

# **PCA9306**

**Dual bidirectional I2C-bus and SMBus voltage-level translator**

**Rev. 9.3 — 14 November 2022 Product data sheet**

# **1 General description**

The PCA9306 is a dual bidirectional  $I^2C$ -bus and SMBus voltage-level translator with an enable (EN) input, and is operational from 1.0 V to 3.6 V ( $V_{ref(1)}$ ) and 1.8 V to 5.5 V  $(V_{bias(ref)(2)}).$ 

The PCA9306 allows bidirectional voltage translations between 1.0 V and 5 V without the use of a direction pin. The low ON-state resistance  $(R_{on})$  of the switch allows connections to be made with minimal propagation delay. When EN is HIGH, the translator switch is on, and the SCL1 and SDA1 I/O are connected to the SCL2 and SDA2 I/O, respectively, allowing bidirectional data flow between ports. When EN is LOW, the translator switch is off, and a high-impedance state exists between ports.

The PCA9306 is not a bus buffer like the PCA9509 or PCA9517A that provide both level translation and physically isolate the capacitance to either side of the bus when both sides are connected. The PCA9306 only isolates both sides when the device is disabled and provides voltage level translation when active.

The PCA9306 can also be used to run two buses, one at 400 kHz operating frequency and the other at 100 kHz operating frequency. If the two buses are operating at different frequencies, the 100 kHz bus must be isolated when the 400 kHz operation of the other bus is required. If the controller is running at 400 kHz, the maximum system operating frequency may be less than 400 kHz because of the delays added by the translator.

As with the standard  $I^2C$ -bus system, pull-up resistors are required to provide the logic HIGH levels on the translator's bus. The PCA9306 has a standard open-collector configuration of the  $I^2C$ -bus. The size of these pull-up resistors depends on the system, but each side of the translator must have a pull-up resistor. The device is designed to work with Standard-mode, Fast-mode and Fast-mode Plus I<sup>2</sup>C-bus devices in addition to SMBus devices. The maximum frequency is dependent on the RC time constant, but generally supports > 2 MHz.

When the SDA1 or SDA2 port is LOW, the clamp is in the ON-state and a low resistance connection exists between the SDA1 and SDA2 ports. Assuming the higher voltage is on the SDA2 port when the SDA2 port is HIGH, the voltage on the SDA1 port is limited to the voltage set by VREF1. When the SDA1 port is HIGH, the SDA2 port is pulled to the drain pull-up supply voltage ( $V_{pu(D)}$ ) by the pull-up resistors. This functionality allows a seamless translation between higher and lower voltages selected by the user without the need for directional control. The SCL1/SCL2 channel also functions as the SDA1/SDA2 channel.

All channels have the same electrical characteristics and there is minimal deviation from one output to another in voltage or propagation delay. This is a benefit over discrete transistor voltage translation solutions, since the fabrication of the switch is symmetrical. The translator provides excellent ESD protection to lower voltage devices, and at the same time protects less ESD-resistant devices.



# **2 Features and benefits**

- 2-bit bidirectional translator for SDA and SCL lines in mixed-mode I<sup>2</sup>C-bus applications
- Standard-mode, Fast-mode, and Fast-mode Plus I<sup>2</sup>C-bus and SMBus compatible
- **•** Less than 1.5 ns maximum propagation delay to accommodate Standard-mode and Fast-mode  $I^2C$ -bus devices and multiple controllers
- **•** Allows voltage level translation between:
	- **–** 1.0 V Vref(1) and 1.8 V, 2.5 V, 3.3 V or 5 V Vbias(ref)(2)
	- **–** 1.2 V Vref(1) and 1.8 V, 2.5 V, 3.3 V or 5 V Vbias(ref)(2)
	- **–** 1.8 V Vref(1) and 3.3 V or 5 V Vbias(ref)(2)
	- **–** 2.5 V Vref(1) and 5 V Vbias(ref)(2)
	- $-3.3$  V V<sub>ref(1)</sub> and 5 V V<sub>bias(ref)(2)</sub>
- **•** Provides bidirectional voltage translation with no direction pin
- **•** Low 3.5 Ω ON-state connection between input and output ports provides less signal distortion
- Open-drain I<sup>2</sup>C-bus I/O ports (SCL1, SDA1, SCL2 and SDA2)
- 5 V tolerant  $1^2$ C-bus I/O ports to support mixed-mode signal operation
- **•** High-impedance SCL1, SDA1, SCL2 and SDA2 pins for EN = LOW
- **•** Lock-up free operation
- **•** Flow through pinout for ease of printed-circuit board trace routing
- **•** ESD protection exceeds 2000 V HBM per JESD22-A114 and 1000 V CDM per JESD22-C101
- **•** Packages offered: SO8, TSSOP8, VSSOP8, XQFN8, XSON8, X2SON8

# <span id="page-2-1"></span><span id="page-2-0"></span>**3 Ordering information**

<span id="page-2-7"></span><span id="page-2-5"></span><span id="page-2-4"></span><span id="page-2-3"></span><span id="page-2-2"></span>

[1] Same footprint and pinout as the Texas Instruments PCA9306DCU. VSSOP8 transfers to ASEN in dark green - refer to PCN202103046A.<br>[2] PCA9306DC1/DG is functionally the same (electrically and mechanically) as the PCA9306D [2] PCA9306DC1/DG is functionally the same (electrically and mechanically) as the PCA9306DC1 and the Texas Instruments PCA9306DCU. It is produced in dark green (lead-free and halogen/antimony-free) package material, with a unique orderable part number for customers who desire to order and only receive dark green package material.

[3] Also known as MSOP8.<br>[4] Same footprint and pino

<sup>[4]</sup> Same footprint and pinout as the Texas Instruments PCA9306DCT.<br>[5] PCA9306GF will be phased out and replaced by PCA9306JK with p to PCA9306GF will be phased out and replaced by PCA9306JK with package version SOT2015-1.<br>[6] X' will change based on date code.

'X' will change based on date code.

# <span id="page-2-6"></span>**3.1 Ordering options**

#### **Table 2. Ordering options**



<span id="page-3-0"></span>**Table 2. Ordering options***...continued*

<span id="page-3-1"></span>

<b>Type number</b>	Orderable part number	Package	<b>Packing method</b>	<b>Minimum</b> order quantity	<b>Temperature</b>
PCA9306DP1	PCA9306DP1.125	TSSOP8	Reel 7" Q3/T4 *standard mark	3000	$T_{amb}$ = -40 °C to +105 °C
<b>PCA9306GF</b>	PCA9306GF.115	XSON <sub>8</sub>	Reel 7" Q1/T1 *standard mark SMD	5000	$T_{amb}$ = -40 °C to +105 °C
PCA9306JK	PCA9306JKZ	X <sub>2</sub> SON <sub>8</sub>	Reel 7" Q1/T1 *standard mark	5000	$T_{amb}$ = -40 °C to +105 °C
PCA9306GM	PCA9306GM.125	XQFN8	Reel 7" Q3/T4 *standard mark	4000	$T_{amb}$ = -40 °C to +105 °C

[1] Discontinuation notice 202108009DN - move to PCA9306DC1Z.<br>[2] This packing method uses a Static Shielding Bag (SSB) solution

This packing method uses a Static Shielding Bag (SSB) solution. Material should be kept in the sealed bag between uses.

# **4 Functional diagram**

<span id="page-3-2"></span>

# **5 Pinning information**

# **5.1 Pinning**

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### **5.2 Pin description**

#### <span id="page-4-0"></span>**Table 3. Pin description**



# **6 Functional description**

<span id="page-5-0"></span>Refer to [Figure 1.](#page-3-2)

## **6.1 Function table**

<span id="page-5-1"></span>*H = HIGH level; L = LOW level.* **Table 4. Function selection (example)**



[1] EN is controlled by the V<sub>bias(ref)(2</sub>) logic levels and should be at least 1 V higher than V<sub>ref(1)</sub> for best translator operation.

# **7 Limiting values**

#### <span id="page-5-2"></span>**Table 5. Limiting values**

*In accordance with the Absolute Maximum Rating System (IEC 60134). Over operating free-air temperature range.*



[1] The input and input/output negative voltage ratings may be exceeded if the input and input/output clamp current ratings are observed.

# **8 Recommended operating conditions**



<span id="page-5-3"></span>**Table 6. Operating conditions**

[1]  $V_{ref(1)} \le V_{bias(ref)(2)} - 1$  V for best results in level shifting applications.

# <span id="page-6-3"></span><span id="page-6-0"></span>**9 Static characteristics**

#### <span id="page-6-4"></span><span id="page-6-1"></span>**Table 7. Static characteristics**

<span id="page-6-2"></span>*Tamb = -40 °C to +105 °C, unless otherwise specified.*



[1] All typical values are at  $T_{amb} = 25 °C$ .<br>[2] Measured by the voltage drop betwee Measured by the voltage drop between the SCL1 and SCL2, or SDA1 and SDA2 terminals at the indicated current through the switch. ON-state resistance is determined by the lowest voltage of the two terminals.

[3] Guaranteed by design.

[4] For DC, DC1 (VSSOP8) and GD1 (XSON8U) packages only.

# **10 Dynamic characteristics**

#### <span id="page-6-5"></span>**Table 8. Dynamic characteristics (translating down)**

*Tamb = -40 °C to +105 °C, unless otherwise specified. Values guaranteed by design.*





#### **Table 8. Dynamic characteristics (translating down)***...continued*

*Tamb = -40 °C to +105 °C, unless otherwise specified. Values guaranteed by design.*

#### <span id="page-7-1"></span>**Table 9. Dynamic characteristics (translating up)**

*Tamb = -40 °C to +105 °C, unless otherwise specified. Values guaranteed by design.*

Symbol	Parameter	<b>Conditions</b>		$C_L = 50$ pF		$C_L$ = 30 pF		$C_L = 15 pF$		Unit
				<b>Min</b>	<b>Max</b>	Min	<b>Max</b>	Min	<b>Max</b>	
$V_{I(EN)}$ = 3.3 V; V <sub>IH</sub> = 2.3 V; V <sub>IL</sub> = 0 V; V <sub>TT</sub> = 3.3 V; V <sub>M</sub> = 1.15 V; R <sub>L</sub> = 300 Ω (see Figure 8)										
t <sub>PLH</sub>	LOW to HIGH propagation delay	from (input) SCL1 or SDA1 to (output) SCL2 or SDA2		$\Omega$	1.75	$\Omega$	1.0	$\Omega$	0.5	ns
t <sub>PHL</sub>	<b>HIGH to LOW</b> propagation delay	from (input) SCL1 or SDA1 to (output) SCL2 or SDA2		$\Omega$	2.75	$\Omega$	1.65	$\Omega$	0.8	ns
$V_{I(EN)}$ = 2.5 V; V <sub>IH</sub> = 1.5 V; V <sub>IL</sub> = 0 V; V <sub>TT</sub> = 2.5 V; V <sub>M</sub> = 0.75 V; R <sub>L</sub> = 300 Ω (see Figure 8)										
t <sub>PLH</sub>	LOW to HIGH propagation delay	from (input) SCL1 or SDA1 to (output) SCL2 or SDA2		$\Omega$	1.75	$\mathbf{0}$	1.0	$\mathbf{0}$	0.5	ns
t <sub>PHL</sub>	<b>HIGH to LOW</b> propagation delay	from (input) SCL1 or SDA1 to (output) SCL2 or SDA2		$\Omega$	3.3	$\Omega$	2.0	$\Omega$	1.0	ns



<span id="page-7-0"></span> $S1$  = translating up;  $S2$  = translating down.

 $C_1$  includes probe and jig capacitance.

All input pulses are supplied by generators having the following characteristics: PRR ≤ 10 MHz; Z<sub>o</sub> = 50 Ω; t<sub>r</sub> ≤ 2 ns; t<sub>f</sub> ≤ 2 ns.

The outputs are measured one at a time, with one transition per measurement.

**Figure 8. Load circuit for outputs**

# **11 Application information**

<span id="page-8-0"></span>

<span id="page-8-1"></span>

# **11.1 Bidirectional translation**

For the bidirectional clamping configuration (higher voltage to lower voltage or lower voltage to higher voltage), the EN input must be connected to VREF2 and both pins pulled to HIGH side V<sub>pu(D)</sub> through a pull-up resistor (typically 200 kΩ). This allows VREF2 to regulate the EN input. A filter capacitor on VREF2 is recommended. The  $I^2C$ -

<span id="page-9-0"></span>bus controller output can be totem pole or open-drain (pull-up resistors may be required) and the  $1<sup>2</sup>C$ -bus device output can be totem pole or open-drain (pull-up resistors are required to pull the SCL2 and SDA2 outputs to  $V_{\text{pu(D)}}$ . However, if either output is totem pole, data must be unidirectional or the outputs must be 3-stateable and be controlled by some direction-control mechanism to prevent HIGH-to-LOW contentions in either direction. If both outputs are open-drain, no direction control is needed.

The reference supply voltage  $(V_{ref(1)})$  is connected to the processor core power supply voltage. When VREF2 is connected through a 200 kΩ resistor to a 3.3 V to 5.5 V V<sub>pu(D)</sub> power supply, and  $V_{ref(1)}$  is set between 1.0 V and ( $V_{pu(D)}$  - 1 V), the output of each SCL1 and SDA1 has a maximum output voltage equal to VREF1, and the output of each SCL2 and SDA2 has a maximum output voltage equal to  $V_{pu(D)}$ .



<span id="page-9-1"></span>**Table 10. Application operating conditions**

[1] All typical values are at  $T_{amb} = 25 \degree C$ .

### **11.2 How to size pull-up resistor value**

Sizing the pull-up resistor on an open-drain bus is specific to the individual application and is dependent on the following driver characteristics:

- **•** The driver sink current
- The V<sub>OL</sub> of driver

*Refer to [Figure 9](#page-8-0).*

- The V<sub>II</sub> of the driver
- **•** Frequency of operation

The following tables can be used to estimate the pull-up resistor value in different use cases so that the minimum resistance for the pull-up resistor can be found.

[Table 11](#page-10-0), [Table 12](#page-10-1) and [Table 13](#page-10-2) contain suggested minimum values of pull-up resistors for the PCA9306 and NVT20xx devices with typical voltage translation levels and drive currents. The calculated values assume that both drive currents are the same.  $V_{OL} = V_{IL}$ = 0.1 × V<sub>CC</sub> and accounts for a ±5 % V<sub>CC</sub> tolerance of the supplies, ±1 % resistor values. It should be noted that the resistor chosen in the final application should be equal to or larger than the values shown in [Table 11](#page-10-0), [Table 12](#page-10-1) and [Table 13](#page-10-2) to ensure that the pass voltage is less than 10 % of the  $V_{CC}$  voltage, and the external driver should be able to sink the total current from both pull-up resistors. When selecting the minimum resistor value in [Table 11](#page-10-0), [Table 12](#page-10-1) or [Table 13,](#page-10-2) the drive current strength that should be chosen should be the lowest drive current seen in the application and account for any drive strength current scaling with output voltage. For the GTL devices, the resistance table should be recalculated to account for the difference in ON resistance and bias voltage limitations between  $V_{CC(B)}$  and  $V_{CC(A)}$ .

A-side	<b>B-side</b>							
	1.2V	1.5V	1.8V	2.5V	3.3V	5.0 V		
1.0V	$R_{pu(A)} = 750 \Omega$ $R_{pu(B)} = 750 \Omega$	$R_{pu(A)} = 845$ Ω $R_{pu(B)} = 845$ Ω	$R_{pu(A)} = 976 \Omega$ $R_{pu(B)} = 976 \Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 887 \Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.18 kΩ$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.82 kΩ$		
1.2V		$R_{pu(A)} = 931 \Omega$ $R_{pu(B)} = 931 \Omega$	$R_{pu(A)} = 1.02 kΩ$ $R_{pu(B)} = 1.02 kΩ$	$R_{pu(A)}$ = none $R_{pu(B)} = 887 Ω$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.18 k\Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.82 k\Omega$		
1.5V			$R_{pu(A)} = 1.1 kΩ$ $R_{pu(B)} = 1.1 k\Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 866 \Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.18 kΩ$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.78$ kΩ		
1.8V				$R_{pu(A)} = 1.47$ kΩ $R_{pu(B)} = 1.47 k\Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.15 k\Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 1.78 k\Omega$		
2.5V					$R_{pu(A)}$ = 1.96 kΩ $R_{pu(B)} = 1.96$ kΩ	$R_{pu(A)}$ = none $R_{pu(B)} = 1.78$ kΩ		
3.3V						$R_{pu(A)}$ = none $R_{pu(B)}$ = 1.74 kΩ		

<span id="page-10-0"></span>Table 11. Pull-up resistor minimum values, 3 mA driver sink current for PCA9306 and NVT20xx

<span id="page-10-1"></span>



<span id="page-10-2"></span>



A-side	<b>B-side</b>								
	1.2V	1.5V	1.8V	2.5V	3.3V	5.0V			
1.8V				$R_{pu(A)}$ = 294 $\Omega$ $R_{pu(B)} = 294 \Omega$	$R_{pu(A)}$ = none $R_{pu(B)} = 232 Ω$	$R_{pu(A)}$ = none $R_{pu(B)} = 357 Ω$			
2.5V					$R_{pu(A)} = 392 \Omega$ $R_{pu(B)} = 392 Ω$	$R_{pu(A)}$ = none $R_{pu(B)} = 357 Ω$			
3.3V						$R_{pu(A)}$ = none $R_{pu(B)} = 348 \Omega$			

**Table 13. Pull-up resistor minimum values, 15 mA driver sink current for PCA9306 and NVT20xx***...continued*

### **11.3 How to design for maximum frequency operation**

The maximum frequency is limited by the minimum pulse width LOW and HIGH as well as rise time and fall time. See [Equation 1](#page-11-0) as an example of the maximum frequency. The rise and fall times are shown in [Figure 11](#page-11-1).

<span id="page-11-0"></span> $f_{max} = \frac{1}{t_{LOW(min)} + t_{HIGH(min)} + t_{Hactual}}(1)$ 

<span id="page-11-1"></span>

The rise and fall times are dependent upon translation voltages, the drive strength, the total node capacitance  $(C_{L(tot)})$  and the pull-up resistors  $(R_{PU})$  that are present on the bus. The node capacitance is the addition of the PCB trace capacitance and the device capacitance that exists on the bus. Because of the dependency of the external components, PCB layout and the different device operating states the calculation of rise and fall times is complex and has several inflection points along the curve.

The main component of the rise and fall times is the RC time constant of the bus line when the device is in its two primary operating states: when device is in the ON state and it is low-impedance, the other is when the device is OFF isolating the A-side from the Bside.

A description of the fall time applied to either An or Bn output going from HIGH to LOW is as follows. Whichever side is asserted first, the B-side down must discharge to the  $V_{CG(A)}$  voltage. The time is determined by the pull-up resistor, pull-down driver strength and the capacitance. As the level moves below the  $V_{CC(A)}$  voltage, the channel resistance drops so that both A and B sides equal. The capacitance on both sides is connected to form the total capacitance and the pull-up resistors on both sides combine to the parallel equivalent resistance. The  $R_{on}$  of the device is small compared to the pull-up resistor values, so its effect on the pull-up resistance can be neglected and the fall is determined by the driver pulling the combined capacitance and pull-up resistor currents. An estimation of the actual fall time seen by the device is equal to the time it takes for the B-side to fall to the  $V_{\text{CC}(A)}$  voltage and the time it takes for both sides to fall from the  $V_{\text{CC(A)}}$  voltage to the  $V_{\text{IL}}$  level.

A description of the rise time applied to either An or Bn output going from LOW to HIGH is as follows. When the signal level is LOW, the  $R_{on}$  is at its minimum, so the A and B sides are essentially one node. They will rise together with an RC time constant that is the sum of all the capacitance from both sides and the parallel of the resistance from both sides. As the signal approaches the  $V_{CC(A)}$  voltage, the channel resistance goes up and the waveforms separate, with the B side finishing its rise with the RC time constant of the B side. The rise to  $V_{CC(A)}$  is essentially the same for both sides.

There are some basic guidelines to follow that will help maximize the performance of the device:

- **•** Keep trace length to a minimum by placing the NVT device close to the processor.
- **•** The signal round trip time on trace should be shorter than the rise or fall time of signal to reduce reflections.
- **•** The faster the edge of the signal, the higher the chance for ringing.
- **•** The higher drive strength controlled by the pull-up resistor (up to 15 mA), the higher the frequency the device can use.

The system designer must design the pull-up resistor value based on external current drive strength and limit the node capacitance (minimize the wire, stub, connector and trace length) to get the desired operation frequency result.

# **12 Package outline**

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# **13 Soldering of SMD packages**

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

### **13.1 Introduction to soldering**

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### **13.2 Wave and reflow soldering**

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- **•** Through-hole components
- **•** Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- **•** Board specifications, including the board finish, solder masks and vias
- **•** Package footprints, including solder thieves and orientation
- **•** The moisture sensitivity level of the packages
- **•** Package placement
- **•** Inspection and repair
- **•** Lead-free soldering versus SnPb soldering

### **13.3 Wave soldering**

Key characteristics in wave soldering are:

- **•** Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- **•** Solder bath specifications, including temperature and impurities

### **13.4 Reflow soldering**

Key characteristics in reflow soldering are:

- **•** Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 20](#page-23-0)) than a SnPb process, thus reducing the process window
- **•** Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- **•** Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 14](#page-22-0) and [Table 15](#page-22-1)

#### <span id="page-22-0"></span>**Table 14. SnPb eutectic process (from J-STD-020D)**



#### <span id="page-22-1"></span>**Table 15. Lead-free process (from J-STD-020D)**



Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 20](#page-23-0).

<span id="page-23-0"></span>

For further information on temperature profiles, refer to Application Note *AN10365 "Surface mount reflow soldering description"*.

# **14 Soldering: PCB footprints**

<span id="page-23-1"></span>

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# **15 Abbreviations**

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# **16 Revision history**

#### <span id="page-34-1"></span>**Table 17. Revision history**



# <span id="page-35-0"></span>**17 Legal information**

# **17.1 Data sheet status**



[1] Please consult the most recently issued document before initiating or completing a design.<br>[2] The term 'short data sheet' is explained in section "Definitions".

Ferm 'short data sheet' is explained in section "Definitions".<br>
[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

# **17.2 Definitions**

**Draft** — A draft status on a document indicates that the content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included in a draft version of a document and shall have no liability for the consequences of use of such information.

**Short data sheet** — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

**Product specification** — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

# **17.3 Disclaimers**

## **17.4 Trademarks**

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# **Tables**





# **Figures**



