General Description

The Himalaya series of voltage regulator ICs and power modules enables cooler, smaller, and simpler power supply solutions. The MAXM17536 is an easy-to-use, step-down power module that combines a switching power supply controller, dual n-channel MOSFET power switches, fully shielded inductor, and the compensation components in a low-profile, thermally-efficient system-in-package (SiP). The device operates over a wide input-voltage range of 4.5V to 60V and delivers up to 4A continuous output current with excellent line and load regulation over an output-voltage range of 0.9V to 12V. The high level of integration significantly reduces design complexity, manufacturing risks, and offers a true plug-and-play power supply solution, reducing time-to-market.

The device can be operated in the pulse-width modulation (PWM), pulse-frequency modulation (PFM), or discontinuous conduction mode (DCM) control schemes.

The MAXM17536 is available in a low-profile, highly thermal-emissive, compact, 29-pin, 9mm x 15mm x 4.32mm SiP package that reduces power dissipation in the package and enhances efficiency. The package is easily soldered onto a printed circuit board and suitable for automated circuit board assembly.

Applications

- Test and Measurement Equipment
- **Distributed Supply Regulation**
- FPGA and DSP Point-of-Load Regulator
- **Base-Station Point-of-Load Regulator**
- **HVAC and Building Control Systems**

Typical Application Circuit

Benefits and Features

- Reduces Design Complexity, Manufacturing Risks, and Time-to-Market
	- Integrated Synchronous Step-Down DC-DC **Converter**
	- Integrated Inductor
	- Integrated FETs
	- Integrated Compensation Components
- Saves Board Space in Space-Constrained Applications
	- Complete Integrated Step-Down Power Supply in a Single Package
	- Small Profile, 9mm x 15mm x 4.32mm SiP Package
	- Simplified PCB Design with Minimal External BOM **Components**
- Offers Flexibility for Power-Design Optimization
	- Wide Input-Voltage Range from 4.5V to 60V
	- Output-Voltage Adjustable Range from 0.9V to 12V
	- Adjustable Frequency with External Frequency Synchronization (100kHz to 2.2MHz)
	- PWM, PFM, or DCM Current-Mode Control
	- Programmable Soft-Start
	- Auxiliary Bootstrap LDO for Improved Efficiency
	- Optional Programmable EN/UVLO
- Operates Reliably in Adverse Environments
	- Integrated Thermal Protection
	- Hiccup Mode Overload Protection
	- RESET Output-Voltage Monitoring
	- Ambient Operating Temperature Range (-40°C to +125°C)/Junction Temperature Range (-40°C to +150°C)
	- Complies with CISPR22(EN55022) Class B Conducted and Radiated Emissions

[Ordering Information](#page-20-0) appears at end of data sheet.

Absolute Maximum Ratings

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

PACKAGE TYPE: 29-PIN SiP

For the latest package outline information and land patterns (footprints), go to **www.maximintegrated.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Note 1: Junction temperature greater than +125°C degrades operating lifetimes. **Note 2:** Package thermal resistance is measured on an evaluation board with natural convection.

Electrical Characteristics

 $(V_{IN} = V_{EN/UVLO} = 24V$, $R_{RT} =$ OPEN (450kHz), $V_{PGND} = V_{SGND} = V_{MODE/SYNC} = 0V$, LX = SS = RESET = CF = DL = $V_{CC} =$ OUT = open, V_{EXTVCC} = 0V, V_{BST} to V_{LX} = 5V, V_{FB} = 1V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to SGND, unless otherwise noted.) (Note 3)

Electrical Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, R_{RT} = OPEN (450kHz), V_{PGND} = V_{SGND} = V_{MODE/SYNC} = 0V, LX = SS = RESET = CF = DL = V_{CC} = OUT = open, V_{EXTVCC} = 0V, V_{BST} to V_{LX} = 5V, V_{FB} = 1V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to SGND, unless otherwise noted.) (Note 3)

Electrical Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, R_{RT} = OPEN (450kHz), V_{PGND} = V_{SGND} = V_{MODE/SYNC} = 0V, LX = SS = RESET = CF = DL = V_{CC} = OUT = open, V_{EXTVCC} = 0V, V_{BST} to V_{LX} = 5V, V_{FB} = 1V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to SGND, unless otherwise noted.) (Note 3)

Note 3: Electrical specifications are production tested at T_A = + 25°C. Specifications over the entire operating temperature range are guaranteed by design and characterization.

Typical Operating Characteristics

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

EFFICIENCY vs. LOAD CURRENT (1.5V OUTPUT, PWM MODE, $f_{SW} = 400kHz$ **)** 100 toc09 90 80 70 EFFICIENCY (%) EFFICIENCY (%) 60 50 V_{IN} = 12V 40 $V_{IN} = 5V$ 30 20 10 θ 0 1000 2000 3000 4000 LOAD CURRENT (mA)

EFFICIENCY vs. LOAD CURRENT

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

EFFICIENCY vs. LOAD CURRENT (1.8V OUTPUT, PFM MODE, fSW = 400kHz)

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

STEADY-STATE SWITCHING WAVEFORMS $(V_{IN} = 24V, V_{OUT} = 5V, I_{OUT} = 25mA, PFM MODE)$

EFFICIENCY vs. LOAD CURRENT (12V OUTPUT, PFM MODE, fSW = 900kHz)

STEADY-STATE SWITCHING WAVEFORMS $(V_{IN} = 24V, V_{OUT} = 5V, I_{OUT} = 4A, PWM MODEL)$

STEADY-STATE SWITCHING WAVEFORMS $(V_{IN} = 24V, V_{OUT} = 5V, I_{OUT} = 100mA, DCM MODE)$

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

POWER-UP AND DOWN THROUGH EN/UVLO (VIN = 24V, VOUT = 5V, IOUT = 25mA, PFM MODE)

OUTPUT VOLTAGE vs. LOAD CURRENT (5V OUTPUT, PFM MODE, f_{SW} = 450kHz)

POWER-UP AND DOWN THROUGH EN/UVLO $(V_{IN} = 24V, V_{OUT} = 3.3V, I_{OUT} = 25mA, PFM MODE)$

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

LOAD TRANSIENT $(V_{IN} = 24V, V_{OUT} = 5V, I_{OUT} = 0A TO 2A, PWM MODE)$

POWER-UP WITH 2.5V BIAS (VIN = 24V, VOUT = 3.3V, IOUT = 0A, PWM MODE)

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

LOAD TRANSIENT (VIN = 24V, VOUT = 5V, IOUT = 25mA TO 2A, DCM MODE)

Typical Operating Characteristics (continued)

(V_{IN} = V_{EN/UVLO} = 24V, V_{SGND} = V_{PGND} = 0V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at T_A = +25°C. All voltages are referenced to GND, unless otherwise noted. The circuit values for different output-voltage applications are as in [Table 1,](#page-18-0) unless otherwise noted.)

CONDUCTED EMISSION PLOT (WITH FILTER C18 = C19 = C20 = C21 = C22 = 4.7µF, L1 = 8.2µH)

RADIATED EMISSION PLOT (NO FILTER C18 = C19 = C20 = C21 = C22 = OPEN, L1 = SHORT) **FILTER C18 = C**

Pin Configuration

Pin Description

Pin Description (continued)

Functional Diagrams

Internal Diagram

Detailed Description

The MAXM17536 is a high-efficiency, high-voltage, synchronous step-down module with dual-integrated MOSFETs that operates over a 4.5V to 60V input, and supports a programmable output voltage from 0.9V to 12V, delivering up to 4A current. Built-in compensation for the entire output-voltage range eliminates the need for external components. The feedback (FB) regulation accuracy over -40°C to +125°C is ±1.5%.

The device features a peak-current-mode control architecture. An internal transconductance-error amplifier produces an integrated error voltage at an internal node that sets the duty cycle using a PWM comparator, a highside current-sense amplifier, and a slope-compensation generator. At each rising edge of the clock, the highside MOSFET turns on and remains on until either the appropriate or maximum duty cycle is reached, or the peak current limit is detected. During the high-side MOSFET's on-time, the inductor current ramps up. During the second half of the switching cycle, the high-side MOSFET turns off and the low-side MOSFET turns on. The inductor releases the stored energy as its current ramps down and provides current to the output. The device features a MODE/SYNC pin that can be used to operate the device in PWM, PFM, or DCM control schemes and to synchronize the switching frequency to an external clock. The device integrates adjustable-input undervoltage lockout, adjustable soft-start, open-drain RESET, auxiliary bootstrap LDO, and DL-to-OUT short-detection features.

Mode Selection (MODE)

The logic state of the MODE/SYNC pin is latched when V_{CC} and EN/UVLO voltages exceed the respective UVLO rising thresholds and all internal voltages are ready to allow LX switching. If the MODE/SYNC pin is open at power-up, the device operates in PFM mode at light loads. If the MODE/SYNC pin is grounded at power-up, the device operates in constant-frequency PWM mode at all loads. Finally, if the MODE/SYNC pin is connected to V_{CC} at power-up, the device operates in constant frequency DCM mode at light loads. State changes on the MODE/SYNC pin are ignored during normal operation.

PWM-Mode Operation

In PWM mode, the inductor current is allowed to go negative. PWM operation provides constant frequency operation at all loads, and is useful in applications sensitive to changes in switching frequency. However, the PWM mode of operation gives lower efficiency at light loads compared to PFM and DCM modes of operation.

PFM-Mode Operation

The PFM mode of operation disables negative inductor current and additionally skips pulses at light loads for high efficiency. In PFM mode, the inductor current is forced to a fixed peak of 2A (typ) every clock cycle until the output rises to 102.3% of the nominal voltage. Once the output reaches 102.3% of the nominal voltage, both the highside and low-side FETs are turned off and the device enters hibernate operation until the load discharges the output to 101.1% of the nominal voltage. Most of the internal blocks are turned off in hibernate operation to minimize quiescent current. After the output falls below 101.1% of the nominal voltage, the device comes out of hibernate operation, turns on all internal blocks, and again commences the process of delivering pulses of energy to the output until it reaches 102.3% of the nominal output voltage. The advantage of the PFM mode is higher efficiency at light loads because of lower quiescent current drawn from the supply. The disadvantage is that the output-voltage ripple is higher compared to PWM or DCM modes of operation and switching frequency is not constant at light loads.

DCM-Mode Operation

DCM mode of operation features constant frequency operation down to lighter loads than PFM mode, by not skipping pulses but only disabling negative inductor current at light loads. DCM operation offers efficiency performance that lies between PWM and PFM modes

Linear Regulator

The MAXM17536 has two internal low-dropout (LDO) regulators that powers V_{CC} . During power-up, when the EN/UVLO pin voltage is above the true shutdown voltage (0.8V), then the V_{CC} is powered from INLDO. When V_{CC} voltage is above the V_{CC} UVLO threshold and EXTVCC voltage is greater than 4.7V (typ) the V_{CC} is powered from EXTVCC LDO. Only one of the two LDOs is in operation at a time depending on the voltage level present at EXTVCC. Powering V_{CC} from EXTVCC increases efficiency at higher input voltages. EXTVCC voltage should not exceed 24V.

Typical V_{CC} output voltage is 5V. Internally V_{CC} is bypassed with a 2.2μF ceramic capacitor to PGND. See the *[Electrical Characteristics](#page-1-0)* table for the current limit details for both the regulators. In applications where the buck converter output is connected to the EXTVCC pin, if the output is shorted to ground, then the transfer from EXTVCC LDO to INLDO happens seamlessly without any impact on the normal functionality.

Setting the Switching Frequency (RT)

The switching frequency of the MAXM17536 can be programmed from 100kHz to 2.2MHz by using a resistor connected from RT to SGND. The switching frequency (f_{SW}) is related to the resistor connected at the RT pin (R_{RT}) by the following equation:

$$
R_{RT} \cong \frac{19 \times 10^3}{f_{SW}} - 1.7
$$

where R_{RT} is in kΩ and f_{SW} is in kHz. Leaving the RT pin open causes the device to operate at the default switching frequency of 450kHz. See the *[Electrical Characteristics](#page-1-0)* table for RT resistor value recommendations for a few common frequencies.

Operating Input-Voltage Range

The minimum and maximum operating input voltages for a given output voltage should be calculated as follows:

$$
V_{IN(MIN)} = \frac{V_{OUT} + (I_{OUT(MAX)} \times 0.076)}{1 - (f_{SW(MAX)} \times 230 \times 10^{-9})} + (I_{OUT(MAX)} \times 0.04)
$$

$$
V_{IN(MAX)} = \frac{V_{OUT}}{f_{SW(MAX)} \times t_{ON(MIN)}}
$$

where,

 V_{OUT} = Steady-state output voltage,

 $I_{OUT(MAX)} = Maximum load current,$

 $f_{SW(MAX)} =$ Maximum switching frequency,

 $t_{ON(MIN)}$ = Worst-case minimum switch on-time (160ns). Also, for duty cycle > 0.5 :

$$
V_{IN(MIN)} = (4.04 \times V_{OUT}) - (35 \times 10^{-6} \times f_{SW})
$$

where f_{SW} is the switching frequency in Hz.

Choose the greater of the two $V_{IN(MIN)}$ values obtained from the above equations as the minimum operating input voltage.

The *[Component Selection Table](#page-18-1)*, [Table 1](#page-18-0) provides the operating input-voltage range and the optimum switchingfrequency range for the different selected output voltages.

External Frequency Synchronization (SYNC)

The internal oscillator of the MAXM17536 can be synchronized to an external clock signal on the MODE/ SYNC pin. The external synchronization clock frequency must be between 1.1 x f_{SW} and 1.4 x f_{SW} , where f_{SW} is the frequency programmed by the RT resistor. When an external clock is applied to the MODE/SYNC pin, the internal oscillator frequency changes to the external clock frequency (from the original frequency based on the RT setting) after detecting 16 external clock edges. The converter operates in PWM mode during synchronization operation. When the external clock is applied to the MODE/SYNC pin, the mode of operation changes to PWM from the initial state of PFM/DCM. When the external clock is removed on-the-fly then the internal oscillator frequency changes to the RT set frequency and the converter still continues to operate in PWM mode. The minimum external clock pulse-width high should be greater than 50ns. See the MODE/SYNC section in the *[Electrical Characteristics](#page-1-0)* table for details.

DL-to-OUT Short Detection

In the MAXM17536, DL and OUT pins are adjacent to each other. To prevent damage to the low-side FET in case the DL pin is shorted to the OUT pins, the DL-to-OUT short detection feature has been implemented. If the MAXM17536 detects that the DL pin is shorted to the OUT pins before startup, the startup sequence is not initiated and output voltage is not soft-started.

Overcurrent Protection

The MAXM17536 is provided with a robust overcurrent protection (OCP) scheme that protects the modules under overload and output short-circuit conditions. A cycle-bycycle peak current limit turns off the high-side MOSFET whenever the high-side switch current exceeds an internal limit of 7.8A (typ). The module enters hiccup mode of operation, either if one occurrence of the runaway current limit 8.8A (typ), or if the FB node goes below 64.5% of its nominal regulation threshold after soft-start is complete. In hiccup mode, the module is protected by suspending switching for a hiccup timeout period of 32,768 switching cycles. Once the hiccup timeout period expires, soft-start is attempted again. Hiccup mode of operation ensures low power dissipation under output overload or short-circuit conditions. Note that when soft-start is attempted under overload condition, if feedback voltage does not exceed 64.5% of desired output voltage, the device switches at half the programmed switching frequency.

The MAXM17536 is designed to support a maximum load current of 4A. The inductor ripple current is calculated as follows:

$$
\Delta I = \left(\frac{V_{IN} - V_{OUT} - 0.071 \times I_{OUT}}{L \times f_{SW}}\right) \times \left(\frac{V_{OUT} + 0.051 \times I_{OUT}}{V_{IN} - 0.02 \times I_{OUT}}\right)
$$

where:

 $V_{OU}T$ = Steady-state output voltage

 V_{1N} = Operating input voltage

 f_{SW} = Switching frequency

L = Power module output inductance $(4.7\mu H \pm 20\%)$

 I_{OUT} = Required output (load) current

The following condition should be satisfied at the desired load current, I_{OUT} :

$$
I_{OUT}+\frac{\Delta I}{2}<7.15
$$

RESET Output

The MAXM17536 includes a comparator to monitor the output voltage. The open-drain RESET output requires an external pullup resistor. RESET goes high (high impedance) 1024 switching cycles after the regulator output increases above 95.5% of the designed nominal regulated voltage. RESET goes low when the regulator output voltage drops to below 92.5% of the nominal regulated voltage. RESET also goes low during thermal shutdown.

Prebiased Output

When the MAXM17536 starts into a prebiased output, both the high-side and the low-side switches are turned off so that the converter does not sink current from the output. High-side and low-side switches do not start switching until the PWM comparator commands the first PWM pulse, at which point switching commences. The output voltage is then smoothly ramped up to the target value in alignment with the internal reference.

Thermal-Shutdown Protection

Thermal shutdown protection limits total power dissipation in the MAXM17536. When the junction temperature of the device exceeds +165°C (typ), an on-chip thermal sensor shuts down the device, allowing the device to cool. The thermal sensor turns the device on again after the junction temperature cools by 10°C. Soft-start resets during thermal shutdown. Carefully evaluate the total power dissipation (see the *[Power Dissipation](#page-18-2)* section) to avoid unwanted triggering of the thermal shutdown in normal operation.

Applications Information

Input-Capacitor Selection

The input-filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the circuit's switching. The input capacitor RMS current requirement (I_{RMS}) is defined by the following equation:

$$
I_{RMS} = I_{OUT(MAX)} \times \frac{\sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}
$$

where, $I_{\text{OUT}(MAX)}$ is the maximum load current. I_{RMS} has a maximum value when the input voltage equals twice the output voltage (V_{IN} = 2 x V_{OUT}), so $I_{RMS(MAX)}$ = $I_{OUT(MAX)}/2$. Choose an input capacitor that exhibits less than a +10°C temperature rise at the RMS input current for optimal long-term reliability. Use low-ESR ceramic capacitors with high ripple-current capability at the input. X7R capacitors are recommended in industrial applications for their temperature stability. The C_{IN} capacitor values in [Table 1](#page-18-0) are the minimum recommended values for the associated operating conditions.

In applications where the source is located distant from the MAXM17536 input, an electrolytic capacitor should be added in parallel to the ceramic capacitor to provide necessary damping for potential oscillations caused by the inductance of the longer input power path and input ceramic capacitor.

Output-Capacitor Selection

X7R ceramic output capacitors are preferred due to their stability over temperature in industrial applications. The output capacitors are usually sized to support a step load of 50% of the maximum output current in the application, so the output-voltage deviation is contained to 3% of the output-voltage change. The minimum required output capacitance can be calculated as follows:

$$
C_{OUT} = \frac{1}{2} \times \frac{I_{STEP}}{\Delta V_{OUT}}
$$

tressense $\approx \frac{0.33}{f_C} + \frac{1}{f_{SW}}$

where:

 $I_{STEP} = Load-current step,$

tRESPONSE = Response time of the controller,

 V_{OUT} = Allowable output-voltage deviation,

 f_C = Target closed-loop crossover frequency,

 f_{SW} = Switching frequency. Select f_C to be 1/10th of f_{SW} if the swtiching frequency is less than or equal to 400kHz. Select f_C to be 40kHz if the switching frequency is more than 400kHz.

Soft-Start Capacitor Selection

The MAXM17536 implements adjustable soft-start operation to reduce inrush current. A capacitor connected from the SS pin to SGND programs the soft-start time. The selected output capacitance (C_{SF}) and the output voltage (V_{OUT}) determine the minimum required soft-start capacitor as follows:

$$
C_{SS} \geq 28 \times 10^{-6} \times C_{SEL} \times V_{OUT}
$$

The soft-start time (t_{SS}) is related to the capacitor connected at SS (C_{SS}) by the following equation:

$$
t_{SS} = \frac{C_{SS}}{5.55}
$$

where t_{SS} is in milliseconds and C_{SS} is in nanofarads. For example, to program a 4ms soft-start time, a 22nF capacitor should be connected from the SS pin to SGND.

Setting the Input Undervoltage-Lockout Level

The MAXM17536 offers an adjustable input undervoltage lockout level. Set the voltage at which MAXM17536 turns on. Calculate R3 as follows:

$$
R3 = \frac{3.32 \times 1.215}{(V_{\text{INU}} - 1.215)}
$$

where R3 is in MΩ and V_{INU} is the voltage at which the MAXM17536 is required to turn on. Ensure that V_{INV} is higher than $0.8 \times V_{\text{OUT}}$.

Loop Compensation

The MAXM17536 is internally loop-compensated. Connect a 2.2pF capacitor from CF to FB for stable operation.

Typically, designs with crossover frequency (f_C) less than fSW/10 and less than 40kHz offers good phase margin and transient response. For other choices of f_C , the design should be carefully evaluated according to user requirements.

Adjusting Output Voltage

Set the output voltage with a resistive voltage-divider connected from the positive terminal of the output capacitor (V_{OUT}) to SGND (see [Figure 2\)](#page-18-3). Connect the center node of the divider to the FB pin. To choose the resistive voltage-divider values calculate for resistor R1, then R2.

First, calculate resistor R1 from the output to FB as follows:

$$
R1 = \frac{451 \times 10^3}{f_C \times C_{OUT}}
$$

where:

R1 is in kΩ

 f_C = Desired crossover frequency (kHz)

 C_{OUT} = Derated value of the capacitor (μ F)

Then, calculate resistor R2 from FB to SGND as follows:

$$
R2 = \frac{R1 \times 0.9}{(V_{OUT} - 0.9)}
$$

Figure 1. Setting the Input-Undervoltage Lockout Figure 2. Setting the Output Voltage

Component Selection Table

Table 1. Selection Component Values

Power Dissipation

The power dissipation inside the module leads to increase in the junction temperature of the MAXM17536. The power loss inside the module at full load can be estimated as follows:

$$
P_{LOSS} = P_{OUT} \left(\frac{1}{\eta} - 1\right) - \frac{P_{OUT}^2}{1000 \times V_{OUT}} \times \frac{(1 + 0.0043 \times T_A) \times \left(\frac{45.15}{V_{OUT}} - \frac{21.67}{V_{IN}}\right)}
$$

where:

 P_{OUT} = Total output power

 V_{OUT} = Output voltage

 V_{IN} = Input voltage

η is the efficiency of the power module at the desired operating conditions. See the *[Typical Operating](#page-4-0) [Characteristics](#page-4-0)* for the power-conversion efficiency or measure the efficiency to determine the total power dissipation. The junction temperature (T_J) of the module can be estimated at any given maximum ambient temperature (T_A) from the following equation:

$T_{\rm J}$ = $T_{\rm A}$ + ($\theta_{\rm J}$ x $P_{\rm I}$ oss)

For the MAXM17536 evaluation board, the thermal resistance from junction-to-ambient (θ_{JA}) is 24°C/W. Operating the module at junction temperatures greater than +125°C degrades operating lifetimes. An EE-SIM model is available for the MAXM17536 to simulate efficiency and power loss for the desired operating conditions.

PCB Layout Guidelines

- All connections carrying pulsed currents must be very short and as wide as possible. The inductance of these connections must be kept to an absolute minimum due to the high di/dt of the currents. Since inductance of a current carrying loop is proportional to the area enclosed by the loop, if the loop area is made very small, inductance is reduced. Additionally, small current-loop areas reduce radiated EMI.
- A ceramic input-filter capacitor should be placed close to the IN pins of the module. This eliminates as much trace-inductance effects as possible and gives the module a cleaner voltage supply.
- PCB layout also affects the thermal performance of the design. A number of thermal vias that connect to a large ground plane should be provided under the exposed pad of the part, for efficient heat dissipation.
- For a sample layout that ensures first pass success, refer to the MAXM17536 evaluation kit PCB layout available at **www.maximintegrated.com**.

Typical Application Circuits

Typical Application Circuit for 5V Output

Typical Application Circuits (continued)

Typical Application Circuit 3.3V

Ordering Information

#Denotes a RoHS-compliant device that may include lead(Pb) that is exempt under the RoHS requirements.

T = Tape and reel.