

# 3A, 50V, 100kHz Step-Down Converter with Programmable Output OVP Threshold

The Future of Analog IC Technology

# **DESCRIPTION**

The MP2497 is a monolithic step-down switch mode converter with a programmable output current limit. It achieves 3A continuous output current over a wide input supply range with excellent load and line regulation. An internal 2~4ms soft start prevents inrush current at turning on. And it is capable of providing output line drop compensation.

MP2497 achieves low EMI signature with well controlled switching edges.

Fault condition protection includes hiccup current limit and short circuit protection, programmable output over voltage protection and thermal shutdown.

The MP2497 requires a minimum number of readily available standard external components. The MP2497 is available in SOIC8 and SOIC8E package.

# **FEATURES**

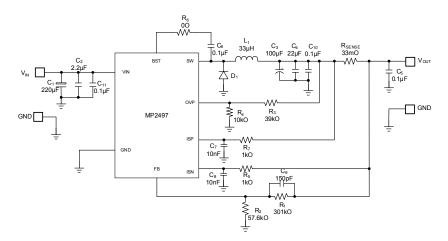
- Wide 4.5V to 50V Operating Input Range
- Programmable Output Over Voltage Protection
- Output Adjustable from 0.8V to 25V
- 0.15Ω Internal Power MOSFET Switch
- Internal 4ms Soft Start
- Stable with Low ESR Output Ceramic Capacitors
- Fixed 100kHz Frequency
- Low EMI Signature
- Thermal Shutdown
- Output Line Drop Compensation
- Hiccup Circuit Limit and Short Circuit Protection
- Available in SOIC8 and SOIC8E Package

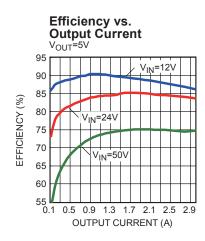
## **APPLICATIONS**

- USB Power Supplies
- Automotive Cigarette Lighter Adapters
- Power Supply for Linear Chargers

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## TYPICAL APPLICATION







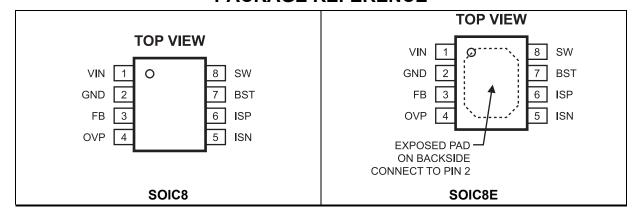
# **ORDERING INFORMATION**

Part Number	Package	Top Marking	Operating Temperature (T <sub>J</sub> )
MP2497DS*	SOIC8	MP2497	-40°C to +125°C
MP2497DN**	SOIC8E	MP2497	-40°C to +125°C

\* For Tape & Reel, add suffix –Z (e.g. MP2497DS–Z); For RoHS, compliant packaging, add suffix –LF (e.g. MP2497DS–LF–Z).

\*\* For Tape & Reel, add suffix –Z (e.g. MP2497DN–Z); For RoHS, compliant packaging, add suffix –LF (e.g. MP2497DN–LF–Z).

## PACKAGE REFERENCE



# ABSOLUTE MAXIMUM RATINGS (1)

Input Voltage V <sub>IN</sub>	60V
V <sub>ISN</sub> , V <sub>ISP</sub>	0V to 25V
$ V_{ISN} V_{ISP} $	0V to 0.4V
V <sub>SW</sub>	
V <sub>BST</sub>	$V_{SW}$ + 6.5V
All Other Pins	0.3V to +6.5V
Junction Temperature	150°C
Lead Temperature	260°C
Storage Temperature	65°C to +150°C
Continuous Power Dissipation	on (T <sub>A</sub> = +25°C) <sup>(2)</sup>
SOIC8	
SOIC8E	2.5W

Recommended Operating Conditions (3)				
Input Voltage V <sub>IN</sub>				
Output Voltage V <sub>OUT</sub> (V <sub>IN</sub> >26.5V).	0.8V to 25V			
Output Voltage V <sub>OUT</sub> (V <sub>IN</sub> <=26.5V)	)			
8.0	V to $(V_{IN}-1.5)V$			
Maximum Junction Temp. (T <sub>J</sub> )	+125°C			

Thermal Resistance <sup>(4)</sup>	$oldsymbol{ heta}_{JA}$	$oldsymbol{ heta}_{JC}$
SOIC8	90	45 °C/W
SOIC8E	50	10 °C/W

#### Notes:

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature  $T_J$  (MAX), the junction-to-ambient thermal resistance  $\theta_{JA}$ , and the ambient temperature  $T_A$ . The maximum allowable continuous power dissipation at any ambient temperature is calculated by  $P_D$  (MAX) = ( $T_J$  (MAX)- $T_A$ )/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- 4) Measured on JESD51-7, 4-layer PCB.



# **ELECTRICAL CHARACTERISTICS**

 $V_{IN}$  = 12V,  $T_A$  = +25°C, unless otherwise noted.

Parameters	Symbol	Condition	Min	Тур	Max	Units
Feedback Voltage	$V_{FB}$	$4.5V \leq V_{IN} \leq 50V$	0.78	0.8	0.82	V
Feedback Bias Current	I <sub>BIAS(FB)</sub>	V <sub>FB</sub> = 0.8V		10		nA
Output Over Voltage Reference	V <sub>OVREF</sub>	T <sub>A</sub> =-40°C to +85°C	1.10	1.23	1.36	V
Input Bias Current (OVP)	I <sub>BIAS(OVP)</sub>	V <sub>OVP</sub> =1.23V		0.1		μΑ
Switch On Resistance	$R_{DS(ON)}$			0.15		Ω
Switch Leakage		$V_{OVP} = 2V$ , $V_{SW} = 0V$		0.1	10	μA
Current Limit		Duty Cycle=10%		5		Α
Oscillator Frequency	f <sub>SW</sub>	V <sub>FB</sub> = 0.6V	80	100	120	kHz
Boot-Strap Voltage	V <sub>BST</sub> - V <sub>SW</sub>			4.5		V
Minimum On Time	t <sub>ON</sub>			100		ns
SW Rising Edge	t <sub>RISE</sub>			50		ns
SW Falling Edge	t <sub>FALL</sub>			50		ns
Under Voltage Lockout Threshold Rising			2.9	3.4	3.9	V
Under Voltage Lockout Threshold Hysteresis				200		mV
Load Line Compensation Gain	$G_{LLC}$	$V_{\text{ISP}}$ - $V_{\text{ISN}}$ =100mV, check $I_{\text{FB}}$	15	20	25	μA/V
Current Sense Voltage	V <sub>ISP</sub> –V <sub>ISN</sub>	V <sub>ISP</sub> , V <sub>ISN</sub> 0.5–15V	90	100	110	mV
Input Bias Current (ISN, ISP)	I <sub>BIAS (ISN,ISP)</sub>	V <sub>ISP</sub> , V <sub>ISN</sub> 0.5–15V	-1	-0.5	+1	μA
Supply Current (Quiescent)		$V_{OVP}$ = 0V, $V_{FB}$ = 1V		1.2	1.5	mA
Thermal Shutdown				150		°C
Thermal Shutdown Hysteresis				30		°C



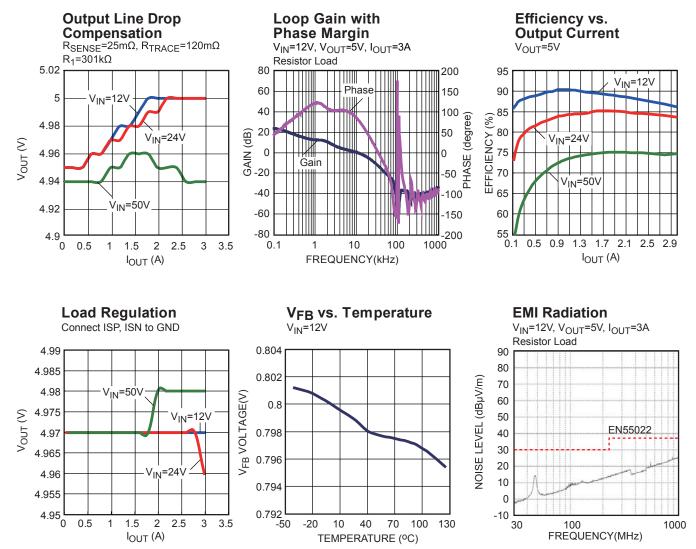
# **PIN FUNCTIONS**

Package Pin #	Name	Description
1	VIN	Supply Voltage. The MP2497 operates from a +4.5V to +50V unregulated input. $C_{\text{IN}}$ is needed to prevent large voltage spikes from appearing at the input. Put $C_{\text{IN}}$ as close to the IC as possible. It is the drain of the internal power device and power supply for the whole chip.
2	GND, Exposed Pad	Ground. This pin is the voltage reference for the regulated output voltage. For this reason care must be taken in its layout. This node should be placed outside of the D1 to $C_{\text{IN}}$ ground path to prevent switching current spikes from inducing voltage noise into the part. Connect exposed pad to GND plane for optimal thermal performance.
3	FB	Feedback. An external resistor divider from the output to GND tapped to the FB pin sets the output voltage. To prevent current limit run away during a short circuit fault condition the frequency-fold-back comparator lowers the oscillator frequency when the FB voltage is below 250mV.
4	OVP	Output Over Voltage Protection. Connect OVP to the center point of an external resistor divider from output to GND. The OVP reference is 1.23V.
5	ISN	Negative Current Sense Input. It is used for load current limiting and output line drop compensation.
6	ISP	Positive Current Sense Input. It is used for load current limiting and output line drop compensation.
7	BST	Bootstrap. This capacitor is needed to drive the power switch's gate above the supply voltage. It is connected between SW and BST pins to form a floating supply across the power switch driver. An on-chip regulator is used to charge up the external boot-strap capacitor. If the on-chip regulator is not strong enough, one optional diode can be connected from IN or OUT to charge the external boot-strap capacitor.
8	SW	Switch Output. It is the source of power device.



## TYPICAL PERFORMANCE CHARACTERISTICS

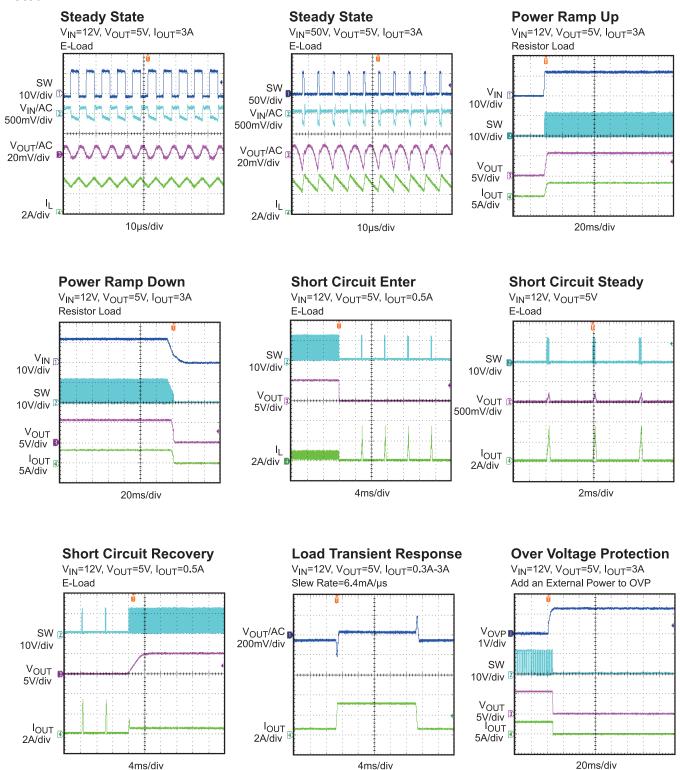
C1=220 $\mu$ F, C2=2.2 $\mu$ F, C3=100 $\mu$ F, C4=22 $\mu$ F, L=33 $\mu$ H, R<sub>SENSE</sub>=33m $\Omega$ , T<sub>A</sub>=25°C, unless otherwise noted.





# TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

C1=220 $\mu$ F, C2=2.2 $\mu$ F, C3=100 $\mu$ F, C4=22 $\mu$ F, L=33 $\mu$ H, R<sub>SENSE</sub>=33m $\Omega$ , T<sub>A</sub>=25°C, unless otherwise noted.





# **BLOCK DIAGRAM**

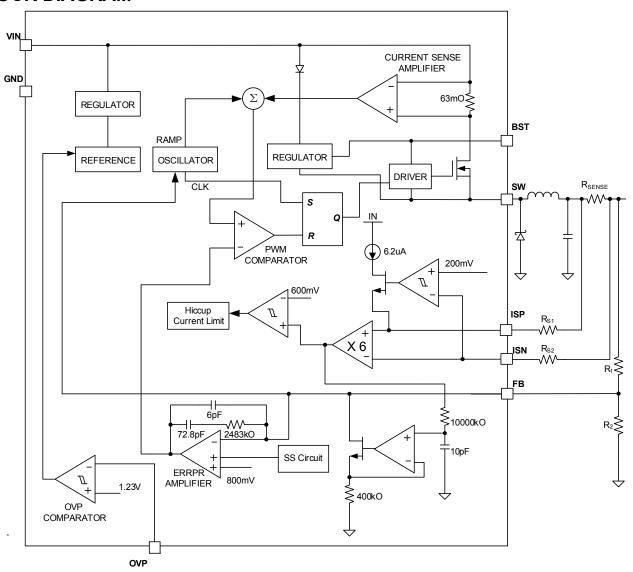


Figure 1—Functional Block Diagram



#### **OPERATION**

#### **Main Control Loop**

The MP2497 is a current mode buck regulator. That is, the EA output voltage is proportional to the peak inductor current.

At the beginning of a cycle SW is off; the Error Amplifier output voltage is higher than the Current Sense Amplifier output. The rising edge of the 100kHz CLK signal sets the RS Flip-Flop. Its output turns on SW thus connecting the SW pin and inductor to the input supply.

The increasing inductor current is sensed and amplified by the Current Sense Amplifier. Ramp Compensation is summed to Current Sense Amplifier output and compared to the Error Amplifier output by the PWM Comparator. When the Current Sense Amplifier plus Slope Compensation signal exceeds the Error Amplifier output voltage, the RS Flip-Flop is reset and the MP2497 reverts to its initial SW off state.

If the Current Sense Amplifier plus Slope Compensation signal does not exceed the COMP voltage, then the falling edge of the CLK resets the Flip-Flop.

The output of the Error Amplifier integrates the voltage difference between the feedback and the reference. The polarity is such that an FB pin voltage is lower than 0.8V increases the EA output voltage. Since the EA output voltage is proportional to the peak inductor current, an increase in its voltage increases current delivered to the output. An external Schottky Diode (D1) carries the inductor current when SW is off.

#### **Hiccup Mode Current Limit Protection**

The output current information for current limit protection is sensed via the ISP and ISN pins. The sense voltage limit threshold is set at 100mV. MP2497 has hiccup over current limit function. Once the  $V_{\text{SENSE}}$  exceeds the 100mV, the current limit loop will turn off high side switch immediately. Meanwhile, internal soft start circuit will be reset after FB is lower than 0.3V, and then the high side switch turns on and MP2497 restarts with a full soft start. This hiccup process is repeated until the fault is removed. And, current limit value can be programmed to be lower by internal current source and external resistors connected to ISN and ISP pins, when output voltage is lower than 200mV. Then, the average short circuit current can be greatly reduced.

## **Output Over Voltage Protection**

The MP2497 has output over voltage protection. The OVP reference 1.23V is on the positive input of the OVP comparator. The output voltage is fed to OVP pin through an external resistor divider. If the voltage on OVP pin is higher than 1.23V, the high side switch will be turned off immediately and part will be lathed off after a timer delay.

# **Output Line Drop Compensation**

If the trace from MP2497 output terminator to the load is too long, there will be a voltage drop on the long trace which is variable with load current. MP2497 is capable of compensating the output voltage drop to keep a constant voltage at load, whatever the load current is. The output voltage is compensated by feeding a current to the top feedback resistance R1. The load line compensation gain can be programmed according to  $R_{\text{SENSE}}$  and  $R_{\text{TRACE}}$  (Figure 2) values.

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#### APPLICATION INFORMATION

# **Setting the Output Line Drop Compensation**

Figure 2 shows the block of output line drop compensation.

If the trace to the load is long, there is a voltage drop between  $V_{\text{OUT}}$  and  $V_{\text{LOAD}}$ .  $V_{\text{OUT}}$  (voltage at output terminator) is not equal to  $V_{\text{LOAD}}$ (voltage at load). The voltage drop can be described by:

$$V_{DROP} = I_{OUT} \times R_{TRACE}$$
 (1)

Where, the  $R_{TRACE}$  is the resistance of the output line. (  $R_{TRACE} = R_{TRACE1} + R_{TRACE2}$  )

Then, the V<sub>LOAD</sub> is:

$$V_{LOAD} = V_{OUT} - I_{OUT} \times R_{TRACE}$$
 (2)

To keep an accurate and constant load voltage, the output line drop compensation is necessary.

MP2497 offers a compensation method, by adjusting the FB voltage slightly according to the load current.

The relation between  $V_{\text{OUT}}$  and  $V_{\text{FB}}$  can be described by:

$$\frac{V_{\text{OUT}} - V_{\text{FB}}}{R1} = \frac{V_{\text{FB}}}{R2} + \frac{I_{\text{OUT}} \times R_{\text{SENSE}} \times 6}{400 \text{k}\Omega} \quad (3)$$

Where,  $V_{FB}$  is 0.8V.

Then, the  $V_{OUT}$  can be calculated by:

$$V_{\text{OUT}} = (1 + \frac{\text{R1}}{\text{R2}}) \times 0.8\text{V} + \frac{I_{\text{OUT}} \times R_{\text{SENSE}} \times 6 \times \text{R1}}{400\text{k}\Omega} \tag{4}$$

The  $V_{LOAD}$  is determined by:

$$V_{LOAD} = (1 + \frac{R1}{R2}) \times 0.8V + \frac{I_{OUT} \times R_{SENSE} \times 6 \times R1}{400 k\Omega}$$
 (5)  
$$-I_{OUT} \times R_{TRACE}$$

To maintain the  $V_{LOAD}$  is not variable with load current. The equation below should be satisfied:

$$\frac{I_{\text{OUT}} \times R_{\text{SENSE}} \times 6 \times R1}{400 \text{k}\Omega} = I_{\text{OUT}} \times R_{\text{TRACE}} \qquad (6)$$

Simplify the formula above, we can get:

$$R1 = \frac{R_{TRACE} \times 400k\Omega}{6 \times R_{SENSE}}$$
 (7)

In the formula above,  $R_{\text{SENSE}}$  is known. And  $R_{\text{TRACE}}$  can be tested or evaluated. So, we can select a proper top feedback resistor R1 according to the  $R_{\text{TRACE}}$  and  $R_{\text{SENSE}}$  to compensate the output line voltage drop.

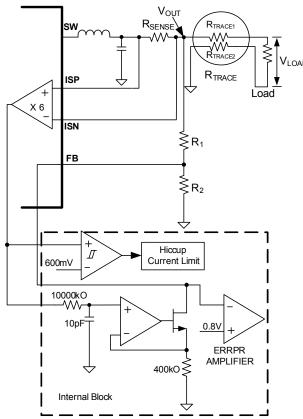


Figure 2—Output Line Drop Compensation

#### **Setting the Output Voltage**

The external resistor divider is used to set the output voltage (see the typical application circuit on the front page). The feedback resistor R1 is decided by output line drop compensation. R2 is then given by:

$$R2 = \frac{R1}{\frac{V_{OUT}}{0.8V} - 1}$$
 (8)



#### Selecting the Inductor

A  $10\mu H$  to  $47\mu H$  inductor with a DC current rating of at least 25% percent higher than the maximum load current is recommended for most applications. For highest efficiency, the inductor DC resistance should be less than  $200m\Omega$ . For most designs, the inductance value can be derived from the following equation.

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_{L} \times f_{OSC}}$$
(9)

Where  $\Delta I_L$  is the inductor ripple current.

Choose inductor current ripple to be approximately 30% of the maximum load current, 3A. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_{L}}{2}$$
 (10)

Under light load conditions below 100mA, larger inductance is recommended for improving efficiency.

#### **Selecting the Input Capacitor**

The input capacitor reduces the surge current drawn from the input and also the switching noise from the device. The input capacitor impedance at the switching frequency should be less than the input source impedance to prevent high frequency switching current from passing to the input. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, a 4.7µF capacitor is sufficient.

#### **Selecting the Output Capacitor**

The output capacitor keeps output voltage small and ensures regulation loop stability. The output capacitor impedance should be low at the switching frequency. Ceramic capacitors with X5R or X7R dielectrics are recommended.

#### **Setting the Output OVP Threshold**

The output OVP threshold is set by connecting an external resistor divider (R3, R4 see the typical application circuit on the front page) at OVP pin. Choose R3 to be  $39k\Omega$  for lower power dissipation. Then, R4 is given by:

$$R4 = \frac{R3}{\frac{V_{OVP}}{V_{OVPEF}} - 1} (k\Omega)$$
 (11)

Where,  $V_{\text{OVREF}}$  is the OVP reference, 1.23V.  $V_{\text{OVP}}$  is over voltage protection threshold.

## **Setting the Current Limit**

The hiccup current limit can be set by the DC resistance (DCR) of the inductor, as shown in Figure 3a.

For more accurate sensing, use a more accurate sense resistor.

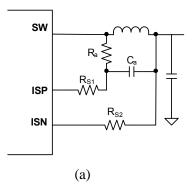
In Figure 3a, the output current limit is set as:

$$I_{OUT\_L} = \frac{100mV}{DCR}$$
 (12)

Where, DCR is the DC resistance of the inductor winding. R<sub>a</sub> and C<sub>a</sub> is a low pass filter.

In Figure 3b, the output current limit is set as:

$$I_{OUT\_L} = \frac{100mV}{R_{SENSE}}$$
 (13)



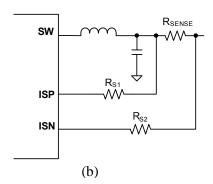


Figure 3—Current Sensing Methods



# **Programming the Short Circuit Current Limit**

The hiccup current limit at output short condition can be programmed to be lower by external resisters ( $R_{S1}$ ,  $R_{S2}$ ,  $R_{S1}$ = $R_{S2}$ ), as shown in figure 4.

When output voltage is lower than 200mV, the current limit is described by:

$$I_{OUT~SL} \times R_{SENSE} + 6.2\mu A \times R_{S1} = 100 \text{mV} \qquad (14)$$

The current limit at output short condition is:

$$I_{OUT\_SL} = \frac{100mV - 6.2\mu A \times R_{S1}}{R_{SENSE}}$$
 (15)

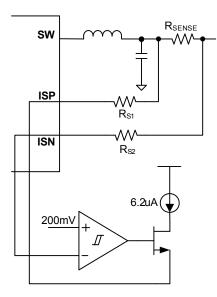


Figure 4—Short Circuit Current Limit

# **PC Board Layout**

The high frequency path (IN, SW and GND) should be placed very close to the device with short, direct and wide traces. The input capacitor needs to be as close as possible to the IN and GND pins. The external feedback resistors should be placed next to the FB pin. Keep the switching node SW short and away from the feedback network.

#### **External Bootstrap Diode**

It is recommended that an external bootstrap diode be added when the system has a 5V fixed input or the power supply generates a 5V output. This helps improve the efficiency of the regulator. The bootstrap diode can be a low cost one such as IN4148 or BAT54.

This diode is also recommended for high duty cycle operation (when  $\frac{V_{\text{OUT}}}{V_{\text{IN}}}$  >65%) and high output voltage ( $V_{\text{OUT}}$ >12V) applications.

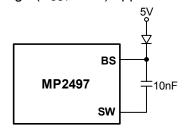


Figure 5—External Bootstrap Diode

#### **Design Example**

Below is a design example following the application guidelines for the specifications:

$V_{IN}$	8 to 50V
$V_{OUT}$	5V
$V_{OVP}$	6V
F <sub>SW</sub>	100kHz
I <sub>OUT-L</sub>	3A

The detailed application schematic is shown in Figure 6. The typical performance and circuit waveforms have been shown in the Typical Performance Characteristics section. For more possible applications of this device, please refer to related Evaluation Board Data Sheets.



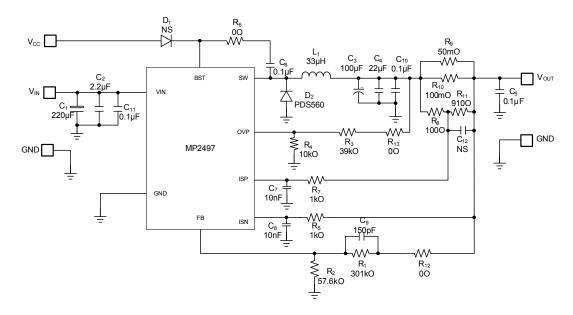
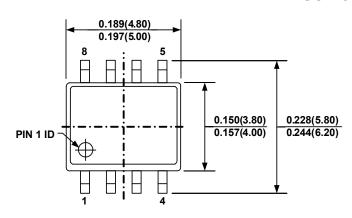


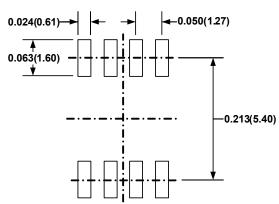
Figure 6—Detailed Application Schematic



## PACKAGE INFORMATION

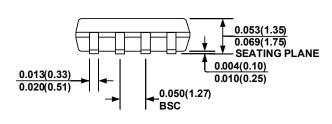
#### SOIC8



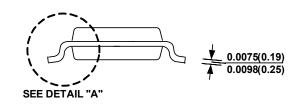


**TOP VIEW** 

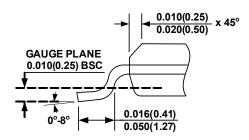
**RECOMMENDED LAND PATTERN** 



**FRONT VIEW** 



**SIDE VIEW** 



**DETAIL "A"** 

## **NOTE:**

- 1) CONTROL DIMENSION IS IN INCHES DIMENSION IN BRACKET IS IN MILLIMETERS
- 2) PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH PROTRUSIONS OR GATE BURRS
- 3) PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
- 4) LEAD COPLANARITY(BOTTOM OF LEADS AFTER FORMING SHALL BE0.004" INCHES MAX.
- 5) DRAWING CONFORMS TO JEDEC MS012, VARIATION AA
- 6) DRAWING IS NOT TO SCALE