega$ , and the MAX5472/MAX5475 have an end-to-end resistance of 100k $\Omega$ . The MAX5471/MAX5472 wiper is connected to the high terminal, and the low terminal is internally connected to ground, making the device a variable resistor. The MAX5474/MAX5475 allow access to the high, low, and wiper terminals for a standard voltage-divider configuration.

The wiper is moved among the 32 tap points through a simple 3-wire interface. Nonvolatile memory allows the wiper position to be stored and recalled to the same point upon power-up.

**Digital Interface** Logic inputs  $\overline{CS}$ , U/ $\overline{D}$ , and  $\overline{INC}$  control the wiper position and store it in nonvolatile memory (see the *Truth Table*). The chip-select ( $\overline{CS}$ ) input enables the serial interface when low and disables the interface when high. The position of the wiper is stored when  $\overline{CS}$  transitions from low to high and  $\overline{INC}$  is high (see the *Storing Wiper Position* section).

With the serial interface active ( $\overline{CS}$  low), a high-to-low (falling edge) transition on  $\overline{INC}$  moves the wiper position by one resistive element in the direction determined by the state of U/ $\overline{D}$ . If U/ $\overline{D}$  is high, the wiper increments and it increases the resistance between W and L (it decreases the resistance between H and W). If U/ $\overline{D}$  is low, the wiper decrements and it decreases the resistance between H and W). If U/ $\overline{D}$  is low, the wiper decrements and it decreases the resistance between H and W). The direction of the wiper

### 

(state of  $U/\overline{D}$ ) can be changed at any time as long as the setup and hold times are met.

Since the MAX5471/MAX5472 have the wiper internally connected to H, an increment command increases the resistance between H and GND, and a decrement command decreases the resistance between H and GND.

The wiper performs a make-before-break transition, ensuring that there is never an open circuit during a transition from one resistor tap to another. When the wiper is at either end of the resistor array (max/min), additional transitions in the direction of the endpoint do not change the counter value (the wiper does not wrap around).

#### **Storing Wiper Position**

The position of the wiper is stored in nonvolatile memory whenever CS transitions low-to-high (rising edge) while INC is high. Upon power-up, the wiper returns to this stored position. By keeping INC low while taking CS high, the serial interface can be disabled and the potentiometer placed in standby without storing the latest wiper position. The factory-default wiper position is midscale.

These devices can also be operated like a one-time programmable (OTP) device. Once the desired wiper position is trimmed and stored in nonvolatile memory, disable the serial interface by connecting  $\overline{CS}$  to V<sub>DD</sub>, and  $\overline{INC}$  to GND. The disabled interface places the device in standby and disallows any changes to the wiper position. In OTP mode, these devices become a fixed 3-terminal potentiometer or a 1-terminal resistor to GND with less than 1µA of supply current.

Truth Table

<u>cs</u>	U/D	INC	w		
L	L	$\downarrow$	Decrement		
L	Н	$\downarrow$	Increment		
L	Х	$\uparrow$	No change		
Н	Х	Х	No change		
$\downarrow$	Х	Х	No change		
$\uparrow$	Х	L	Position not stored		
$\uparrow$	Х	Н	Position stored		

 $\downarrow$  = High-to-low transition.

 $\uparrow$  = Low-to-high transition.

X = Don't care.

- Dunt care.

#### **Standby Mode**

The MAX5471/MAX5472/MAX5474/MAX5475 are always in standby mode, except during the transition of a logic input or while the wiper position is being stored. When in standby mode, the static supply current is reduced to less than  $1\mu$ A and the resistive terminals (H, W, and L) are unaffected.

### **Applications Information**

The MAX5471/MAX5472/MAX5474/MAX5475 are intended for circuits requiring digitally controlled adjustable resistance, such as LCD contrast control (where voltage biasing adjusts the display contrast), or programmable filters with adjustable gain and/or cutoff frequency.

#### **Positive LCD Bias Control**

Figures 4 and 5 show an application where the voltagedivider or variable resistor is used to make an adjustable, positive LCD-bias voltage. The op amp provides buffering and gain to the resistor-divider network made by the potentiometer (Figure 4) or to a fixed resistor and a variable resistor (Figure 5).

#### **Programmable Filter**

Figure 6 shows the configuration of a 1st-order programmable filter. The gain of the filter is adjusted by R2, and the cutoff frequency is adjusted by R3. Use the following equations to calculate the gain (G) and the 3dB cutoff frequency ( $f_C$ ):

$$G = 1 + \frac{R1}{R2}$$
$$f_{C} = \frac{1}{2\pi \times R3 \times C}$$

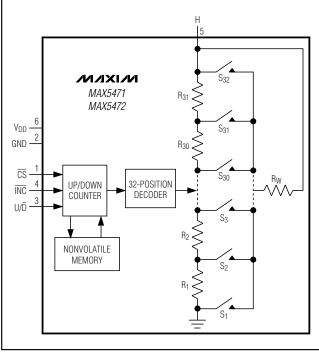


Figure 2. MAX5471/MAX5472 Functional Diagram

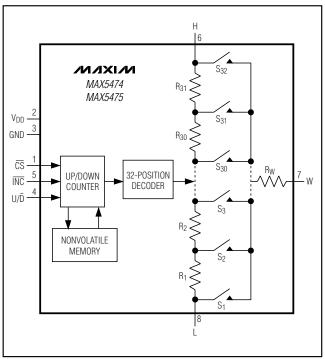


Figure 3. MAX5474/MAX5475 Functional Diagram



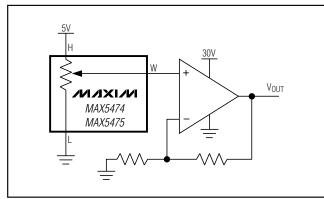


Figure 4. Positive LCD Bias Control Using a Voltage-Divider

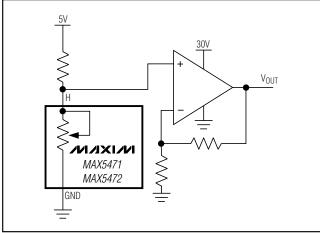


Figure 5. Positive LCD Bias Control Using a Variable Resistor

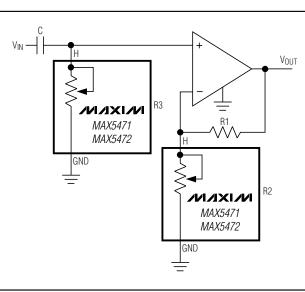


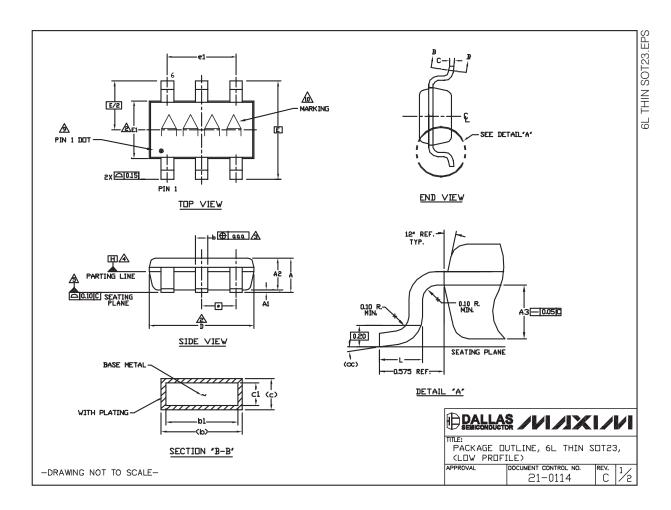
Figure 6. Programmable Filter

### **Chip Information**

TRANSISTOR COUNT: 5031 PROCESS: BICMOS

### **Package Information**

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)



### \_Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)

		SYM	BOLS		
1. ALL DIMENSIONS ARE IN MILLIMETERS.					
2. D' AND 'E1' ARE REFERENCE DATUM AND DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS, AND ARE MEASURED AT THE BOTTOM PARTING LINE. MOLD FLASH OR	A	MIN	NDM	MAX	
PROTRUSION SHALL NOT EXCEED 0.15mm ON 'D' AND 0.25mm ON 'E' PER SIDE. $\wedge$	A1	_		1.10	
3. THE LEAD WIDTH DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.07mm TOTAL IN EXCESS OF THE LEAD WIDTH	A1 A2	0.00	0.075	0.10	
DIMENSION AT MAXIMUM MATERIAL CONDITION.	A3	0.85 0.88 0.90 0.50 BSC			
4 datum plane "H" located at NOLD parting line and coincident with lead, Where lead exits plastic body at the bottom of parting line,	b	0.30	0.30 830	0,45	
$f_{\rm S}$ the lead tips must line within a specified tolerance zone. This	b1	0.25	0.35	0.40	
TILLERANCE ZONE IS DEFINED BY TWO PARALLEL LINES. ONE PLANE IS THE SEATING PLANE, DATUM [-C-], AND THE OTHER PLANE IS AT THE SPECIFIED	с	0.15	-	0.20	
DISTANCE FROM (-C-) IN THE DIRECTION INDICATED. FORMED LEADS SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITH 0.00mm AT SEATING PLANE.	c1	0.12	0.127	0.15	
	D	2.80	2.90	3.00	
6. THIS PART IS COMPLIANT WITH JEDEC SPECIFICATION MD-193 EXCEPT FOR THE "e" DIMENSION WHICH IS 0.95mm INSTEAD OF 1.00mm. THIS PART IS IN FULL	E		2.75 BSC		
COMPLIANCE TO EIAJ SPECIFICATION SC-74.	E1	1.55	1.60	1.65	
<ol> <li>COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERNINALS. COPLANARITY SHALL NOT EXCEED 0.08mm.</li> </ol>	L	0.30	0.40	0.50	
8. WARPAGE SHALL NOT EXCEED 0.10mm.	e1	1.90 BSC			
9. The terminal #1 identifier and terminal numbering convention shall	e		0.95 BSC		
CONFORM TO JESD 95-1 PP-012, DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIDINAL, THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR NARKED	20	0*	4*	8*	
FEATURE.	aaa	codes: Z6-1; Z6-2			
100 Marking is for package orientation reference only.	Ркд. с	odesi 26	-1, 26-2		
11. ALL DIMENSIONS APPLY TO BOTH LEADED (-> AND LEAD FREE (+> PACKAGE CODES.					
			////)		
	TTLE: PACKA (LOW	GE OUTLI PROFILE)	NE, 6L TH	IN SOT23	
-DRAWING NOT TO SCALE-	APPROVAL	DOCU	MENT CONTROL N	10. REV.	

Γ