# **mikrolCD**<sup>™</sup> in-circuit debugger

Whether you are a beginner, or a professional, this powerful tool, with intuitive interface and convenient set of commands will enable you to track down bugs quickly. mikroICD<sup>TM</sup> is one of the fastest, and most reliable debugging tools on the market.

## Exploit the full potential of real-time hardware debugging

<b>B</b>			\$()	₽,	()₽>	¢I				<b>1</b>
Start Debugger [F9]	Kun/Pause Debugger [f6]	Stop Debugger [Ctrl+F2]	Step into [F7]	Step Over [F8]	Step Out [Ctrl+F8]	Run To Cursor [F4]	Toggle Breakpoint [F5]	Show/Hide Breakpoints [Shift+F4]	Clear breakpoints [Ctrl+Shift+F5]	Jump To Interrupt [F2]

## TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

The PIC®, dsPIC®, PIC24®, PIC32® and Windows® logos and product names are trademarks of Microchip Technology® and Microsoft® in the U.S.A. and other countries

## Table of Contents

4
4
4
5
5
5
6
7
7
7
8
10
10
10
10
10

4	Step 2 - Add variable	11
4	5. Debugger toolbar	12
4	Debug commands	12
5	Execute commands	12
5	Managing breakpoints	12
5	6. Real-Time debugging	14
6	Step by Step	14
7	Execute remaining lines	14
7	Execute to cursor	14
7	7. Using Breakpoints	15
8	Hardware and software breakpoints	15
10	8. Advanced Breakpoints Option	16
10	9. Disassembly view	18
10	10. EEPROM Watch window	19
10	11. RAM window	20
10	12. CODE Watch window	21

## Introduction to mikrolCD<sup>TM</sup>

### What is mikrolCD<sup>™</sup>?

**mikrolCD<sup>TM</sup>** is a highly effective tool for a Real-Time debugging on hardware level. The mikrolCD<sup>TM</sup> debugger enables you to execute your program on the host microcontroller and view variable values, Special Function Registers (SFR), RAM, CODE and EEPROM memory along with the mikrolCD<sup>TM</sup> code execution on hardware. In order to use **mikrolCD<sup>TM</sup>** it is necessary to have the appropriate hardware (**mikroProg<sup>TM</sup> for PIC®**, **dsPIC® and PIC32®**) and software (Mikroelektronika compilers for PIC®, dsPIC® or PIC32®).

### **Key features**



Supported in all Mikroelektronika hardware programers for PIC®, dsPIC® and PIC32® (mikroProg<sup>™</sup> for PIC®, dsPIC® and PIC32®)



Supported in all MikroElektronika compilers for PIC<sup>®</sup>, dsPIC<sup>®</sup> and PIC32<sup>®</sup> (mikroC<sup>TM</sup>, mikroBasic<sup>TM</sup> and mikroPascal<sup>TM</sup>)



Real time step by step debugging Can monitor SFR, RAM, CODE and EEPROM memory

## Hardware and software

### mikroProg<sup>™</sup> programmer

mikroICD<sup>TM</sup> is included with on-board programmers on mikroElektronika development systems and on mikroProg<sup>TM</sup> for PIC<sup>®</sup>, dsPIC<sup>®</sup> and PIC32<sup>®</sup> stand alone programmer. Microcontroller on target device is connected with programmer via PGC, PGD and MCLR pins. These pins are used for programing purposes and cannot be used as I/O while mikroICD<sup>TM</sup> is in use. Before using mikroICD<sup>TM</sup> it is necessary to program target microcontroller with a debug-enabled version of your output HEX file.



### **Compilers**

All MikroElektronika compilers (mikroC<sup>TM</sup>, mikroBasic<sup>TM</sup> and mikroPascal<sup>TM</sup>) for PIC<sup>®</sup>, dsPIC<sup>®</sup> and PIC32<sup>®</sup> natively support mikroICD<sup>TM</sup>. Specialized mikroICD<sup>TM</sup> DLL module allows compilers to exploit the full potential of fast hardware debugging. Along with compilers, make sure to install the appropriate programmer drivers and mikroProg Suite<sup>TM</sup> for PIC<sup>®</sup> programming software.

## 1. Starting compiler

After the appropriate software and hardware is installed and attached to your PC it's time to start the chosen compiler.



In this manual we will use **mikroC PRO for PIC** compiler. All other compilers (mikroBasic<sup>TM</sup> and mikroPascal<sup>TM</sup> for PIC<sup>®</sup>, dsPIC<sup>®</sup> and PIC32<sup>®</sup>) have the same IDE so using **mikroICD<sup>TM</sup>** is the same for all.

After the compiler is started write a new project or open the existing one.

mikroC PRO for	PIC v.5.4.0 - C:\User	s\Public\Docu	ments\Mikroelektronika\mi	roC PRO for PIC\Examples\Development Systems\	EASYPIC7\Led Blinking\LedBlinking.mcppi			•
ile <u>E</u> dit <u>V</u> iew	Project Build R	un Iools <u>H</u>	Help					
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Code Explorer	8	LedBinkin	g.c			주 💌	🖃 Image Preview	- 平 []
달 허		•	/*			~		
- Functions		•	* Project name:				CARLE CARLES	
🗌 main		•		(Simple 'Hello World' project)			- Oshiniki asi inana	
Globals		•	* Copyright:					
Externs		-	(c) Mikroelek	ronika, 2011.			A REAL PROPERTY.	
- TupeDef	E		* Revision Histor	11				
Tags			20110929:				A CONTRACTOR OF A CONTRACTOR A CONTRACT	
- Includes			- initial r	lease (FJ);				
Directives			* Description:					
- Web Links		10		ole 'Hello World' project. It turn	s on/off LEDs connected to	E	DS, HE HE HEAD PICKY	1
	w1.microchip.com/			PORTC, PORTD and PORTE.			Project Manager [1/1] - LedBlinking.mcpp	8
	*		* Test configurat.					
		13	<ul> <li>Test conrigurat.</li> <li>MCII;</li> </ul>	PIC18F45K22			888888	- *
Project Settings		13	MCO 1	http://ww1.microchip.com/downl			🖃 陷 LedBlinking.mcppi	
Device					oads/en/DeviceDoc/41412D.pdr		E- Cources	
4.		-	Dev.Board:	EasyPIC7 - <u>ac:LEDs</u>			- 📓 LedBinking.c	
ame: P18F4	ak 22 -	•		http://www.mikroe.com/eng/prod		lopmer	- 🗀 Header Files	
Tune. Trorts.	****	•	Oscillator:	HS-PLL 32.0000 MHz, 8.0000 MHz	Crystal		💼 Binaries	
		•	Ext. Modules:	None.			- i Project Level Defines	
6 MCU Clock		•	SW:	mikroC PRO for PIC			🗄 💼 Image Files	
•		20		http://www.mikroe.com/eng/prod	ucts/view/7/mikroc-pro-for-pi		LEDs.jpg	
			* NOTES:				EasyPIC7.jpg	
Frequency:	32.000000 MHz		- Turn ON the	PORT LEDs at SW3.			- EEPROM Files	
			*/				Active Comments Files	
							- 🔛 LEDs.xml	
Build/ Debugger 1	ype	- 8	void main() {					_
Build Type		· T					🛄 Library Manager 燥 Project Explorer	
Release	ICD Debug		TRISA = 0;	// set direction to be output			🛸 🌯 🗂 🏹 🦳 🌁 LibSto	odc
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Software	mikrolCD		INISC - 0;	// set direction to be output		*	B- Button	
		* m				•	CAN SPI	
Messages 🔝	Quick Converter						Compact Flash	
Errors	Varnings	Hints					Compact_nash     Compact Flash FAT16	
Citions .	warnings	(M) rants					Compact_hash_PAT to     Conversions	
e M	essage No.		Message Text		Unit	^	B C Math	
12	7		All files Compiled in	31 ms			B C Stdib	
	144			0 (1%) Free RAM (bytes): 1515 (99%)	Used RAM (bytes)	0 (1%)	B C String	
	144			120 (1%) Free ROM (bytes): 32648 (99%)	Used ROM (bytes)		B C Type	
11	25		Project Linked Suc		LedBlinking.mcppi	=	B EEPROM	
12	18		Linked in 47 ms				EPSON S1D13700	
12	19		Project 'LedBlinking	.mcppi' completed: 281 ms		-	B- FLASH	
							e God	
	Insert		Compiled	C:\\mikroC PRO for PIC\Examples\Develo				

#### Figure 1-1: mikroC PRO for PIC window

## 2. Preparing mikrolCD<sup>m</sup>

In order to use mikrolCD<sup>TM</sup>, you have to program your microcontroller with debug-enabled .HEX file of your project. This is done in two simple steps:

## Step 1 - Enable mikrolCD<sup>™</sup>

Under Project Settings - Build /Debugger Type, select ICD Debug and mikrolCD<sup>™</sup> options.

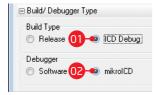


Figure 2-1: Build/Debugger Type options



Select ICD Debug option to create debug output HEX file.

Select **mikrolCD<sup>™</sup> option** to enable usage of mikrolCD<sup>™</sup> debugger for debugging

## Step 2 - Build your project

Next step is to build your project and to program it to MCU memory. To do that click on **Build > Build + Program [Ctrl+F11]** option or click on 🌺 icon in the build toolbar. Compiler will automatically build the program and start mikroProg Suite<sup>™</sup> for PIC® software which will program the code into microcontroller.

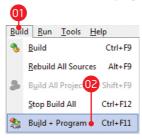


Figure 2-2: Build menu

🗄 💻 🛃 🚺 🚺 2 Build And Program 🎭 Build current project and (CTRI + F11)

Figure 2-3: Build toolbar



### Activate **Build** Menu

From drop down menu select **Build + Program** option or press [Ctrl+F11] on your keyboard

## **3. Start mikrolCD<sup>™</sup> debugging**

To start **mikroICD**<sup>TM</sup> debugging open the **Run** menu and click the **Start Debugger [F9]** option or **b**, icon from Run toolbar.

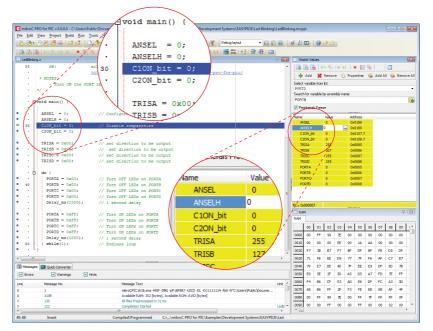


#### Figure 3-1: Run menu

01

Click the **Run** option

From drop down menu select **Start Debugger** option or press **[F9]** on keyboard





Make sure to enable power supply on your device

### Figure 3-2: mikroC window during debugging

When **mikroICD**<sup>TM</sup> debugging is started a program line which will be next executed is highlighted with a blue strip.

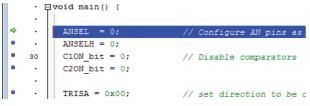


Figure 3-3: Execution line is highlighted

Next step is to select values which will be monitored. Click on **View** -> **Debug Windows** -> **Watch Window [Shift+F5]** or click the & icon to open **Watch Values** window.

Viev	v <u>P</u> roject <u>B</u> uild <u>R</u> un <u>T</u> ools	H	elp		
	D <u>e</u> bug Windows	•	66°	Watch Window	Shift+F5
	<u>T</u> oolbars	۲	Ō	<u>S</u> topwatch	
	<u>B</u> ookmarks		:=	<u>B</u> reakpoints	Shift+F4
Ē	<u>C</u> ode Explorer			Advanced Breakpoints	Shift+Ctrl+A

Figure 3-4: Open watch values window

Within **Watch Values** window you can set which registers or variables are going be monitored.

Watch Values				×
🗈 🗟 🔓	♦0 <sup>0</sup> 0 0♦ ♦]	🔹 🗄 🕵		
💠 Add 🔰	Remove 🤣	Properties 候	Add All 💊	Remove All
Select variable fro	m list:			
PORTD				•
Search for variable	e by assembly nam	ie:		
PORTB				<b>E</b>
Peripherals Free	eze			
Name	Value	Address		
ANSEL	0	0x0188		
ANSELH	0			
C1ON_bit	0	0x0107.7		
C2ON_bit	0	0x0108.7		
TDICA				
TRISA	255	0x0085		
TRISA	255 127	0x0085 0x0086		
TRISB	127	0x0086		
TRISB TRISC	127 255	0x0086 0x0087		
TRISB TRISC TRISD	127 255 255	0x0086 0x0087 0x0088		
TRISB TRISC TRISD PORTA	127 255 255 0	0x0086 0x0087 0x0088 0x0088		

#### Figure 3-5: Watch values window

## 4. Watch Window

### What are the Watch Variables?

Each special function register (SFR), and user defined variables which are not removed by the optimizer, can be monitored in **Watch Window** during the debugging process. With execution of each program line, values of selected variables are automatically updated. Watch Window also provides the information about the **memory address** and the full **assembly name** of each variable.

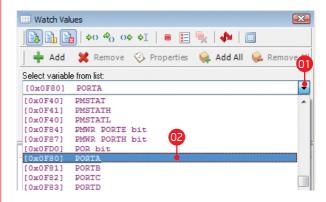
### **Types of variables**

Purple colored variables are special **function registers and sbit variables** from the definition file of the selected microcontroller. Black colored variables represent **user defined variables**, or variables used internally by compiler libraries.

### **Adding Watch Variables**

Adding variable for monitoring can be done in two simple ways: by selecting the variable from the drop down list, or by searching for the desired variable using the search box.

### Step 1 - Select variable



#### Figure 4-1: Select variable for monitoring



Click to show drop down menu.

2 Select desired variable for monitoring

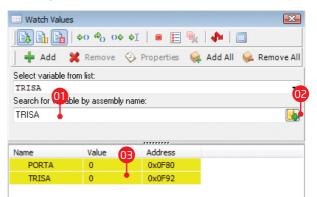
## Step 2 - Add variable

Watch Values				<b>—</b>
<b>01</b> , <b>6</b>   •	o 🍖 o	• •I   🔳 🧮	۱ 🍁 🛛	
Add 💥	Remove	Properties	解 Add All	候 Remove All
Select variable from				
PORTA -	-02			-
Search for variable	oy assembl	ly name:		
PORTA				
Name	Value	Address		
PORTA	0	0x0F80		

#### Figure 4-2: Add variable for monitoring



Click the **Add** button and selected variable will be added to list List with selected variables Instead of selecting variable from list you can type in variable assembly name in the search box.



#### Figure 4-3: Search for variable



Type in variable assembly name

Click on add variable button

Variable is added to list

## 5. Debugger toolbar

To simplify debugging compiler IDE contains toolbar with icons that allow single click access to **mikroICD**<sup>TM</sup> commands.

### **Debug commands**

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The first three icons on the toolbar are used for starting/stopping debugger:



Start debugger [F9]



Run/Pause Debugger [F6]



Stop Debugger [Ctrl + F2]

### Execution commands

⇔() ≈<sub>()</sub> ()⇔ ⇒]

Next set of icons enables you to execute program in real time:

- ⇔() Step Into [F7]
- 🗟 Step Over [F8]
- ()⇔ Step Out [Ctrl + F8]
- ⇔I Run To Cursor [F4]

#### Figure 5-1: Debugger toolbar

🖹 📴 📴 🗠 🕫 🖓 🗛

### Managing breakpoints



Last set of icons is related to breakpoints and interrupt option:

Toggle Breakpoint [F5]



Show/Hide breakpoints [Shift+F4]



Clears breakpoints [Shift+Ctrl+F5]

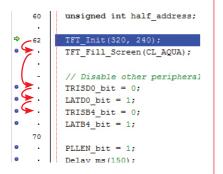
Jump to interrupt [F2]

Toolbar Icon	Name	Shortcut	Description
	Start Debugger	[F9]	Starts Debugger.
	Run/Pause Debugger	[F6]	Run/Pause Debugger.
<b>₽</b> ×	Stop Debugger	[Ctrl + F2]	Stops Debugger.
\$()	Step Into	[F7]	Executes the current program line, then halts. If the executed program line calls another routine, the debugger steps into the routine and halts after executing the first instruction within it.
₽ <sub>0</sub>	Step Over	[F8]	Executes the current program line, then halts. If the executed program line calls another routine, the debugger will not step into it. The whole routine will be executed and the debugger halts at the first instruction following the call.
()⇔	Step Out	[Ctrl + F8]	Executes all remaining program lines within the subroutine. The debugger halts immediately upon exiting the subroutine.
¢I	Run To Cursor	[F4]	Executes the program until reaching the cursor position.
	Toggle Breakpoint	[F5]	Toggle breakpoints option sets new breakpoints or removes those already set at the current cursor position.
	Show/Hide breakpoints	[Shift+F4]	Shows/Hides window with all breakpoints
	Clears breakpoints	[Shift+Ctrl+F5]	Deletes selected breakpoints
4	Jump to interrupt	[F2]	Opens window with available interrupts (doesn't work in mikrolCD $^{ extsf{m}}$ mode)

## 6. Real-Time debugging

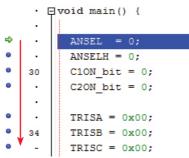
Real-Time debugging enables execution of program in three different ways:

### Step by Step



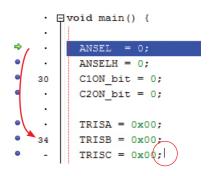
To execute program one line at the time you can use **Step Into** (F7) and **Step Over** (F8) options

### **Execute remaining lines**



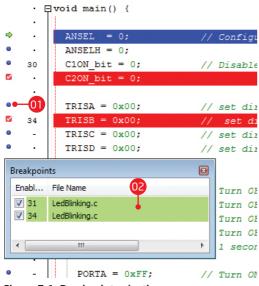
Execution of all remaining program lines is available via **Step Out** OP [Ctrl+F8] option. Debugging will stop when all lines in subroutine are executed.

### **Execute to cursor**



In order to execute program starting from the current line to one where cursor is placed, use option **Run to Cursor I**[**F4**]. Program will start execution at the current line (blue strip) and it will stop at line where cursor is placed.

## 7. Using Breakpoints



#### Figure 7-1: Breakpoint selection



Click on a blue dot to place a breakpoint Lines 31 and 34 are enabled as breakpoints The **mikroICD**<sup>TM</sup> enables each program line to be marked with a **breakpoint**. The breakpoint is an intentional stopping or pausing place in the program used for the purpose of debugging.

**Breakpoints** are placed in the program by clicking the blue dots to the left of the program line or by pressing icon **[F5]**. By selecting the **Run** command icon **[F6]**, the microcontroller will execute the program from the current location (highlighted in blue) until it reaches a breakpoint (highlighted in red). The debugger halts after reaching the breakpoint.

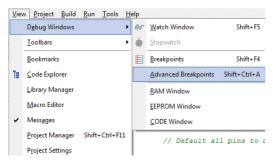
### Hardware and software breakpoints

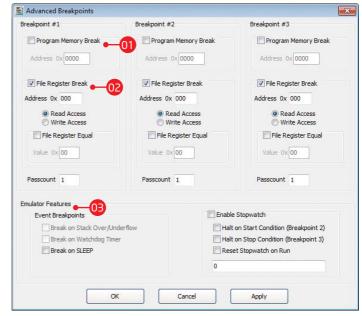
There are two kinds of breakpoints - hardware and software breakpoints. The only visible difference between them is in the speed of program execution before it reaches the specified program line.

Hardware breakpoints are placed within the microcontroller chip and provide considerably faster program execution. The total number of software breakpoints goes up to 16, while the number of hardware breakpoints is much smaller. For example, PIC16<sup>®</sup> microcontrollers have only one, whereas PIC18<sup>®</sup> microcontrollers have up to 3 hardware breakpoints. When all hardware breakpoints are used, then remaining breakpoints in the program will be used as **software breakpoints**.

## 8. Advanced Breakpoints Option

The **mikroICD**<sup>TM</sup> provides the means for using the **Advanced Breakpoints option** with PIC18<sup>®</sup>, PIC24<sup>®</sup> and dsPIC<sup>®</sup> microcontrollers. To enable it, check the Advanced Breakpoints check box within the Watch Values window. To configure the Advanced Breakpoints option it is necessary to start up mikroICD<sup>TM</sup> [F9] and select the **View > Debug Windows > Advanced Breakpoints** option or to use the keyboard shortcut [Ctrl+Shift+A].





#### Figure 8-1: Advanced breakpoints menu

#### Figure 8-2: Advanced breakpoints window

Page 16

The **Program Memory Break** option is used for placing breakpoints at specified addresses in the program memory. The value entered in the Address field must be in the HEX format.

The File Register Break option is used for stopping code execution when read/write access to the specified data memory location occurs. If the Read Access option is selected, the File Register Equal option can be used for setting the appropriate value in the Value field. The program execution will be stopped when the value read from the specified data memory location matches the value written in the Value field. All the values entered in the Value field must be in the HEX format.

03 Emulator Features enables the usage of Event Breakpoints and Stopwatch.

#### **Event Breakpoints**

Break on Stack Overflow/Underflow : not implemented.

Break on Watchdog Timer :

not implemented.

**Break on SLEEP** : break on SLEEP instruction. SLEEP instruction will not be executed. If you choose to continue the mikroICD debugging [F6] then the program execution will start from the first instruction following the SLEEP instruction.

#### **Enable Stopwatch**

To use the Stopwatch define **Breakpoint#2** and **Breakpoint#3** as a Start and Stop conditions and check the Enable Stopwatch checkbox.

**Halt on Start Condition (Breakpoint#2) :** when checked, the program execution will stop on Breakpoint#2. Otherwise, Breakpoint#2 will be used only to start the Stopwatch.

**Halt on Stop Condition (Breakpoint#3):** when checked, the program execution will stop on Breakpoint#3. Otherwise, Breakpoint#3 will be used only to stop the Stopwatch.

**Reset Stopwatch on Run :** when checked, the Stopwatch will be cleared before continuing program execution and the next counting will start from zero. Otherwise, the next counting will start from the previous Stopwatch value.

## 9. Disassembly view

During the process of compiling, each program line written in a highlevel programming language is replaced with one or more assembly instructions. To display program in the assembly language, select the **View > Listing** option or click <u>I</u> icon in toolbar. In this case, the process of simulating and debugging is performed in the same way as if the program is written in a high-level programming language. To toggle between high-level language and assembly language press **[Alt+D]** on your keyboard or click on **[]** icon.

	20	SW:	mikroC PRO for PIC
			http://www.mikroe.com/eng/produc
	•	* NOTES:	
	•	- Turn ON the	PORT LEDs at SW9.
	·	*/	
	-		
	۰Ę	<pre>void main() {</pre>	
	•		
>	28	ANSEL = 0;	// Configure AN pins as digit.
	·	ANSELH = 0;	
	30	ANSELH = 0; C1ON_bit = 0;	<pre>// Disable comparators</pre>
			// Disable comparators
	30	ClON_bit = 0;	// Disable comparators
	30	ClON_bit = 0;	<pre>// Disable comparators // set direction to be output</pre>
	30	C10N_bit = 0; C20N_bit = 0;	<pre>// set direction to be output</pre>
	30	C10N_bit = 0; C20N_bit = 0; TRISA = 0x00;	<pre>// set direction to be output // set direction to be output</pre>
	30	C10N_bit = 0; C20N_bit = 0; TRISA = 0x00; TRISB = 0x00;	

	LedBlink	ing.c 🔀 📄 L	edBlinking.lst 🎫			
	•	; LST file	e generated	by mikrol	istExporte	r - v.2.0
	·	; Date/Time	e: 7/1/2011	2:31:27 H	PM	
	·	;				
	-	;Address O	pcode	ASM		
•	•	0x0000	0x2803		GOTO	3
	•	_main:				
		;LedBlinki	ng.c,26 ::		void	main() {
	•	;LedBlinki	ng.c,28 ::		ANSEL	L = 0;
\$	10	0x0003	0x1683		BSF	STATUS, 5
۰	•	0x0004	0x1703		BSF	STATUS, 6
۰	•	0x0005	0x0188		CLRF	ANSEL
	·	;LedBlinki	ng. <i>c,29 ::</i>		ANSE	LH = 0;
•	•	0x0006	0x0189		CLRF	ANSELH
	-	;LedBlinki	ng.c,30 ::		C10N	bit = 0;
•	·	0x0007	0x1283		BCF	STATUS, 5
•	•	8000 <b>x</b> 0	0x1387		BCF	C1ON_bit,
	·	;LedBlinki	ng.c,31 ::		C20N	bit = 0;
•	·	0x0009	0x1388		BCF	C2ON bit,

#### Figure 9-1: High-level programming language

#### Figure 9-2: Assembly language

## **10. EEPROM Watch window**

You can start **EEPROM Watch window** using **View > Debug Windows > EEPROM Window** option. It shows the values currently stored in the MCU internal EEPROM memory.

R	Read El	EPROM		Wr	ite EEP	ROM											
	01	01	02	03	02	05	06	07	08	09	0A	0B	0C	0D	0E	0F	ASCII
0000	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0010	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0020	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0030	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0040	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0050	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0060	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0070	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0080	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0090	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
00A00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	

Click the **Read EEPROM** button to read the contents of microcontroller EEPROM memory which will be shown in the EEPROM Watch window.

Click the **Write EEPROM** button to program the data from the EEPROM Watch window into the internal EEPROM memory of the microcontroller.

#### Figure 10-1: EEPROM watch window

## **11. RAM window**

The **mikrolCD<sup>™</sup>** allows you to view the contents of the microcontroller's RAM memory using the **RAM window**. You can activate it by clicking the **View > Debug Windows > RAM Window** option.

	00	01	02	03	04	05	06	07	08	09	0A	OB	0C	0D	0E	OF	ASCII
0F20	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0F30	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0F40	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0F50	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
0F60	00	00	00	00	Æ	20	00	00	00	00	03	00	00	00	00	22	~ <spc> <etx></etx></spc>
0F70	00	FB	FF	00	FE	FF	00	FF	00	00	FE	BB	40	00	40	00	.ű`.ţ`.`ţ»@.@.
0F80	00	10	10	FB	00	00	08	00	00	37	FF	],⊧	FF	E4	A4	1F	
0F90	DF	F7	ЗF	FF	FF	FF	FF	E4	1F	FF	FF	00	00	00	00	FF	β÷?````ä <us>```</us>
0FA0	00	00	FF	00	00	FF	00	00	02	00	00	00	00	02	00	00	
0FB0	00	00	BF	8B	00	00	00	DF	F7	00	00	00	EC	FA	00	00	ż<β÷ěú
0FC0	40	00	00	F9	F3	00	00	00	00	02	00	FF	00	00	FF	FD	@ůó <stx>.``ý</stx>
0FD0	3C	1F	1F	6C	81	FF	FF	00	07	87	00	00	00	00	00	00	< <us> <us> 1 ``. <bell> `</bell></us></us>
0FE0	00	EB	00	00	00	00	00	00	74	DD	00	00	00	00	00	00	.ëtÝ
0FF0	C0	FF	01	FB	FF	00	00	00	00	CA	00	20	02	CA	20	00	

Figure 11-2: RAM window

Unlike the Watch Window option, all memory locations are displayed in a table. The content of each RAM location is displayed in the hexadecimal format and may be changed at any time during the operation of the microcontroller. Changed values are directly written in to the microcontroller by pressing Enter key.

In the table cell you can type in value in hexadecimal format. To write typed value into the MCU RAM memory press Enter key on your keyboard.

## 12. CODE Watch window

The CODE Watch window will appear by selecting the View > Debug Windows > CODE Window option. It shows the values currently stored in the MCU internal FLASH memory.

Deedo	ead Code 000000 01FFF7								
Read Code			000000						
01	00	01	02	03	04	05	06	0207	ASCII
0000	00	00	00	00	00	00	00	00	
8000	00	00	00	00	00	00	00	00	
0010	00	00	00	00	00	00	00	00	
0018	00	00	00	00	00	00	00	00	
0020	00	00	00	00	00	00	00	00	
0028	00	00	00	00	00	00	00	00	
0030	00	00	00	00	00	00	00	00	
0038	00	00	00	00	00 0	3 00	00	00	
0040	00	00	00	00	00	00	00	00	
0048	00	00	00	00	00	00	00	00	
0050	00	00	00	00	00	00	00	00	
0058	00	00	00	00	00	00	00	00	

01 Click the **Read Code** button to read content of MCU FLASH memory



**02 Progress bar** monitors code reading process



(02) After code reading is finished you can preview it in the table

Figure 12-1: CODE Watch





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