Sure Cross® QM30VT2 Vibration and Temperature Sensor



Datasheet

Continuously monitor machine health, run time, and detect unexpected machine failures such as early bearing failure, unbalance, misalignment, etc. with the Sure Cross Vibration and Temperature QM30VT2 Sensor. The QM30VT2 works in a variety of machines to identify and predict failures in rotating components. Paired with a Sure Cross wireless radio, the QM30VT2 becomes the ultimate predictive maintenance tool for wireless vibration and temperature monitoring.



- Detects dual-axis vibration up to 4 kHz bandwidth
- Output actionable data such as RMS Velocity, RMS High Frequency Acceleration, Peak Velocity, etc. which is pre-processed from the vibration waveforms in the sensor
- Provides high accuracy vibration and temperature measurements
- · Industrial grade sensor with small form factor to fit in the tightest locations
- Manufactured with stainless steel or aluminum housing, depending on the model
- Connects to a MultiHop Modbus radio or any Modbus network for easy set up and installation, even in the hardest to reach and rugged locations
- Functions as a Modbus slave device via RS-485

For additional information, updated documentation, and a list of accessories, refer to Banner Engineering's website, www.bannerengineering.com.

Models

| Model | Housing Type | Connections and Cable | I/O | |
|---------------|------------------------|--|-------------------------------|--|
| QM30VT2-SS-9M | 316L Stainless Steel | 9.1 m (30 ft) Flying Leads | | |
| QM30VT2-SS-QP | 3 TOL Stairliess Steel | 150 mm (6 in) cable with a 5-pin M12 male quick disconnect (QD) | Vibration and temperature via | |
| QM30VT2 | Aluminum | 2.09 m (6.85 ft) cable with a 5-pin M12 male quick disconnect (QD) | RS-485 Modbus | |
| QM30VT2-QP | | 150 mm (6 in) cable with a 5-pin M12 male quick disconnect (QD) | | |

The Sensor Configuration Software offers an easy way to manage sensor parameters, retrieve data, and visually show sensor data from a number of different sensors. The Sensor Configuration Software runs on any Windows machine and uses an adapter cable to connect the sensor to your computer. Download the most recent version of the software from Banner Engineering's website: www.bannerengineering.com and select **Software** from the **Products** drop-down list.

Configure this sensor using the Sensor Configuration Software (instruction manual p/n 170002) and USB to RS-485 adapter cable model **BWA-UCT-900** (datasheet p/n 140377). When updating the firmware, you must use one of the two USB to RS-485 adapter cables

Holding Registers

Aliased register addresses are user configurable. Aliased addressed registers are sequenced to be read with one single Modbus read.

| Register Alias | Modbus Register Address | Description | I/O Range | | Holding Register Representation | |
|----------------|-------------------------|--|-----------|--------|------------------------------------|-----------|
| Address | Address | | Min | Max | Min (dec) | Max (dec) |
| 45201 | 42401 | Z-Axis RMS Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 45202 | 42403 | Z-Axis RMS Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45203 | 40049 | Temperature (°F) ³ | -327.68 | 327.67 | -32768 | 32767 |
| 45204 | 40043 | Temperature (°C) ³ | -327.68 | 327.67 | -32768 | 32767 |
| 45205 | 42451 | X-Axis RMS Velocity (in/sec) 1, 5 | 0 | 6.5535 | 0 | 65535 |
| 45206 | 42453 | X-Axis RMS Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45207 | 42407 | Z-Axis Peak Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45208 | 42457 | X-Axis Peak Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45209 | 42405 | Z-Axis Peak Velocity Component Frequency (Hz) ⁴ , 5 | 0 | 6553.5 | 0 | 65535 |



| Modbus Register Alias Modbus Regis Address | | Description | I/O Range | | Holding Register Representation | |
|--|--|---|------------------------------------|---------------|------------------------------------|-----------|
| Address | Address | | Min | Max | Min (dec) | Max (dec) |
| 45210 | 42455 | X-Axis Peak Velocity Component Frequency (Hz) ^{4,} 5 | 0 | 6553.5 | 0 | 65535 |
| 45211 | 42406 | Z-Axis RMS Acceleration (G) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45212 | 42456 | X-Axis RMS Acceleration (G) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45213 | 42409 | Z-Axis Kurtosis ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45214 | 42459 | X-Axis Kurtosis ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45215 | 42408 | Z-Axis Crest Factor ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45216 | 42458 | X-Axis Crest Factor ² , ⁶ | 0 | 65.535 | 0 | 65535 |
| 45217 | 42402 | Z-Axis Peak Velocity (in/sec) ^{1, 5} | 0 | 6.5535 | 0 | 65535 |
| 45218 | 42404 | Z-Axis Peak Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45219 | 42452 | X-Axis Peak Velocity (in/sec) 1, 5 | 0 | 6.5535 | 0 | 65535 |
| 45220 | 42454 | X-Axis Peak Velocity (mm/sec) ^{2, 5} | 0 | 65.535 | 0 | 65535 |
| 45221 | 42410 | Z-Axis High-Frequency RMS Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| 45222 | 42460 | X-Axis High-Frequency RMS Acceleration (G) ^{2, 6} | 0 | 65.535 | 0 | 65535 |
| | 46101 | Baud | 0=9.6k, 1=19.2k (default), 2=38.4k | | ·k | |
| | 46102 | Parity | | 0=none (defau | lt), 1=odd, 2=ever | 1 |
| | 46103 | Modbus Slave Address | 1 (default) through 247 | | | |
| | 42601 | Rotational Speed (RPM) (default = 1725 RPM) Used in vibration spectral band measurements | 0 | 65535 | 0 | 65535 |
| | Rotational Speed (Hz) (default = 29 Hz) Used in vibration spectral band measurements | | 0 | 65535 | 0 | 65535 |

¹ Value = Register value ÷ 10000

By default, data is sampled every five seconds. The minimum recommended sample rate is three seconds. Use the Sensor Configuration Tool to adjust the sensor's sample rate if a different value is needed.

Temperature values outside of the operating range of the device are forced to the maximum or minimum values.

Installation Instructions

Connecting the Vibration/Temperature Sensor

To install the sensor to a device with a 5-pin M12 female connector:

- 1. Align the notch in the female connector with the key in the sensor's male connector.
- 2. Gently slide the sensor end into the connector.
- 3. Rotate the threaded nut to tighten the sensor down.

Wiring

This sensor is designed for use as a Modbus slave. This sensor can be plugged into any Modbus RS-485 network, including compatible MultiHop Data Radios. Flying lead models use the listed wire colors and sensor connections.

| 5-pin M12 Male Connector | Pin | Wire Color | Sensor Connection |
|--------------------------|-----|------------|--|
| | 1 | brown (bn) | Power IN (+): 10 to 30 V DC |
| 1 | 2 | white (wh) | RS485 / D1 / B / + |
| 1 4 | 3 | blue (bu) | Ground (-) |
| 3 5 | 4 | black (bk) | RS485 / D0 / A / – |
| | 5 | gray (gy) | Not Used. When updating the firmware, you must ground pin 5 by connecting it to pin 3. |

² Value = Register value ÷ 1000

³ Value = Register value ÷ 100

⁴ Value = Register value ÷ 10

⁵ Measurement bandwidth = 10 Hz to 1 kHz

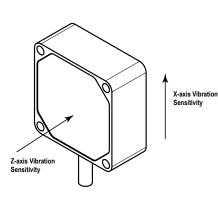
⁶ Measurement bandwidth = 1 kHz to 4 kHz

Installing the QM30VTx Sensor

The vibration sensors have an X and Z axis indication on the face of the sensor. Install the X axis (parallel to sensor) in line with the shaft of the motor or axially. Install the Z axis (plane of the sensor) to go into or through the motor or radial.

For the best results, install the sensor as close to the motor bearing as possible. If this is not possible, install the sensor on a surface that is in rigid connection with vibration characteristics of the motor. Using a cover shroud or other flexible mounting location may result in reduced accuracy or reduced ability to detect certain vibration characteristics. After determining the sensor direction and location, mount the sensor for the best possible vibration sensing accuracy.







| Mounting Options | QM30 Housing Type | Description |
|---|------------------------------|---|
| BWA-QM30-FTAL | Aluminum | When available, directly mounting the bracket to the motor using an 1/4-28 × 1/2-inch screw provides a rigid surface with the highest sensor accuracy and frequency response. This mounting option offers flexibility for future sensor and bracket movement. |
| | | Another mounting option is to use an epoxy to adhere the bracket to the motor. Banner recommends using an epoxy designed for accelerometer mounting, such as Loctite Depend 330 and 7388 activator. |
| BWA-QM30-FTSS | Stainless steel | Epoxying a bracket to a motor provides a permanent installation of the bracket to which the sensor can be attached. This more rigid mounting solution ensures some of the best sensor accuracy and frequency response, but is not flexible for future adjustments. |
| | | A third option is to use the included thermally conductive adhesive tape. This often provides a more than sufficient mounting type but does introduce some additional flex that reduces accuracy. |
| BWA-QM30-CEAL Curved bracket epoxied to the motor | Aluminum | This lightweight aluminum bracket provides a close connection to the motor with ridges to sit on curved surfaces and ensure a tight fit. The bracket is epoxied to the motor and the sensor is screwed into the bracket. |
| | | Gives a solid, strong, and adjustable mount to a motor, but with a motor's curved surface it may not provide the best connection if the motor is too small for the magnet to get a full connection with the motor housing. |
| BWA-QM30-FMSS Flat magnet bracket | Aluminum and stainless steel | Magnet mounts are susceptible to accident rotation or a change in the sensor location if an outside force bumps or moves the sensor. This can lead to a change in sensor information that differs from the time-trended data from the previous location. |
| | | The bracket is stainless steel and the magnet insert is neodymium. |
| | | Gives a solid, strong, and adjustable mount to a motor, intended for use when the flat magnetic bracket does not make a good connection with the motor's surface. |
| BWA-QM30-CMAL Curved surface magnet bracket | Aluminum and stainless steel | Magnet mounts are susceptible to accidental rotation or change in the sensor location if an outside force bumps or moves the sensor. This can lead to a change in the sensor information that differs from the time-trended data from the previous location. |
| | | The bracket is aluminum and the magnet insert is samarium-cobalt. |
| BWA-QM30-FSALR | Aluminum | This larger aluminum bracket mounts to the motor with a 1/4-28 × 1/2-inch screw to provide a rigid connection to the motor. On the right or left side, a set-screw is hand-tightened to secure the sensor to the bracket, allowing for rapid release and installation of a sensor compared to other mounting options. |
| BWA-QM30-FSSSR | Stainless steel | This larger stainless steel bracket mounts to the motor with a 1/4-28 × 1/2-inch screw to provide a rigid connection to the motor. A set-screw is hand-tightened to secure the sensor to the bracket, allowing for rapid release and installation of a sensor compared to other mounting options. |

Specifications

Supply Voltage

10 V DC to 30 V DC

Current

Active comms: 9 mA at 30 V DC

Communication

Interface: RS-485 serial

Baud rates: 9.6k, 19.2k (default), or 38.4k

Data format: 8 data bits, no parity (default), 1 stop bit (even or odd parity

available)
Protocol: Modbus RTU

Mounting Options

The sensor can be mounted using a variety of methods, including M4 × 0.7 hex screw, epoxy, thermal tape, or magnetic mount.

MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y, and Z axes, 18 shocks), with device operating

Certifications



Vibration Sensor

Measuring Range: 0 to 46 mm/sec or 0 to 1.8 in/sec RMS

Frequency Range: 10 Hz to 4 kHz Accuracy: ±10% at 25 °C

Sampling Frequency: 20 kHz (default) Record Length: 8192 points (default) Sample Duration: 0.4 s (default)

Temperature Sensor

Measuring Range: -40 °C to +105 °C (-40 °F to +221 °F)

Resolution: 1 °C Accuracy: ± 3 °C

Operating the sensor at higher voltages can induce internal heating that can reduce the accuracy.

Environmental Rating Stainless steel model: IP69K per DIN 40050-9

Aluminium model: IP67

Operating Temperature

-40 °C to +105 °C (-40 °F to +221 °F) 1



WARNING:

- Do not use this device for personnel protection
- Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A device failure or malfunction can cause either an energized (on) or deenergized (off) output condition.

Vibration Severity Per ISO 10816

ISO 10816 provides guidance for evaluating vibration velocity severity motors, pumps, fans, compressors, gear boxes, blowers, dryers, presses, and other machines that operate in the 10 to 1000 Hz frequency range.

Figure 2. Vibration Severity per ISO 10816

| | Machine | | Class I | Class II | Class III | Class IV |
|-------------------------|---------|------|----------------|-----------------|------------------------|-----------------------|
| | in/s | mm/s | Small Machines | Medium Machines | Large Rigid Foundation | Large Soft Foundation |
| | 0.01 | 0.28 | | | | |
| | 0.02 | 0.45 | | | | |
| · . | 0.03 | 0.71 | | good | | |
| Vr.m. | 0.04 | 1.12 | | | | |
| Vibration Velocity Vrms | 0.07 | 1.80 | | | | |
| Velo | 0.11 | 2.80 | | satisfactory | | |
| tion | 0.18 | 4.50 | | | | |
| ibra | 0.28 | 7.10 | | unsatisfactory | | |
| > | 0.44 | 11.2 | | | | |
| | 0.70 | 18.0 | | | | |
| | 1.10 | 28.0 | | unacceptable | | |
| | 1.77 | 45.9 | | | | |

Vibration Spectral Band Measurements

To use vibration spectral band measurements, follow the instructions in the Vibration Spectral Band Measurement Start Guide (p/n b 4510565).

Operating the devices at the maximum operating conditions for extended periods can shorten the life of the device.

Dimensions

All measurements are listed in millimeters [inches], unless noted otherwise.

Figure 3. Aluminium model

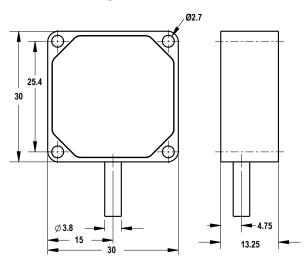
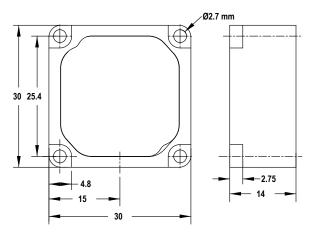


Figure 4. Stainless steel models



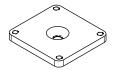
Accessories

Brackets

Bracket **BWA-QM30-FTAL** is included with the aluminium sensor models. Bracket **BWA-QM30-FTSS** is included with the stainless steel models. All other brackets are available for order, but are not included with the sensor.

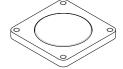
BWA-QM30-FTSS

- Use when measuring high frequency vibrations or when mounting the sensor to curved surfaces
- Includes SMBQM30 stainless steel bracket, four mounting screws, and one ½-28 ×1/2 screw mount
- 30 mm × 30 mm
- Refer to the Bracket Assembly Quick Start Guide for installation instructions (p/n 213323)



BWA-QM30-FMSS

- Includes magnetic mounting bracket SMBQM30 and four mounting screws (two sets of mounting screws for both the aluminum and stainless steel models)
- 30 mm × 30 mm
- Refer to the Bracket Assembly Quick Start Guide for installation instructions (p/n 213323)



BWA-QM30-FTAL

- Use when measuring high frequency vibrations or when mounting the sensor to curved surfaces
- Includes SMBQM30

 aluminum bracket, four mounting screws, one ¼-28
 × 1/2 screw mount, and one piece of 3M™ thermally conductive adhesive transfer tape
- 30 mm × 30 mm
- Refer to the Bracket Assembly Quick Start Guide for installation instructions (p/n 213323)



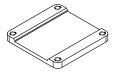
BWA-QM30-CMAL

- Magnet mount for curved surfaces
- 30 mm × 30 mm, 14.4 mm
- Includes four M2.5 × 16 mm socket head cap screws
- Refer to the Bracket
 Assembly Quick Start
 Guide for installation
 instructions (p/n 213323)



BWA-QM30-CEAL

- Glue-mount for curved surfaces
- Aluminum



BWA-QM30-FSALR Flat Surface Rapid Release Bracket (Aluminum)

- Aluminum
- Circular bracket with center
- screw for mounting the bracket to the motor Side set-screw for quick release mounting of the sensor to the bracket



BWA-QM30-FSSSR Flat Surface Rapid Release Bracket (Stainless Steel)

- Stainless steel
 Circular bracket with center screw for mounting the bracket to the motor
- Side set-screw for quick release mounting of the sensor to the bracket



Cordsets

| 5-Pin Threaded M12 Cordsets—Single Ended | | | | | | | |
|--|----------------|-------------|--|--|--|--|--|
| Model | Length | Style | Dimensions | Pinout (Female) | | | |
| MQDC1-501.5 | 0.5 m (1.5 ft) | | | | | | |
| MQDC1-503 | 0.9 m (2.9 ft) | | 44 Typ | | | | |
| MQDC1-506 | 2 m (6.5 ft) | Straight | | | | | |
| MQDC1-515 | 5 m (16.4 ft) | Straight | M42 v.4 | | | | |
| MQDC1-530 | 9 m (29.5 ft) | | M12 x 1 — 9 14.5 — | 1 (000) 3 5 | | | |
| MQDC1-560 | 18 m (59 ft) | | | | | | |
| MQDC1-506RA | 2 m (6.5 ft) | | | | | | |
| MQDC1-515RA | 5 m (16.4 ft) | | 32 Typ. | | | | |
| MQDC1-530RA | 9 m (29.5 ft) | | [1.26"] | 1 = Brown | | | |
| MQDC1-560RA | 19 m (62.3 ft) | Right-Angle | 30 Typ. [1.18"] M12 x 1 ø 14.5 [0.57"] | 2 = White 3 = Blue 4 = Black 5 = Gray | | | |

| 5-Pin Threaded M12 Cordsets—Double Ended | | | | | | | | |
|--|---------------------|-----------------|-----------------------|------------------------|-----------------|--|--|--|
| Model | Length | Style | Dimensions | Pinout (Male) | Pinout (Female) | | | |
| MQDEC-501SS | 0.31 m (1.02 ft) | | 40 Typ. —— | 2 4 5 | 1 2 3 3 5 | | | |
| MQDEC-503SS | 0.91 m (2.99 ft) | Male Straight/ | M12 x 1 J Ø 14.5 J | | | | | |
| MQDEC-506SS | 1.83 m (6 ft) | Female Straight | 44 Typ. ——— | 4 5 | | | | |
| MQDEC-512SS | 3.66 m (12 ft) | | | 1 = Brown 2 = White | 4 = Black | | | |
| MQDEC-515SS | 5 m (16.4 ft) | | M12 x 1 | 3 = Blue | 5 = Gray | | | |
| MQDEC-530SS | 9 m (29.5 ft) | | ø 14.5 | | | | | |
| MQDEC-550SS | 15 m (49.2 ft) | | | | | | | |

| 5-Pin M12 Shielded Twi | | | | |
|------------------------|----------------|----------|---------------------|--|
| Model | Length | Style | Dimensions | Pinout (Female) |
| MQDC-STP-501 | 0.31 m (1 ft) | | | 2 |
| MQDC-STP-503 | 0.92 m (3 ft) | | 44 Typ. ——— | 1 (000) |
| MQDC-STP-506 | 1.83 m (6 ft) | | | 4 3 5 |
| MQDC-STP-515 | 4.57 m (15 ft) | Straight | | 1 = Brown |
| MQDC-STP-530 | 9.15 m (30 ft) | | M12×1 → ø 14.5 → | 2 = White 3 = Blue 4 = Black 5 = Shield |

| 5-Pin Threaded M12 Shielded Twisted Pair Cordsets—Double Ended | | | | | | | | |
|--|---------------------|-----------------|---------------|------------------------------------|-------------------------|--|--|--|
| Model | Length | Style | Dimensions | Pinout (Male) | Pinout (Female) | | | |
| MQDEC-STP-501SS | 0.31 m (1 ft) | | 40 Typ. | | | | | |
| MQDEC-STP-503SS | 0.91 m (2.99 ft) | | | 2 | 1 (00) | | | |
| MQDEC-STP-506SS | 1.83 m (6 ft) | Male Straight/ | M12 x 1 — | 3 5 | 4 5 | | | |
| MQDEC-STP-515SS | 4.58 m (15 ft) | Female Straight | Wale Straight | | | | | |
| MQDEC-STP-530SS | 10 m (32.8 ft) | | | , _ | | | | |
| MQDEC-STP-550SS | 15 m (49.2 ft) | | | 1 = Brown 2 = White 3 = Blue | 4 = Black 5 = Shield | | | |

| 5-Pin Threaded M12 Stainless Steel Washdown Cordsets—Single Ended | | | | | | | |
|---|---------------|----------|------------------|---|--|--|--|
| Model | Length | Style | Dimensions | Pinout (Female) | | | |
| MQDC-WDSS-0506 | 2 m (6.56 ft) | | | € -2 | | | |
| MQDC-WDSS-0515 | 5 m (16.4 ft) | | | 1 (000) | | | |
| MQDC-WDSS-0530 | 9 m (29.5 ft) | Straight | Ø15.5 mm Ø4.8 mm | 1 = Brown 2 = White 3 = Blue 4 = Black 5 = Gray | | | |

| 5-Pin Threaded M12 Stainless Steel Washdown Cordsets—Double Ended | | | | | | | | |
|---|------------------|-------------------|--|------------------------------------|-----------------------|--|--|--|
| Model | Length | Style | Dimensions | Pinout (Male) | Pinout (Female) | | | |
| MQDEC-WDSS-505SS | 1.52 m (4.99 ft) | Male Straight/ | 40 Typ. ———————————————————————————————————— | 2 4 | 1 (00) 3 4 5 | | | |
| MQDEC-WDSS-510SS | 3.05 m (10 ft) | Female Straight | 1 | | | | | |
| MQDEC-WDSS-515SS | 4.57 m (15 ft) | r cindic Straight | 44 Typ. M12 x 1 g 14.5 | 1 = Brown 2 = White 3 = Blue | 4 = Black 5 = Gray | | | |

| 5-Pin Threaded M12 Splitter Tee | | | | |
|---------------------------------|--|--|--|-----------------|
| Model | Description | | Pinout (Male) | Pinout (Female) |
| CSB-M1250M1250-T | Female trunk, 1 female branch, 1 male branch | | 2 4 3 5 1 = Brown 2 = White 3 = Blue | 1 |