

## 1A, 1.5MHz, 6V CMCOT Synchronous Step-Down Converter

### General Description

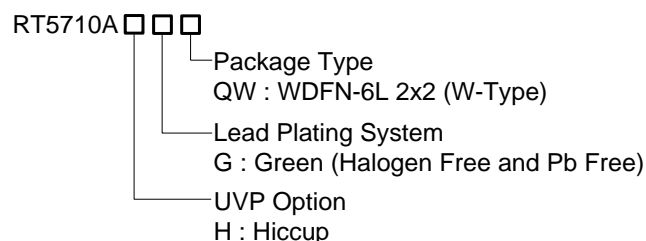
The RT5710A is a high efficiency synchronous step-down DC-DC converter. Its input voltage range is from 2.5V to 6V and provides an adjustable regulated output voltage from 0.6V to 3.4V while delivering up to 1A of output current.

The internal synchronous low on-resistance power switches increase efficiency and eliminate the need for an external Schottky diode. The Current Mode Constant-On-time (CMCOT) operation with internal compensation allows the transient response to be optimized over a wide range of loads and output capacitors.

### Applications

- STB, Cable Modem, & xDSL Platforms
- LCD TV Power Supply & Metering Platforms
- General Purpose Point of Load (POL)

### Ordering Information



Note :

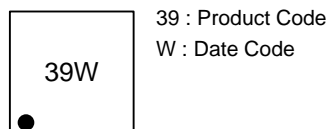
Richtek products are :

- ▶ RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

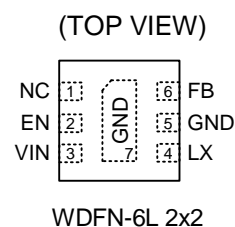
### Features

- Efficiency Up to 95%
- $R_{DS(on)}$  160mΩ HS / 110mΩ LS
- $V_{IN}$  Range 2.5V to 6V
- $V_{REF}$  0.6V with  $\pm 2\%$  Accuracy
- CMCOT™ Control Loop Design for Best Transient Response, Robust Loop Stability with Low-ESR (MLCC)  $C_{OUT}$
- Fixed Soft-Start 1.2ms
- Cycle-by-Cycle Over-Current Protection
- Input Under-Voltage Lockout
- Output Under-Voltage Protection (UVP Hiccup)
- Thermal Shutdown Protection
- Power Saving at Light Load

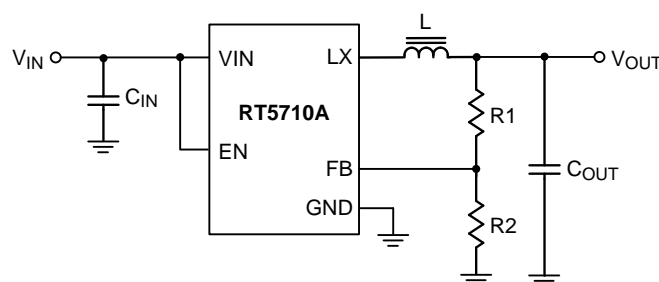
### Marking Information



### Pin Configuration



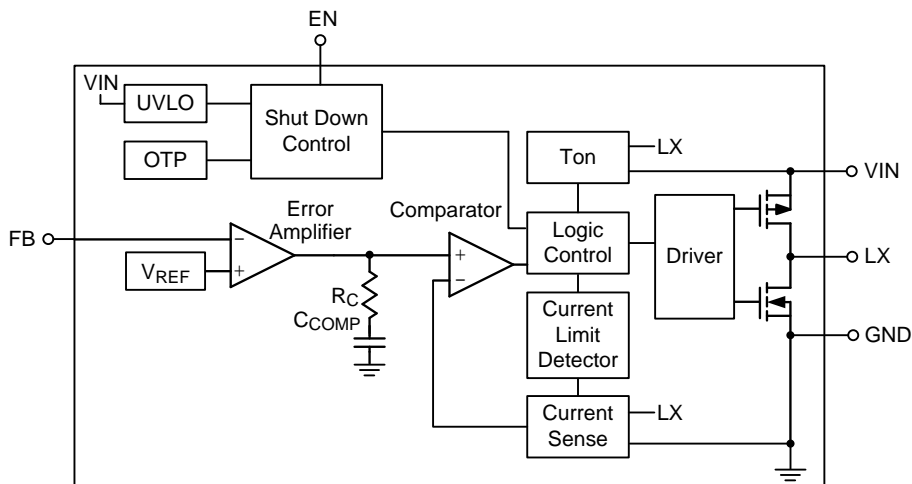
### Simplified Application Circuit



## Functional Pin Description

Pin No.	Pin Name	Pin Function
1	NC	No internal connection.
2	EN	Enable control input.
3	VIN	Supply voltage input. The RT5710A operates from a 2.5V to 6V input.
4	LX	Switch node.
5, 7 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum thermal dissipation.
6	FB	Feedback.

## Functional Block Diagram



## Operation

The RT5710A is a synchronous low voltage step-down converter that can support the input voltage range from 2.5V to 6V and the output current can be up to 1A. The RT5710A uses a constant on-time, current mode architecture. In normal operation, the high-side P-MOSFET is turned on when the switch controller is set by the comparator and is turned off when the Ton comparator resets the switch controller.

Low-side MOSFET peak current is measured by internal RSENSE. The error amplifier EA adjusts COMP voltage by comparing the feedback signal ( $V_{FB}$ ) from the output voltage with the internal 0.6V reference. When the load current increases, it causes a drop in the feedback voltage relative to the reference, then the COMP voltage rises to allow higher inductor current to match the load current.

### UV Comparator

If the feedback voltage ( $V_{FB}$ ) is lower than threshold voltage 0.2V, the UV comparator's output will go high and the switch controller will turn off the high-side MOSFET. The output under-voltage protection is designed to operate in Hiccup mode.

### Enable Comparator

A logic-high enables the converter; a logic-low forces the IC into shutdown mode.

### Soft-Start (SS)

An internal current source charges an internal capacitor to build the soft-start ramp voltage. The  $V_{FB}$  voltage will track the internal ramp voltage during soft-start interval. The typical soft-start time is 1.2ms.

**Over-Current Protection (OCP)**

The RT5710A provides over-current protection by detecting low-side MOSFET valley inductor current. If the sensed valley inductor current is over the current limit threshold (1.5A typ.), the OCP will be triggered. When OCP is tripped, the RT5710A will keep the over current threshold level until the over current condition is removed.

**Thermal Shutdown (OTP)**

The device implements an internal thermal shutdown function when the junction temperature exceeds 150°C. The thermal shutdown forces the device to stop switching when the junction temperature exceeds the thermal shutdown threshold. Once the die temperature decreases below the hysteresis of 20°C, the device reinstates the power up sequence.

## Absolute Maximum Ratings (Note 1)

• Supply Input Voltage	-----	-0.3V to 6.5V
• LX Pin Switch Voltage	-----	-0.3V to (V <sub>IN</sub> + 0.3V)
<20ns	-----	-4.5V to 7.5V
• Power Dissipation, P <sub>D</sub> @ T <sub>A</sub> = 25°C		
WDFN-6L 2x2	-----	0.833W
• Package Thermal Resistance (Note 2)		
WDFN-6L 2x2, θ <sub>JA</sub>	-----	120°C/W
WDFN-6L 2x2, θ <sub>JC</sub>	-----	7°C/W
• Lead Temperature (Soldering, 10 sec.)	-----	260°C
• Junction Temperature	-----	-40°C to 150°C
• Storage Temperature Range	-----	-65°C to 150°C
• ESD Susceptibility (Note 3)		
HBM (Human Body Model)	-----	2kV

## Recommended Operating Conditions (Note 4)

• Supply Input Voltage	-----	2.5V to 6V
• Ambient Temperature Range	-----	-40°C to 85°C
• Junction Temperature Range	-----	-40°C to 125°C

## Electrical Characteristics

(V<sub>IN</sub> = 3.6V, T<sub>A</sub> = 25°C, unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Input Voltage	V <sub>IN</sub>		2.5	--	6	V
Feedback Reference Voltage	V <sub>REF</sub>		0.588	0.6	0.612	V
Feedback Leakage Current	I <sub>FB</sub>	V <sub>FB</sub> = 0.6V	--	--	0.1	μA
DC Bias Current		Active, V <sub>FB</sub> = 0.63V, not switching	--	22	--	μA
		Shutdown	--	--	1	
Switching Leakage Current			--	--	1	μA
Switching Frequency			--	1.5	--	MHz
Switch On Resistance, High	R <sub>PMOS</sub>	I <sub>SW</sub> = 0.3A	--	160	--	mΩ
Switch On Resistance, Low	R <sub>NMOS</sub>	I <sub>SW</sub> = 0.3A	--	110	--	mΩ
Valley Current Limit	I <sub>LIM</sub>		1.1	1.5	2	A
Under-Voltage Lockout Threshold	V <sub>UVLO</sub>	V <sub>DD</sub> rising	--	2.25	2.5	V
		V <sub>DD</sub> falling	--	2	--	
Over-Temperature Threshold			--	150	--	°C
Enable Input Voltage	Logic-High	V <sub>IH</sub>	1.5	--	--	V
	Logic-Low	V <sub>IL</sub>	--	--	0.4	
Soft-Start Time	t <sub>SS</sub>		--	1.2	--	ms

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Minimum Off Time			--	120	--	ns
Output Discharge Switch On Resistance			--	1.8	--	kΩ

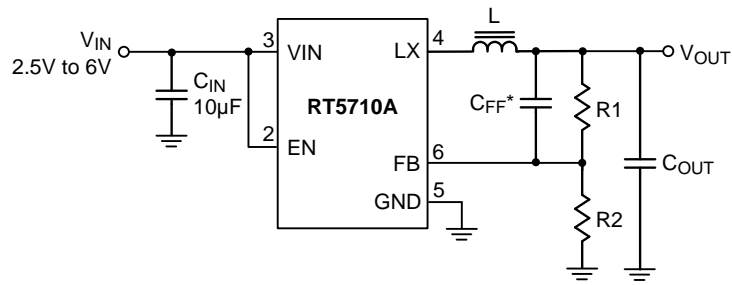
**Note 1.** Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

**Note 2.**  $\theta_{JA}$  is measured under natural convection (still air) at  $T_A = 25^\circ\text{C}$  with the component mounted on a high effective-thermal-conductivity four-layer test board on a JEDEC 51-7 thermal measurement standard.  $\theta_{JC}$  is measured at the exposed pad of the package.

**Note 3.** Devices are ESD sensitive. Handling precaution recommended.

**Note 4.** The device is not guaranteed to function outside its operating conditions.

## Typical Application Circuit

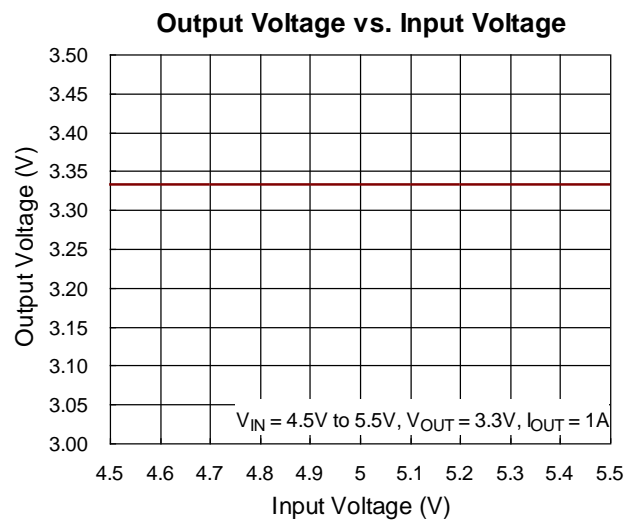
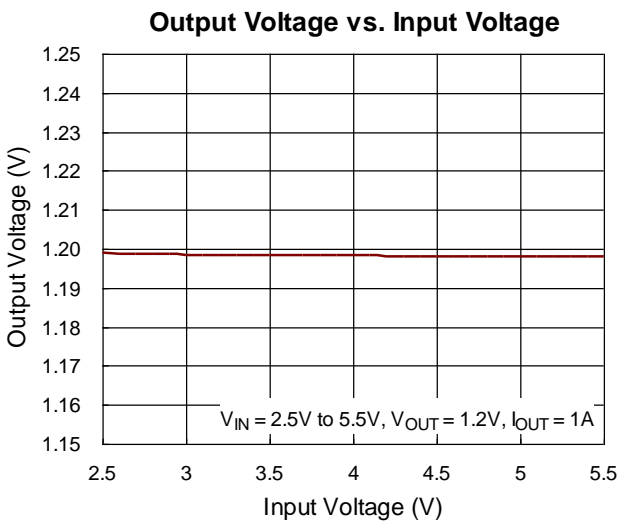
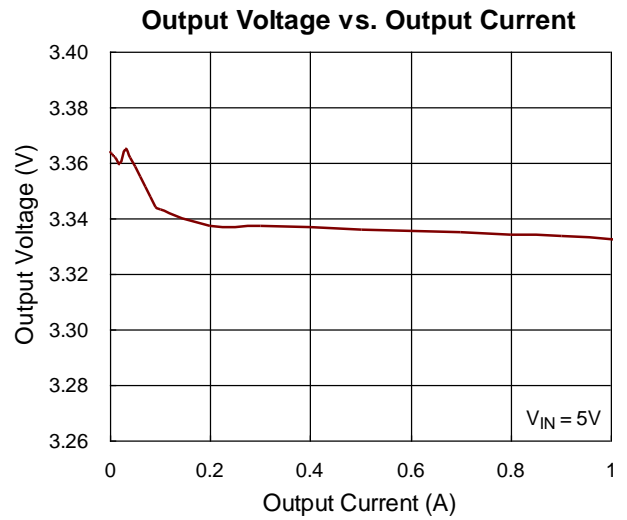
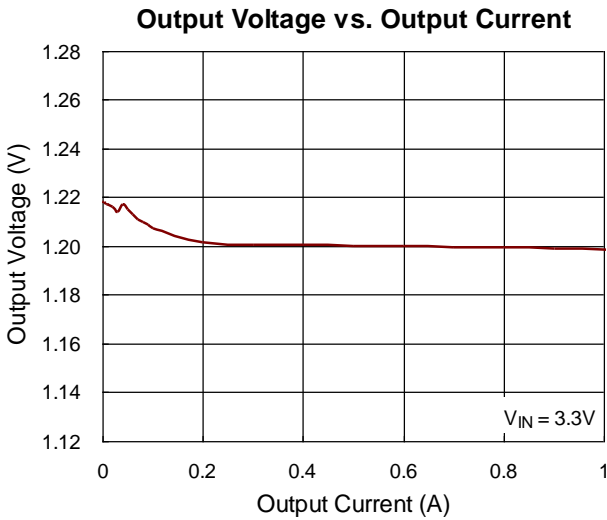
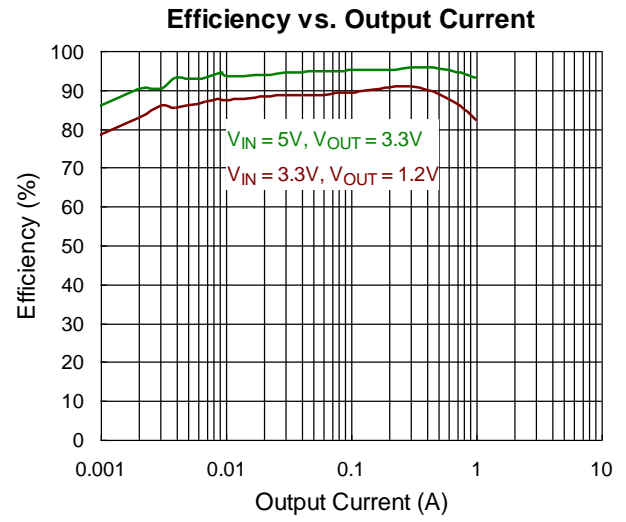
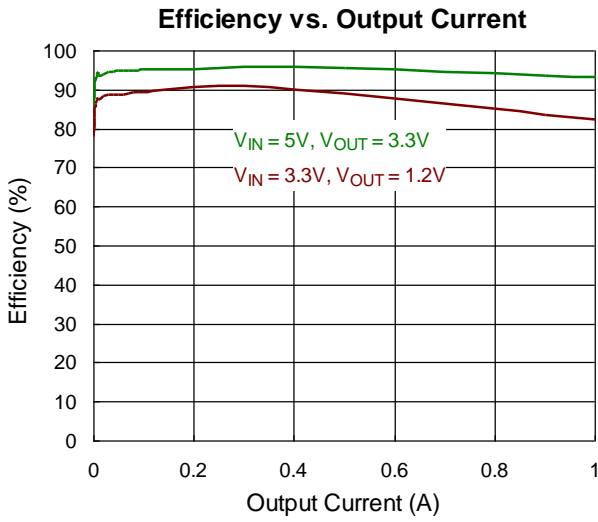


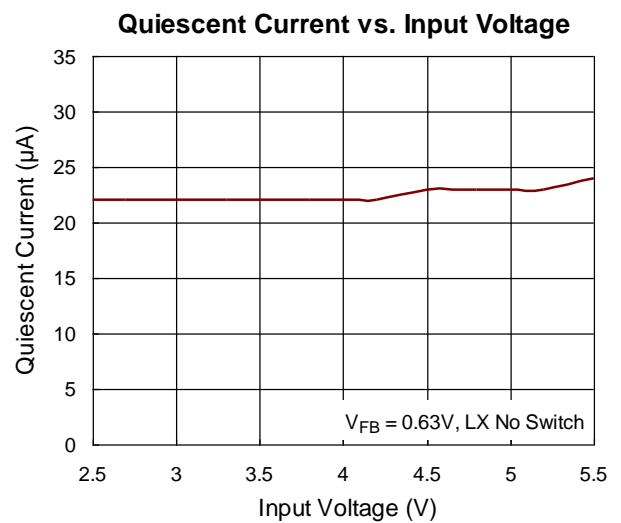
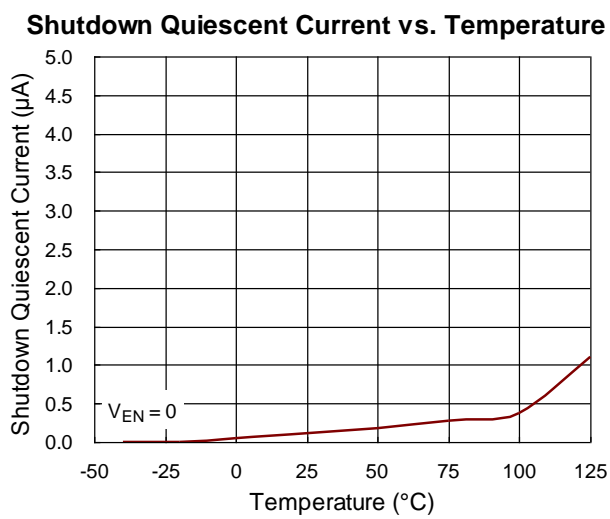
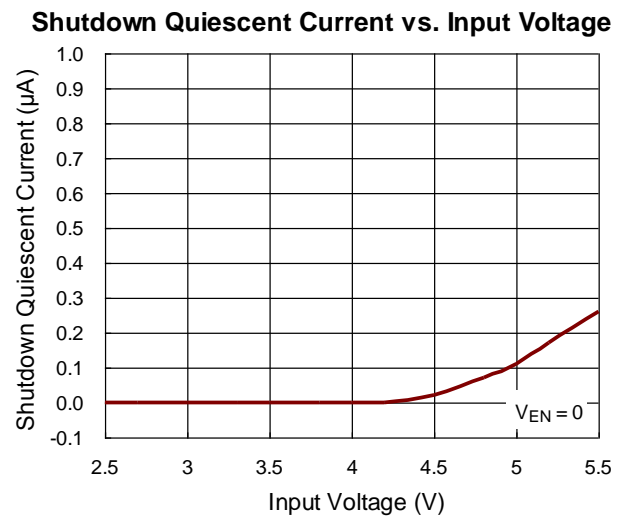
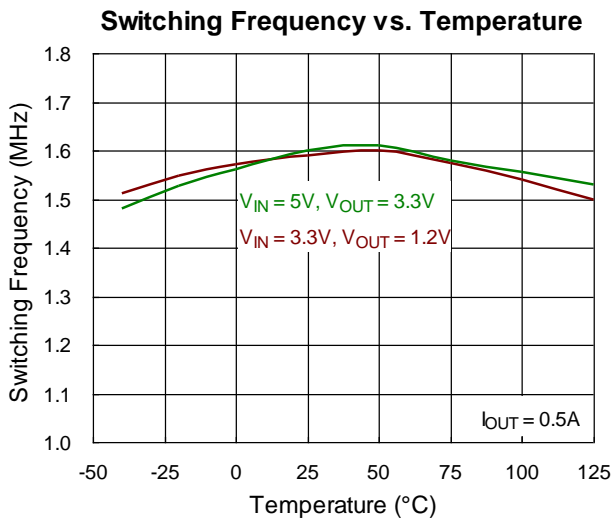
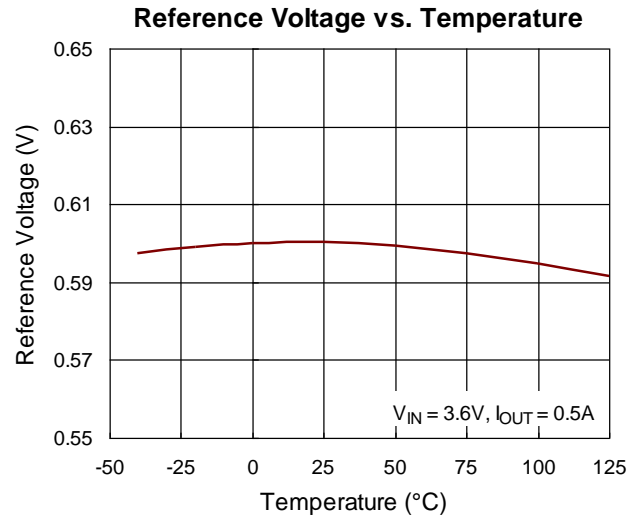
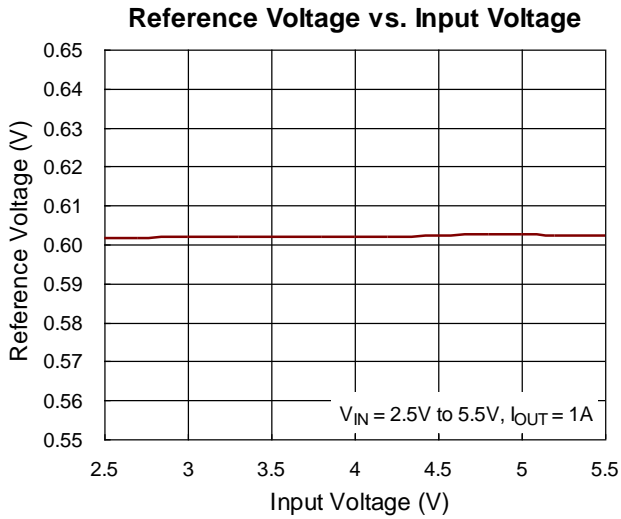
\*CFF : Optional for performance fine-tune

**Table 1. Suggested Component Values**

V <sub>OUT</sub> (V)	R1 (kΩ)	R2 (kΩ)	L (μH)	C <sub>OUT</sub> (μF)
3.3	90	20	1.5	10
1.8	100	50	1.5	10
1.5	100	66.6	1.5	10
1.2	100	100	1.5	10
1.05	100	133	1.5	10
1	100	148	1.5	10

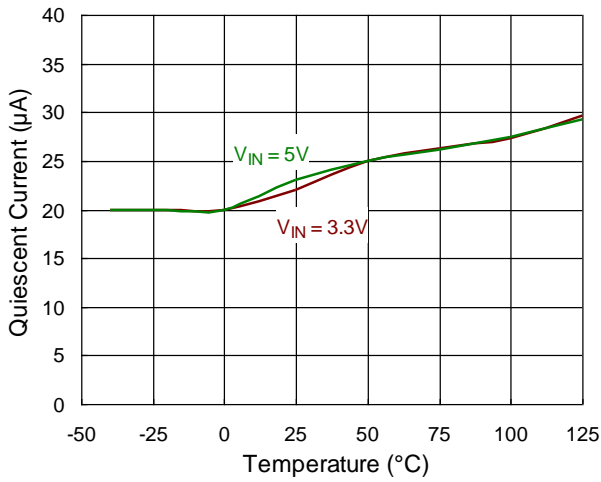
**Typical Operating Characteristics**



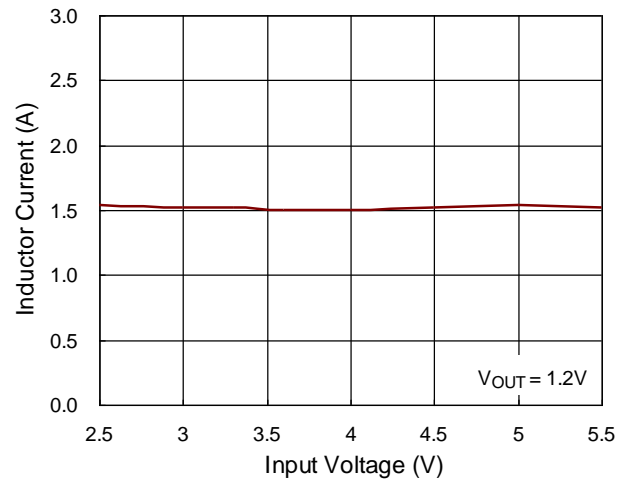




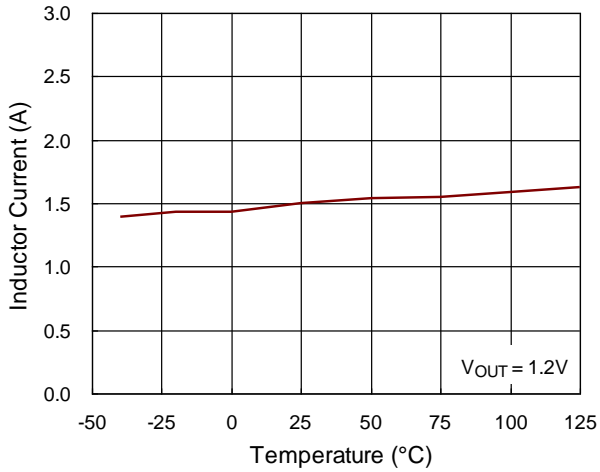
**Quiescent Current vs. Temperature**



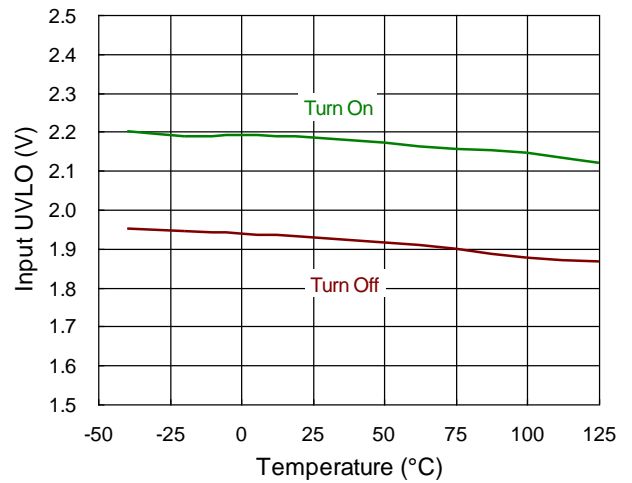
**Inductor Current Limit vs. Input Voltage**



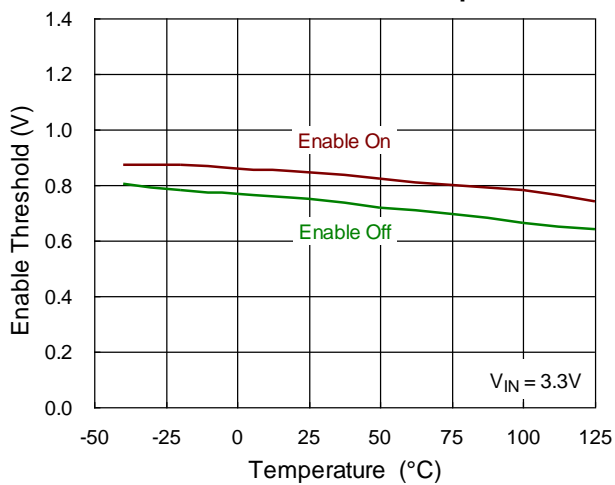
**Inductor Current Limit vs. Temperature**



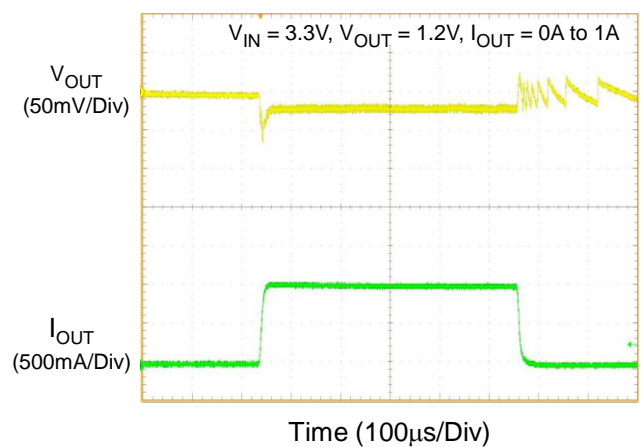
**Input UVLO vs. Temperature**



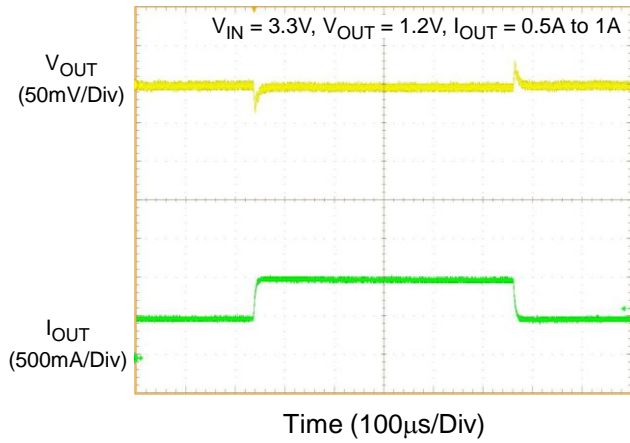
**Enable Threshold vs. Temperature**



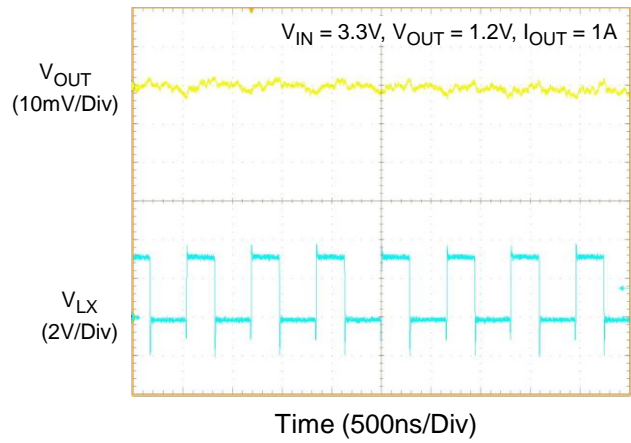
**Load Transient Response**



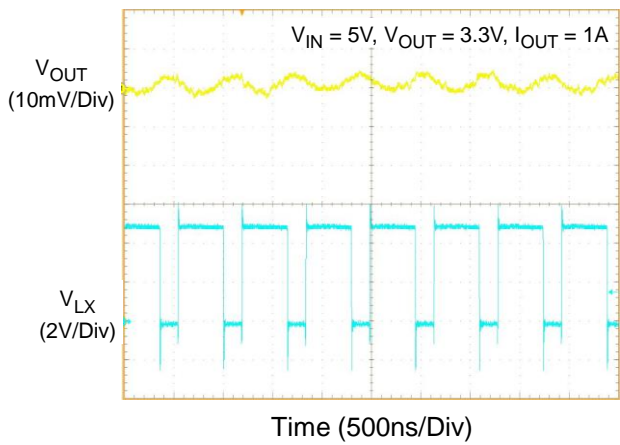
### Load Transient Response



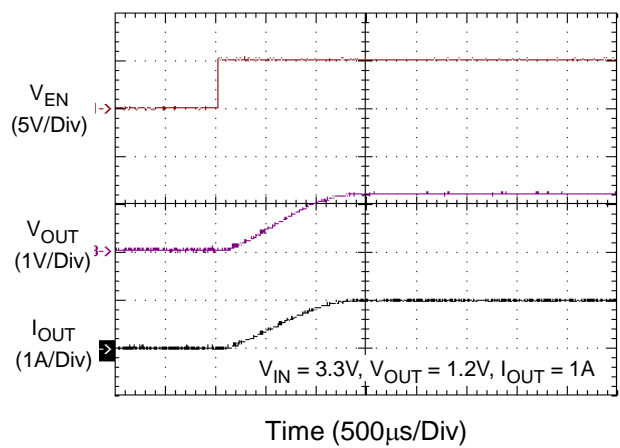
### Voltage Ripple



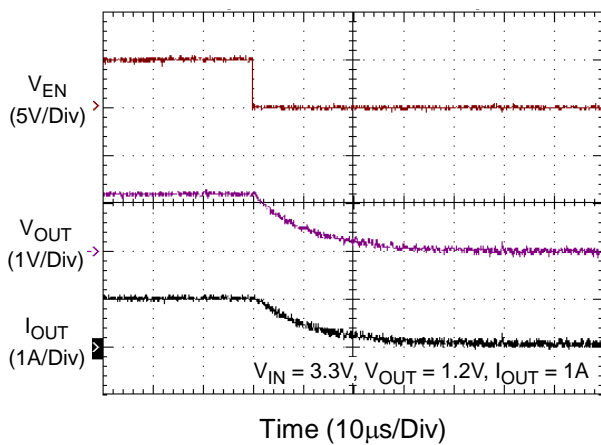
### Voltage Ripple



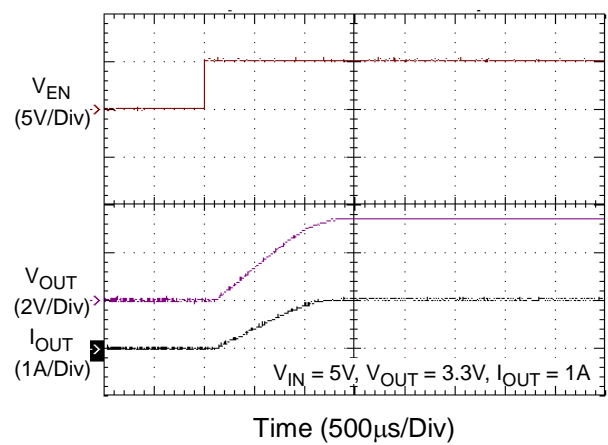
### Power On from EN



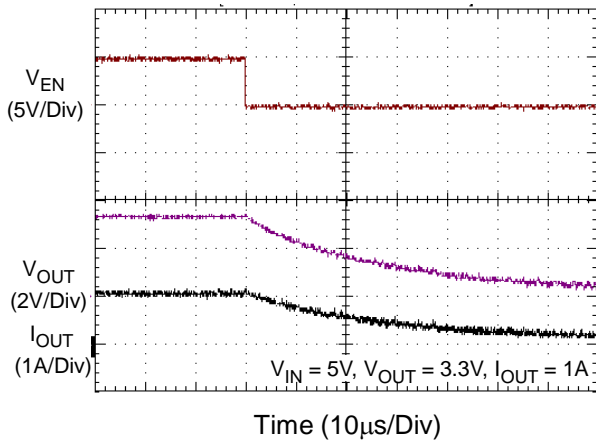
### Power Off from EN



### Power On from EN



Power Off from EN



## Application Information

The RT5710A is a single-phase step-down converter. It provides single feedback loop, constant on-time current mode control with fast transient response. An internal 0.6V reference allows the output voltage to be precisely regulated for low output voltage applications. A fixed switching frequency (1.5MHz) oscillator and internal compensation are integrated to minimize external component count. Protection features include over-current protection, under-voltage protection and over-temperature protection.

### Output Voltage Setting

Connect a resistive voltage divider at the FB between  $V_{OUT}$  and GND to adjust the output voltage. The output voltage is set according to the following equation :

$$V_{OUT} = V_{REF} \times \left(1 + \frac{R1}{R2}\right)$$

where  $V_{REF}$  is the feedback reference voltage 0.6V (typ.).

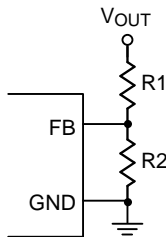


Figure 1. Setting  $V_{OUT}$  with a Voltage Divider

### Chip Enable and Disable

The EN pin allows for power sequencing between the controller bias voltage and another voltage rail. The RT5710A remains in shutdown if the EN pin is lower than 400mV. When the EN pin rises above the  $V_{EN}$  trip point, the RT5710A begins a new initialization and soft-start cycle.

### Internal Soft-Start

The RT5710A provides an internal soft-start function to prevent large inrush current and output voltage overshoot when the converter starts up. The soft-start (SS) automatically begins once the chip is enabled. During soft-start, the internal soft-start capacitor becomes charged and generates a linear ramping up voltage across the capacitor. This voltage clamps the

voltage at the FB pin, causing PWM pulse width to increase slowly and in turn reduce the input surge current. The internal 0.6V reference takes over the loop control once the internal ramping-up voltage becomes higher than 0.6V.

### UVLO Protection

The RT5710A has input Under Voltage Lockout protection (UVLO). If the input voltage exceeds the UVLO rising threshold voltage (2.25V typ.), the converter resets and prepares the PWM for operation. If the input voltage falls below the UVLO falling threshold voltage during normal operation, the device will stop switching. The UVLO rising and falling threshold voltage has a hysteresis to prevent noise-caused reset.

### Inductor Selection

The switching frequency (on-time) and operating point (% ripple or LIR) determine the inductor value as shown below :

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{f_{SW} \times LIR \times I_{LOAD(MAX)} \times V_{IN}}$$

where LIR is the ratio of the peak-to-peak ripple current to the average inductor current.

Find a low loss inductor having the lowest possible DC resistance that fits in the allotted dimensions. The core must be large enough not to saturate at the peak inductor current ( $I_{PEAK}$ ) :

$$I_{PEAK} = I_{LOAD(MAX)} + \left(\frac{LIR}{2} \times I_{LOAD(MAX)}\right)$$

The calculation above serves as a general reference. To further improve transient response, the output inductor can be further reduced. This relation should be considered along with the selection of the output capacitor.

Inductor saturation current should be chosen over IC's current limit.

### Input Capacitor Selection

High quality ceramic input decoupling capacitor, such as X5R or X7R, with values greater than 10 $\mu$ F are recommended for the input capacitor. The X5R and

X7R ceramic capacitors are usually selected for power regulator capacitors because the dielectric material has less capacitance variation and more temperature stability.

Voltage rating and current rating are the key parameters when selecting an input capacitor. Generally, selecting an input capacitor with voltage rating 1.5 times greater than the maximum input voltage is a conservatively safe design.

The input capacitor is used to supply the input RMS current, which can be approximately calculated using the following equation :

$$I_{IN\_RMS} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$

The next step is selecting a proper capacitor for RMS current rating. One good design uses more than one capacitor with low equivalent series resistance (ESR) in parallel to form a capacitor bank.

The input capacitance value determines the input ripple voltage of the regulator. The input voltage ripple can be approximately calculated using the following equation :

$$\Delta V_{IN} = \frac{I_{OUT(MAX)}}{C_{IN} \times f_{SW}} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

**Output Capacitor Selection**

The output capacitor and the inductor form a low pass filter in the Buck topology. In steady state condition, the ripple current flowing into/out of the capacitor results in ripple voltage. The output voltage ripple ( $V_{P-P}$ ) can be calculated by the following equation :

$$V_{P-P} = LIR \times I_{LOAD(MAX)} \times \left(ESR + \frac{1}{8 \times C_{OUT} \times f_{SW}}\right)$$

When load transient occurs, the output capacitor supplies the load current before the controller can respond. Therefore, the ESR will dominate the output voltage sag during load transient. The output voltage undershoot ( $V_{SAG}$ ) can be calculated by the following equation :

$$V_{SAG} = \Delta I_{LOAD} \times ESR$$

For a given output voltage sag specification, the ESR value can be determined.

Another parameter that has influence on the output voltage sag is the equivalent series inductance (ESL). The rapid change in load current results in di/dt during transient. Therefore, the ESL contributes to part of the voltage sag. Using a capacitor with low ESL can obtain better transient performance. Generally, using several capacitors connected in parallel can have better transient performance than using a single capacitor for the same total ESR.

**Thermal Considerations**

The junction temperature should never exceed the absolute maximum junction temperature  $T_{J(MAX)}$ , listed under Absolute Maximum Ratings, to avoid permanent damage to the device. The maximum allowable power dissipation depends on the thermal resistance of the IC package, the PCB layout, the rate of surrounding airflow, and the difference between the junction and ambient temperatures. The maximum power dissipation can be calculated using the following formula :

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction-to-ambient thermal resistance.

For continuous operation, the maximum operating junction temperature indicated under Recommended Operating Conditions is 125°C. The junction-to-ambient thermal resistance,  $\theta_{JA}$ , is highly package dependent. For WDFN-6L 2x2 package, the thermal resistance,  $\theta_{JA}$ , is 120°C/W on a standard JEDEC 51-7 high effective-thermal-conductivity four-layer test board. The maximum power dissipation at  $T_A = 25^\circ\text{C}$  can be calculated as below :

$$P_{D(MAX)} = (125^\circ\text{C} - 25^\circ\text{C}) / (120^\circ\text{C/W}) = 0.833\text{W for a WDFN-6L 2x2 package.}$$

The maximum power dissipation depends on the operating ambient temperature for the fixed  $T_{J(MAX)}$  and the thermal resistance,  $\theta_{JA}$ . The derating curve in Figure 2 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

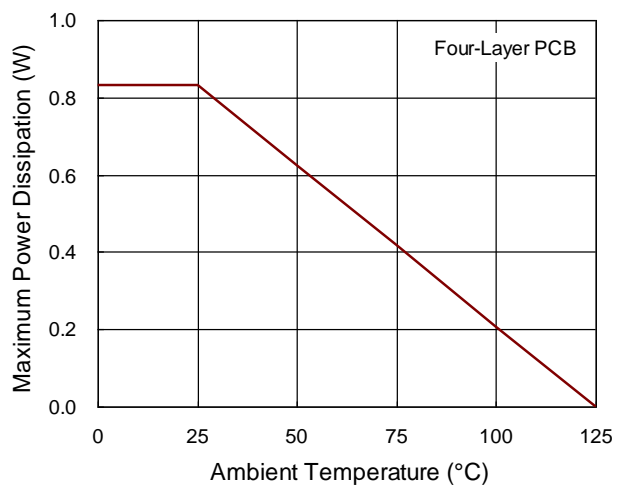


Figure 2. Derating Curve of Maximum Power Dissipation