

## **MPQ18021HN-A** 100V, 2.5A, High-Frequency, Half-Bridge Gate Driver AEC-Q100 Qualified

## DESCRIPTION

The MPQ18021HN-A is a high-frequency, 100V, half-bridge, N-channel power MOSFET driver. Its low-side and high-side driver channels are controlled independently and matched with a time delay of less than 5ns. Under-voltage lockout (UVLO) on both the high-side and low-side supplies force their outputs low in the case of an insufficient supply. The integrated bootstrap diode reduces the external component count.

The MPQ18021HN-A is available in a costeffective SOIC-8E package.

## FEATURES

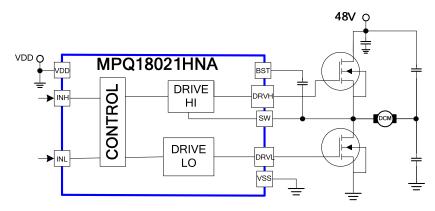
- Guaranteed Industrial / Automotive Temperature Range Limits
- Drives N-Channel MOSFET Half-Bridge
- 100V V<sub>BST</sub> Voltage Range
- On-Chip Bootstrap Diode
- Typical 16ns Propagation Delay Time
- Less than 5ns Gate Drive Matching
- Drives 1nf Load with 12ns/9ns Rise/Fall Times with 12V VDD
- TTL-Compatible Input
- Less than 160µA Quiescent Current
- UVLO for both High-Side and Low-Side
- Available in a SOIC-8E Package
- Available in AEC-Q100 Qualified Grade 1

#### APPLICATIONS

- Car DC/DC Power Systems
- Half Bridge Motor Drivers

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## TYPICAL APPLICATION





## **ORDERING INFORMATION**

Part Number	Package	Top Marking
MPQ18021HN-A-AEC1	SOIC-8E	See Below

\* For Tape & Reel, add suffix –Z (e.g. MPQ18021HN-A-AEC1–Z).

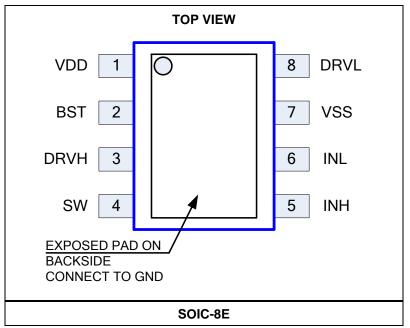
## **TOP MARKING**

MP18021A LLLLLLL

MPSYWW

MP18021A: Part number LLLLLLL: Lot number MPS: MPS prefix Y: Year code WW: Week code

## PACKAGE REFERENCE





## **PIN FUNCTIONS**

Pin #	Name	Description		
1	VDD	<b>Supply input.</b> VDD supplies power to all of the internal circuitries. Place a decoupling capacitor to ground close to VDD to ensure a stable and clean supply.		
2	BST	<b>Bootstrap.</b> BST is the positive power supply for the internal floating high-side MOSFET driver. Connect a bypass capacitor between BST and SW.		
3	DRVH	Floating high-side driver output.		
4	SW	Switching node.		
5	INH	Control signal input for the floating driver.		
6	INL	Control signal input for the low-side driver.		
7	VSS	<b>Chin ground</b> Connect the expected and to VSS for proper thermal operation		
Exposed Pad		<b>Chip ground.</b> Connect the exposed pad to VSS for proper thermal operation.		
8	DRVL	Low-side driver output.		

#### ABSOLUTE MAXIMUM RATINGS (1)

Supply voltage (V <sub>DD</sub> )	0.3V to +18V
SW voltage (V <sub>HS</sub> )	5.0V to +110V
BST voltage (V <sub>HB</sub> )	
BST to SW	
DRVH to SW0.3V	/ to (BST - SW) + 0.3V
DRVL to VSS	-0.3V to (VDD + 0.3V)
All other pins	0.3V to (V <sub>DD</sub> + 0.3V)
CDM rating (AEC-Q100-0	
All pins	Class C6
HBM rating (AEC-Q100-0	02)
BST, DRVH	Class H1B
SW	Class H1C
Other pins	Class H2
Continuous power dissipa	tion (T <sub>A</sub> = 25°C) <sup>(2)</sup>
Junction temperature	
Lead temperature	
Storage temperature	
	(3)

#### Recommended Operating Conditions <sup>(3)</sup>

Supply voltage (V <sub>DD</sub> )	
SW voltage (V <sub>HS</sub> )	1.0V to +100V - VDD
SW slew rate	<50V/ns
Operation junction temp	. (T <sub>J</sub> )40°C to +125°C

#### Thermal Resistance <sup>(4)</sup> θյΑ $\theta_{JC}$ SOIC-8E ...... 50 ..... 12 ...°C/W

#### NOTES:

- Exceeding these ratings may damage the device. 1)
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub>(MAX), the junction-toambient thermal resistance  $\theta_{JA}$ , and the ambient temperature  $T_A$ . The maximum allowable continuous power dissipation at any ambient temperature is calculated by  $P_D(MAX)=(T_J(MAX) T_A$ )/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation produces an excessive die temperature, causing the regulator to go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- 3) The device is not guaranteed to function outside of its operating conditions.
- 4) Measured on JESD51-7, 4-layer PCB.

# MPQ18021HN-

## **ELECTRICAL CHARACTERISTICS**

 $V_{DD} = V_{BST} - V_{SW} = 12V$ ,  $V_{SS} = V_{SW} = 0V$ , no load at DRVH and DRVL,  $T_J = -40^{\circ}C$  to  $+125^{\circ}C$ , typical values tested at  $T_J = +25^{\circ}C$ , unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Supply Currents						
VDD quiescent current	IDDQ	INH = INL= 0		120	160	μA
VDD operating current	Iddo	f <sub>sw</sub> = 500kHz		2.8	3.5	mA
Floating driver quiescent current	IBSTQ	INH = INL = 0		70	100	μA
Floating driver operating current	I <sub>BSTO</sub>	f <sub>sw</sub> = 500kHz		2.1	3	mA
Leakage current	I <sub>LK</sub>	HB = SW = 100V		0.05	2.5	μA
Inputs			•			
INL/INH high				2.2	2.6	V
INL/INH low			1	1.5		V
INL/INH internal pull-down resistance	RIN			185		kΩ
Under-Voltage Protection (UVF	')	•	•	•		•
VDD rising threshold	V <sub>DDR</sub>		7.4	8.1	8.9	V
VDD hysteresis	Vddh			0.5		V
(BST-SW) rising threshold	VBSTR		6.5	7.1	7.7	V
(BST-SW) hysteresis	VBSTH			0.55		V
Bootstrap Diode		•	·	•		•
Bootstrap diode VF @ 100µA	V <sub>F1</sub>			0.5		V
Bootstrap diode VF @ 100mA	V <sub>F2</sub>			1		V
Bootstrap diode dynamic R	RD	@ 100mA		2.5		Ω
Low Side Gate Driver						
Low-level output voltage	Voll	I <sub>0</sub> = 100mA		0.15	0.32	V
High-level output voltage to rail	VOHL	I <sub>0</sub> = -100mA		0.45	1	V
Peak pull-up current <sup>(5)</sup>		$V_{LO} = 0V, V_{DD} = 12V$		1.5		Α
	IOHL	$V_{LO} = 0V, V_{DD} = 16V$		2.5		Α
Peak pull-down current (5)	Ioll	$V_{LO} = V_{DD} = 12V$		2.5		Α
Feak puil-down current (*)		$V_{LO} = V_{DD} = 16V$		3.5		Α
Floating Gate Driver						
Low-level output voltage	Volh	I <sub>O</sub> = 100mA		0.15	0.32	V
High-level output voltage to rail	Vонн	I <sub>0</sub> = -100mA		0.45	1	V
Peak pull-up current (5)	Іонн	$V_{HO} = 0V, V_{DD} = 12V$		1.5		Α
	юпп	V <sub>HO</sub> = 0V, V <sub>DD</sub> = 16V		2.5		A
Peak pull-down current (5)	IOLH	$V_{HO} = V_{DD} = 12V$		2.5		A
•	IOLH	V <sub>HO</sub> = V <sub>DD</sub> = 16V		3.5		A
Switching spec – low-side gate driver						
Turn-off propagation delay INL falling to DRVL falling	TDLFF			16		ns
Turn-on propagation delay INL rising to DRVL rising	T <sub>DLRR</sub>			16		
DRVL rise time		C <sub>L</sub> = 1nF		12		ns
DRVL fall time		C <sub>L</sub> = 1nF		9		ns



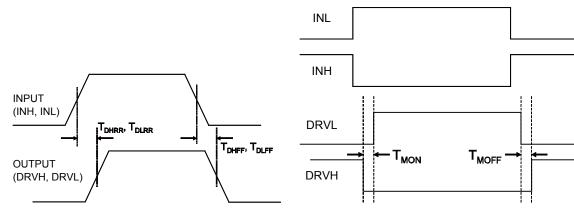
**ELECTRICAL CHARACTERISTICS** *(continued)*  $V_{DD} = V_{BST} - V_{SW} = 12V$ ,  $V_{SS} = V_{SW} = 0V$ , no load at DRVH and DRVL,  $T_J = -40^{\circ}C$  to  $+125^{\circ}C$ , typical values tested at  $T_J = +25^{\circ}C$ , unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Switching Spec – Floating Gate	e Driver					
Turn-off propagation delay INL falling to DRVH falling	TDHFF			16		ns
Turn-on propagation delay INL rising to DRVH rising	T <sub>DHRR</sub>			16		ns
DRVH rise time		C∟ = 1nF		12		ns
DRVH fall time		C∟ = 1nF		9		ns
Switching Spec – Matching						
Floating driver turn-off to low- side drive turn-on <sup>(5)</sup>	T <sub>MON</sub>			1	5	ns
Low-side driver turn-off to floating driver turn-on <sup>(5)</sup>	TMOFF			1	5	ns
Minimum input pulse width that changes the output	T <sub>PW</sub>				50 <sup>(5)</sup>	ns
Bootstrap diode turn-on or turn- off time	T <sub>BS</sub>			10 (5)		ns
Thermal shutdown (5)				170		°C
Thermal shutdown hysteresis (5)				25		°C

NOTE:

5) Guaranteed by design.

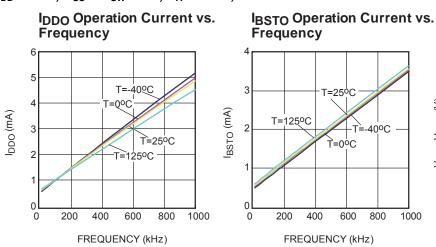
## **TIMING DIAGRAM**

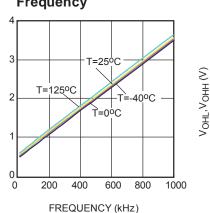


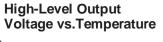
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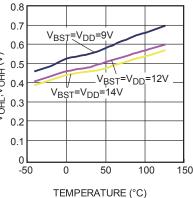
## **TYPICAL PERFORMANCE CHARACTERISTICS**

 $V_{DD}$  = 12V,  $V_{SS}$  =  $V_{SW}$  = 0V,  $T_A$  = 25°C, unless otherwise noted.

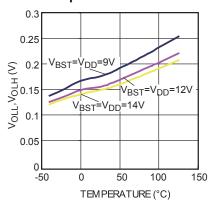


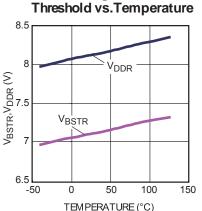






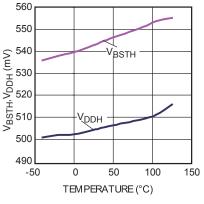
Low-Level Output Voltage vs. **Temperature** 

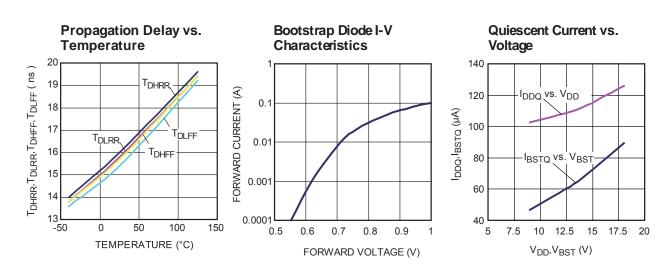




**Under-Voltage Lockout** 

**Under-Voltage Lockout** Hysteresis vs. Temperature





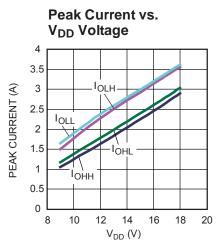
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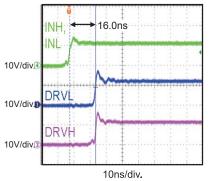


## **TYPICAL PERFORMANCE CHARACTERISTICS** (continued)

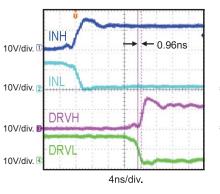
 $V_{DD}$  = 12V,  $V_{SS}$  =  $V_{SW}$  = 0V,  $T_A$  = 25°C, unless otherwise noted.



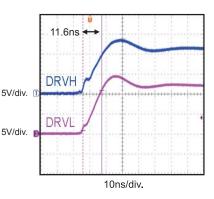
#### **Turn-On Propagation Delay**



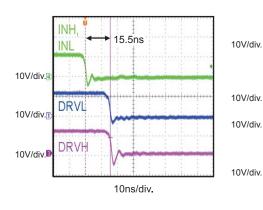
#### Gate Drive Matching TMOFF



#### Drive Rise Time (1nF Load)

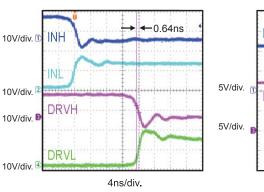


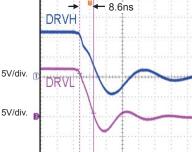
**Turn-Off Propagation Delay** 



#### Gate Drive Matching TMON

## Drive Fall Time (1nF Load)





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## **BLOCK DIAGRAM**

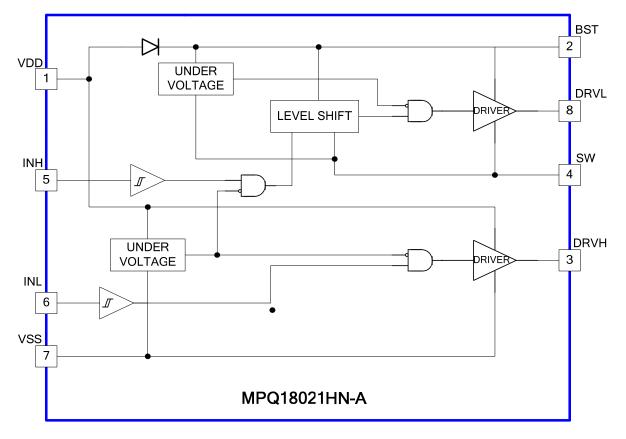
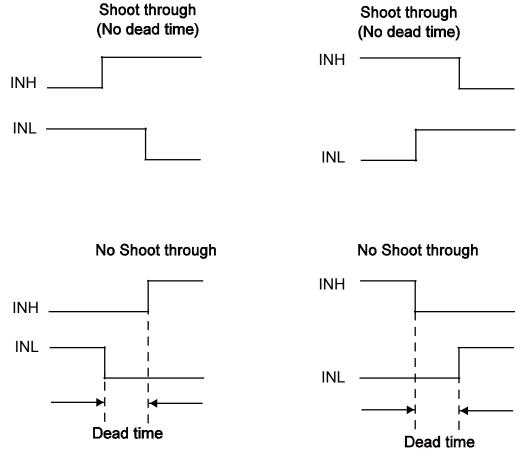


Figure 1: Functional Block Diagram



## **APPLICATION**

The input signals of INH and INL can be controlled independently. If both INH and INL are controlling the high-side MOSFET (HS-FET) and low-side MOSFET (LS-FET) of the same bridge, shoot through can be prevented by setting a sufficient dead time between INH and INL low, and vice versa (see Figure 2). Dead time is defined as the time interval between INH low and INL low.





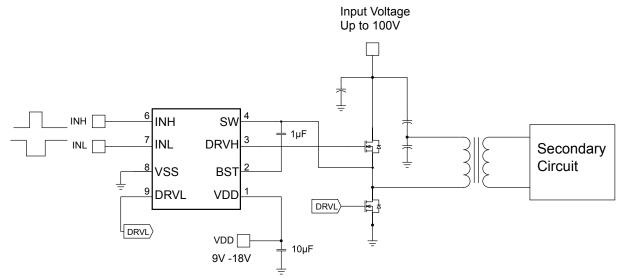
# MPQ18021HN-A – 100V, 2.5A, HIGH-FREQUENCY HALF-BRIDGE GATE DRIVER, AEC-Q100

## **REFERENCE DESIGN CIRCUITS**

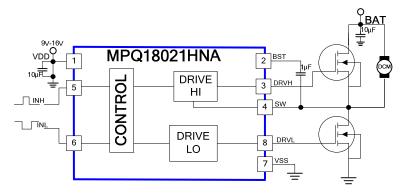
#### Half-Bridge Converter

In the half-bridge converter topology, the MOSFETs are driven alternately with some dead time. Therefore, INH and INL are driven

with alternating signals from the pulse-width modulation (PWM) controller. The input voltage can rise as high as 100V in this application (see Figure 3 through Figure 5).



#### Figure 3: Half-Bridge Converter



#### Figure 4: Half-Bridge for Unidirectional Motor

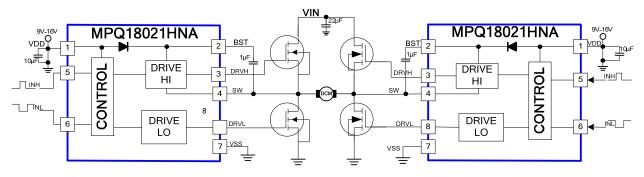


Figure 5: 2x MPQ18024 for One Bidirectional DC Motor