Synchronous-Rectified Buck MOSFET Driver

General Description

The RT9612A/B is a high frequency, synchronous rectified, single phase dual MOSFET driver designed to adapt from normal MOSFET driving applications to high performance CPU VR driving capabilities.

The RT9612A/B can be utilized under both V_{CC} = 5V or V_{CC} = 12V applications. The RT9612A/B also builds in an internal power switch to replace external boot strap diode. The RT9612A/B can support switching frequency efficiently up to 500kHz. The RT9612A/B has the UGATE driving circuit and the LGATE driving circuit for synchronous rectified DC/DC converter applications. The driving rise/ fall time capability is designed within 30ns and the shoot through protection mechanism is designed to prevent shoot through of high side and low side power MOSFETs. The RT9612A/B has PWM tri-state shut down function which can force driver output into high impedance.

The difference of the RT9612A and the RT9612B is the propagation delay, $t_{UGATEpdh}$. The RT9612B has comparatively large $t_{UGATEpdh}$ than RT9612B. Hence, the RT9612A is usually recommended to be utilized in performance oriented applications, such as high power density CPU VR or GPU VR. The RT9612A/B comes in a small footprint with SOP-8, SOP-8 (Exposed Pad) and WDFN-8EL 3x3.
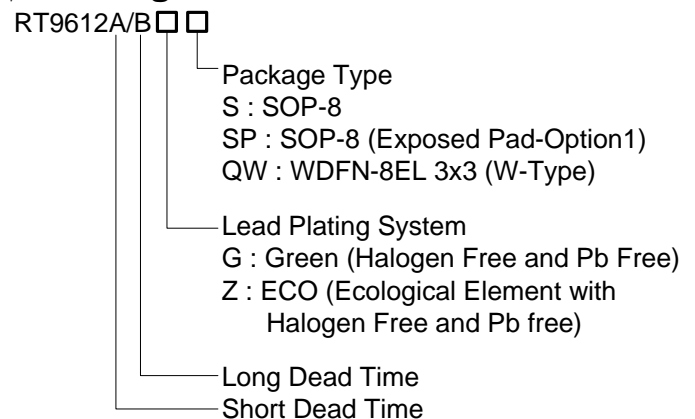
Features

- **Drive Two N-MOSFETs**
- **Adaptive Shoot Through Protection**
- **Embedded Bootstrap Diode**
- **Support High Switching Frequency**
- **Fast Output Rise Time**
- **Tri-State Input for Bridge Shutdown**
- **Small SOP-8, SOP-8 (Exposed Pad) and 8-Lead WDFN Packages**
- **RoHS Compliant and Halogen Free**

Applications

- Core Voltage Supplies for Desktop, Motherboard CPU
- High Frequency Low Profile DC/DC Converters
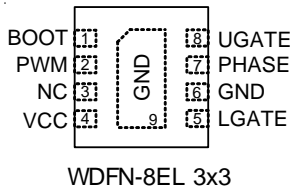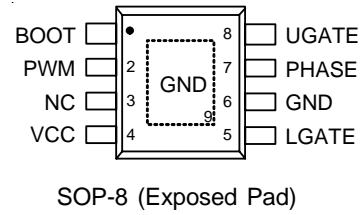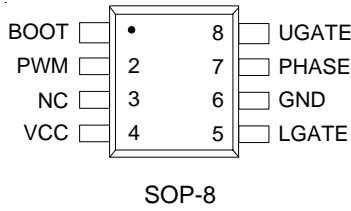- High Current Low Voltage DC/DC Converters

Ordering Information

RT9612A/B□ □

Package Type
S : SOP-8
SP : SOP-8 (Exposed Pad-Option1)
QW : WDFN-8EL 3x3 (W-Type)

Lead Plating System
G : Green (Halogen Free and Pb Free)
Z : ECO (Ecological Element with Halogen Free and Pb free)

Long Dead Time
Short Dead Time

Note :

Richtek products are :

‣ RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
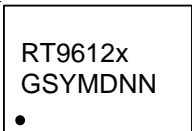
‣ Suitable for use in SnPb or Pb-free soldering processes.
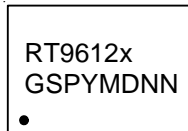
RICHTEK

Pin Configurations

(TOP VIEW)

```
BOOT    1 •        8   UGATE
PWM     2          7   PHASE
NC      3          6   GND
VCC     4          5   LGATE
```

SOP-8

```
BOOT    1 •        8   UGATE
PWM     2    GND   7   PHASE
NC      3          6   GND
VCC     4      9   5   LGATE
```

SOP-8 (Exposed Pad)

```
BOOT    1          8   UGATE
PWM     2   GND    7   PHASE
NC      3          6   GND
VCC     4     9    5   LGATE
```

WDFN-8EL 3x3

Marking Information

RT9612xGS

```
RT9612x
GSYMDNN
•
```

RT9612xGS : Product Number

x : A or B

YMDNN : Date Code

RT9612xGSP

```
RT9612x
GSPYMDNN
•
```

RT9612xGSP : Product Number

x : A or B

YMDNN : Date Code

RT9612xZS

```
RT9612x
ZSYMDNN
•
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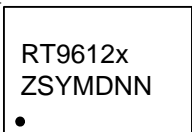
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x : A or B

YMDNN : Date Code

RT9612xZSP

```
RT9612x
ZSPYMDNN
•
```
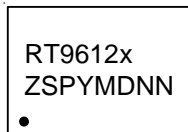
RT9612xZSP : Product Number

x : A or B

YMDNN : Date Code

RT9612AGQW

```
16=YM
DNN
●
```
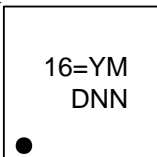
16= : Product Code

YMDNN : Date Code

RT9612BGQW

```
17=YM
DNN
●
```
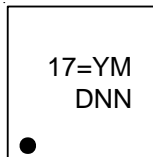
17= : Product Code

YMDNN : Date Code

RT9612AZQW

```
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DNN
●
```
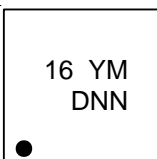
16 : Product Code

YMDNN : Date Code

RT9612BZQW

```
17  YM
DNN
●
```
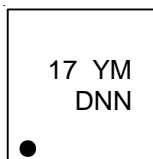
17 : Product Code

YMDNN : Date Code

Typical Application Circuit
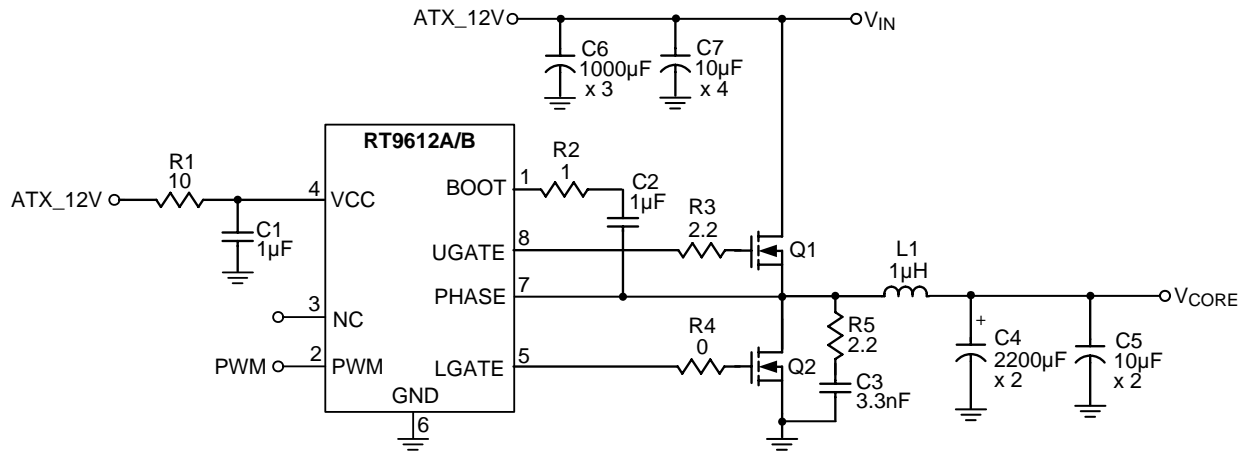
Timing Diagram

www.richtek.com
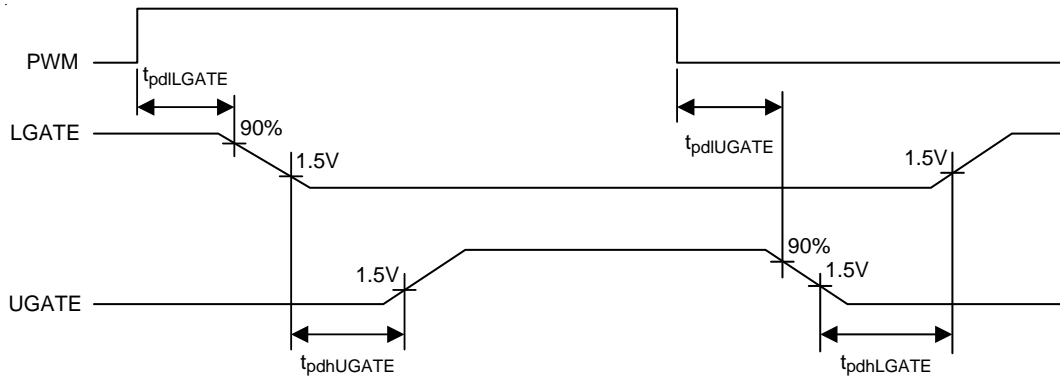
Function Pin Description

Pin No.		Pin Name	Pin Function
SOP-8	SOP-8 (Exposed Pad)/ WDFN-8EL 3x3		
1	1	BOOT	Floating Bootstrap Supply pin for Upper Gate Drive.
2	2	PWM	Input PWM Signal for Controlling the Driver.
3	3	NC	No Internal Connection.
4	4	VCC	12V Supply Voltage.
5	5	LGATE	Lower Gate Driver Output. Connect this pin to gate of low side power N-MOSFET.
6	6, 9 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.
7	7	PHASE	Connect this pin to the source of the high side MOSFET and the drain of the low side MOSFET.
8	8	UGATE	Upper Gate Drive Output. Connect this pin to gate of high side power N-MOSFET.

Function Block Diagram
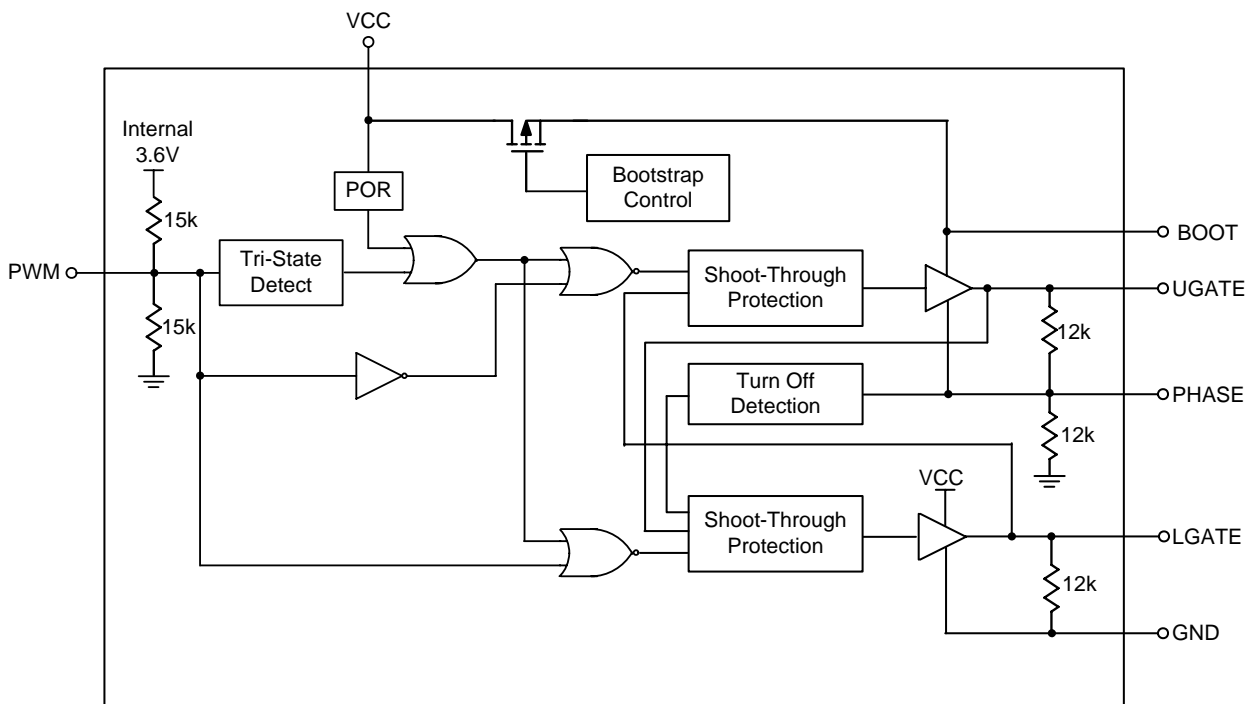
Absolute Maximum Ratings   (Note 1)

- Supply Voltage, VCC -- −0.3V to 15V
- BOOT to PHASE --- −0.3V to 15V
- PHASE to GND
   DC -- −5V to 15V
   < 200ns -- −10V to 30V
- LGATE
   DC --- (GND − 0.3V) to (V_{CC} + 0.3V)
   < 200ns --- −2V to (VCC + 0.3V)
- UGATE -- (V_{PHASE} − 0.3V) to (V_{BOOT} + 0.3V)
   < 200ns --- (V_{PHASE} − 2V) to (V_{BOOT} + 0.3V)
- PWM Input Voltage --- (GND − 0.3V) to 7V
- Power Dissipation, P_D @ T_A = 25°C
   SOP-8 --- 0.833W
   SOP-8 (Exposed Pad) --- 1.333W
   WDFN-8EL 3x3 --- 1.429W
- Package Thermal Resistance   (Note 2)
   SOP-8, θ_{JA} --- 120°C/W
   SOP-8 (Exposed Pad), θ_{JA} --- 75°C/W
   SOP-8 (Exposed Pad), θ_{JC} --- 15°C/W
   WDFN-8EL 3x3, θ_{JA} --- 70°C/W
   WDFN-8EL 3x3, θ_{JC} --- 8.2°C/W
- Lead Temperature (Soldering, 10 sec.) --- 260°C
- Junction Temperature --- 150°C
- Storage Temperature Range --- −65°C to 150°C
- ESD Susceptibility   (Note 3)
   HBM (Human Body Model) -- 2kV

Recommended Operating Conditions   (Note 4)

- Supply Voltage, VCC --- 12V ± 10%
- Junction Temperature Range -- −40°C to 125°C
- Ambient Temperature Range --- −40°C to 85°C

Electrical Characteristics

(V_{CC} = 12V, T_A = 25°C unless otherwise specified)

Parameter		Symbol	Test Conditions	Min	Typ	Max	Unit
Power Supply Voltage		V_{CC}		4.5	--	13.5	V
Power Supply Current		I_{VCC}	V_{BOOT} = 12V, PWM = 0V	--	1.2	--	mA
Power On Reset							
POR Threshold		V_{POR}	V_{CC} Rising	3	4	4.4	V
Hysteresis		V_{CCh_ys}		--	0.5	--	V
PWM Input							
Maximum Input Current		I_{PWM}	PWM = 0V or 5V	--	300	--	μA
PWM Floating Voltage		V_{PWM_fl}	V_{CC} = 12V	1.6	1.8	2	V
PWM Rising Threshold		V_{PWM_rth}		2.8	--	--	V
PWM Falling Threshold		V_{PWM_fth}		--	--	0.8	V
Timing							
UGATE Rise Time		t_{UGATEr}	V_{CC} = 12V, 3nF Load	--	25	--	ns
UGATE Fall Time		t_{UGATEf}	V_{CC} = 12V, 3nF Load	--	12	--	ns
LGATE Rise Time		t_{LGATEr}	V_{CC} = 12V, 3nF Load	--	24	--	ns
LGATE Fall Time		t_{LGATEf}	V_{CC} = 12V, 3nF Load	--	10	--	ns
Propagation Delay	RT9612A	$t_{UGATEpdh}$	$V_{BOOT} - V_{PHASE}$ = 12V See Timing Diagram	--	22	--	ns
	RT9612B			--	60	--	
	RT9612A/B	$t_{UGATEpdl}$		--	22	--	
		$t_{LGATEpdh}$	See Timing Diagram	--	20	--	
		$t_{LGATEpdl}$		--	8	--	
Output							
UGATE Drive Source		I_{UGATE_sr}	$V_{BOOT} - V_{PHASE}$ = 12V $V_{UGATE} - V_{PHASE}$ = 12V	--	2	--	A
UGATE Drive Sink		R_{UGATE_sk}	$V_{BOOT} - V_{PHASE}$ = 12V	--	1.4	--	Ω
LGATE Drive Source		I_{LGATE_sr}	V_{CC} = 12V , V_{LGATE} = 2V	--	2.2	--	A
LGATE Drive Sink		R_{LGATE_sk}	V_{CC} = 12V	--	1.1	--	Ω

Note 1. Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
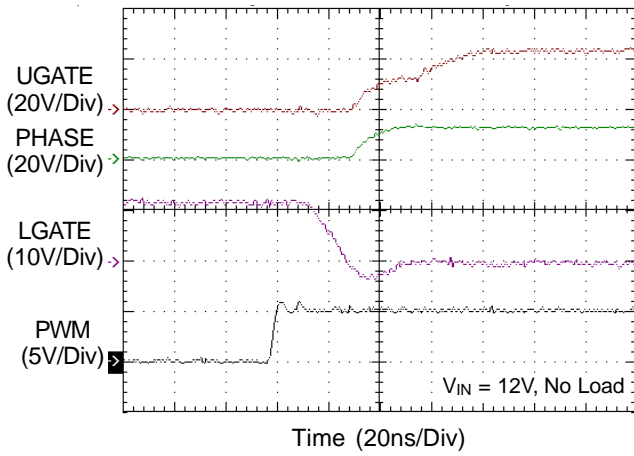
Note 2. $θ_{JA}$ is measured at T_A = 25°C on a high effective thermal conductivity four-layer test board per JEDEC 51-7. $θ_{JC}$ is measured at the exposed pad of the package.

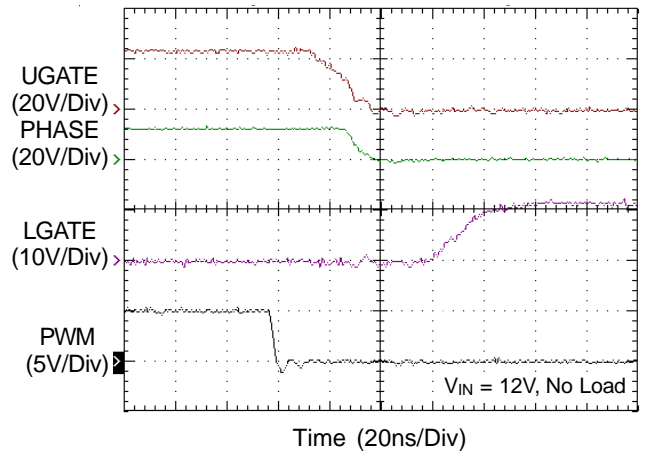**Note 3.** Devices are ESD sensitive. Handling precaution is recommended.

Note 4. The device is not guaranteed to function outside its operating conditions.
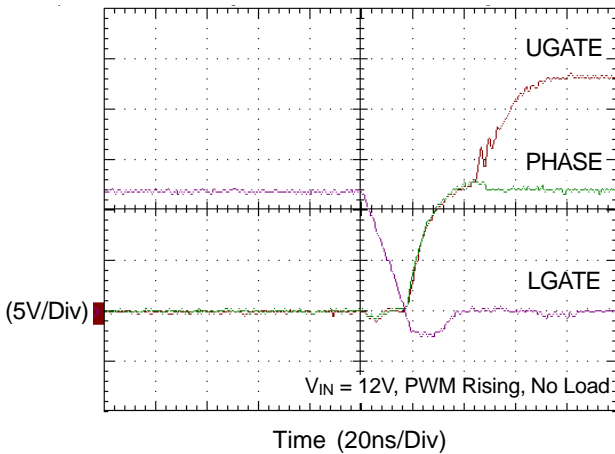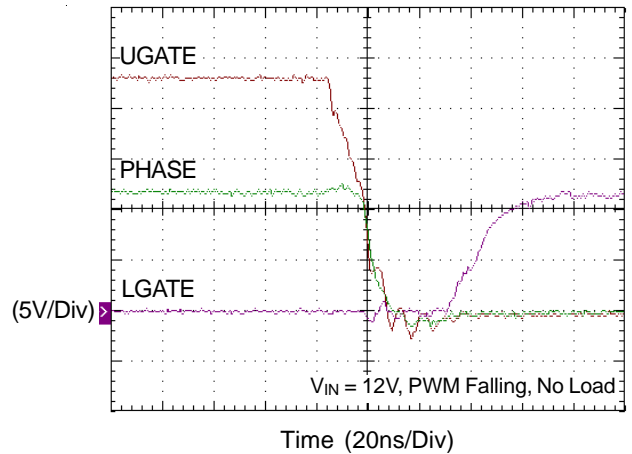
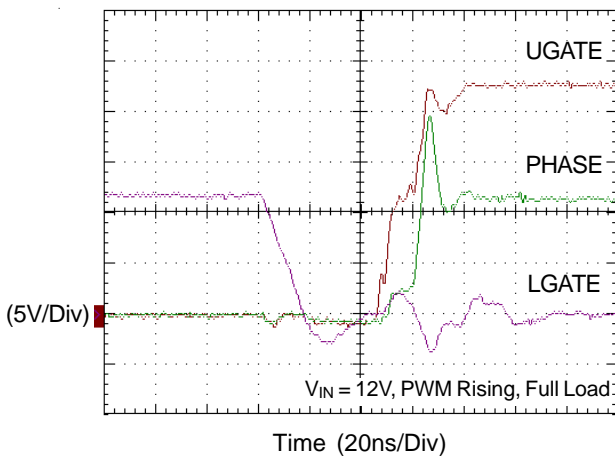## Typical Operating Characteristics

PWM Rising Edge

UGATE (20V/Div)
PHASE (20V/Div)
LGATE (10V/Div)
PWM (5V/Div)

V$_{IN}$ = 12V, No Load

Time (20ns/Div)

PWM Falling Edge

UGATE (20V/Div)
PHASE (20V/Div)
LGATE (10V/Div)
PWM (5V/Div)

V$_{IN}$ = 12V, No Load

Time (20ns/Div)

Dead Time

UGATE
PHASE
LGATE
(5V/Div)

V$_{IN}$ = 12V, PWM Rising, No Load

Time (20ns/Div)

Dead Time

UGATE
PHASE
LGATE
(5V/Div)

V$_{IN}$ = 12V, PWM Falling, No Load

Time (20ns/Div)

Dead Time

UGATE
PHASE
LGATE
(5V/Div)

V$_{IN}$ = 12V, PWM Rising, Full Load

Time (20ns/Div)

Dead Time

UGATE
PHASE
LGATE
(5V/Div)

V$_{IN}$ = 12V, PWM Falling, Full Load

Time (20ns/Div)

Short Pulse
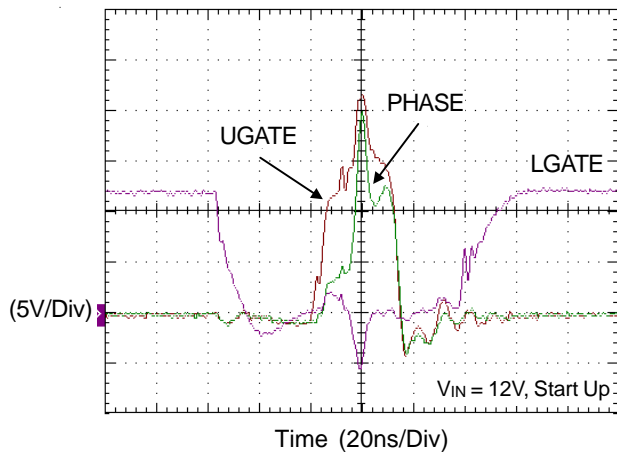

Time (20ns/Div)
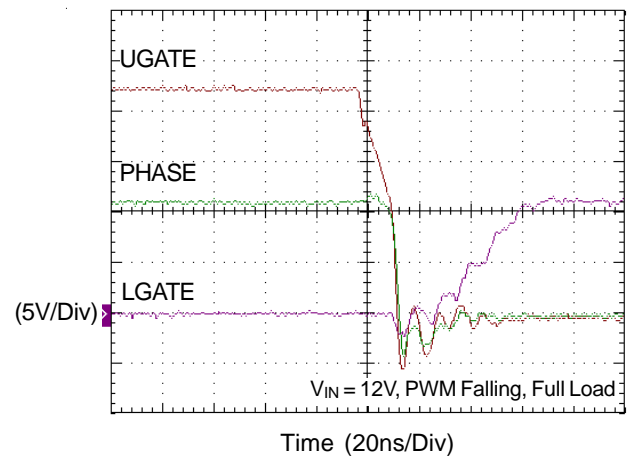
Application Information

The RT9612A/B is a High frequency, synchronous rectified, single phase dual MOSFET driver containing Richtek's advanced MOSFET driver technologies. The RT9612A/B is designed to be able to adapt from normal MOSFET driving applications to high performance CPU VR driving capabilities. The RT9612A/B can be utilized under both $V_{CC} = 5V$ or $V_{CC} = 12V$ applications which may happen in different fields of electronics application circuits. In the efficiency point of view, higher V_{CC} equals higher driving voltage of UG/LG which may result in higher switching loss and lower conduction loss of power MOSFETs. The choice of $V_{CC} = 12V$ or $V_{CC} = 5V$ can be a tradeoff to optimize system efficiency.

The RT9612A/B are designed to drive both high side and low side N-MOSFET through external input PWM control signal. It has power on protection function which held UGATE and LGATE low before the VCC voltage rises to higher than rising threshold voltage. After the initialization, the PWM signal takes the control. The rising PWM signal first forces the LGATE signal turns low then UGATE signal is allowed to go high just after a non-overlapping time to avoid shoot through current. The falling of PWM signal first forces UGATE to go low. When UGATE and PHASE signal reach a predetermined low level, LGATE signal is allowed to turn high.

The PWM signal is acted as "High" if the signal is above the rising threshold and acted as "Low" if the signal is below the falling threshold. Any signal level enters and remains within the shutdown window is considered as "tri-state", the output drivers are disabled and both MOSFET gates are pulled and held low. If the PWM signal is left floating, the pin will be kept around 1.8V by the internal divider and provide the PWM controller with a recognizable level.

The RT9612A/B builds in an internal bootstrap power switch to replace external bootstrap diode, and this can facilitate PCB design and reduce total BOM cost of the system. Hence, no external bootstrap diode is required in real applications.

The difference of the RT9612A and the RT9612B is the propagation delay, $t_{UGATEpdh}$. The RT9612B has comparatively large $t_{UGATEpdh}$ to further prevent from shoot through when high side power MOSFETs are going to be turned on. The long propagation delay of the RT9612B sacrifices efficiency for compromise of system safety. Hence, the RT9612A is usually recommended to be utilized in performance oriented applications, such as high power density CPU VR or GPU VR.

Non-overlap Control

To prevent the overlap of the gate drives during the UGATE pull low and the LGATE pull high, the non-overlap circuit monitors the voltages at the PHASE node and high side gate drive (UGATE-PHASE). When the PWM input signal goes low, UGATE begins to pull low (after propagation delay). Before LGATE can pull high, the non-overlap protection circuit ensures that the monitored voltages have gone below 1.1V. Once the monitored voltages fall below 1.1V, LGATE begins to turn high. For short pulse condition, if the PHASE pin had not gone high after LGATE pulls low, the LGATE has to wait for 200ns before pull high. By waiting for the voltages of the PHASE pin and high side gate drive to fall below 1.1V, the non-overlap protection circuit ensures that UGATE is low before LGATE pulls high.

Also to prevent the overlap of the gate drives during LGATE pull low and UGATE pull high, the non-overlap circuit monitors the LGATE voltage. When LGATE go below 1.1V, UGATE is allowed to go high.

Driving Power MOSFETs

The DC input impedance of the power MOSFET is extremely high. When V_{gs1} or V_{gs2} is at 12V or 5V, the gate draws the current only for few nano-amperes. Thus once the gate has been driven up to "ON" level, the current could be negligible.

However, the capacitance at the gate to source terminal should be considered. It requires relatively large currents to drive the gate up and down 12V (or 5V) rapidly. It is also required to switch drain current on and off with the required speed. The required gate drive currents are calculated as follows.
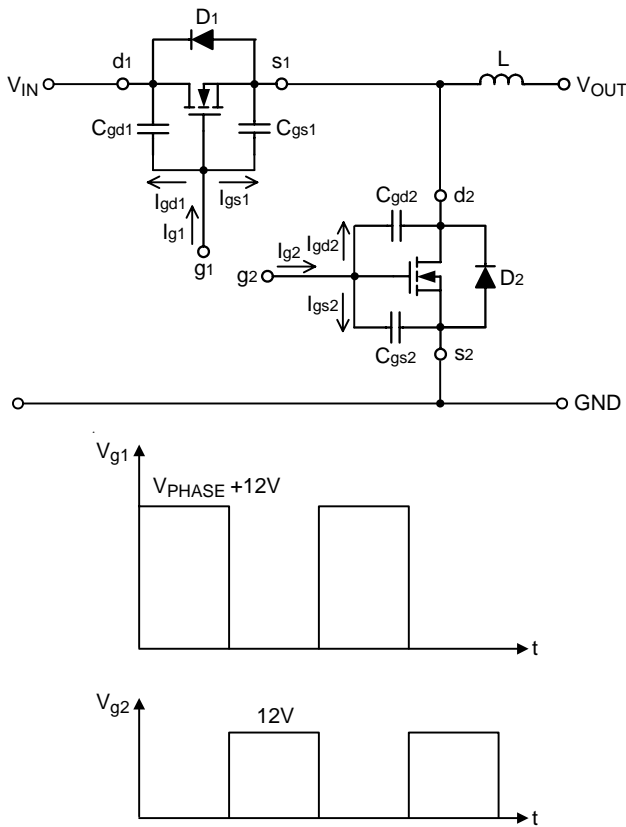
Figure 1. Equivalent Circuit and Associated Waveforms

In Figure 1, the current I_{g1} and I_{g2} are required to move the gate up to 12V. The operation consists of charging C_{gd1}, C_{gd2}, C_{gs1} and C_{gs2}. C_{gs1} and C_{gs2} are the capacitors from gate to source of the high side and the low side power MOSFETs, respectively. In general data sheets, the C_{gs1} and C_{gs2} are referred as "C_{iss}" which are the input capacitors. C_{gd1} and C_{gd2} are the capacitors from gate to drain of the high side and the low side power MOSFETs, respectively and referred to the data sheets as "C_{rss}" the reverse transfer capacitance. For example, t_{r1} and t_{r2} are the rising time of the high side and the low side power MOSFETs respectively, the required current I_{gs1} and I_{gs2}, are shown as below :

$$I_{gs1} = C_{gs1}\frac{dV_{g1}}{dt} = \frac{C_{gs1} \times 12}{t_{r1}} \tag{1}$$

$$I_{gs2} = C_{gs1}\frac{dV_{g2}}{dt} = \frac{C_{gs1} \times 12}{t_{r2}} \tag{2}$$

Before driving the gate of the high side MOSFET up to 12V (or 5V), the low side MOSFET has to be off; and the high side MOSFET will be turned off before the

low side is turned on. From Figure 1, the body diode "D_2" will be turned on before high side MOSFETs turn on.

$$I_{gd1} = C_{gd1}\frac{dV}{dt} = C_{gd1}\frac{12}{t_{r1}} \tag{3}$$

Before the low side MOSFET is turned on, the C_{gd2} have been charged to V_{IN}. Thus, as C_{gd2} reverses its polarity and g_2 is charged up to 12V, the required current is

$$I_{gd2} = C_{gd2}\frac{dV}{dt} = C_{gd2}\frac{Vi+12}{t_{r2}} \tag{4}$$

It is helpful to calculate these currents in a typical case. Assume a synchronous rectified buck converter, input voltage V_{IN} = 12V, V_{g1} = V_{g2} = 12V. The high side MOSFET is PHB83N03LT whose C_{iss} = 1660pF, C_{rss} = 380pF, and t_r = 14ns. The low side MOSFET is PHB95N03LT whose C_{iss} = 2200pF, C_{rss} = 500pF and t_r = 30ns, from the equation (1) and (2) we can obtain

$$I_{gs1} = \frac{1660 \times 10^{-12} \times 12}{14 \times 10^{-9}} = 1.428 \quad (A) \tag{5}$$

$$I_{gs2} = \frac{2200 \times 10^{-12} \times 12}{30 \times 10^{-9}} = 0.88 \quad (A) \tag{6}$$

from equation. (3) and (4)

$$I_{gd1} = \frac{380 \times 10^{-12} \times 12}{14 \times 10^{-9}} = 0.326 \quad (A) \tag{7}$$

$$I_{gd2} = \frac{500 \times 10^{-12} \times (12+12)}{30 \times 10^{-9}} = 0.4 \quad (A) \tag{8}$$

the total current required from the gate driving source can be calculated as following equations.

$$I_{g1} = I_{gs1} + I_{gd1} = (1.428 + 0.326) = 1.754 \quad (A) \tag{9}$$

$$I_{g2} = I_{gs2} + I_{gd2} = (0.88 + 0.4) = 1.28 \quad (A) \tag{10}$$

By a similar calculation, we can also get the sink current required from the turned off MOSFET.

Select the Bootstrap Capacitor

Figure 2 shows part of the bootstrap circuit of the RT9612A/B. The V_{CB} (the voltage difference between BOOT and PHASE on RT9612A/B) provides a voltage to the gate of the high side power MOSFET. This supply needs to be ensured that the MOSFET can be driven. For this, the capacitance C_B has to be selected properly. It is determined by following constraints.
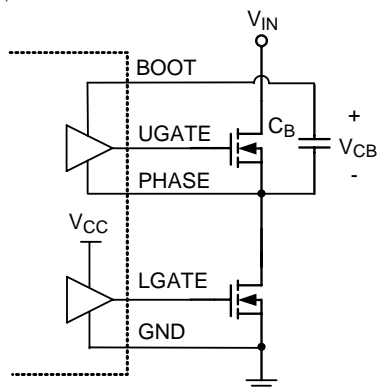
Figure 2. Part of Bootstrap Circuit of RT9612A/B

In practice, a low value capacitor C_B will lead to the over charging that could damage the IC. Therefore, to minimize the risk of overcharging and to reduce the ripple on V_{CB}, the bootstrap capacitor should not be smaller than 0.1μF, and the larger the better. In general design, using 1μF can provide better performance. At least one low-ESR capacitor should be used to provide good local de-coupling. It is recommended to adopt a ceramic or tantalum capacitor.

Power Dissipation

To prevent driving the IC beyond the maximum recommended operating junction temperature of 125°C, it is necessary to calculate the power dissipation appropriately. This dissipation is a function of switching frequency and total gate charge of the selected MOSFET.

Figure 3 shows the power dissipation test circuit. C_L and C_U are the UGATE and LGATE load capacitors, respectively. The bootstrap capacitor value is 1μF.
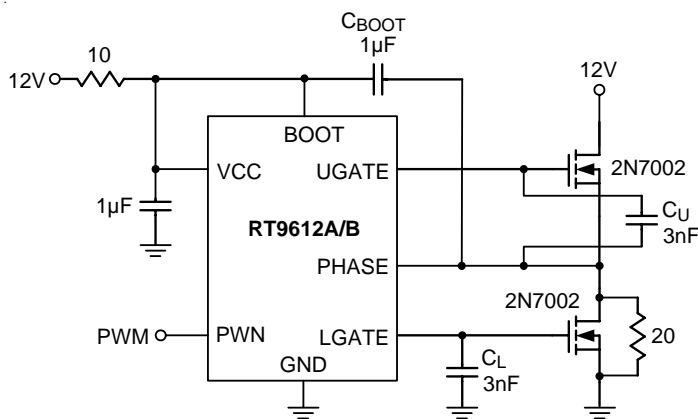

Figure 3. Test Circuit

Figure 4 shows the power dissipation of the RT9612A/B as a function of frequency and load capacitance. The value of C_U and C_L are the same and the frequency is varied from 100kHz to 1MHz.
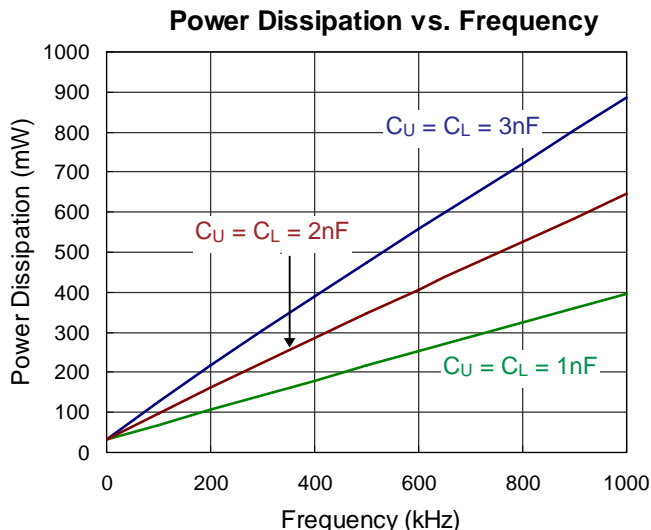

Figure 4. Power Dissipation vs. Frequency

The operating junction temperature can be calculated from the power dissipation curves (Figure 4). Assume

V_{CC} = 12V, operating frequency is 200kHz and $C_U = C_L$ = 1nF which emulate the input capacitances of the high side and low side power MOSFETs. From Figure 4, the power dissipation is 100mW. Thus, for example, with the SOP-8 package, the package thermal resistance θ_{JA} is 120°C/W. The operating junction temperature is then calculated as :

$$T_J = (120°C/W \times 100mW) + 25°C = 37°C \qquad (11)$$

where the ambient temperature is 25°C.

Thermal Considerations

For recommended operating condition specifications, the maximum junction temperature is 125°C. The junction to ambient thermal resistance, θ_{JA}, is layout dependent. For SOP-8 packages, the thermal resistance, θ_{JA}, is 120°C/W on a standard JEDEC 51-7 four-layer thermal test board. For SOP-8 (Exposed Pad) packages, the thermal resistance, θ_{JA}, is 75°C/W on a standard JEDEC 51-7 four-layer thermal test board. For WDFN-8EL 3x3 packages, the thermal resistance, θ_{JA}, is 70°C/W on a

standard JEDEC 51-7 four-layer thermal test board. The maximum power dissipation at $T_A = 25°C$ can be calculated by the following formulas :

$P_{D(MAX)} = (125°C - 25°C) / (120°C/W) = 0.833W$ for SOP-8 package

$P_{D(MAX)} = (125°C - 25°C) / (75°C/W) = 1.333W$ for SOP-8 (Exposed Pad) package

$P_{D(MAX)} = (125°C - 25°C) / (70°C/W) = 1.429W$ for WDFN-8EL 3x3 package

The maximum power dissipation depends on the operating ambient temperature for fixed $T_{J(MAX)}$ and thermal resistance, θ_{JA}. The derating curves in Figure 5 allow the designer to see the effect of rising ambient temperature on the maximum power dissipation.
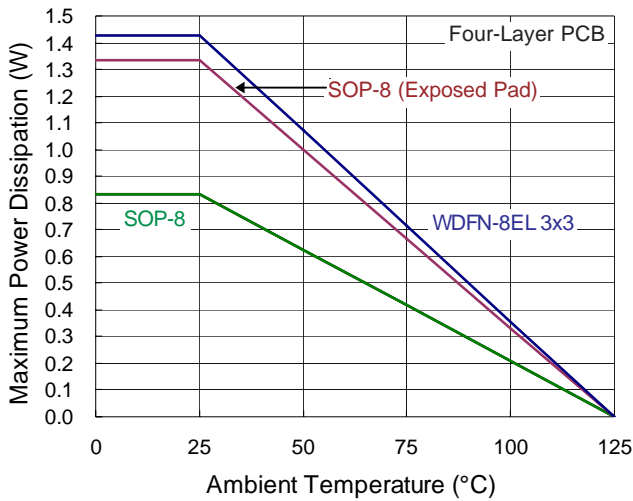

Figure 5. Derating Curve of Maximum Power Dissipation

Layout Consideration

Figure 6 shows the schematic circuit of a synchronous buck converter to implement the RT9612A/B. The converter operates from 5V to 12V of input Voltage.

When layout the PCB, it should be very careful. The power circuit section is the most critical one. If not configured properly, it will generate a large amount of EMI. The junction of Q1, Q2, L2 should be very close.

Next, the trace from UGATE, and LGATE should also be short to decrease the noise of the driver output signals. PHASE signals from the junction of the power MOSFET, carrying the large gate drive current pulses, should be as heavy as the gate drive trace. The bypass capacitor C4 should be connected to GND directly. Furthermore, the bootstrap capacitors (C_B) should always be placed as close to the pins of the IC as possible.
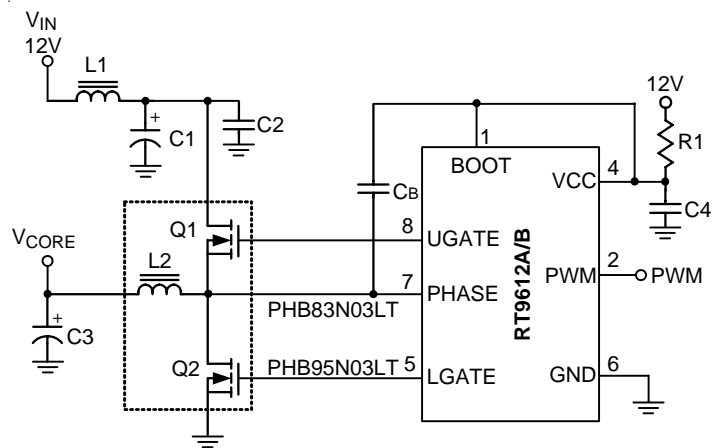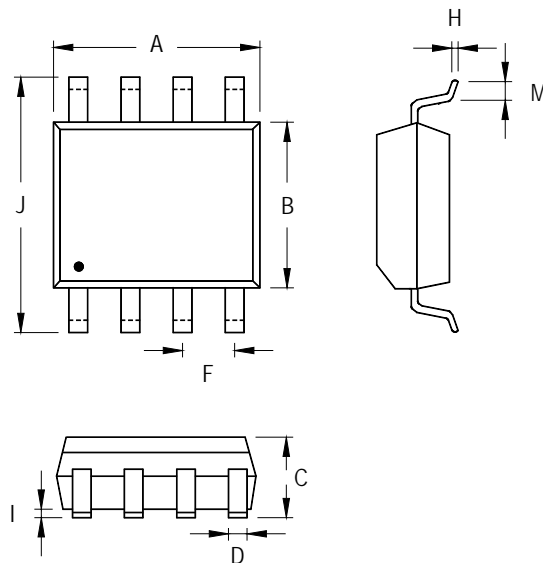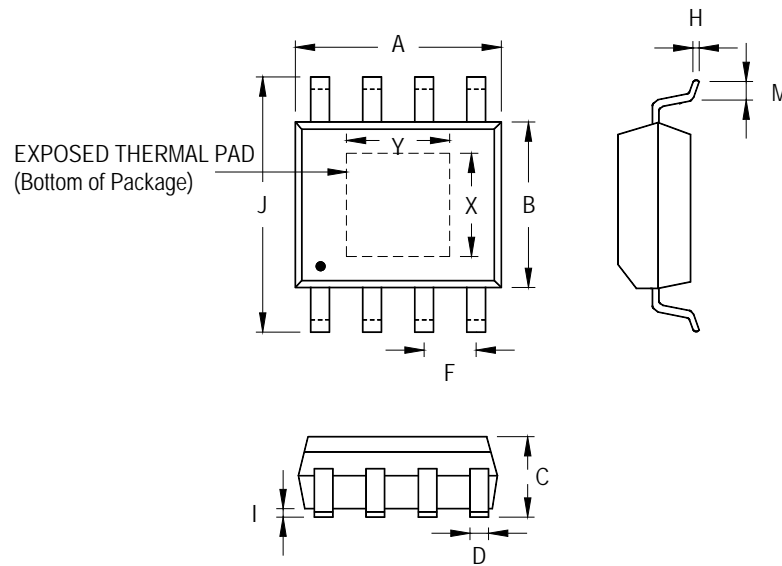

Figure 6. Synchronous Buck Converter Circuit

Outline Dimension

Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	4.801	5.004	0.189	0.197
B	3.810	3.988	0.150	0.157
C	1.346	1.753	0.053	0.069
D	0.330	0.508	0.013	0.020
F	1.194	1.346	0.047	0.053
H	0.170	0.254	0.007	0.010
I	0.050	0.254	0.002	0.010
J	5.791	6.200	0.228	0.244
M	0.400	1.270	0.016	0.050

8-Lead SOP Plastic Package

Symbol		Dimensions In Millimeters		Dimensions In Inches	
		Min	Max	Min	Max
A		4.801	5.004	0.189	0.197
B		3.810	4.000	0.150	0.157
C		1.346	1.753	0.053	0.069
D		0.330	0.510	0.013	0.020
F		1.194	1.346	0.047	0.053
H		0.170	0.254	0.007	0.010
I		0.000	0.152	0.000	0.006
J		5.791	6.200	0.228	0.244
M		0.406	1.270	0.016	0.050
Option 1	X	2.000	2.300	0.079	0.091
	Y	2.000	2.300	0.079	0.091
Option 2	X	2.100	2.500	0.083	0.098
	Y	3.000	3.500	0.118	0.138

8-Lead SOP (Exposed Pad) Plastic Package