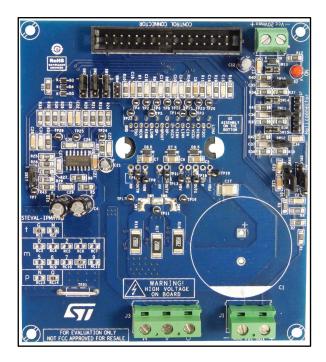


STEVAL-IPMnG8Q

Motor control power board based on the SLLIMM-nano 2nd series

Data brief



Features

- Input voltage: from 125 to 400 V_{DC}
- Nominal power: up to 600 W
- Nominal current: up to 4.8 A_{rms}
- Input auxiliary voltage: up to 20 V_{DC}
- Single- or three-shunt resistors for current sensing (with sensing network)
- Three options for current sensing: dedicated external op-amps, internal SLLIMM-nano opamp (single) or via MCU
- Overcurrent hardware protection
- IPM temperature monitoring and protection
- Hall sensor or encoder input
- IGBT intelligent power module:
 - 2nd series SLLIMM-nano IPM (STGIPQ8C60T-HZ – full molded package)

- Motor control connector (32 pins) interfacing with ST MCU boards
- Universal design for further evaluation with bread board and testing pins
- Very compact size
- RoHS compliant

Description

The STEVAL-IPMnG8Q is a compact motor drive power board based on SLLIMM™-nano (small low-loss intelligent molded module) 2nd series product (STGIPQ8C60T-HZ) . It provides an affordable and easy-to-use solution for driving high power motors in a wide range of applications such as power white goods, air conditioning, compressors, power fans and 3-phase inverters for motor drives in general.

The main characteristics of this evaluation board are small size, minimal BOM and high efficiency. It features an interface circuit (BUS and $V_{\rm CC}$ connectors), bootstrap capacitors, snubber capacitor, hardware short-circuit protection, fault event signal and temperature monitoring. It is designed to work in single- or three-shunt configuration and with triple current sensing options: three dedicated on-board op-amps, opamps embedded on MCU or single internal IPM op-amp. The Hall/Encoder part completes the circuit.

The system is designed to achieve accurate and fast conditioning of current feedback to satisfy the typical requirements for field oriented control (FOC).

The STEVAL-IPMnG8Q is compatible with ST's control board based on STM32, providing a complete platform for motor control.

Schematic diagrams

Figure 1: STEVAL-IPMNG8Q circuit schematic (1 of 5)

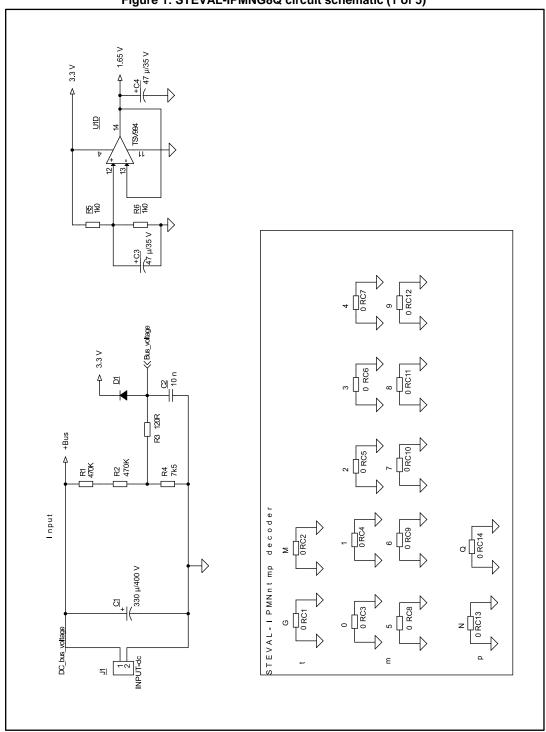
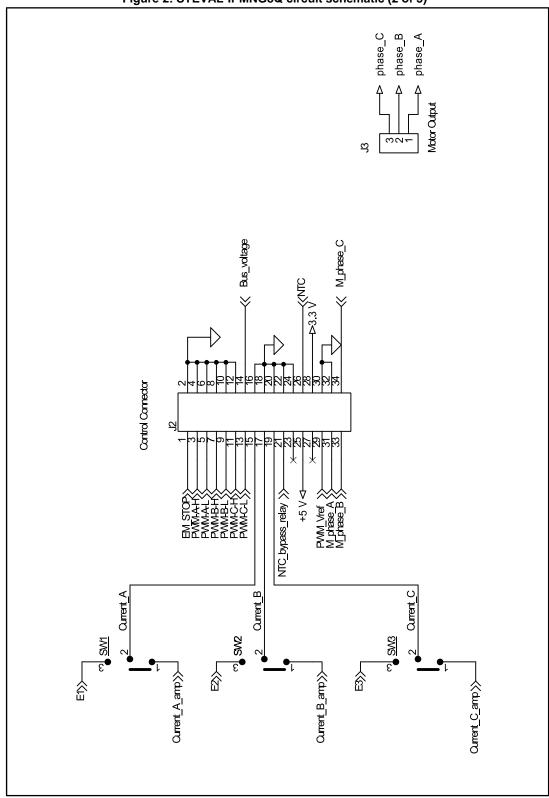


Figure 2: STEVAL-IPMNG8Q circuit schematic (2 of 5)



Schematic diagrams STEVAL-IPMnG8Q

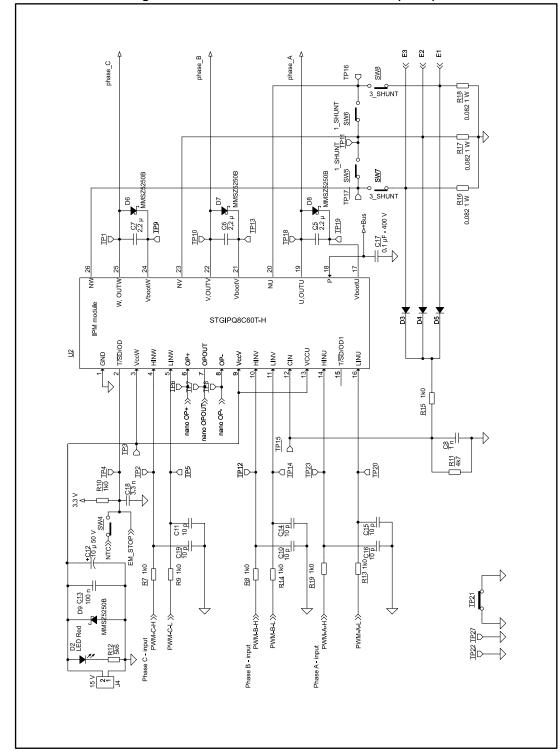


Figure 3: STEVAL-IPMNG8Q circuit schematic (3 of 5)

3.3 V U1C R25 1k9 R29 1k9 100 p 1k0 1,0 R26 Current_A_amp 1.65 V R27 R22 图 [] 100 n C21 U1B N1A R20 1k9 R24 1k9 R28 1k9 R33 1k9 100 p 5 R32 R23 1.65 V

Figure 4: STEVAL-IPMNG8Q circuit schematic (4 of 5)

R42 4k7 <u>SW14</u> ^O <u>SW15</u> R41 4K7 R40 4k7 SW13 O C37 10 p R36 4k7 C36 10 p R35 47 Hall/Encoder C35 10 p R34 47 2k4 100 [∞] SW16 3.3 V

Figure 5: STEVAL-IPMNG8Q circuit schematic (5 of 5)

STEVAL-IPMnG8Q Revision history

Revision history

Table 1: Document revision history

Date	Version	Changes
12-Sep-2017	1	Initial release.