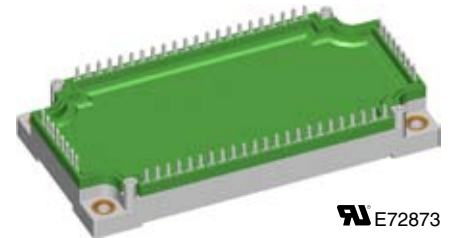
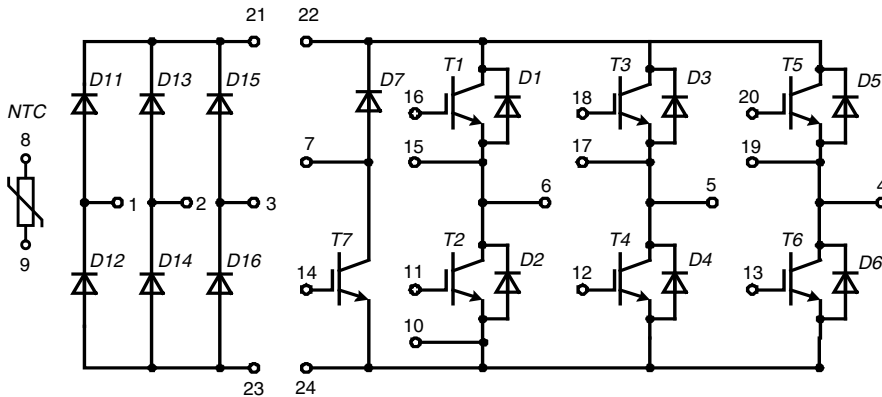


# Converter - Brake - Inverter Module (CBI3) with Trench IGBT technology



E72873

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 2200 \text{ V}$	$V_{CES} = 1700 \text{ V}$	$V_{CES} = 1700 \text{ V}$
$I_{FAVM} = 60 \text{ A}$	$I_{C25} = 48 \text{ A}$	$I_{C25} = 74 \text{ A}$
$I_{FSM} = 550 \text{ A}$	$V_{CE(sat)} = 2.1 \text{ V}$	$V_{CE(sat)} = 2.0 \text{ V}$

Input Rectifier Bridge D11 - D16			
Symbol	Conditions	Maximum Ratings	
$V_{RRM}$		2200	V
$I_{FAV}$	$T_C = 80^\circ\text{C}$ ; sine $180^\circ$	40	A
$I_{DAVM}$	$T_C = 80^\circ\text{C}$ ; rectangular; $d = 1/3$ ; bridge	130	A
$I_{FSM}$	$T_C = 25^\circ\text{C}$ ; $t = 10 \text{ ms}$ ; sine 50 Hz	550	A
$P_{tot}$	$T_C = 25^\circ\text{C}$	110	W

Symbol	Conditions	Characteristic Values			
		(T <sub>VJ</sub> = 25°C, unless otherwise specified)			
		min.	typ.	max.	
$V_F$	$I_F = 50 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$		1.25	1.5	V
		$T_{VJ} = 125^\circ\text{C}$		1.25	
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$		0.8	0.05	mA
	$T_{VJ} = 125^\circ\text{C}$				mA
$R_{thJC}$	(per diode)			1.1	K/W

### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- Electric braking operation

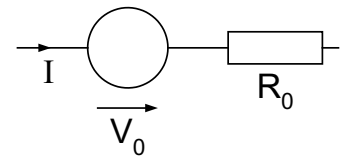
### Features

- High level of integration - only one power semiconductor module required for the whole drive
- IGBT technology with low saturation voltage, low switching losses and tail current, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6			
Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1700	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	74	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	53	A
$I_{CM}$	$T_C = 80^{\circ}\text{C}$ ; $t_p = 1$ ms	100	A
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	290	W

Symbol	Conditions	Characteristic Values				
		(T <sub>VJ</sub> = 25°C, unless otherwise specified)				
		min.	typ.	max.		
$V_{CE(sat)}$	$I_C = 50$ A; $V_{GE} = 15$ V	$T_{VJ} = 25^{\circ}\text{C}$		2.0	2.4	V
		$T_{VJ} = 125^{\circ}\text{C}$		2.4		V
$V_{GE(th)}$	$I_C = 2$ mA; $V_{GE} = V_{CE}$	5		6.5	V	
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0$ V			0.4	mA	
			1.0		mA	
$I_{GES}$	$V_{CE} = 0$ V; $V_{GE} = \pm 20$ V			400	nA	
$C_{ies}$	$V_{CE} = 25$ V; $V_{GE} = 0$ V; $f = 1$ MHz		4.4		nF	
$Q_{Gon}$	$V_{CE} = 900$ V; $V_{GE} = 15$ V; $I_C = 75$ A		600		nC	
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 900$ V; $I_C = 50$ A $V_{GE} = \pm 15$ V; $R_G = 8$ $\Omega$		250		ns	
$t_r$			50		ns	
$t_{d(off)}$			500		ns	
$t_f$			480		ns	
$E_{on}$			11		mJ	
$E_{off}$			12		mJ	
<b>RBSOA</b>	$I_C = I_{CM}$ ; $V_{GE} = 15$ V $R_G = 27$ $\Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$	$V_{CEK} \leq V_{CES} - L_S di/dt$			V	
<b><math>t_{SC}</math> (SCSOA)</b>	$V_{CE} = 1000$ V; $V_{GE} = \pm 15$ V; $R_G = 27$ $\Omega$ $t_p \leq 10$ $\mu\text{s}$ ; non-repetitive; $T_{VJ} = 125^{\circ}\text{C}$		10		$\mu\text{s}$	
$R_{thJC}$				0.43	K/W	

Output Inverter D1 - D6						
Symbol	Conditions	Maximum Ratings				
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	56	A			
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	39	A			
Symbol	Conditions	Characteristic Values				
		min.	typ.	max.		
$V_F$	$I_F = 50$ A;	$T_{VJ} = 25^{\circ}\text{C}$		2.0	2.4	V
		$T_{VJ} = 125^{\circ}\text{C}$		2.0		V
$I_{RM}$	$I_F = 50$ A; $di_F/dt = -1200$ A/ $\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ ; $V_R = 900$ V; $V_{GE} = 0$ V		80		A	
$Q_{rr}$			20		$\mu\text{C}$	
$t_{rr}$			650		ns	
$E_{rec}$			9		mJ	
$R_{thJC}$	(per diode)			0.65	K/W	

**Equivalent Circuits for Simulation**
**Conduction**

**IGBT (typ. at  $V_{GE} = 15$  V;  $T_J = 125^{\circ}\text{C}$ )**
*T1-T6*

$$V_0 = 1.0 \text{ V}; R_0 = 25 \text{ m}\Omega$$

*T7*

$$V_0 = 1.0 \text{ V}; R_0 = 28 \text{ m}\Omega$$

**Diode (typ. at  $T_J = 125^{\circ}\text{C}$ )**
*D1-D6*

$$V_0 = 1.35 \text{ V}; R_0 = 15 \text{ m}\Omega$$

*D7*

$$V_0 = 1.65 \text{ V}; R_0 = 37 \text{ m}\Omega$$

*D11-D16*

$$V_0 = 0.83 \text{ V}; R_0 = 4.1 \text{ m}\Omega$$

<b>Brake Chopper T7</b>			
<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1700	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	48	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	34	A
$I_{CM}$	$T_C = 80^{\circ}\text{C}; t_p = 1 \text{ ms}$	60	A
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	200	W

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>				
		$(T_{VJ} = 25^{\circ}\text{C}, \text{ unless otherwise specified})$				
		<b>min.</b>	<b>typ.</b>	<b>max.</b>		
$V_{CE(sat)}$	$I_C = 30 \text{ A}; V_{GE} = 15 \text{ V}$		$T_{VJ} = 25^{\circ}\text{C}$	1.9	2.2	V
			$T_{VJ} = 125^{\circ}\text{C}$	2.1		V
$V_{GE(th)}$	$I_C = 2 \text{ mA}; V_{GE} = V_{CE}$	5		6.5	V	
$I_{CES}$	$V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}$		$T_{VJ} = 25^{\circ}\text{C}$		0.3	mA
			$T_{VJ} = 125^{\circ}\text{C}$	0.6		mA
$I_{GES}$	$V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$			400	nA	
$C_{iss}$	$V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$		4.4		nF	
$Q_{Gon}$	$V_{CE} = 900 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 30 \text{ A}$		600		nC	
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 900 \text{ V}; I_C = 30 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 27 \Omega$			165		ns
$t_r$				40		ns
$t_{d(off)}$				700		ns
$t_f$				400		ns
$E_{off}$				7		mJ
$E_{on}$				6		mJ
<b>RBSOA</b>	$I_C = I_{CM}; V_{GE} = 15 \text{ V}$ $R_G = 27 \Omega; T_{VJ} = 125^{\circ}\text{C}$	$V_{CEK} \leq V_{CES} - L_S di/dt$			V	
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = 900 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 45 \Omega$ $t_p \leq 10 \mu\text{s}; \text{ non-repetitive}; T_{VJ} = 125^{\circ}\text{C}$		10		$\mu\text{s}$	
$R_{thJC}$				0.62	K/W	

<b>Brake Chopper D7</b>			
<b>Symbol</b>	<b>Conditions</b>	<b>Maximum Ratings</b>	
$V_{RRM}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	1700	V
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	30	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	21	A

<b>Symbol</b>	<b>Conditions</b>	<b>Characteristic Values</b>				
		<b>min.</b>	<b>typ.</b>	<b>max.</b>		
$V_F$	$I_F = 30 \text{ A};$		$T_{VJ} = 25^{\circ}\text{C}$	2.5	3.3	V
			$T_{VJ} = 125^{\circ}\text{C}$	2.6		V
$I_R$	$V_R = V_{RRM};$			0.05	mA	
			$T_{VJ} = 125^{\circ}\text{C}$	0.2	mA	
$I_{RM}$	$I_F = 30 \text{ A}; di_F/dt = -800 \text{ A}/\mu\text{s}; T_{VJ} = 125^{\circ}\text{C}$ $V_R = 900 \text{ V}$			35	A	
$t_{rr}$				700	ns	
$R_{thJC}$	(per diode)			0.9	K/W	

### Temperature Sensor NTC

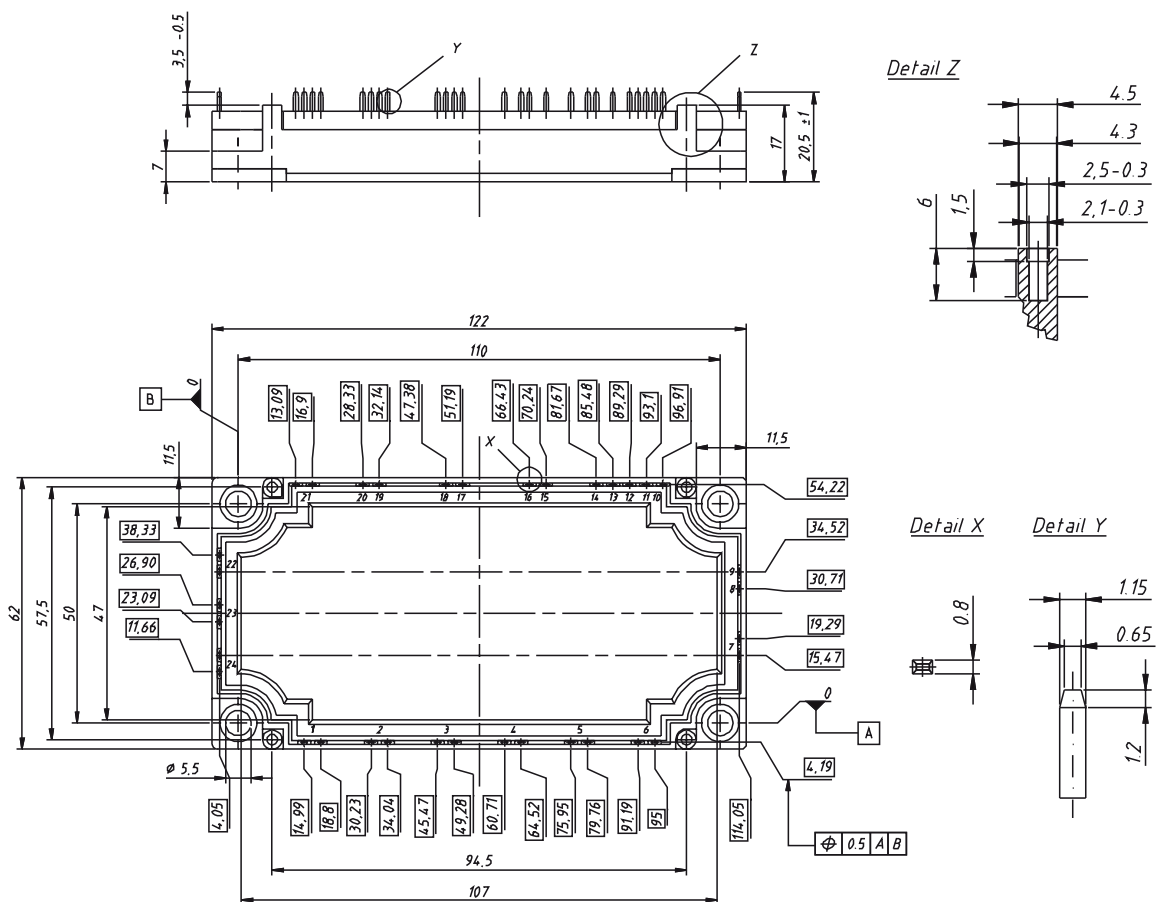
Symbol	Conditions	Characteristic Values			
		min.	typ.	max.	
$R_{25}$	$T = 25^{\circ}\text{C}$	4.75	5.0	5.25	k $\Omega$
$B_{25/50}$			3375		K

### Module

Symbol	Conditions	Maximum Ratings	
$T_{VJ}$	operating	-40...+125	$^{\circ}\text{C}$
$T_{JM}$		+150	$^{\circ}\text{C}$
$T_{stg}$		-40...+125	$^{\circ}\text{C}$
$V_{ISO}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}; 1 \text{ min.}$	3400	V~
$M_d$	Mounting torque (M5)	3 - 6	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{therm-chip}$	Resistance terminal to chip		7	m $\Omega$
$d_s$	Creepage distance on surface	12.7		mm
$d_A$	Strike distance in air	9.6		mm
$R_{thCH}$	with heatsink compound		0.02	K/W
<b>Weight</b>			300	g

Dimensions in mm (1 mm = 0.0394")



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## Input Rectifier Bridge D11 - D16

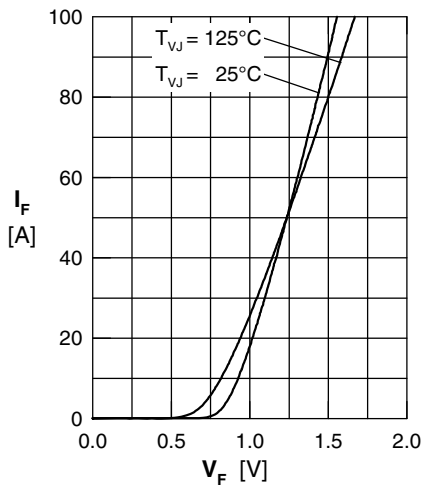


Fig. 1 Typ. forward current vs. voltage drop per diode

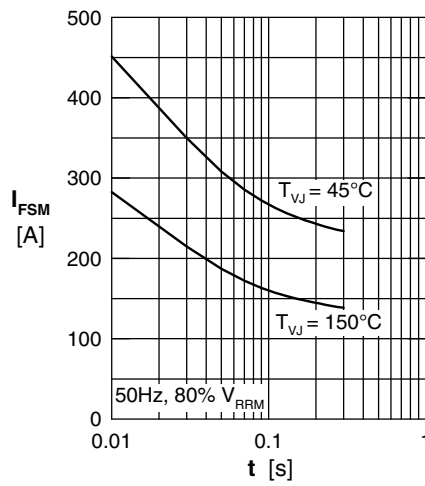


Fig. 2 Surge overload current

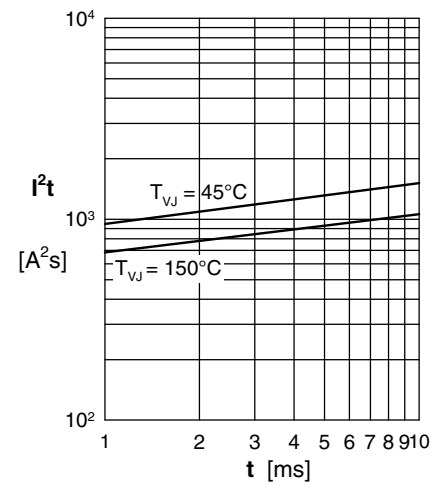


Fig. 3  $I^2t$  versus time per diode

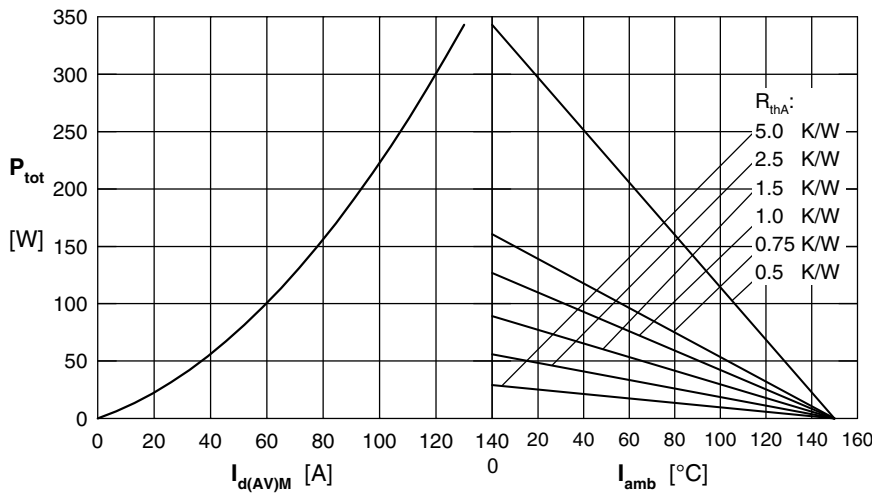


Fig. 4 Power dissipation versus direct output current & ambient temperature, sin 180°

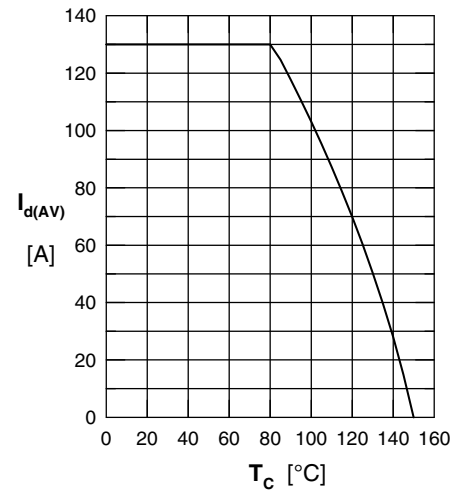


Fig. 5 Max. forward current vs. case temperature

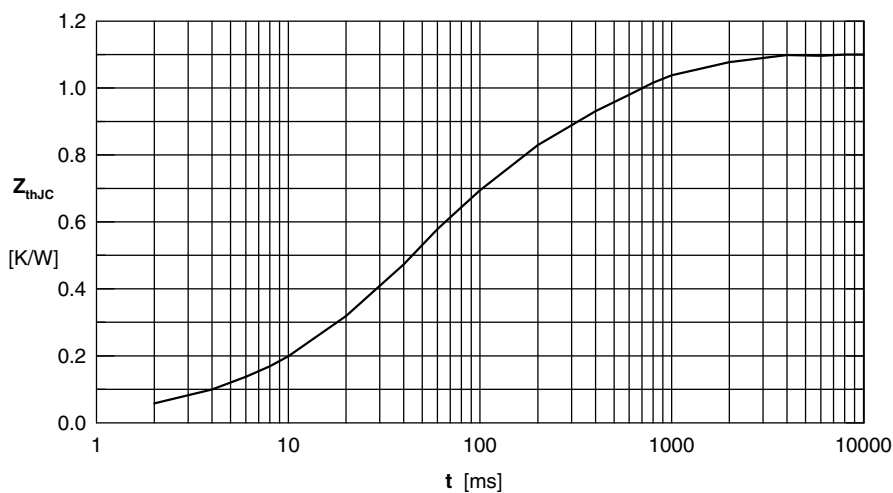
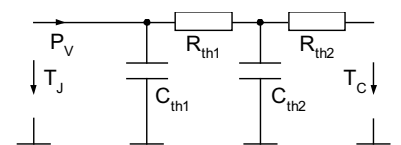


Fig. 6 Transient thermal impedance junction to case



	$R_i$	$\tau_i$
1	0.06	0.0085
2	0.024	0.001
3	0.586	0.045
4	0.114	0.85
5	0.317	0.35

**Output Inverter T1 - T6 / D1 - D6**

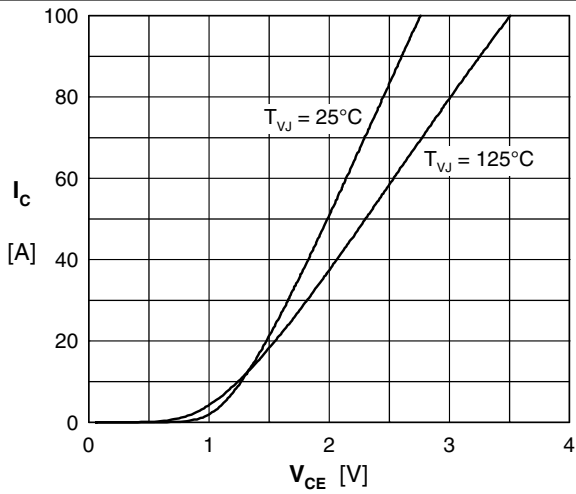


Fig. 7 Typical output characteristic

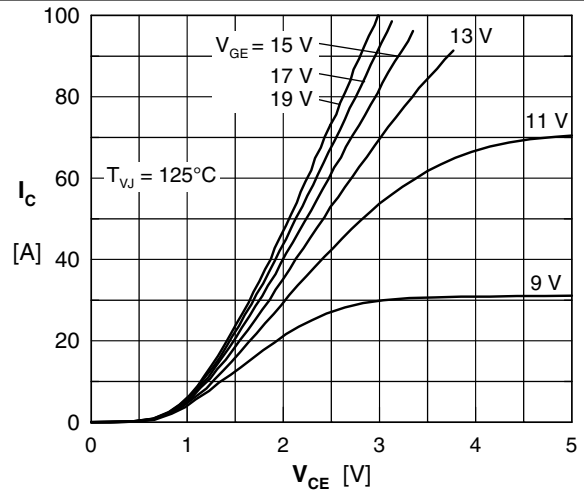


Fig. 8 Typical output characteristic

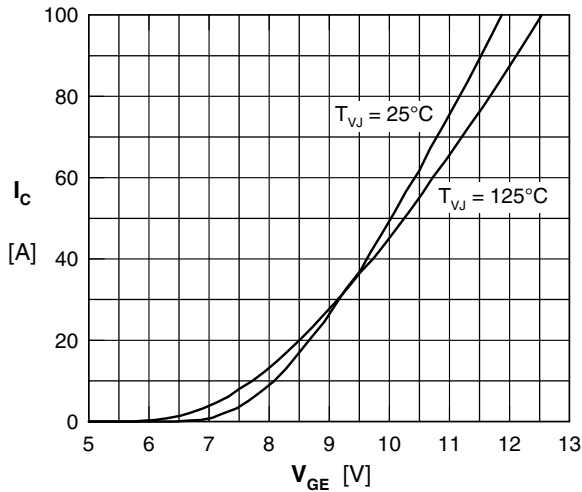


Fig. 9 Typical transfer characteristic

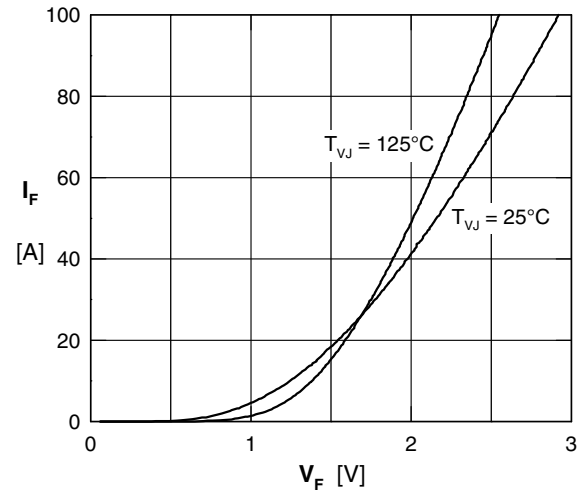


Fig. 10 Typical forward characteristic of free wheeling diode

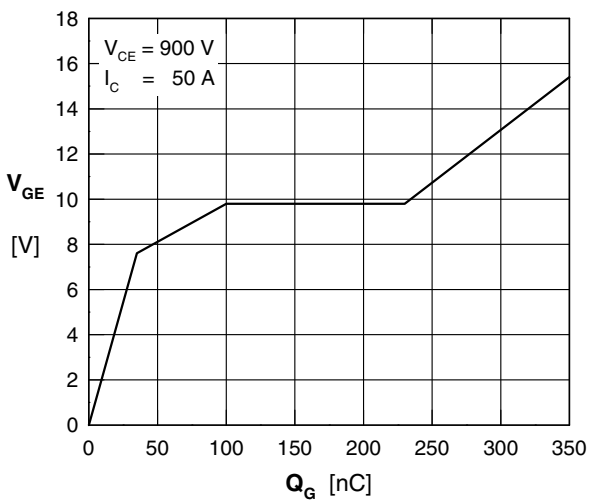


Fig. 11 Typical turn on gate charge

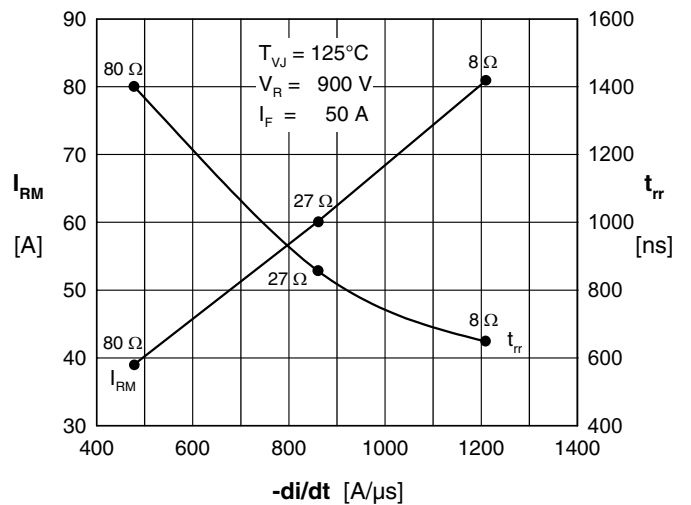


Fig. 12 Typ. turn-off characteristics of free wheeling diode

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### Output Inverter T1 - T6 / D1 - D6

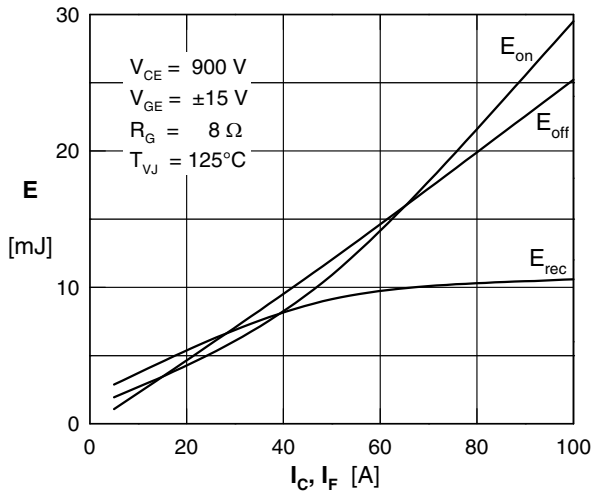


Fig. 13 Typ. turn on energy & switching times versus collector current

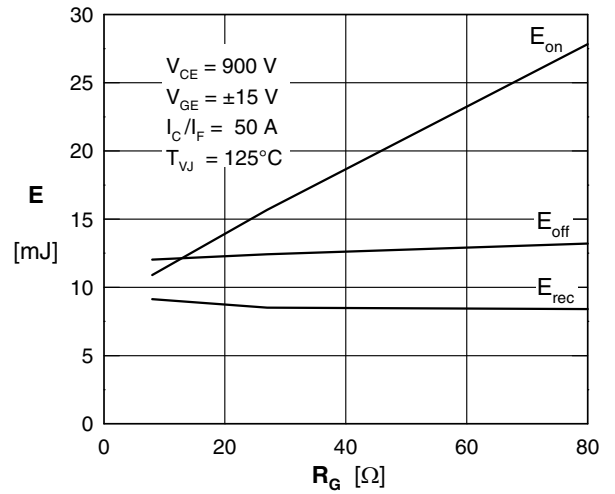


Fig. 14 Typ. turn off energy and switching times versus collector current

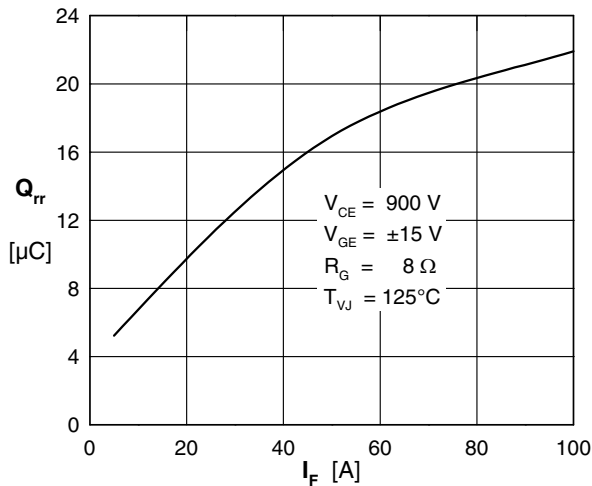


Fig. 15 Typical turn-off characteristics of free wheeling diode

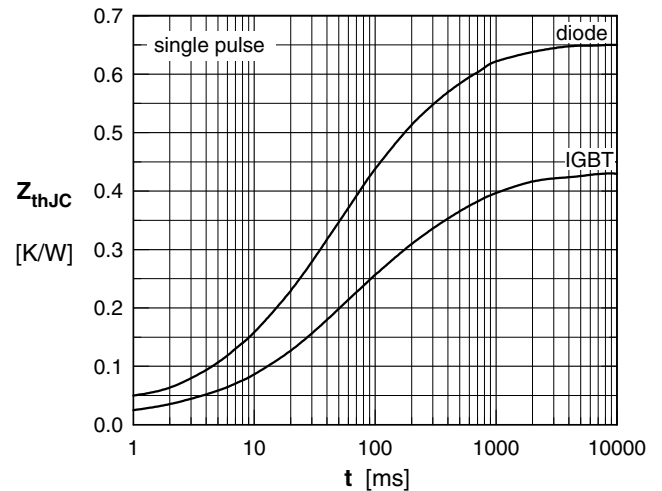


Fig. 16 Transient thermal impedance junction to case

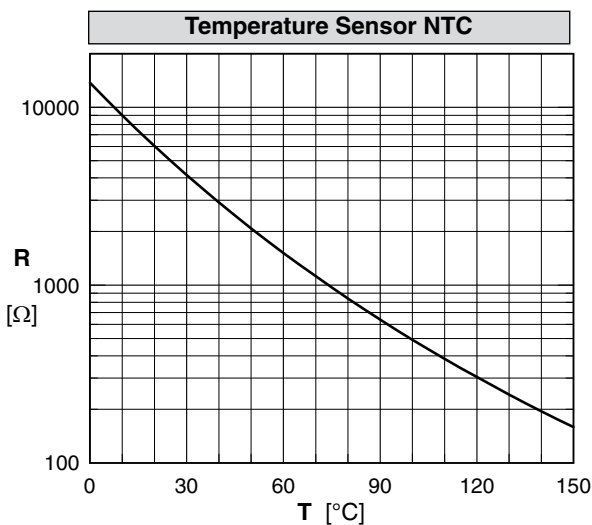


Fig. 17 Typ. NTC resistance vs. temperature

	IGBT		Diode	
	$R_i$	$\tau_i$	$R_i$	$\tau_i$
1	0.0326	0.0014	0.1941	0.0206
2	0.1311	0.0258	0.0542	0.0016
3	0.1492	0.1099	0.2549	0.0930
4	0.1169	0.6361	0.1461	0.5958

