

## **PIC-P26J50 Proto development board** **USER'S MANUAL**

All boards produced by Olimex LTD are ROHS compliant



Initial release, Januray 2012  
Designed by OLIMEX Ltd, 2011

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**Thank you for purchasing the PIC-P26J50 board manufactured by Olimex!**

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# SECTION 1

## OVERVIEW

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Thank you for choosing the PIC-P26J50 development board from Olimex! This document provides a User's Guide for the Olimex PIC-P26J50 development board. As an overview, this chapter gives the scope of this document and lists the board's features. The document's organization is then detailed.

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### 1.1 Scope

The PIC-P26J50 development board enables code development of applications running on the PIC18F26J59 microcontroller. This guide focuses on the PIC-P26J50 board as a development platform for the PIC18F26J59 device.

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### 1.2 Features

- PIC18F26J59 microcontroller with 64K Flash
- USB connector
- 8 LEDs
- Reset button
- User button
- UEXT connector
- mini ICSP/ICD (0,05"") connector for programming
- All PIC free ports available on header close to the prototype area
- Perfect for hobbyists
- Dimensions 61x45 mm (2.4 x 1.77")

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### 1.3 Organization

Each section in this document covers a separate topic, organized as follow:

- Section 1 is an overview of the board usage and features
- Section 2 provides a guide for quickly setting up the board
- Section 3 contains the general board diagram and layout
- Section 4 describes the component that is the heart of the board: the PIC18F26J59 microcontroller
- Section 5 is an explanation of the control circuitry associated with the microcontroller to reset, power and clock the board
- Section 6 covers the connector pinout, peripherals and jumper description
- Section 7 shows the memory map
- Section 8 provides the schematics
- Section 9 contains the revision history

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## SECTION 2

# SETTING UP THE PIC-P26J50 DEVELOPMENT BOARD

This section helps you set up the PIC-P26J50 development board for the first time.

Please consider first the electrostatic warning to avoid damaging the board, then discover the hardware and software required to operate the board.

The procedure to power up the board is given, and a description of the default board behavior is detailed.

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### 2.1 Electrostatic Warning

The PIC-P26J50 development board is shipped in a protective anti-static package. The board must not be exposed to high electrostatic potentials. A grounding strap or similar protective device should be worn when handling the board. Avoid touching the component pins or any other metallic element.

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### 2.2 Requirements

In order to set up the PIC-P26J50 proto board, the following items are required:

- The PIC-P26J50 development board itself
- miniUSB - USB cable

Or

- 3,3 V external power supply

Note: The board is not delivered with an ICSP debugger/programmer, which is needed if you want to reprogram it. Remember that the connector on the board is mini ICSP (6 pin). You may use a pair of the following devices for this purpose:

- Olimex's PIC-ICD2-POCKET + Olimex's PIC-ICSP
- Olimex's PIC-KIT3 + Olimex's PIC-ICSP

Or any compatible PIC programmer with 0,05'' step ICSP connector.

Also, a host-based software toolchain is required in order to program/debug the PIC-P26J50 board.

Our suggestion is to use Microchip's MPLab IDE.

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## 2.3 Powering up the board

The PIC-P26J50 board is self-powered by the miniUSB.

Additionally the board can be powered using the PROTO AREA pads. Provide 3.3 V to the respective pad with the same label. Ground pad is named GND on the opposite side of the 3.3 V.

On powering the board the PWR LED must turn on and the 8 LEDs must start turning on consecutively.

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## 2.4 Prebuilt software

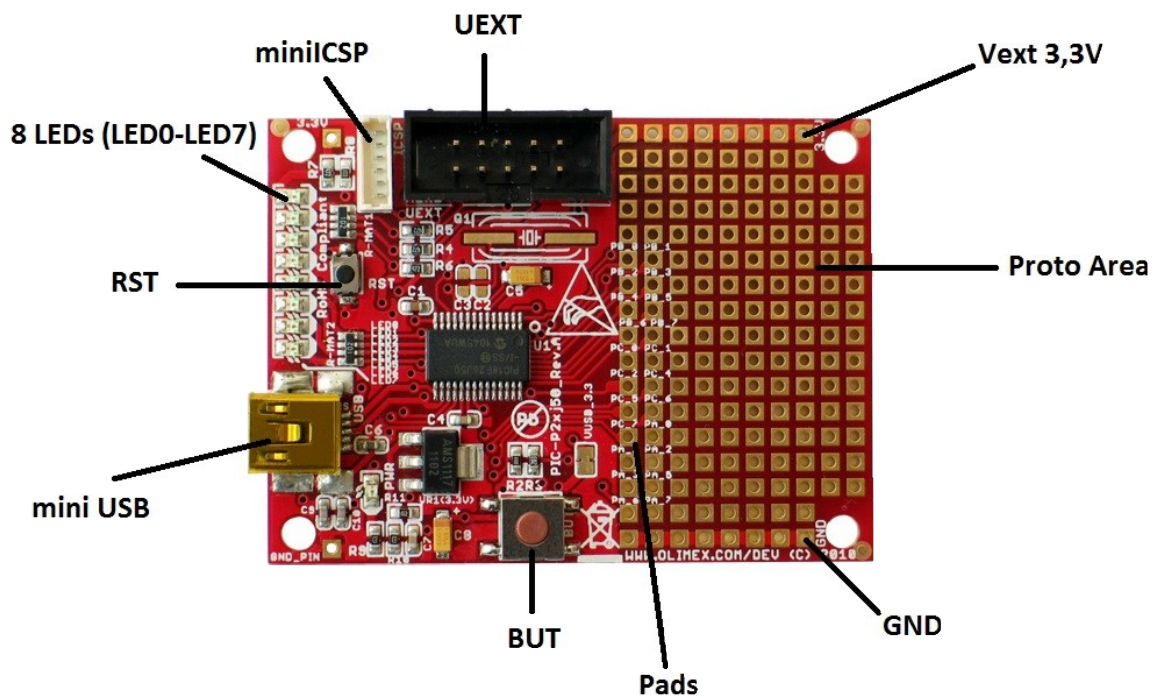
On arrival the board has a simple demo for the LEDS (blinking consecutively) and on pressing BUT they should blink in a different manner.

## SECTION 3

### PIC-P26J50 BOARD DESCRIPTION

Here you get acquainted with the main parts of the board. Note the names used on the board differ from the names used to describe them. For the actual names check the PIC-P26J50 board itself.

#### 3.1 Layout (Top view):



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## SECTION 4

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# THE PIC18F26J50 MICROCONTROLLER

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## 4.1 Features

### Power Management Features with nanoWatt XLP™ for Extreme Low-Power:

- **Deep Sleep mode: CPU off, Peripherals off,**  
Currents Down to 13  $\mu$ A and 850 nA with RTCC:
  - Able to wake-up on external triggers, programmable WDT or RTCC alarm
  - Ultra Low-Power Wake-up (ULPWU)
- Sleep mode: CPU off, Peripherals off, SRAM on, Fast Wake-up, Currents Down to 105  $\mu$ A, Typical
- Idle: CPU off, Peripherals on, Currents Down to 2.3 nA, Typical
- Run: CPU on, Peripherals on, Currents Down to 6.2 nA, Typical
- Timer1 Oscillator w/RTCC: 1 nA, 32 kHz, Typical
- Watchdog Timer: 0.8  $\mu$ A, 2V, Typical

### Special Microcontroller Features:

- Low-Power, High-Speed CMOS Flash Technology
- C Compiler Optimized Architecture for Re-Entrant Code
- Priority Levels for Interrupts
- Self-Programmable under Software Control
- 8 x 8 Single-Cycle Hardware Multiplier
- Extended Watchdog Timer (WDT):
  - Programmable period from 4 ms to 131s
- Single-Supply In-Circuit Serial Programming™(ICSP™) via two pins
- In-Circuit Debug (ICD) w/Three Breakpoints via 2 Pins
- Operating Voltage Range of 2.0V to 3.6V
- On-Chip 2.5V Regulator
- Flash Program Memory of 10,000 Erase/Write Cycles Minimum and 20-Year Data Retention

### Universal Serial Bus (USB) Features

- USB V2.0 Compliant
- Full Speed (12 Mbps) and Low Speed (1.5 Mbps)
- Supports Control, Interrupt, Isochronous and BulkTransfers
- Supports up to 32 Endpoints (16 bidirectional)
- USB module can use any RAM Location on the Device as USB Endpoint Buffers
- On-Chip USB Transceiver with Crystal-less operation

### Flexible Oscillator Structure:

- High-Precision Internal Oscillator ( $\pm 0.15\%$  typ.) for USB
- Two External Clock modes, up to 48 MHz (12 MIPS)
- Low-Power, 31 kHz Internal RC Oscillator
- Tunable Internal Oscillator (31 kHz to 8 MHz, or up to 48 MHz with PLL)
- Secondary Oscillator using Timer1 @ 32 kHz



- Fail-Safe Clock Monitor:
  - Allows for safe shutdown if any clock stops
- Two-Speed Oscillator Start-up
- Programmable Reference Clock Output Generator

**Peripheral Highlights:**

- Peripheral Pin Select:
  - Allows independent I/O mapping of many peripherals
  - Continuous hardware integrity checking and safety interlocks prevent unintentional configuration changes
- Hardware Real-Time Clock and Calendar (RTCC):
  - Provides clock, calendar and alarm functions
- High-Current Sink/Source 25 mA/25 mA (PORTB and PORTC)
- 5.5V Tolerant Inputs (digital only pins)
- Four Programmable External Interrupts
- Four Input Change Interrupts
- Two Enhanced Capture/Compare/PWM (ECCP) modules:
  - One, two or four PWM outputs
  - Selectable polarity
  - Programmable dead time
  - Auto-shutdown and auto-restart
  - Pulse steering control
- Two Master Synchronous Serial Port (MSSP) modules Supporting Three-Wire SPI (all four modes) and I2C™ Master and Slave modes
- Full-Duplex Master/Slave SPI DMA Engine
- 8-Bit Parallel Master Port/Enhanced Parallel Slave Port
- Two-Rail – Rail Analog Comparators with Input Multiplexing
- 10-Bit, up to 13-Channel Analog-to-Digital (A/D) Converter module:
  - Auto-acquisition capability
  - Conversion available during Sleep
  - Self-calibration
- High/Low-Voltage Detect module
- Charge Time Measurement Unit (CTMU):
  - Supports capacitive touch sensing for touch screens and capacitive switches
  - Provides a precise resolution time measurement for both flow measurement and simple temperature sensing
- Two Enhanced USART modules:
  - Supports RS-485, RS-232 and LIN/J2602
  - Auto-Wake-up on Start bit
- Auto-Baud Detect

For comprehensive information on the microcontroller visit the Microchip's web page for a datasheet.

At the moment of writing the microcontroller datasheet can be found at the following link:

<http://ww1.microchip.com/downloads/en/DeviceDoc/39931d.pdf>

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## SECTION 5

### CONTROL CIRCUITRY

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#### 5.1 Power supply

When PIC-P26J50 is connected via a USB cable to a USB host it will take its 3,3V power supply from the USB host source to power the board.

Additionally the board can be powered using the 3.3V pad and the GND pad on the proto area.

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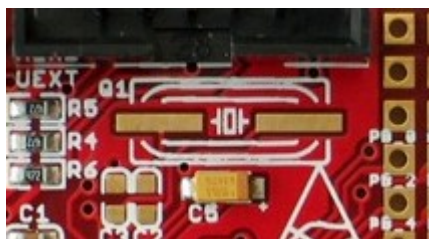
#### 5.2 Reset

PIC-P26J50 reset circuit includes R8 (390Ω), PIC18F26J59 pin 1 (#MCLR/TTL) and a RESET button.

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#### 5.3 Clock

Quartz crystal pad is available but a quartz crystal is not mounted! If you want to use the oscillator you have to mount a quartz crystal 12Mhz/12pF on Q1.

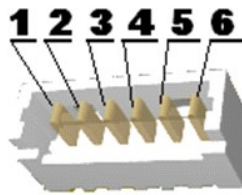


## SECTION 6 HARDWARE

### 6.1 Mini ICSP

The mini ICSP connector provides the interface for In-Circuit-Serial-Programming. The step between its pins is 0.05".

Pin #	Signal Name
1	RSTN/Vpp
2	+3.3V
3	GND
4	PGD
5	PGC
6	Not connected



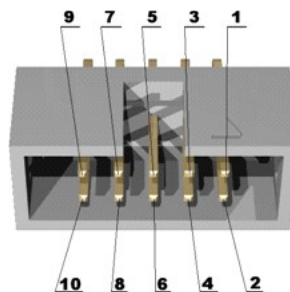
### 6.2 UEXT

PIC32-PINGUINO-MICRO board has UEXT connector and can interface Olimex's UEXT modules.

For more information on UEXT please visit:

<http://www.olimex.com/dev/OTHER/UEXT.pdf>

Pin #	Signal Name
1	+3.3V
2	GND
3	TXD
4	RXD
5	SCL
6	SDA



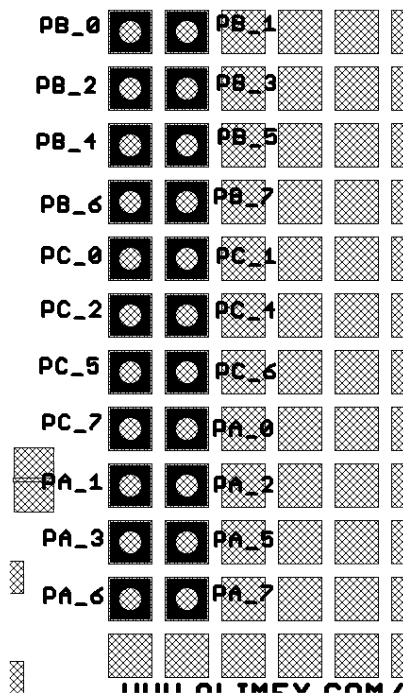
7	MISO
8	MOSI
9	SCK
10	CS

### 6.3 Pads on the proto area

For your convenience the pads are named individually near each of them. Please take extra care about the numbering.

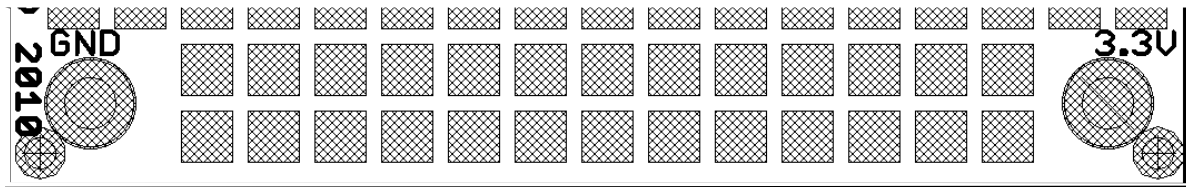
All pads are near the PIC18, except for GND and 3,3V pads.

PAD #	Signal Name
PB_0	USER (RB0/AN12/INT0/RP3)
PB_1	SCK
PB_2	MISO
PB_3	MOSI
PB_4	SCL
PB_5	SDA
PB_6	PGC
PB_7	PGD
PC_0	LED6
PC_1	LED5
PC_2	LED4
PC_4	D-
PC_5	D+
PC_6	TXD
PC_7	RXD
PA_0	LED0
PA_1	LED1
PA_2	LED2
PA_3	LED3
PA_5	LED7
PA_6	OSC2/CLK0 (to quartz pad)



PA_7	Vss OSC (quarz pad)
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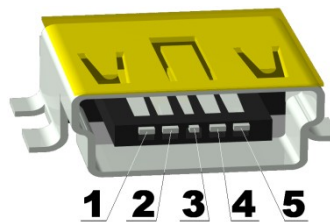
## 6.4 Power pads on the proto area



For your convenience the external power pads are named individually on the top of the board. Please take extra care about the naming.

## 6.5 Mini USB

Pin #	Signal Name
1	+5V_VBUS
2	D -
3	D +
4	Not connected
5	GND



## 6.6 Jumper description

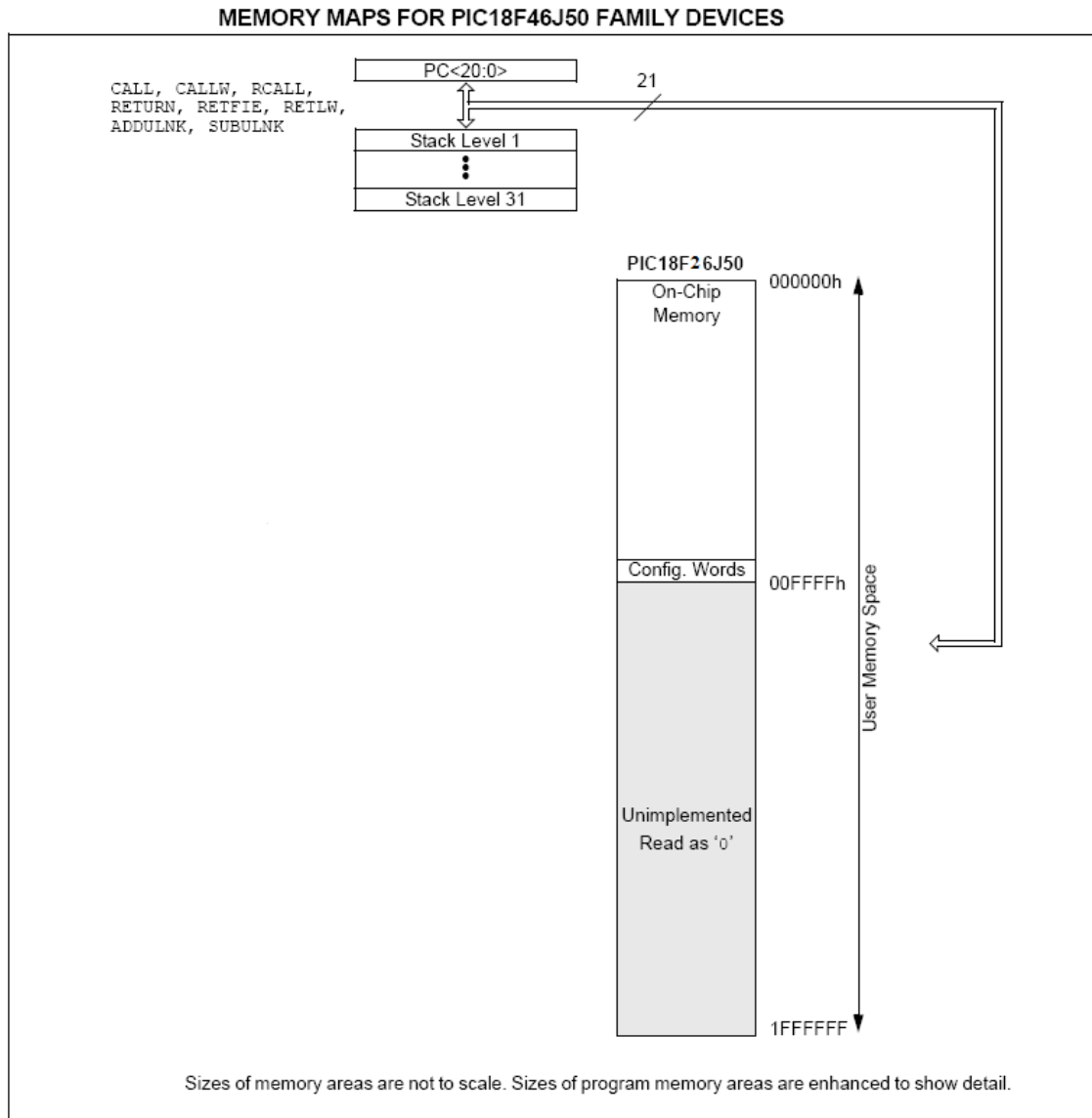
### VUSB\_3.3



This jumper, when closed, enables 3.3 V received from the USB. Default state is closed.

# SECTION 7 MEMORY

## 7.1 Memory map



## SECTION 8

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# SCHEMATICS

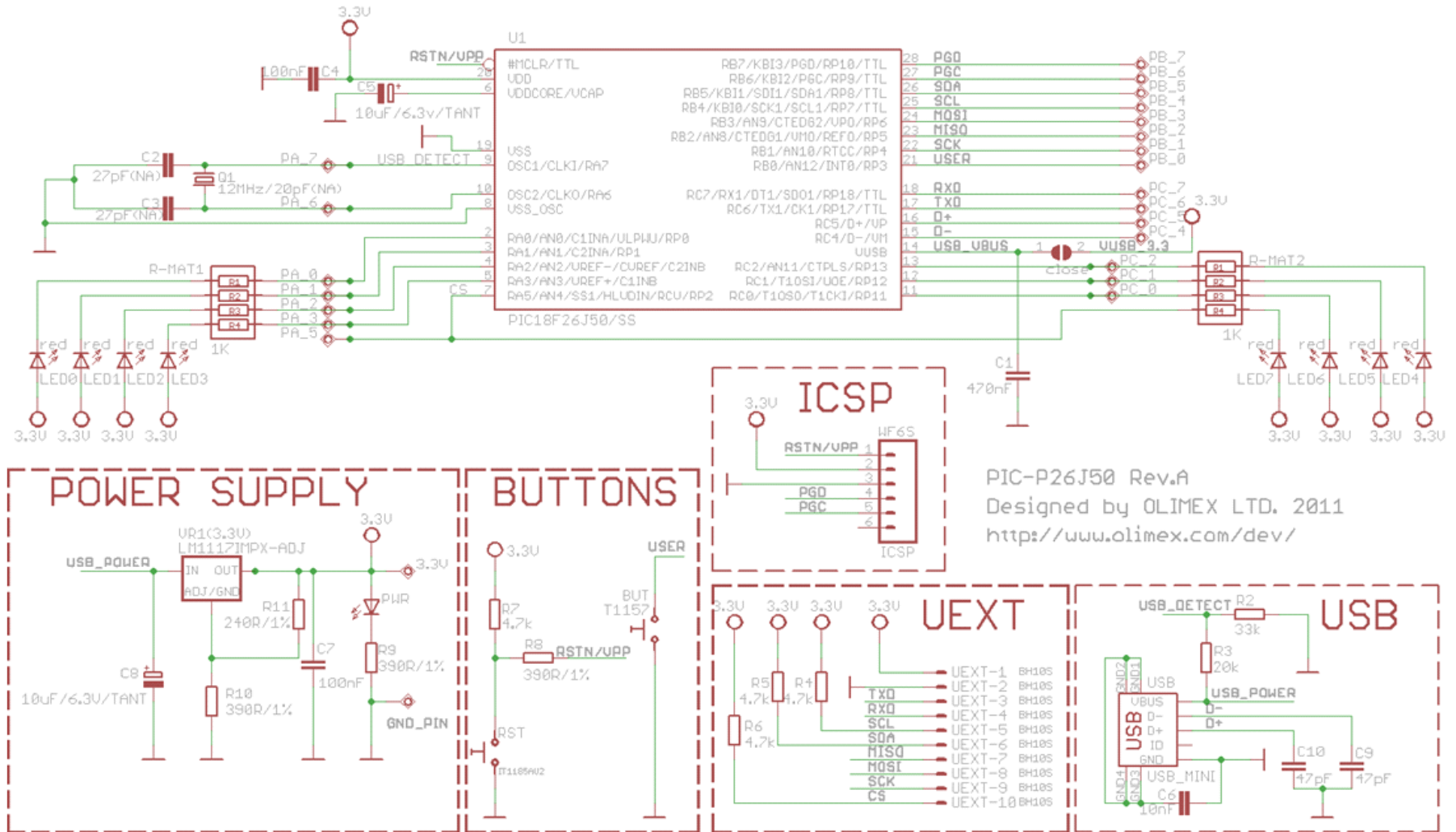
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### 8.1 Eagle schematic

PIC-P26J50 schematic is visible for reference here. You can also find them on separated in the web page for PIC-P26J50 on our site: <http://www.olimex.com/dev/pic-p26j50.html>. They are located in HARDWARE section.

The EAGLE schematic is situated on the next page for quicker reference.





## 8.2 Physical dimensions

Note: All dimensions are in inches!

