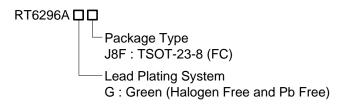


# 2A, 17V Current Mode Synchronous Step-Down Converter

### **General Description**

The RT6296A is a high-efficiency, 2A current mode synchronous step-down DC-DC converter with a wide input voltage range from 4.5V to 17V. The device integrates  $100m\Omega$  high-side and  $40m\Omega$  low-side MOSFETs to achieve high efficiency conversion. The current mode control architecture supports fast transient response and internal compensation. The RT6296A provides TTH pin to adjust transition point from PSM to PWM in order to balance efficiency and output ripple. A cycle-by-cycle current limit function provides protection against shorted output. The RT6296A provides complete protection functions such as input under-voltage lockout, output under-voltage protection, over-current protection, and thermal shutdown. The PWM frequency is adjustable by the EN/SYNC pin. The RT6296A is available in the TSOT-23-8 (FC) package.

# **Ordering Information**



#### Note:

#### Richtek products are:

- ► RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

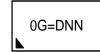
### **Features**

- 4.5V to 17V Input Voltage Range
- 2A Output Current
- Internal N-Channel MOSFETs
- Current Mode Control
- Fixed Switching Frequency: 500kHz
- Synchronous to External Clock: 200kHz to 2MHz
- Cycle-by-Cycle Current Limit
- TTH For Adjustable PSM to PWM Transition
   Threshold
- Internal Soft-Start Function
- Input Under-Voltage Lockout
- Output Under-Voltage Protection
- Thermal Shutdown
- RoHS Compliant and Halogen Free

### **Applications**

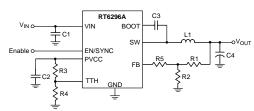
- Industrial and Commercial Low Power Systems
- Computer Peripherals
- LCD Monitors and TVs
- Set-top Boxes

# **Marking Information**



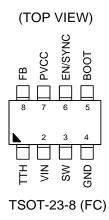
0G=: Product Code DNN: Date Code

# **Simplified Application Circuit**





# **Pin Configuration**

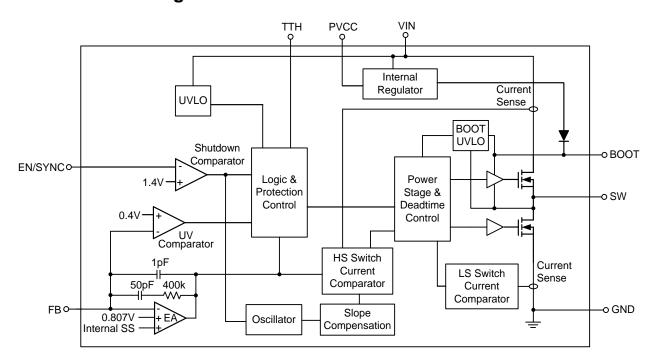


# **Functional Pin Description**

Pin No.	Pin Name	Pin Function			
1	ттн	Transition threshold. The TTH voltage sets the transition point from power saving mode (PSM) to PWM. Connect the tap of 2 resistor dividers to force the RT6296A into non-synchronous mode under light loads. Connect TTH pin high (PVCC) to force the RT6296A into forced PWM mode. Don't leave this pin floating.			
2	VIN	Power input. Support 4.5V to17V Input Voltage. Must bypass with a suital large ceramic capacitor at this pin.			
3	SW	Switch node. Connect to external L-C filter.			
4	GND	System ground.			
5	воот	Bootstrap supply for high-side gate driver. Connect a $0.1\mu F$ ceramic capacitor between the BOOT and SW pins.			
6	EN/SYNC	Enable control input. High = Enable. Apply an external clock to adjust the switching frequency. If using pull high resistor connected to VIN, the recommended value range is $60 \mathrm{k}\Omega$ to $300 \mathrm{k}\Omega$ .			
7	PVCC	5V bias supply output. Connect a minimum of 0.1μF capacitor to ground.			
8	FB	Feedback voltage input. The pin is used to set the output voltage of the converter to regulate to the desired voltage via a resistive divider. Feedback reference = 0.8V.			



## **Functional Block Diagram**





## **Operation**

#### **Power Saving Mode**

The RT6296A automatically enters into power saving mode (PSM) at light load to improve efficiency. In PSM, the RT6296A disable the internal CLK when VFB is above the V<sub>RFF</sub> x 1.005 (typ.). In other words, the device automatically skip the PWM pulse at light load. While V<sub>FB</sub> falls below the V<sub>REF</sub> x 1.005, the RT6296A enables the internal CLK again and hence the new switching cycle is activated. When the internal switches are activated, for each cycle the device detects the peak inductor current (IL PEAK) and keeps high-side switch on until the IL reaches its minimum peak current level (from TTH setting). When low-side switch is turn-on, the zero-current detection is also activated to prevent that IL becomes negative and enables the higher efficiency at light load. During the period that both switches are off, the device turns off the most of the internal circuit to reduce the quiescent power consumption further.

With lower output loading, the non-switching period is longer, so the effective switching frequency becomes lower to reduce the switching loss and switch driving loss.

#### **Transition Threshold (TTH)**

In power saving mode, the minimum peak current (MPC) of each switching pulse, can be adjusted by voltage of TTH (V<sub>TTH</sub>) to set the PSM/Force PWM transition threshold as shown in the Figure 1.

Figure 2 shows the actual minimum peak current versus the TTH setting voltage. When  $V_{TTH}$  is connected to ground, the MPC will be < 20mA. The device clamps the minimum peak current at 3.2A (typ.) if the  $V_{TTH}$  is set higher than 1.2V. The RT6296A maintains forced CCM operation if the  $V_{TTH}$  is set higher than 2.5V (typ.). In PWM, the switching frequency maintains fixed and the output voltage ripple maintains smaller even at light load. As shown Figure 3 and Figure 4, smaller MPC sets the mode transition current lower and enables higher switching frequency at PSM.

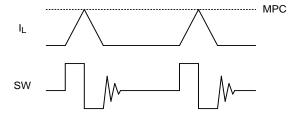


Figure 1. Minimum Peak Current at PSM

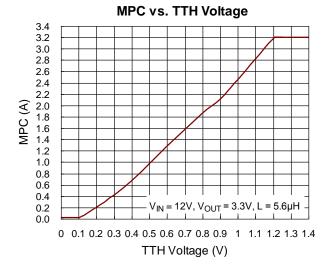


Figure 2 Relation between MPC and VTTH

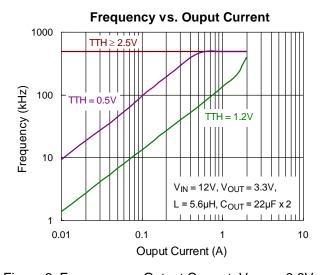


Figure 3. Frequency vs Output Current,  $V_{OUT} = 3.3V$ 

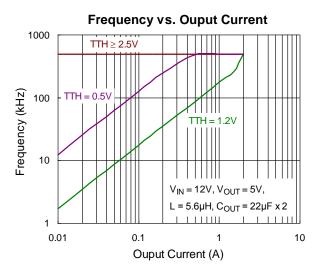


Figure 4. Frequency vs Output Current, Vout = 5V

#### **Under-Voltage Lockout Threshold**

The IC includes an input Under Voltage Lockout Protection (UVLO). If the input voltage exceeds the UVLO rising threshold voltage (3.9V), the converter resets and prepares the PWM for operation. If the input voltage falls below the UVLO falling threshold voltage (3.25V) during normal operation, the device stops switching. The UVLO rising and falling threshold voltage includes a hysteresis to prevent noise caused reset.

#### **Chip Enable**

The EN pin is the chip enable input. Pulling the EN pin low (<1.1V) will shutdown the output voltage. During shutdown mode (<0.4V), the RT6296A's quiescent current drops to lower than  $1\mu A$ . Driving the EN pin high (>1.6V) will turn on the device.

#### **Operating Frequency and Synchronization**

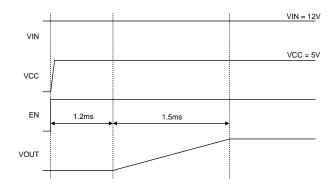
The internal oscillator runs at 500kHz (typ.) when the EN/SYNC pin is at logic-high level (>1.6V). If the EN pin is pulled to low-level over  $8\mu s$ , the IC will shut down. The RT6296A can be synchronized with an external clock ranging from 200kHz to 2MHz applied to the EN/SYNC pin. The external clock duty cycle must be from 20% to 80% with logic-high level = 2V and logic-low level = 0.8V.

#### **Internal Regulator**

The internal regulator generates 5V power and drive internal circuit. When VIN is below 5V, PVCC will drop with VIN. A capacitor (>0.1 $\mu$ F) between PVCC and GND is required.

#### **Internal Soft-Start Function**

The RT7296A provides internal soft-start function. The soft-start function is used to prevent large inrush current while converter is being powered-up. Output voltage starts to rise 1.2ms after EN rising, and the soft-start time ( $V_{FB}$  from 0V to 0.8V) is 1.5ms.



#### **High-Side MOSFET Over-Current Limit**

The RT6296A features cycle-by-cycle current limit protection and prevents the device from the catastrophic damage in output short circuit, over current or inductor saturation. During the on-time of the high side switch, the device monitors the switch current. If the switch current overs the current limit threshold, the device turns off the high side switch to prevent the device from damage.

#### **Output Under-Voltage Protection**

The RT6296A includes output under-voltage protection (UVP) against over-load or short-circuited condition by constantly monitoring the feedback voltage V<sub>FB</sub>. If V<sub>FB</sub> drops below the under-voltage protection trip threshold, 50% (typ.) of the internal reference voltage, the UV comparator will go high to turn off the internal high-side MOSFET switches. If the output under-voltage



condition continues for a period of time, the RT6296A will enter output under-voltage protection with hiccup mode. During hiccup mode, the device remains shut down. After a period of time, a soft-start sequence for auto-recovery will be initiated. Upon completion of the soft-start sequence, if the fault condition is removed, the converter will resume normal operation; otherwise, such cycle for auto-recovery will be repeated until the fault condition is cleared. Hiccup mode allows the circuit to operate safely with low input current and power dissipation, and then resume normal operation as soon as the over-load or short-circuit condition is removed. The UVP profile is shown in Figure 5.

#### **Over-Temperature Protection**

Over-temperature protection is implemented to prevent the chip from operating at excessively high temperatures. When the junction temperature is higher than 150°C, the OTP will shut down switching operation. The chip will automatically resume normal operation with a complete soft-start sequence once the junction temperature cools down by approximately 20°C.

#### **BOOT UVLO**

The RT6296A implements BOOT UVLO function to ensure the V<sub>BOOT</sub>-sw is sufficient to correctly activate the high side switch at any condition. BOOT UVLO usually actives at higher V<sub>OUT</sub>, very light load and small TTH threshold. With such conditions, the low side switch may not have sufficient turn-on time to charge the BOOT capacitor. The BOOT UVLO actives when V<sub>BOOT</sub>-sw is lower than 2.65V (typ.), the device will be forced to turn on the low side switch for 200ns (typ.) to charge the BOOT capacitor. The BOOT UVLO behavior continues for each PWM cycle until the V<sub>BOOT</sub>-sw is higher than 2.9V (typ.).

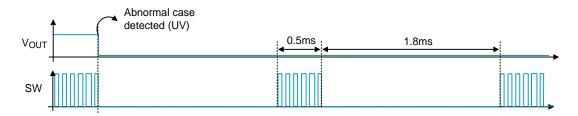


Figure 5. Output Under-Voltage Protection with Hiccup Mode

0.01/40.001/



### **Absolute Maximum Ratings** (Note 1)

<ul> <li>Supply input voltage,</li> </ul>	V IIN	-0.37 to 207
<ul> <li>Switch Voltage, SW</li> </ul>		$-0.3V$ to $V_{IN} + 0.3V$

• Other Pins----- -0.3V to 6V

• Power Dissipation,  $P_D$  @  $T_A = 25^{\circ}C$ 

TSOT-23-8 (FC)------ 1.428W

• Package Thermal Resistance (Note 2)

TSOT-23-8 (FC), θJA ------ 70°C/W
TSOT-23-8 (FC), θJC ------ 15°C/W

• Lead Temperature (Soldering, 10 sec.) ----- 260°C

• Junction Temperature ----- -40°C to 150°C

• ESD Susceptibility (Note 3)

HBM (Human Body Model) ----- 2kV

### Recommended Operating Conditions (Note 4)

• Supply Input Voltage, VIN------ 4.5V to 17V

• Junction Temperature Range ----- --- -40°C to 125°C

• Ambient Temperature Range ----- --- -40°C to 85°C

#### **Electrical Characteristics**

 $(V_{IN} = 12V, T_A = 25^{\circ}C, unless otherwise specified)$ 

Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
Shutdown Supply Current			V <sub>EN</sub> = 0V			1	μΑ	
Quiescent Current with no Load at DCDC Output			V <sub>EN</sub> = 2V, V <sub>FB</sub> = 1V, AAM = 0.5V		0.8	1	mA	
Feedback Voltage		V <sub>FB</sub>		0.799	0.807	0.815	V	
Feedback Current	Feedback Current		V <sub>FB</sub> = 820mV		10	50	nA	
Switch	High-Side	RDS(ON)H			100		m()	
On-Resistance	Low-Side	R <sub>DS(ON)L</sub>			40		mΩ	
Switch Leakage			$V_{EN} = 0V$ , $V_{SW} = 0V$			1	μΑ	
Current Limit		ILIM	Under 40% duty-cycle	3	4	4.6	Α	
Low-Side Switch Current Limit			From drain to source		2		Α	
Oscillation Frequency		fosc	V <sub>FB</sub> = 0.75V	440	500	580	kHz	
SYNC Frequency Range		f <sub>SYNC</sub>		200		2000	kHz	
Fold-Back Frequency			V <sub>FB</sub> < 400mV		125		kHz	
Maximum Duty-Cycle	)	D <sub>MAX</sub>	V <sub>FB</sub> = 0.7V	90	95		%	

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# **RT6296A**

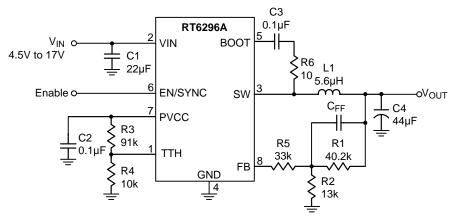


Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
Minimum On-Time		t <sub>ON_MIN</sub>			60		ns	
EN Input Voltage	Logic-High	ViH		1.2	1.4	1.6	V	
EN Input Voltage	Logic-Low	VIL		1.1	1.25	1.4	V	
EN Input Current		les.	V <sub>EN</sub> = 2V		2		μΑ	
		I <sub>EN</sub>	V <sub>EN</sub> = 0V		0			
EN Turn-off Delay		ENtd-off			8		μS	
Input Under-Voltage	V <sub>IN</sub> Rising	V <sub>UVLO</sub>	V <sub>IN</sub> rising	3.7	3.9	4.1	V	
Lockout Threshold	Hysteresis	ΔVυνιο			650		mV	
VCC Regulator		Vcc	I <sub>VCC</sub> = 0mA		5		V	
VCC Load Regulation		$\Delta V_{LOAD}$	I <sub>VCC</sub> = 5mA		3		%	
Soft-Start Time		tss	FB from 0V to 0.8V		1.5		ms	
Thermal Shutdown Temperature		T <sub>SD</sub>			150		°C	
Thermal Shutdown Hysteresis		$\DeltaT_{SD}$			20		°C	

- **Note 1.** Stresses listed as the above "Absolute Maximum Ratings" may cause permanent damage to the device. These are for stress ratings. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may remain possibility to affect device reliability.
- Note 2.  $\theta_{JA}$  is measured at  $T_A = 25^{\circ}\text{C}$  on a high effective thermal conductivity four-layer test board per JEDEC 51-7.  $\theta_{JC}$  is measured at the exposed pad of the package.
- Note 3. Devices are ESD sensitive. Handling precaution recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions.



# **Typical Application Circuit**



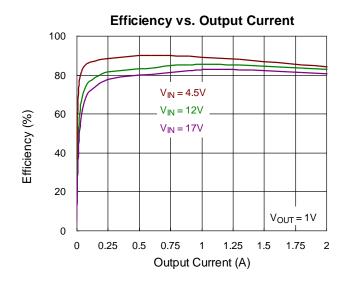
**Table 1. Suggested Component Values** 

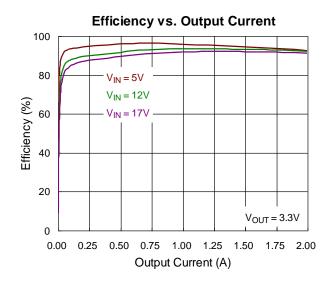
V <sub>OUT</sub> (V)	<b>R1 (k</b> Ω)	<b>R2 (k</b> Ω)	<b>R5 (k</b> Ω)	C <sub>ff</sub> (pF)	<b>C4 (</b> μ <b>F)</b>	<b>L1 (μH)</b>
1.0	20.5	84.5	82	15	44	2.2
3.3	40.2	13	33	15	44	5.6
5.0	40.2	7.68	33	15	44	5.6

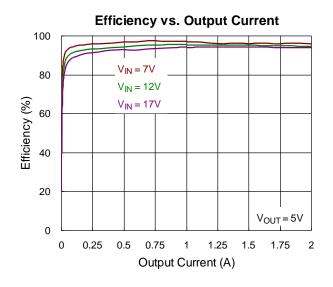
Note: Where the C4 value means the effective output capacitance. Design engineer must be aware that ceramic capacitance varies a great deal with the size, operating voltage and temperature. The variation should be taken into the design consideration of control loop bandwidth. A rule-of-the-thumb is to design the RT6296A control loop bandwidth below 60kHz by changing the value of R5. Generally, increase the value of R5 if a de-rated capacitance is used.

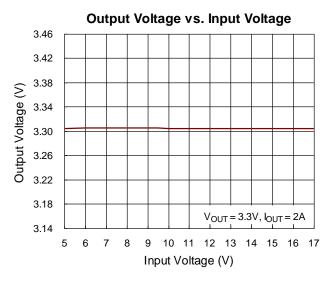


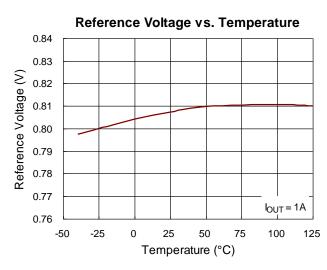
# **Typical Operating Characteristics**

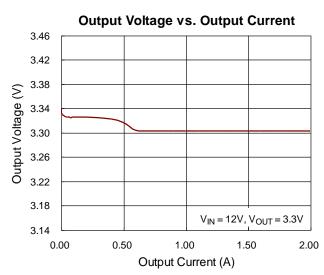




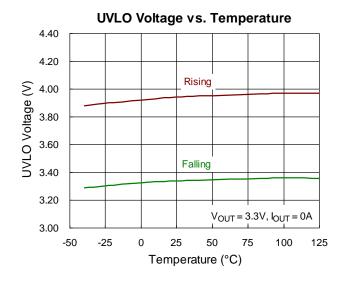


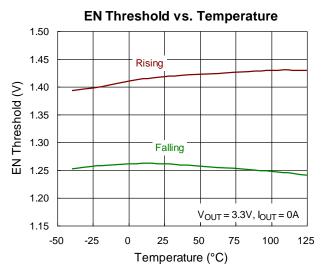


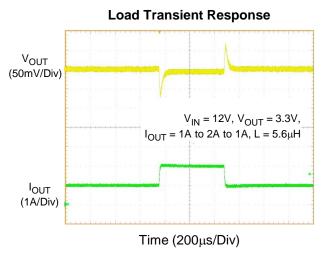


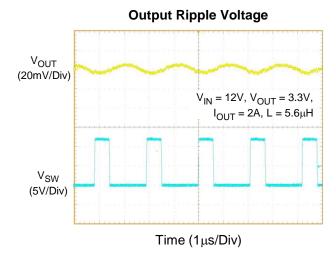


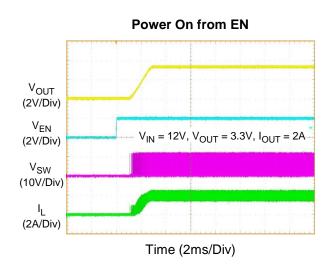


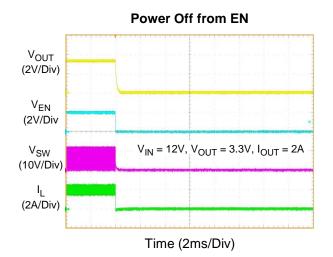








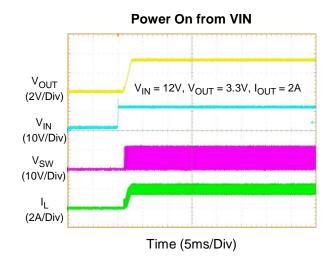


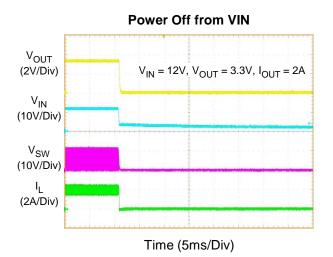


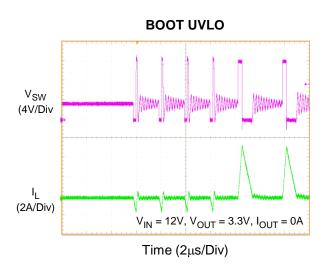
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### **Application Information**

The RT6296A is a high voltage buck converter that can support the input voltage range from 4.5V to 17V and the input voltage range from 4.5V to 17V and the output current can be up to 2A.

#### **Output Voltage Selection**

The resistive voltage divider allows the FB pin to sense a fraction of the output voltage as shown in Figure 6.

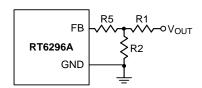


Figure 6. Output Voltage Setting

For adjustable voltage mode, the output voltage is set by an external resistive voltage divider according to the following equation:

$$V_{OUT} = V_{FB} \Biggl( 1 + \frac{R1}{R2} \Biggr)$$

Where  $V_{FB}$  is the feedback reference voltage (0.807V typ.). Table 2 lists the recommended resistors value for common output voltages.

Table 2. Recommended Resistors Value

V <sub>OUT</sub> (V)	R1 (kΩ)	<b>R2 (k</b> Ω)	<b>R5 (k</b> Ω)
1.0	20.5	84.5	82
3.3	40.2	13	33
5.0	40.2	7.68	33

#### **External Bootstrap Diode**

Connect a 100nF low ESR ceramic capacitor between the BOOT pin and SW pin. This capacitor provides the gate driver voltage for the high side MOSFET. It is recommended to add an external bootstrap diode between an external 5V and BOOT pin, as shown as Figure 7, for efficiency improvement when input voltage is lower than 5.5V or duty ratio is higher than 65% .The bootstrap diode can be a low cost one such as IN4148 or BAT54. The external 5V can be a 5V fixed input from system or a 5V output (PVCC) of the RT6296A.

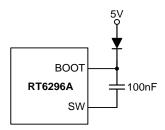


Figure 7. External Bootstrap Diode

#### The TTH Voltage setting

The TTH voltage is used to be change the transition threshold between power saving mode and CCM. Higher TTH voltage gets higher efficiency at light load condition but larger output ripple; a lower TTH voltage can improve output ripple but degrades efficiency during light load condition. A resistor divider from PVCC (5V) of the RT6296A can help to build TTH voltage, as shown in Figure 8. Use the divider resistance less than  $100k\Omega$  to increase the noise immunity. Simply connecting the TTH pin to PVCC, or to remove the R4, can set the RT6296A operate in force PWM mode. Usually, set the minimum peak current smaller than the CCM inductor ripple current to achieve smooth transition from power saving mode to FCCM. For example, designer can set TTH voltage less than 0.5V if the inductor current ripple is 1A at CCM.

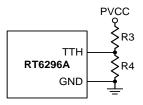


Figure 8. TTH Voltage Setting

#### **Inductor Selection**

The inductor value and operating frequency determine the ripple current according to a specific input and output voltage. The ripple current  $\Delta I_L$  increases with higher VIN and decreases with higher inductance.

$$\Delta I_{L} = \left(\frac{V_{OUT}}{f \times L}\right) \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Having a lower ripple current reduces not only the ESR



losses in the output capacitors but also the output voltage ripple. High frequency with small ripple current can achieve highest efficiency operation. However, it requires a large inductor to achieve this goal.

For the ripple current selection, the value of  $\Delta I_L = 0.3$  (I<sub>MAX</sub>) will be a reasonable starting point. The largest ripple current occurs at the highest VIN. To guarantee that the ripple current stays below the specified maximum, the inductor value should be chosen according to the following equation :

$$L = \left(\frac{V_{OUT}}{f \times \Delta I_{L(MAX)}}\right) \times \left(1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right)$$

The inductor's current rating (caused a 40°C temperature rising from 25°C ambient) should be greater than the maximum load current and its saturation current should be greater than the short circuit peak current limit.

#### **CIN and COUT Selection**

The input capacitance,  $C_{\text{IN}}$ , is needed to filter the trapezoidal current at the source of the top MOSFET. To prevent large ripple current, a low ESR input capacitor sized for the maximum RMS current should be used. The RMS current is given by :

$$I_{RMS} = I_{OUT(MAX)} \frac{V_{OUT}}{V_{IN}} \sqrt{\frac{V_{IN}}{V_{OUT}}} - 1$$

This formula has a maximum at  $V_{\text{IN}} = 2V_{\text{OUT}}$ , where  $I_{\text{RMS}} = I_{\text{OUT}} / 2$ . This simple worst-case condition is commonly used for design because even significant deviations do not offer much relief.

Choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet size or height requirements in the design. The selection of Cout is determined by the required Effective Series Resistance (ESR) to minimize voltage ripple. Moreover, the amount of bulk capacitance is also a key for Cout selection to ensure that the control loop is stable. Loop stability can be checked by viewing

the load transient response as described in a later section. The output ripple,  $\Delta V_{OUT}$ , is determined by :

$$\Delta V_{OUT} \le \Delta I_{L} \times \left( ESR + \frac{1}{8fC_{OUT}} \right)$$

The output ripple will be highest at the maximum input voltage since ∆I<sub>L</sub> increases with input voltage. Multiple capacitors placed in parallel may be needed to meet the ESR and RMS current handling requirement. Dry tantalum, special polymer, aluminum electrolytic and ceramic capacitors are all available in surface mount packages. Special polymer capacitors offer very low ESR value. However, it provides lower capacitance density than other types. Although Tantalum capacitors have the highest capacitance density, it is important to only use types that pass the surge test for use in switching power supplies. Aluminum electrolytic capacitors have significantly higher ESR. However, it can be used in cost-sensitive applications for ripple current rating and long term reliability considerations. capacitors have excellent characteristics but can have a high voltage coefficient and audible piezoelectric effects. The high Q of ceramic capacitors with trace inductance can also lead to significant ringing.

#### **Thermal Considerations**

For continuous operation, do not exceed absolute maximum junction temperature. The maximum power dissipation depends on the thermal resistance of the IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_{A}) / \theta_{JA}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction to ambient thermal resistance.

For recommended operating condition specifications, the maximum junction temperature is 125°C. The



junction to ambient thermal resistance,  $\theta_{JA}$ , is layout dependent. For TSOT-23-8 (FC) package, the thermal resistance,  $\theta_{JA}$ , is 70°C/W on a standard four-layer thermal test board. The maximum power dissipation at  $T_A = 25$ °C can be calculated by the following formula :  $P_{D(MAX)} = (125$ °C - 25°C) / (70°C/W) = 1.428W for TSOT-23-8 (FC) package

The maximum power dissipation depends on the operating ambient temperature for fixed  $T_{J(MAX)}$  and thermal resistance,  $\theta_{JA}$ . The derating curve in Figure 9 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

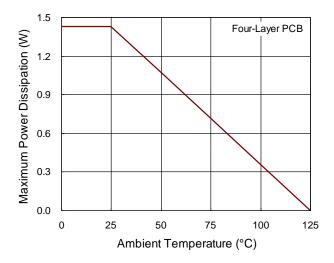


Figure 9. Derating Curve of Maximum Power Dissipation

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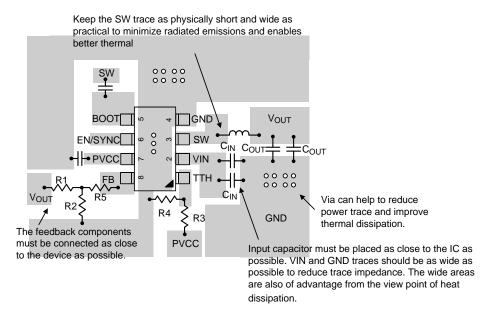


Figure 10. PCB Layout Guide

#### **Layout Considerations**

For best performance of the RT6296A, the following layout guidelines must be strictly followed.

- Input capacitor must be placed as close to the IC as possible.
- ➤ SW should be connected to inductor by wide and short trace. Keep sensitive components away from this trace.
- ► Keep VIN, GND and SW traces connected to pin as wide as possible for improving thermal dissipation.