SKJ

Cable Actuated Sensor
J1939 CANBus Output Signal

The SKJ is an easily customizable linear position sensor for applications from mobile construction equipment to hydraulic lift tables and anything else in between. Available in both 250 and 400-inch stroke ranges, this model offers ease-of-use, compact design and user flexibility. Need to mount it upside down? Simply rotate its stainless mounting bracket to where you want it. Need the electrical connector to point in a different direction? Just rotate the rear cover to point the connector to the desired direction.

Our unique electronic circuitry and an extremely durable spring-loaded stainless steel measuring cable deliver an accurate reliable “absolute” position feedback signal over the entire stroke.

FEATURES

- Flexibility - Every unit offers linear position up to 400” (10m) providing flexibility to work across a wide range of aerial applications. This off-the-shelf series offers a wide selection of industry standard output signals (4-20mA, 0-10Vdc, CANOpen and J1939 CANbus).
- Ease of use - A compact design, a stainless-steel mounting bracket for multiple installation options and an easily-adjustable measuring cable orientation make this sensor easy to install and manage.
- Superior engineering - TE provides engineering partnership to customize for specific applications. There is also an option to have two sensors elements in the same package with no additional space requirement. This provides fail-safe security for aerial applications.

APPLICATIONS

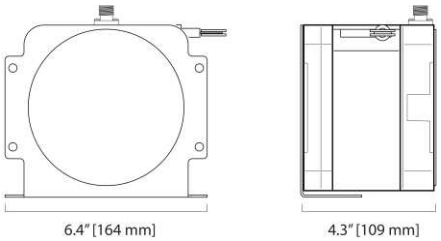
Accurate measurement in customized applications industrial and commercial transportation like:

- Fork lifts
- Telescopic arms
- Boom lifts
- Scissor lifts

Linear Position to 400 inches (10 m) Compact Design • Simple To Install User Adjustable Measuring Cable orientation

Specifications

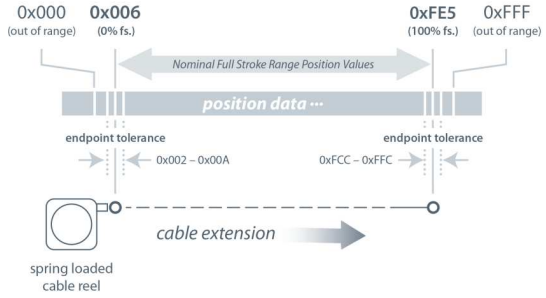
Stroke Range Options	250 inches (6.4 m), 400 inches (10.2 m)
Accuracy	0.35% FS.
Repeatability	0.05% FS.
Resolution	12-bit
Input Voltage	10-36 VDC
Input Current	100 mA, max.
Measuring Cable	0.031-inch dia. bare stainless steel
Maximum Cable Velocity	60 inches per second
Maximum Cable Acceleration	5 g
Measuring Cable Tension	23 oz. (6,4 N) ±40%
Sensor	plastic-hybrid precision potentiometer
Cycle Life	≥ 250,000
Electrical Connection	M12 connector, mating plug included
Enclosure	glass-filled polycarbonate
Environmental	IP67
Operating Temperature	-40˚ to 185˚ F (-40˚ to 85˚ C)



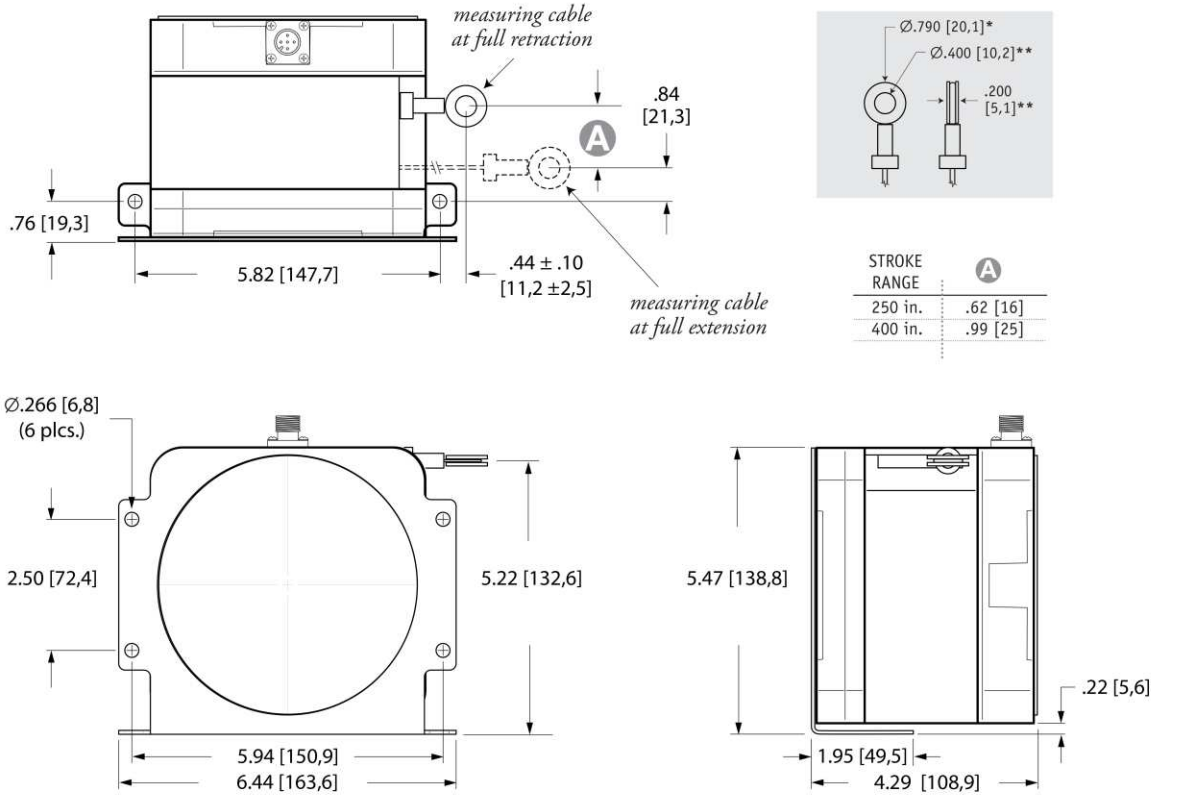
CANopen Specifications

Communication Profile	CANbus SAE J1939
Protocol	Proprietary B
Node ID	Adjustable via dipswitch (0-63), default set to 0
Baud Rate Options	125K (default), 250K, 500K
Data Rate	5ms (default), 20ms, 50ms, 100ms

Output Signal



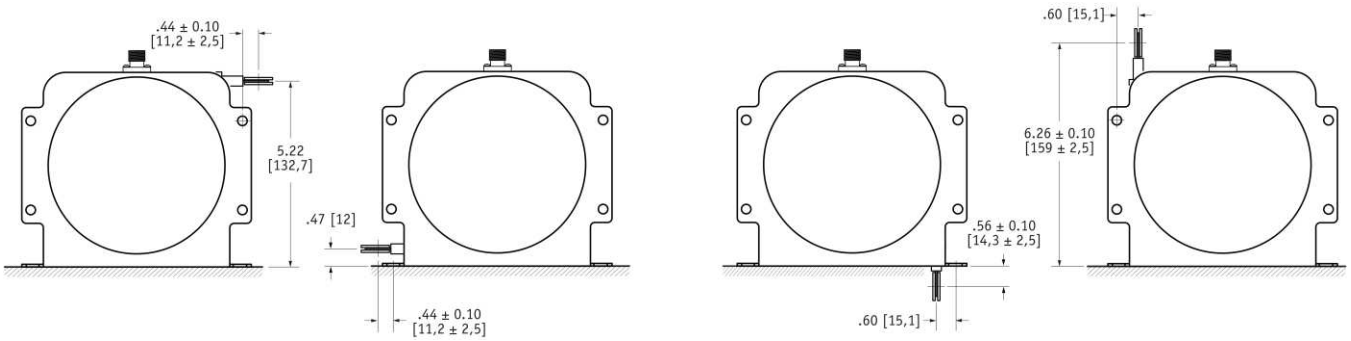
Outline Drawing



DIMENSIONS ARE IN INCHES [MM]
tolerances are 0.04 IN. [1,0 MM] unless otherwise noted.

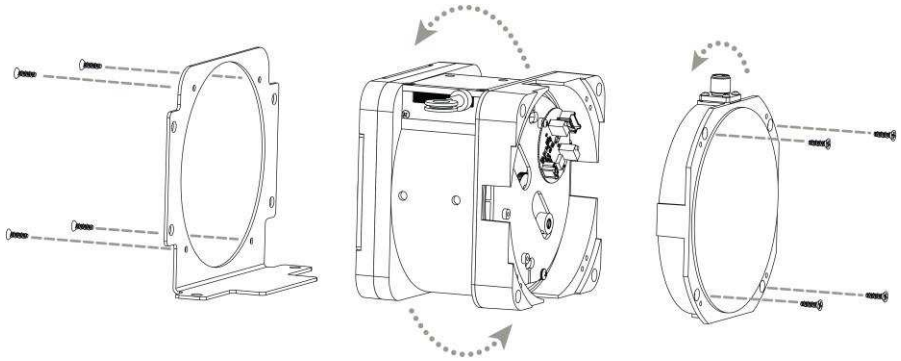
* tolerance = +.005 –.001 [+0,1 –0,0]
** tolerance = +.005 –.005 [+0,1 –0,1]

Mounting Options

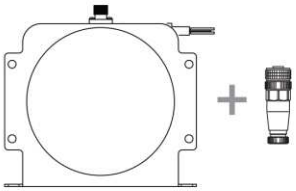


To change cable exit direction: simply remove the 4 bracket mounting screws and rotate sensor body to desired direction.

To change electrical connector orientation: remove the 4 rear screws and carefully remove the rear cover and rotate cover.

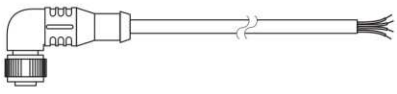


Ordering Information

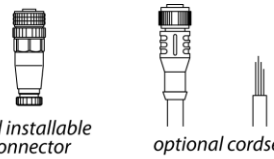


Part Number	full stroke range	accuracy	max. acceleration	measuring cable tension (± 40%)
SKJ-250-4	250 in (6.4 m)	.35%	5 g	23 oz. (6,4 N)
SKJ-400-4	400 in (10.2 m)	.35%	5 g	23 oz. (6,4N)

includes mounting bracket & mating connector.

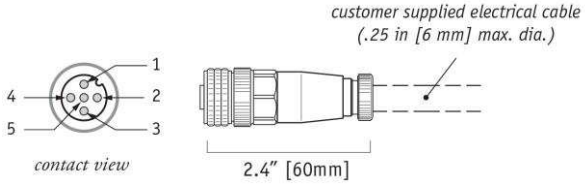
Optional Cordsets	Part Number	length	wire size	connector
	**9036810-0030**	13 ft (4 m)	22 AWG (.34mm²)	straight 5-pin M12
	**9036810-0031**	13 ft (4 m)	22 AWG (.34mm²)	90° 5-pin M12

Electrical Connection

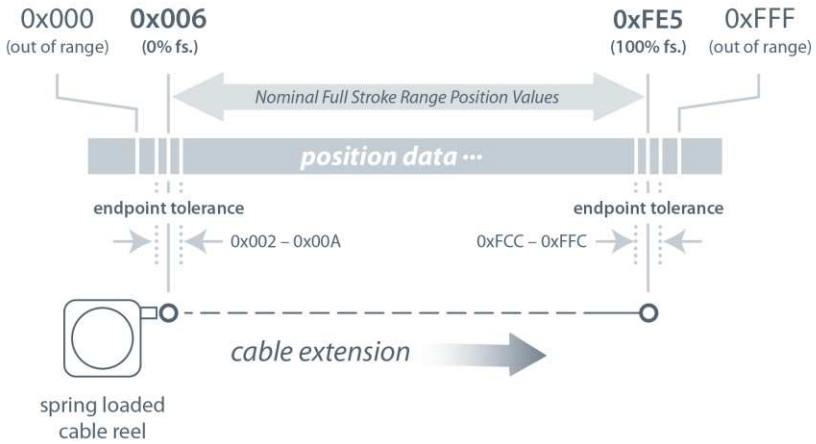


Output Signal	pin	pin - color
n/c	1	1 - brown
10..36 Vdc	2	2 - white
common	3	3 - blue
CAN - High	4	4 - black
CAN - Low	5	5 - green/yellow

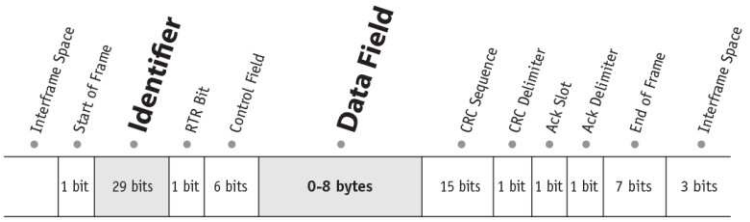
Field Installable Connector



Position Data Overview



I/O Format



Identifier

	Message Priority			Future Use		J1939 Reference Proprietary B								Data Field Type*								Not Used		Node ID**						
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –		0				F				F				5				3				3		F						

*Sensor field data can be factory set to customer specific value. **Customer defined, set via Dips 1-6. Bit values shown for example only, see **Address Setting** below.

Data Field

	B_7	B_6	B_5	B_4	B_3	B_2	B_1	B_0	

Current Measurement Count

The **C**urrent **M**easurement **C**ount (**CMC**) is the output data that indicates the present position of the measuring cable. The CMC is a 12-bit value that occupies bytes B_0 and B_1 of the data field. B_0 is the **LSB** (least significant byte) and B_1 is the **MSB** (most significant byte).

The **CMC** starts at **0x006** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFE5**. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 4061 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\frac{\text{CMC} - 6}{4063}\right) \text{ X } \text{full stroke range}$$

Sample Conversion:

If the full stroke range is **250 inches** and the current position is **0x4FF** (1279 Decimal) then,

$$\left(\frac{1279 - 6}{4061}\right) \text{ X } 250 = 78.8 \text{ inches}$$

	B_7	B_6	B_5	B_4	B_3	B_2	B_1	B_0	

Error Flags

RED and GREEN Indicator LEDS (controller board)

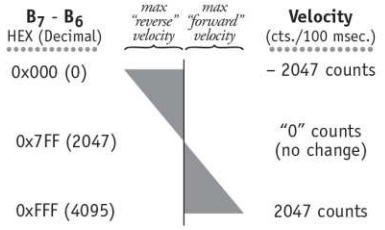
0x00 (GREEN - ON, RED - OFF) indicates the sensor is operating within normal calibrated limits.

0x33, 0x55, 0xAA, 0xCC (RED or GREEN - FLASHING) indicates sensor is at or beyond it's calibrated measurment range. Should any of these conditions occur within calibrated range, return unit to factory for evaluation or service.

	B_7	B_6	B_5	B_4	B_3	B_2	B_1	B_0	

Velocity

Data in bytes B_7 - B_6 is the change in the **CMC** (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.



Velocity Calculation

$$\left(\frac{\text{count change} - 2047}{\text{.1 sec. time period}}\right) \text{X} \left(\frac{\text{full stroke range}}{4063}\right)$$

Sample Calculations

Cable Extension (positive direction):

B_7..B_6 = 0x8D3 (2259Dec), **full stroke = 250 in.**

$$\left(\frac{2259 - 2047}{\text{.1 sec}}\right) \text{X} \left(\frac{250 \text{ in.}}{4063}\right) = 130.45 \text{ in. / sec.}$$

Cable Retraction (negative direction):

B_7..B_6 = 0x7D0 (2000Dec), **full stroke = 250 in.**

$$\left(\frac{2000 - 2047}{\text{.1 sec}}\right) \text{X} \left(\frac{250 \text{ in.}}{4063}\right) = -28.92 \text{ in. / sec.}$$