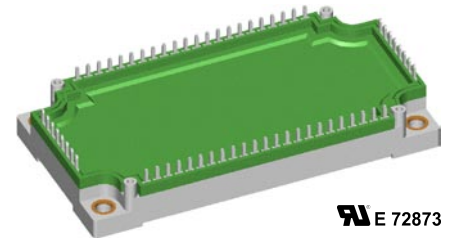
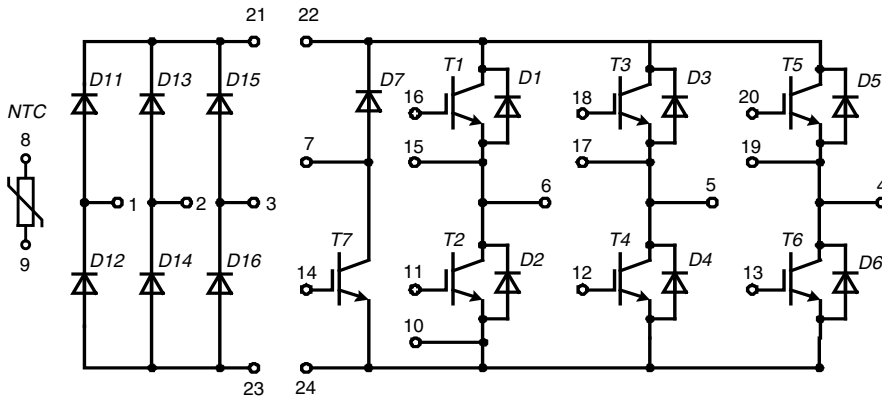


Converter - Brake - Inverter Module (CBI3) with Trench IGBT technology



E 72873

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 1200 \text{ V}$	$V_{CES} = 1200 \text{ V}$
$I_{FAVM} = 50 \text{ A}$	$I_{C25} = 55 \text{ A}$	$I_{C25} = 80 \text{ A}$
$I_{FSM} = 850 \text{ A}$	$V_{CE(sat)} = 1.7 \text{ V}$	$V_{CE(sat)} = 1.7 \text{ V}$

Input Rectifier Bridge D11 - D16			
Symbol	Conditions	Maximum Ratings	
V_{RRM}		1600	V
I_{FAV}	$T_C = 80^\circ\text{C}$; sine 180°	50	A
I_{DAVM}	$T_C = 80^\circ\text{C}$; rectangular; $d = 1/3$; bridge	140	A
I_{FSM}	$T_C = 25^\circ\text{C}$; $t = 10 \text{ ms}$; sine 50 Hz	850	A
P_{tot}	$T_C = 25^\circ\text{C}$	125	W

Symbol	Conditions	Characteristic Values			
		$(T_{VJ} = 25^\circ\text{C}, \text{ unless otherwise specified})$			
		min.	typ.	max.	
V_F	$I_F = 50 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$		1.15	1.3	V
		$T_{VJ} = 125^\circ\text{C}$		1.05	
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$		0.8	0.05	mA
	$T_{VJ} = 125^\circ\text{C}$				mA
R_{thJC}	(per diode)			1.0	K/W

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- IGBT technology with low saturation voltage, low switching losses and tail current, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6			
Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$ to 150°C	1200	V
V_{GES}	Continuous	± 20	V
I_{C25}	$T_C = 25^{\circ}\text{C}$	80	A
I_{C80}	$T_C = 80^{\circ}\text{C}$	50	A
I_{CM}	$T_C = 80^{\circ}\text{C}; t_p = 1 \text{ ms}$	100	A
P_{tot}	$T_C = 25^{\circ}\text{C}$	270	W

Symbol	Conditions	Characteristic Values			
		(T _{VJ} = 25°C, unless otherwise specified)			
		min.	typ.	max.	
$V_{CE(sat)}$	$I_C = 50 \text{ A}; V_{GE} = 15 \text{ V}$				$T_{VJ} = 25^{\circ}\text{C}$
					$T_{VJ} = 125^{\circ}\text{C}$
$V_{GE(th)}$	$I_C = 2 \text{ mA}; V_{GE} = V_{CE}$	5	5.8	6.5	V
I_{CES}	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}$				$T_{VJ} = 25^{\circ}\text{C}$
					$T_{VJ} = 125^{\circ}\text{C}$
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$			400	nA
C_{ies}	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$		3.5		nF
Q_{Gon}	$V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 50 \text{ A}$		470		nC
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 50 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 18 \Omega$				90
					50
					520
					90
					5
					6.5
RBSOA	$I_C = I_{CM}; V_{GE} = 15 \text{ V}$ $R_G = 18 \Omega; T_{VJ} = 125^{\circ}\text{C}$	$V_{CEK} \leq V_{CES} - L_S di/dt$			V
t_{SC} (SCSOA)	$V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 18 \Omega$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^{\circ}\text{C}$		200		A
R_{thJC}				0.46	K/W

Output Inverter D1 - D6					
Symbol	Conditions	Maximum Ratings			
I_{F25}	$T_C = 25^{\circ}\text{C}$	100	A		
I_{F80}	$T_C = 80^{\circ}\text{C}$	50	A		
Symbol	Conditions	Characteristic Values			
		min.	typ.	max.	
V_F	$I_F = 50 \text{ A};$				$T_{VJ} = 25^{\circ}\text{C}$
					$T_{VJ} = 125^{\circ}\text{C}$
I_{RM} Q_{rr} t_{rr} E_{rec}	$I_F = 60 \text{ A}; di_F/dt = -1200 \text{ A}/\mu\text{s};$ $T_{VJ} = 125^{\circ}\text{C}; V_R = 600 \text{ V}; V_{GE} = 0 \text{ V}$				90
					10
					160
					4
R_{thJC}	(per diode)			0.65	K/W

Brake Chopper T7			
Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C to } 150^{\circ}\text{C}$	1200	V
V_{GES}	Continuous	± 20	V
I_{C25}	$T_C = 25^{\circ}\text{C}$	55	A
I_{C80}	$T_C = 80^{\circ}\text{C}$	35	A
I_{CM}	$T_C = 80^{\circ}\text{C}; t_p = 1 \text{ ms}$	70	A
P_{tot}	$T_C = 25^{\circ}\text{C}$	200	W

Symbol	Conditions	Characteristic Values					
		$(T_{VJ} = 25^{\circ}\text{C}, \text{ unless otherwise specified})$					
		min.	typ.	max.			
$V_{CE(sat)}$	$I_C = 35 \text{ A}; V_{GE} = 15 \text{ V}$			$T_{VJ} = 25^{\circ}\text{C}$	1.7	2.15	V
				$T_{VJ} = 125^{\circ}\text{C}$	2.0		V
$V_{GE(th)}$	$I_C = 1.5 \text{ mA}; V_{GE} = V_{CE}$	5	5.8	6.5	V		
I_{CES}	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}$			0.25	mA		
			0.3		mA		
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$			400	nA		
C_{ies}	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$		2.5		nF		
Q_{Gon}	$V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 35 \text{ A}$		330		nC		
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 35 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 27 \Omega$		90		ns		
t_r			50		ns		
$t_{d(off)}$			520		ns		
t_f			90		ns		
E_{off}			4.8		mJ		
RBSOA	$I_C = I_{CM}; V_{GE} = 15 \text{ V}$ $R_G = 27 \Omega; T_{VJ} = 125^{\circ}\text{C}$	$V_{CEK} \leq V_{CES} - L_S di/dt$			V		
t_{SC} (SCSOA)	$V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 27 \Omega$ $t_p \leq 10 \mu\text{s}; \text{ non-repetitive}; T_{VJ} = 125^{\circ}\text{C}$		140		A		
R_{thJC}				0.62	K/W		

Brake Chopper D7			
Symbol	Conditions	Maximum Ratings	
V_{RRM}	$T_{VJ} = 25^{\circ}\text{C to } 150^{\circ}\text{C}$	1200	V
I_{F25}	$T_C = 25^{\circ}\text{C}$	48	A
I_{F80}	$T_C = 80^{\circ}\text{C}$	30	A

Symbol	Conditions	Characteristic Values					
		min.	typ.	max.			
V_F	$I_F = 35 \text{ A};$			$T_{VJ} = 25^{\circ}\text{C}$	2.5	3.3	V
				$T_{VJ} = 125^{\circ}\text{C}$	2.0		V
I_R	$V_R = V_{RRM};$			$T_{VJ} = 25^{\circ}\text{C}$		0.25	mA
				$T_{VJ} = 125^{\circ}\text{C}$	0.5		mA
R_{thJC}	(per diode)					1.2	K/W

Temperature Sensor NTC

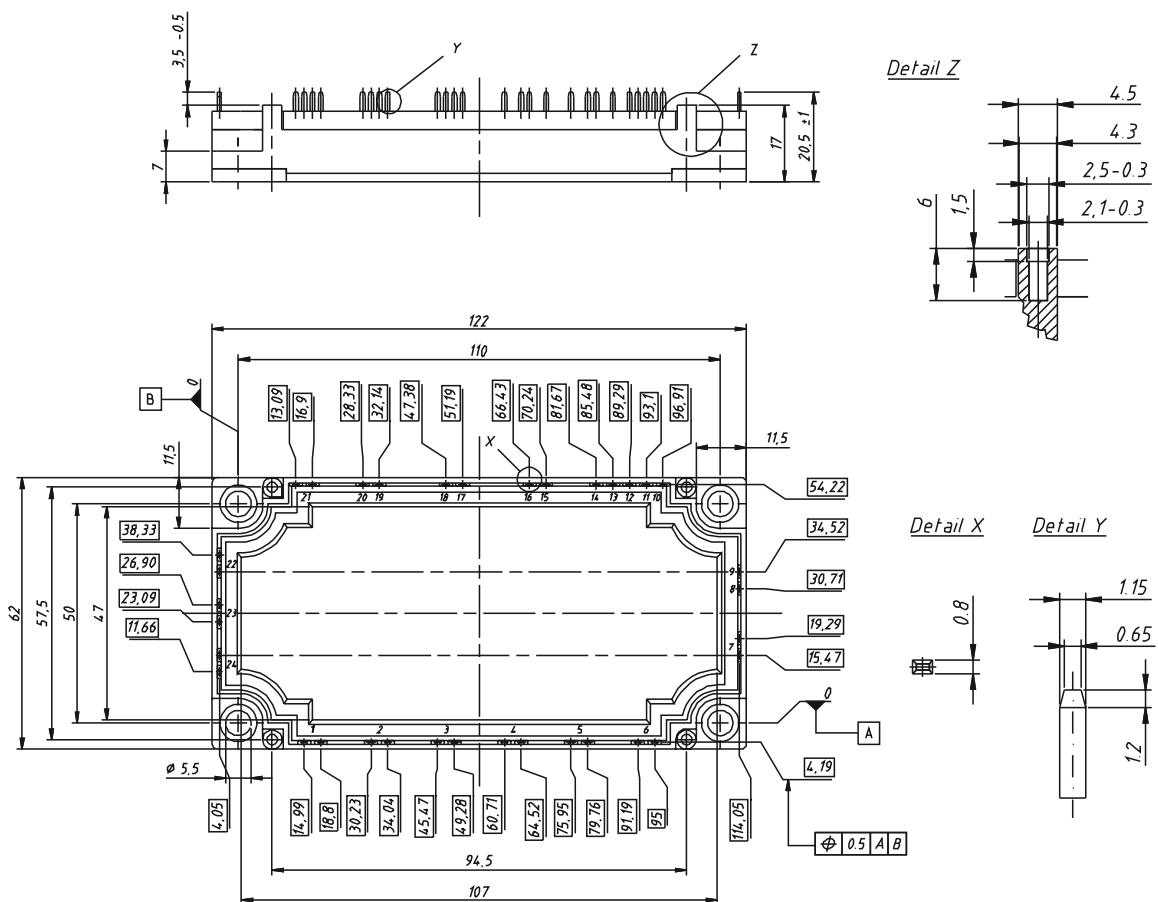
Symbol	Conditions	Characteristic Values			
		min.	typ.	max.	
R_{25}	$T = 25^{\circ}\text{C}$	4.75	5.0	5.25	k Ω
$B_{25/50}$			3375		K

Module

Symbol	Conditions	Maximum Ratings	
T_{VJ}	operating	-40...+125	$^{\circ}\text{C}$
T_{JM}		+150	$^{\circ}\text{C}$
T_{stg}		-40...+125	$^{\circ}\text{C}$
V_{ISO}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
M_d	Mounting torque (M5)	3 - 6	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{\text{therm-chip}}$	Resistance terminal to chip		5	m Ω
d_S	Creepage distance on surface	6		mm
d_A	Strike distance in air	6		mm
R_{thCH}	with heatsink compound		0.01	K/W
Weight			300	g

Dimensions in mm (1 mm = 0.0394")



IXYS reserves the right to change limits, test conditions and dimensions.

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Input Rectifier Bridge D11 - D16

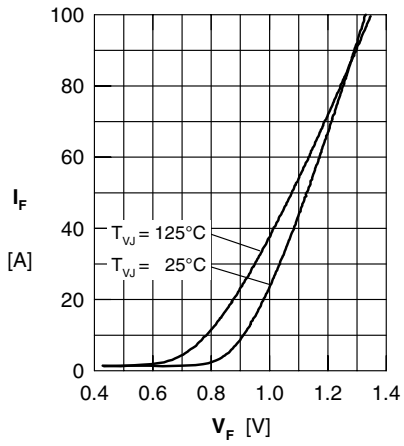


Fig. 1 Typ. forward current vs. voltage drop per diode

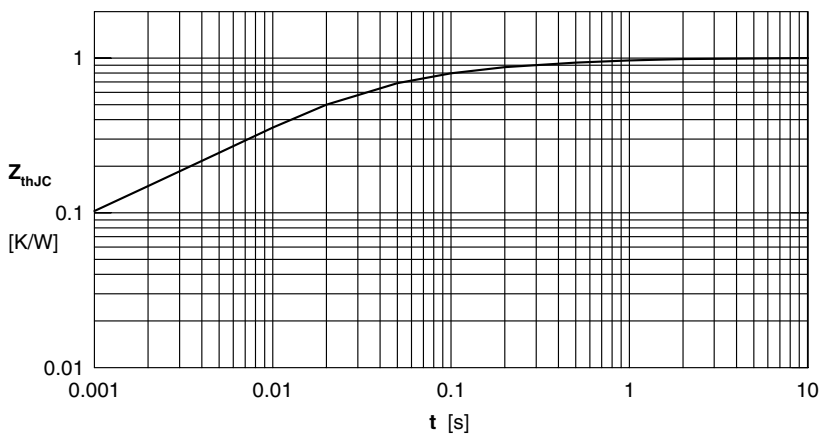


Fig. 2 Transient thermal impedance junction to case

Output Inverter T1 - T6 / D1 - D6

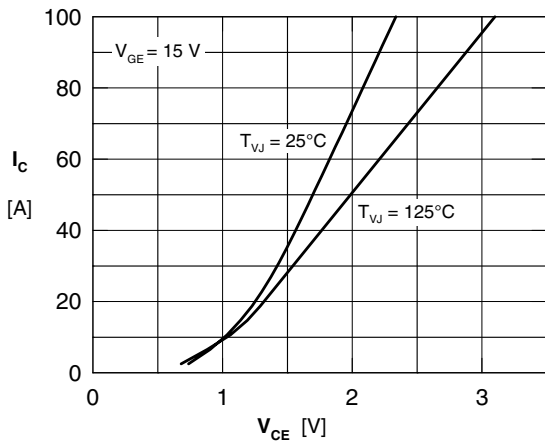


Fig. 3 Typical output characteristic

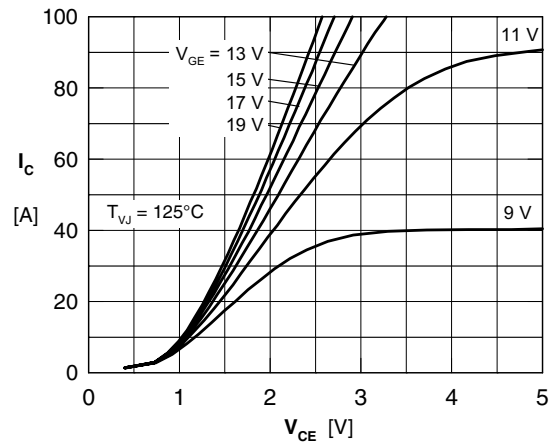


Fig. 4 Typical output characteristic

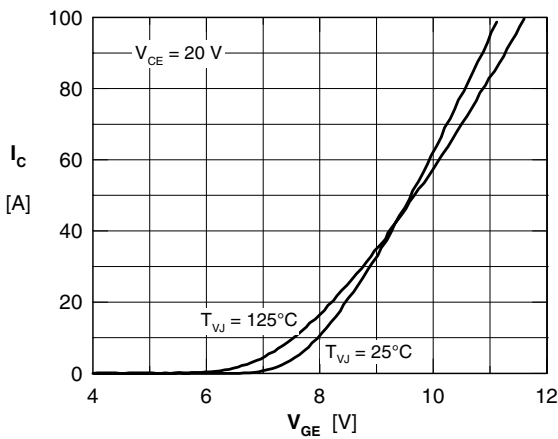


Fig. 5 Typical transfer characteristic

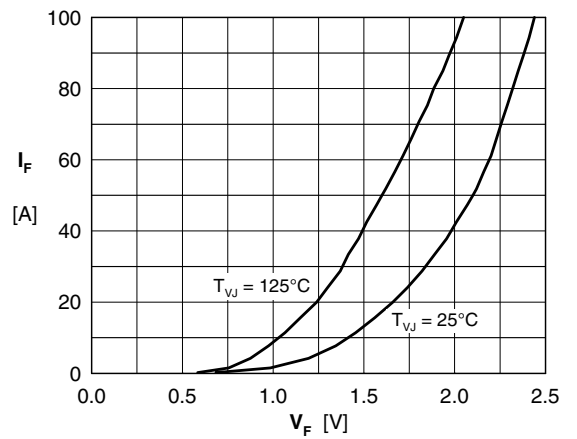


Fig. 6 Typical forward characteristic of free wheeling diode

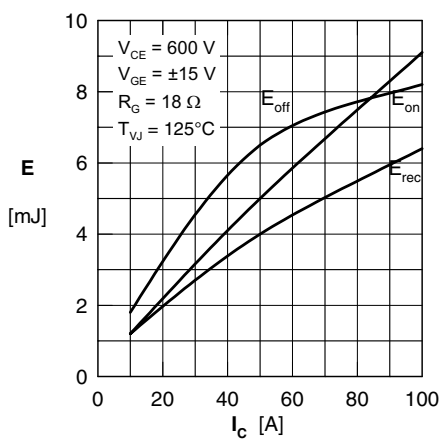


Fig. 7 Typ. switching losses vs. collector current

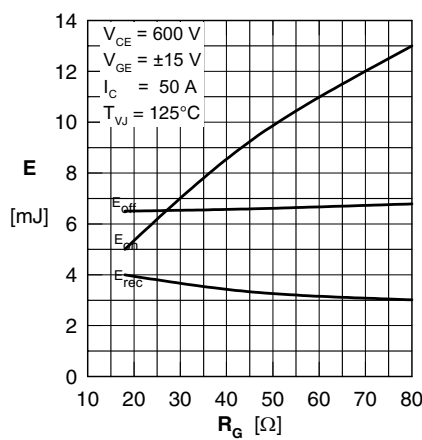


Fig. 8 Typ. switching losses vs. gate resistance

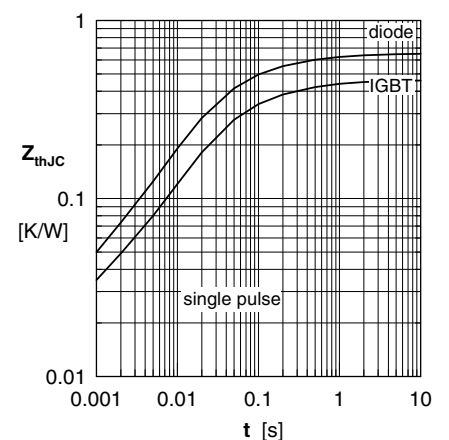


Fig. 9 Transient thermal impedance