

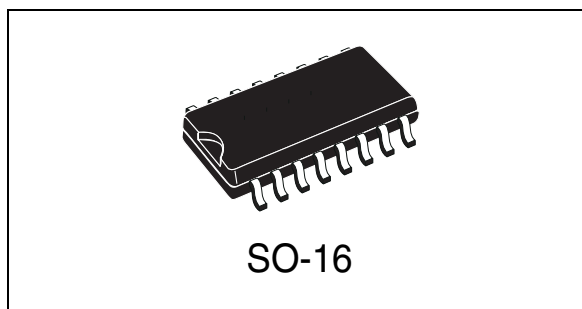
## Double channel high-side driver

### Features

| Type      | $R_{DS(on)}$                  | $I_{OUT}$            | $V_{CC}$ |
|-----------|-------------------------------|----------------------|----------|
| VND810P-E | 160 m $\Omega$ <sup>(1)</sup> | 3.5 A <sup>(1)</sup> | 36 V     |

1. Per each channel.

- ECOPACK®: lead free and RoHS compliant
- Automotive Grade: compliance with AEC Guidelines
- Very low standby current
- CMOS compatible input
- On-state open-load detection
- Off-state open-load detection
- Thermal shutdown protection and diagnosis
- Undervoltage shutdown
- Overvoltage clamp
- Output stuck to  $V_{CC}$  detection
- Load current limitation
- Reverse battery protection
- Electrostatic discharge protection



### Description

The VND810P-E is a monolithic device designed in STMicroelectronics™ VIPower™ M0-3 technology, intended for driving any kind of load with one side connected to ground.

Active  $V_{CC}$  pin voltage clamp protects the device against low energy spikes (see ISO7637 transient compatibility table).

Active current limitation combined with thermal shutdown and automatic restart protect the device against overload.

The device detects open-load condition both in on-state and off-state. Output shorted to  $V_{CC}$  is detected in the off-state. Device automatically turns off in case of ground pin disconnection.

**Table 1. Device summary**

| Package | Order codes |               |
|---------|-------------|---------------|
|         | Tube        | Tape and reel |
| SO-16   | VND810P-E   | VND810PTR-E   |

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# 1 Block diagram and pin description

Figure 1. Block diagram

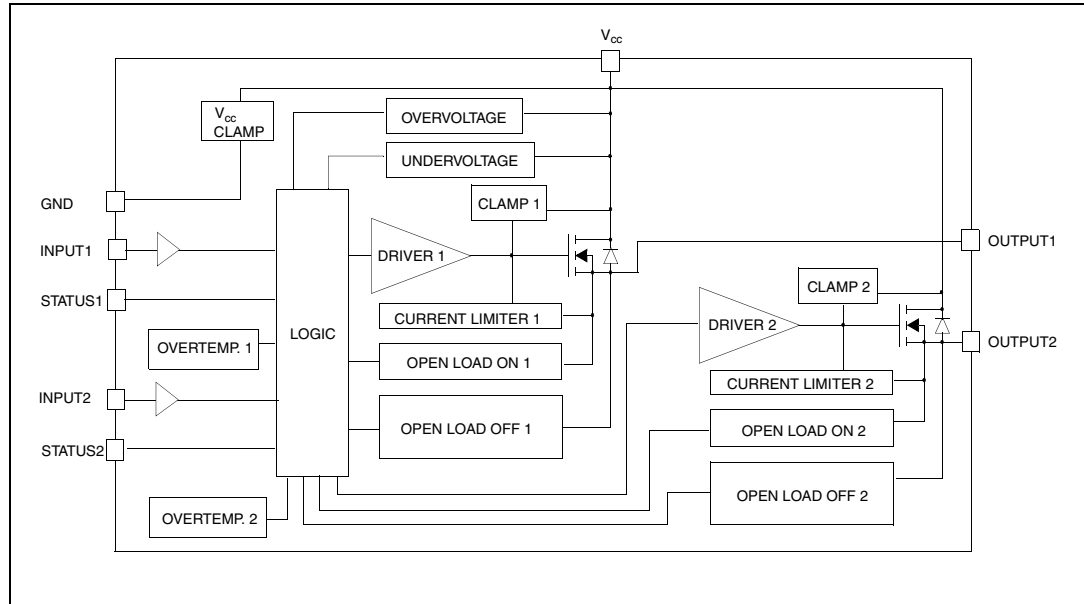


Figure 2. Configuration diagram (top view)

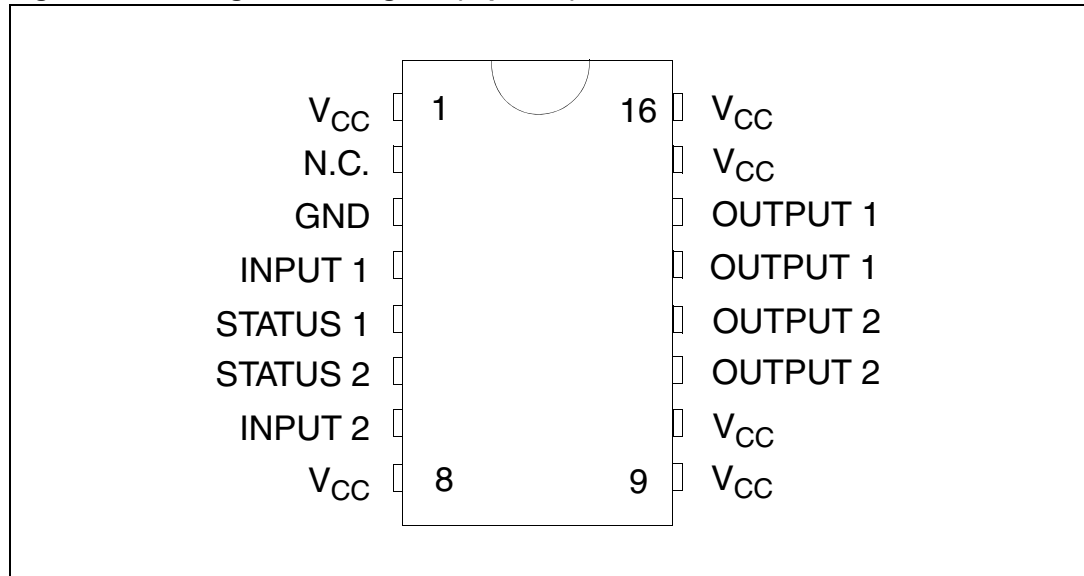


Table 2. Suggested connections for unused and not connected pins

| Connection / pin | Status | N.C. | Output | Input                 |
|------------------|--------|------|--------|-----------------------|
| Floating         | X      | X    | X      | X                     |
| To ground        |        | X    |        | Through 10KΩ resistor |

## 2 Electrical specifications

### 2.1 Absolute maximum ratings

Stressing the device above the rating listed in the “Absolute maximum ratings” table may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality document.

**Table 3. Absolute maximum ratings**

| Symbol     | Parameter   | Value              | Unit       |
|------------|---|--------------------|------------|
| $V_{CC}$   | DC supply voltage   | 41                 | V          |
| $-V_{CC}$  | Reverse DC supply voltage   | - 0.3              | V          |
| $-I_{GND}$ | DC reverse ground pin current   | - 200              | mA         |
| $I_{OUT}$  | DC output current   | Internally limited | A          |
| $-I_{OUT}$ | Reverse DC output current   | - 6                | A          |
| $I_{IN}$   | DC input current  | +/- 10             | mA         |
| $I_{STAT}$ | DC Status current   | +/- 10             | mA         |
| $V_{ESD}$  | Electrostatic discharge (human body model: $R=1.5K\Omega$ ; $C = 100pF$ )   |                    |            |
|            | – INPUT   | 4000               | V          |
|            | – STATUS  | 4000               | V          |
|            | – OUTPUT  | 5000               | V          |
|            | – $V_{CC}$  | 5000               | V          |
| $E_{MAX}$  | Maximum switching energy<br>( $L = 1.5mH$ ; $R_L = 0\Omega$ ; $V_{bat} = 13.5V$ ; $T_{jstart} = 150^\circ C$ ; $I_L = 5A$ ) | 26                 | mJ         |
| $P_{tot}$  | Power dissipation (per island) at $T_{lead} = 25^\circ C$   | 8.3                | W          |
| $T_j$      | Junction operating temperature  | Internally limited | $^\circ C$ |
| $T_c$      | Case operating temperature  | - 40 to 150        |            |
| $T_{stg}$  | Storage temperature   | - 55 to 150        | $^\circ C$ |

## 2.2 Thermal data

**Table 4. Thermal data (per island)**

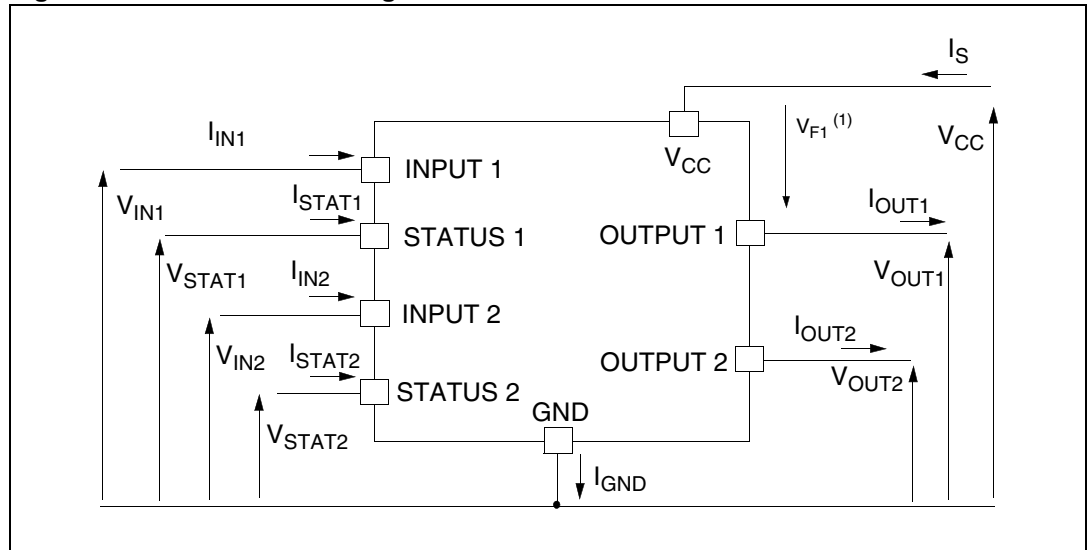
| Symbol         | Parameter                           | Value             |                   | Unit |
|----------------|-------------------------------------|-------------------|-------------------|------|
| $R_{thj-lead}$ | Thermal resistance junction-lead    | 15                |                   | °C/W |
| $R_{thj-amb}$  | Thermal resistance junction-ambient | 77 <sup>(1)</sup> | 57 <sup>(2)</sup> | °C/W |

1. When mounted on a standard single-sided FR-4 board with 0.5 cm<sup>2</sup> of Cu (at least 35 μm thick) connected to all V<sub>CC</sub> pins. Horizontal mounting and no artificial air flow.
2. When mounted on a standard single-sided FR-4 board with 4 cm<sup>2</sup> of Cu (at least 35 μm thick) connected to all V<sub>CC</sub> pins. Horizontal mounting and no artificial air flow.

## 2.3 Electrical characteristics

Values specified in this section are for 8 V < V<sub>CC</sub> < 36 V; -40 °C < T<sub>j</sub> < 150 °C, unless otherwise stated.

**Figure 3. Current and voltage conventions**



1.  $V_{Fn} = V_{CCn} - V_{OUTn}$  during reverse battery condition.

**Table 5. Power output**

| Symbol          | Parameter                | Test conditions  | Min. | Typ. | Max.       | Unit     |
|-----------------|--------------------------|--|------|------|------------|----------|
| $V_{CC}^{(1)}$  | Operating supply voltage |  | 5.5  | 13   | 36         | V        |
| $V_{USD}^{(1)}$ | Undervoltage shutdown    |  | 3    | 4    | 5.5        | V        |
| $V_{OV}^{(1)}$  | Overvoltage shutdown     |  | 36   |      |            | V        |
| $R_{ON}$        | On-state resistance      | $I_{OUT} = 1\text{ A}; T_j = 25\text{ °C}$<br>$I_{OUT} = 1\text{ A}; V_{CC} > 8\text{ V}$      |      |      | 160<br>320 | mΩ<br>mΩ |
| $I_S^{(1)}$     | Supply current           | Off-state; $V_{CC} = 13\text{ V};$<br>$V_{IN} = V_{OUT} = 0\text{ V}$                          |      | 12   | 40         | μA       |
|                 |                          | Off-state; $V_{CC} = 13\text{ V};$<br>$V_{IN} = V_{OUT} = 0\text{ V};$<br>$T_j = 25\text{ °C}$ |      | 12   | 25         | μA       |
|                 |                          | On-state; $V_{CC} = 13\text{ V}; V_{IN} = 5\text{ V};$<br>$I_{OUT} = 0\text{ A}$               |      | 5    | 7          | mA       |
| $I_{L(off1)}$   | Off-state output current | $V_{IN} = V_{OUT} = 0\text{ V}$  | 0    |      | 50         | μA       |
| $I_{L(off2)}$   | Off-state output current | $V_{IN} = 0\text{ V}; V_{OUT} = 3.5\text{ V}$  | -75  |      | 0          | μA       |
| $I_{L(off3)}$   | Off-state output current | $V_{IN} = V_{OUT} = 0\text{ V}; V_{CC} = 13\text{ V};$<br>$T_j = 125\text{ °C}$                |      |      | 5          | μA       |
| $I_{L(off4)}$   | Off-state output current | $V_{IN} = V_{OUT} = 0\text{ V}; V_{CC} = 13\text{ V};$<br>$T_j = 25\text{ °C}$                 |      |      | 3          | μA       |

1. Per device.

**Table 6. Protections<sup>(1)</sup>**

| Symbol      | Parameter                           | Test conditions                         | Min.        | Typ.        | Max.        | Unit |
|-------------|-------------------------------------|---|-------------|-------------|-------------|------|
| $T_{TSD}$   | Shutdown temperature                |   | 150         | 175         | 200         | °C   |
| $T_R$       | Reset temperature                   |   | 135         |             |             | °C   |
| $T_{hyst}$  | Thermal hysteresis                  |   | 7           | 15          |             | °C   |
| $t_{SDL}$   | Status delay in overload conditions | $T_j > T_{TSD}$                         |             |             | 20          | μs   |
| $I_{lim}$   | Current limitation                  | $V_{CC} = 13\text{ V}$                  | 3.5         | 5           | 7.5         | A    |
|             |                                     | $5.5\text{ V} < V_{CC} < 36\text{ V}$   |             |             | 7.5         | A    |
| $V_{demag}$ | Turn-off output clamp voltage       | $I_{OUT} = 1\text{ A}; L = 6\text{ mH}$ | $V_{CC}-41$ | $V_{CC}-48$ | $V_{CC}-55$ | V    |

1. To ensure long term reliability under heavy overload or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.



**Table 7.  $V_{CC}$  - output diode**

| Symbol | Parameter          | Test conditions   | Min. | Typ. | Max. | Unit |
|--------|--------------------|---|------|------|------|------|
| $V_F$  | Forward on voltage | $-I_{OUT} = 0.5 \text{ A}$ ; $T_j = 150 \text{ }^\circ\text{C}$ | —    | —    | 0.6  | V    |

**Table 8. Status pin**

| Symbol      | Parameter                    | Test conditions                            | Min. | Typ. | Max. | Unit          |
|-------------|------------------------------|--|------|------|------|---------------|
| $V_{STAT}$  | Status low output voltage    | $I_{STAT} = 1.6 \text{ mA}$                |      |      | 0.5  | V             |
| $I_{LSTAT}$ | Status leakage current       | Normal operation; $V_{STAT} = 5 \text{ V}$ |      |      | 10   | $\mu\text{A}$ |
| $C_{STAT}$  | Status pin Input capacitance | Normal operation; $V_{STAT} = 5 \text{ V}$ |      |      | 100  | pF            |
| $V_{SCL}$   | Status clamp voltage         | $I_{STAT} = 1 \text{ mA}$                  | 6    | 6.8  | 8    | V             |
|             |                              | $I_{STAT} = -1 \text{ mA}$                 |      | -0.7 |      | V             |

**Table 9. Switching ( $V_{CC} = 13\text{V}$ )**

| Symbol                | Parameter              | Test conditions   | Min. | Typ.                          | Max. | Unit                   |
|-----------------------|------------------------|---|------|-------------------------------|------|------------------------|
| $t_{d(on)}$           | Turn-on delay time     | $R_L = 13 \text{ } \Omega$ from $V_{IN}$ rising edge to $V_{OUT} = 1.3 \text{ V}$ (see <a href="#">Figure 5</a> )       | —    | 30                            | —    | $\mu\text{s}$          |
| $t_{d(off)}$          | Turn-off delay time    | $R_L = 13 \text{ } \Omega$ from $V_{IN}$ falling edge to $V_{OUT} = 11.7 \text{ V}$ (see <a href="#">Figure 5</a> )     | —    | 30                            | —    | $\mu\text{s}$          |
| $dV_{OUT}/dt_{(on)}$  | Turn-on voltage slope  | $R_L = 13 \text{ } \Omega$ from $V_{OUT} = 1.3 \text{ V}$ to $V_{OUT} = 10.4 \text{ V}$ (see <a href="#">Figure 5</a> ) | —    | See <a href="#">Figure 21</a> | —    | $\text{V}/\mu\text{s}$ |
| $dV_{OUT}/dt_{(off)}$ | Turn-off voltage slope | $R_L = 13 \text{ } \Omega$ from $V_{OUT} = 11.7 \text{ V}$ to $V_{OUT} = 1.3 \text{ V}$ (see <a href="#">Figure 5</a> ) | —    | See <a href="#">Figure 22</a> | —    | $\text{V}/\mu\text{s}$ |

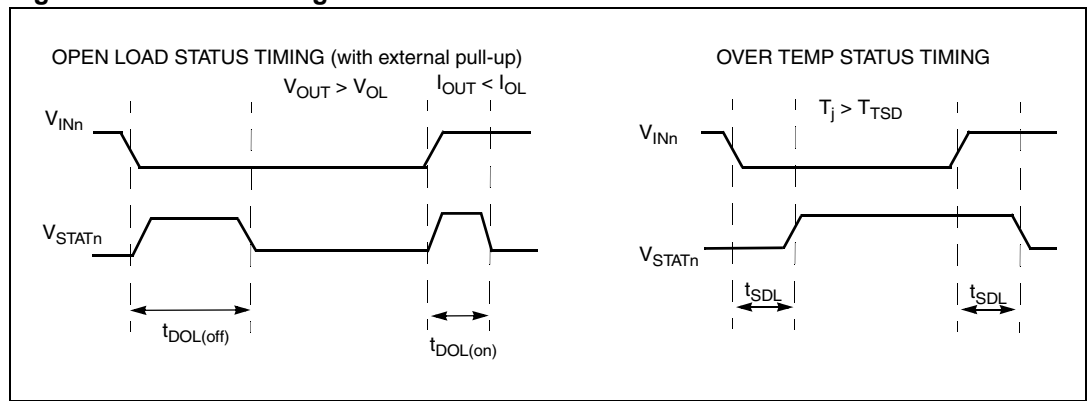
**Table 10. Open-load detection**

| Symbol         | Parameter                                       | Test conditions         | Min. | Typ. | Max. | Unit          |
|----------------|---|-------------------------|------|------|------|---------------|
| $I_{OL}$       | Open-load on-state detection threshold          | $V_{IN} = 5 \text{ V}$  | 20   | 40   | 80   | mA            |
| $t_{DOL(on)}$  | Open-load on-state detection delay              | $I_{OUT} = 0 \text{ A}$ |      |      | 200  | $\mu\text{s}$ |
| $V_{OL}$       | Open-load off-state voltage detection threshold | $V_{IN} = 0 \text{ V}$  | 1.5  | 2.5  | 3.5  | V             |
| $t_{DOL(off)}$ | Open-load detection delay at turn-off           |                         |      |      | 1000 | $\mu\text{s}$ |

**Table 11. Logic inputs**

| Symbol        | Parameter                | Test conditions          | Min. | Typ. | Max. | Unit          |
|---------------|--------------------------|--------------------------|------|------|------|---------------|
| $V_{IL}$      | Input low level          |                          |      |      | 1.25 | V             |
| $I_{IL}$      | Low level input current  | $V_{IN} = 1.25\text{ V}$ | 1    |      |      | $\mu\text{A}$ |
| $V_{IH}$      | Input high level         |                          | 3.25 |      |      | V             |
| $I_{IH}$      | High level input current | $V_{IN} = 3.25\text{ V}$ |      |      | 10   | $\mu\text{A}$ |
| $V_{I(hyst)}$ | Input hysteresis voltage |                          | 0.5  |      |      | V             |
| $V_{ICL}$     | Input clamp voltage      | $I_{IN} = 1\text{ mA}$   | 6    | 6.8  | 8    | V             |
|               |                          | $I_{IN} = -1\text{ mA}$  |      | -0.7 |      | V             |

**Figure 4. Status timings**



**Figure 5. Switching time waveforms**

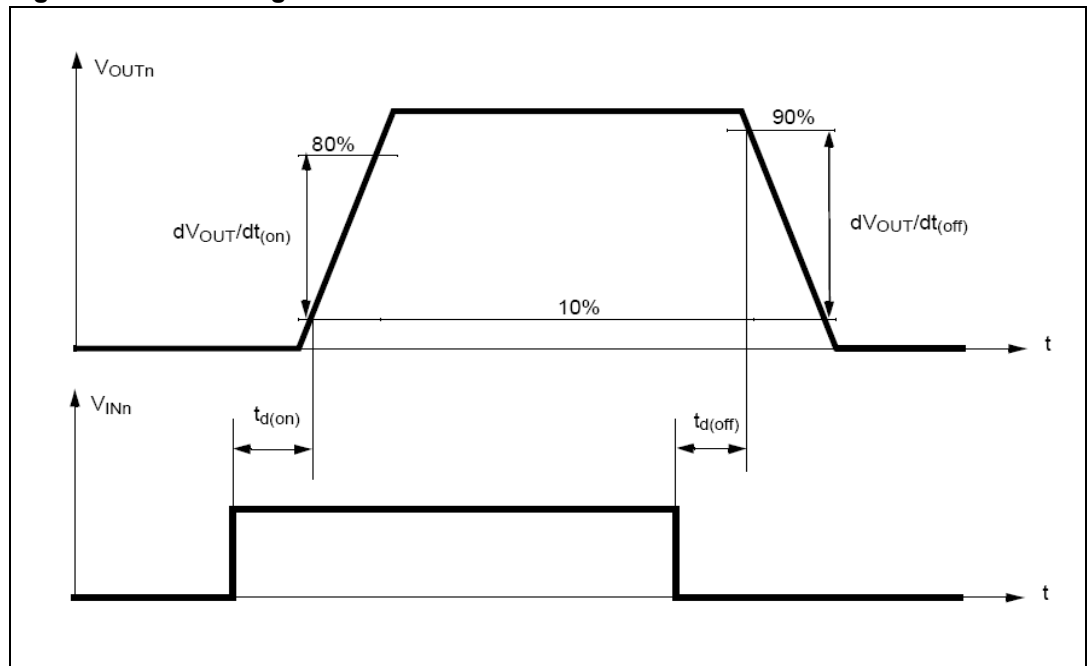


Table 12. Truth table

| Conditions                | Input | Output | Status              |
|---------------------------|-------|--------|---------------------|
| Normal operation          | L     | L      | H                   |
|                           | H     | H      | H                   |
| Current limitation        | L     | L      | H                   |
|                           | H     | X      | $(T_j < T_{TSD})$ H |
|                           | H     | X      | $(T_j > T_{TSD})$ L |
| Overtemperature           | L     | L      | H                   |
|                           | H     | L      | L                   |
| Undervoltage              | L     | L      | X                   |
|                           | H     | L      | X                   |
| Overvoltage               | L     | L      | H                   |
|                           | H     | L      | H                   |
| Output voltage $> V_{OL}$ | L     | H      | L                   |
|                           | H     | H      | H                   |
| Output current $< I_{OL}$ | L     | L      | H                   |
|                           | H     | H      | L                   |

**Table 13. Electrical transient requirements (part 1/3)**

| ISO T/R<br>7637/1<br>Test pulse | Test level |          |          |          | Delays and impedance |
|---------------------------------|------------|----------|----------|----------|----------------------|
|                                 | I          | II       | III      | IV       |                      |
| 1                               | - 25 V     | - 50 V   | - 75 V   | - 100 V  | 2 ms, 10 Ω           |
| 2                               | + 25 V     | + 50 V   | + 75 V   | + 100 V  | 0.2 ms, 10 Ω         |
| 3a                              | - 25 V     | - 50 V   | - 100 V  | - 150 V  | 0.1 μs, 50 Ω         |
| 3b                              | + 25 V     | + 50 V   | + 75 V   | + 100 V  | 0.1 μs, 50 Ω         |
| 4                               | - 4 V      | - 5 V    | - 6 V    | - 7 V    | 100 ms, 0.01 Ω       |
| 5                               | + 26.5 V   | + 46.5 V | + 66.5 V | + 86.5 V | 400 ms, 2 Ω          |

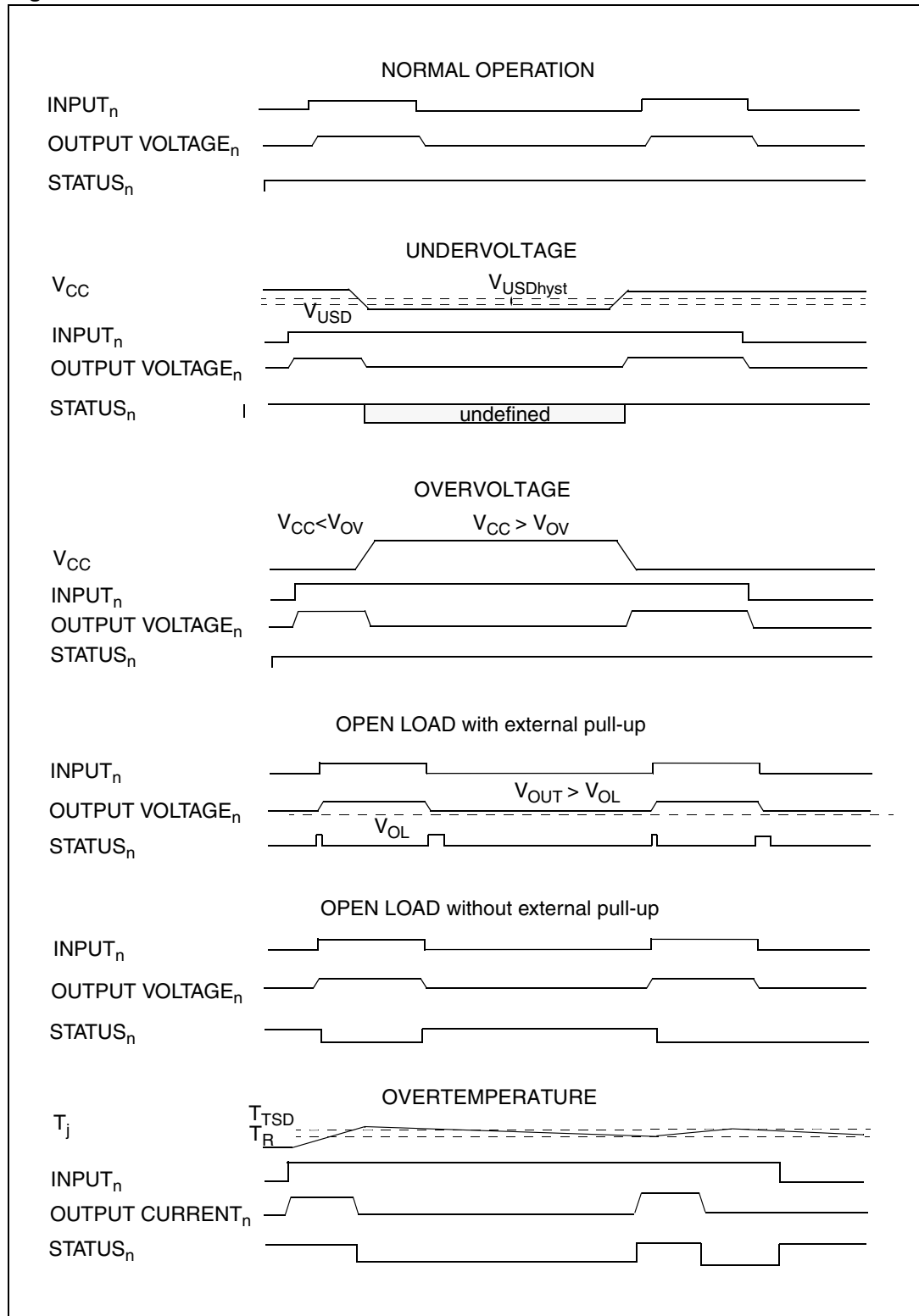
**Table 14. Electrical transient requirements (part 2/3)**

| ISO 7637-1:<br>Test pulse | Test level results |    |     |    |
|---------------------------|--------------------|----|-----|----|
|                           | I                  | II | III | IV |
| 1                         | C                  | C  | C   | C  |
| 2                         | C                  | C  | C   | C  |
| 3a                        | C                  | C  | C   | C  |
| 3b                        | C                  | C  | C   | C  |
| 4                         | C                  | C  | C   | C  |
| 5                         | C                  | E  | E   | E  |

**Table 15. Electrical transient requirements (part 3/3)**

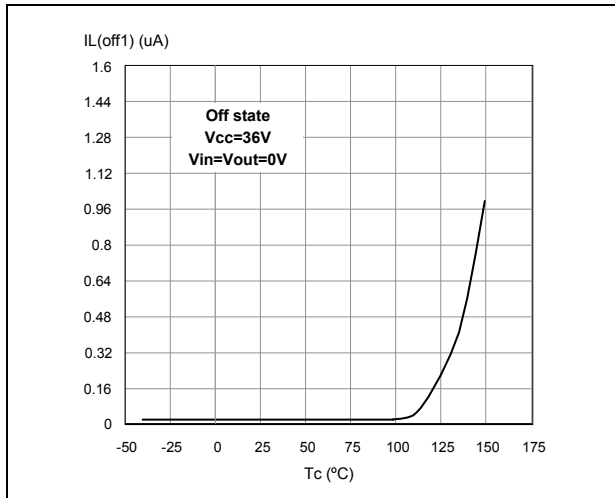
| Class | Contents   |
|-------|--|
| C     | All functions of the device performed as designed after exposure to disturbance.   |
| E     | One or more functions of the device did not perform as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device. |

Figure 6. Waveforms

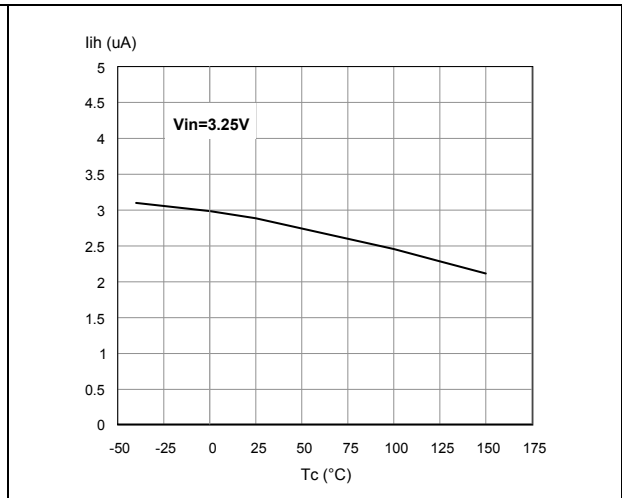


## 2.4 Electrical characteristics curves

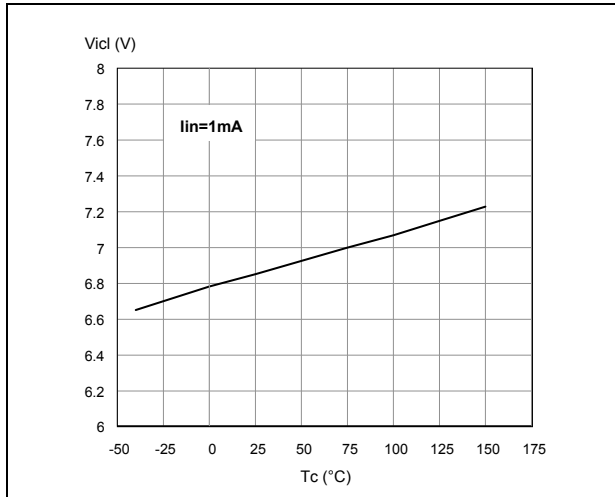
**Figure 7. Off-state output current**



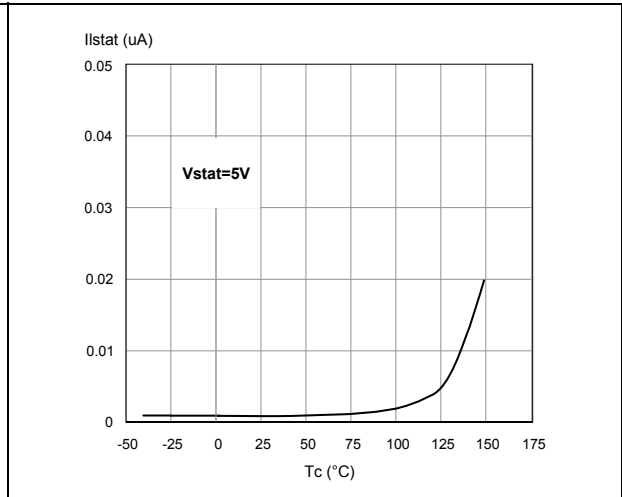
**Figure 8. High level input current**



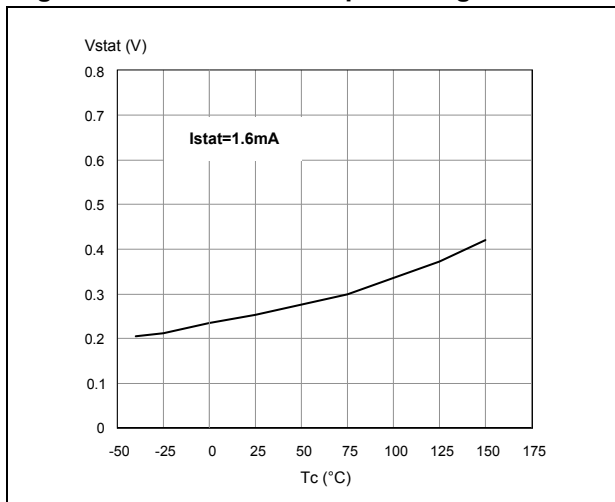
**Figure 9. Input clamp voltage**



**Figure 10. Status leakage current**



**Figure 11. Status low output voltage**



**Figure 12. Status clamp voltage**

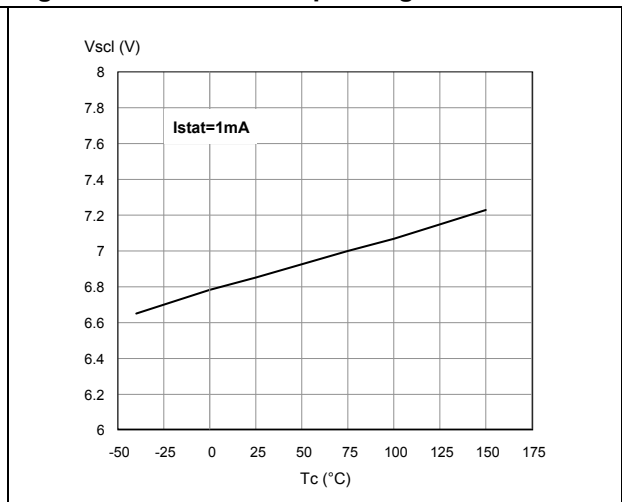


Figure 13. On-state resistance vs  $T_{case}$

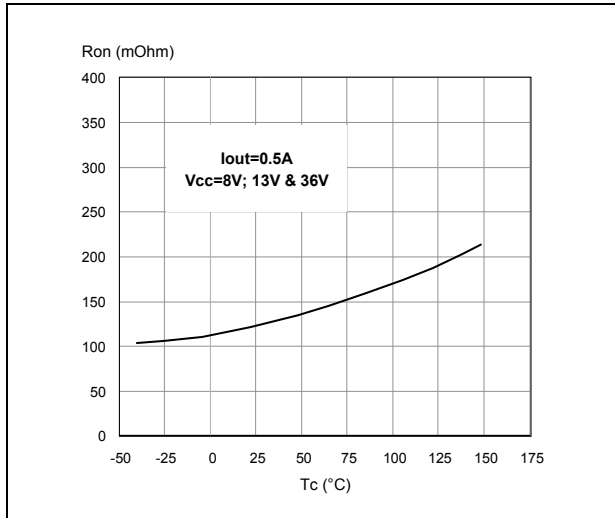


Figure 14. On-state resistance vs  $V_{CC}$

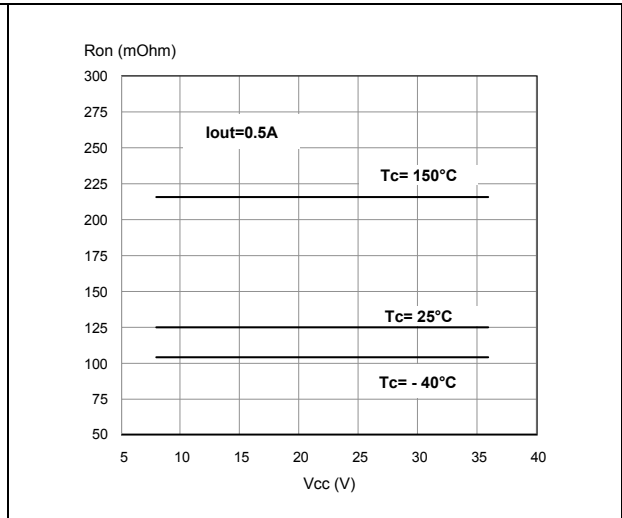


Figure 15. Open-load on-state detection threshold

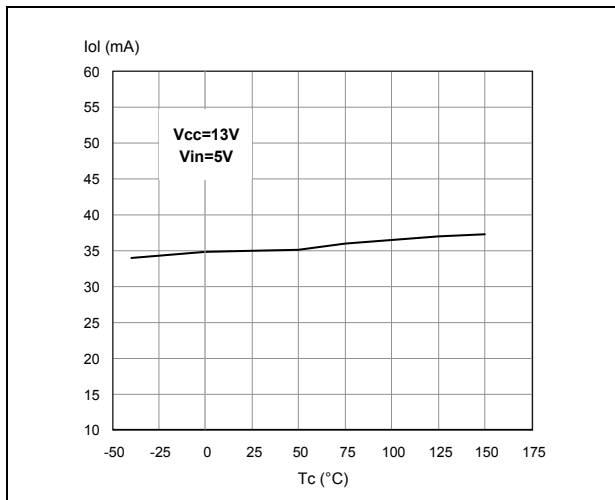


Figure 16. Open-load off-state voltage detection threshold

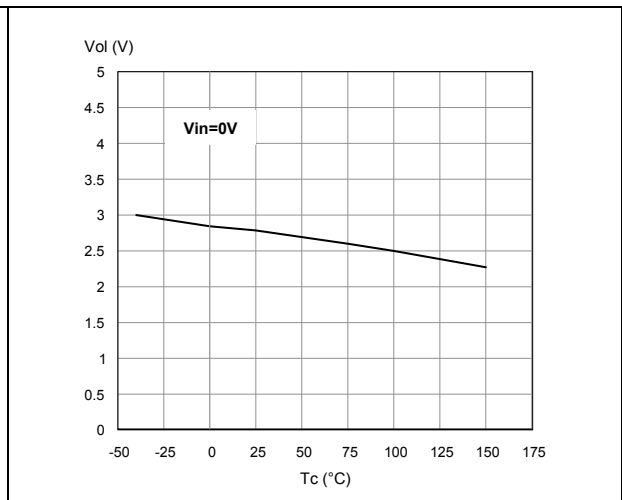


Figure 17. Input high level

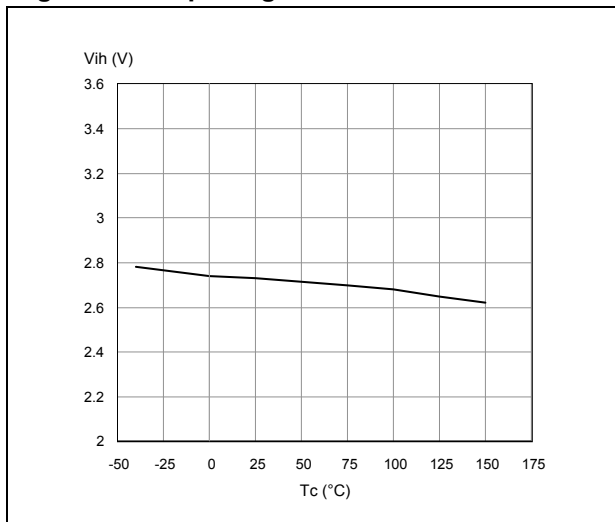


Figure 18. Input low level

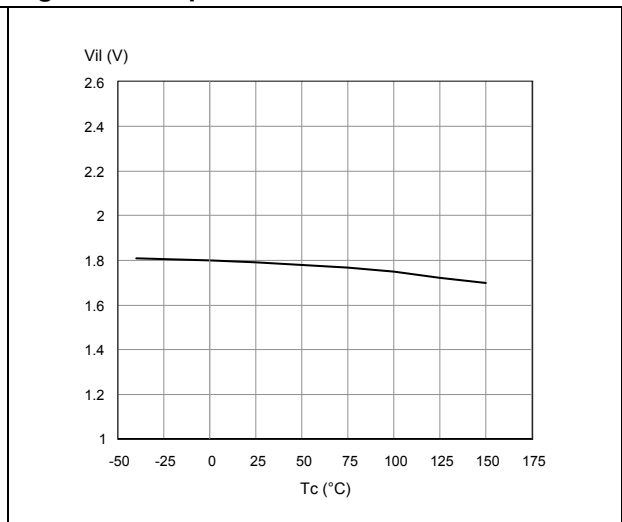


Figure 19. Input hysteresis voltage

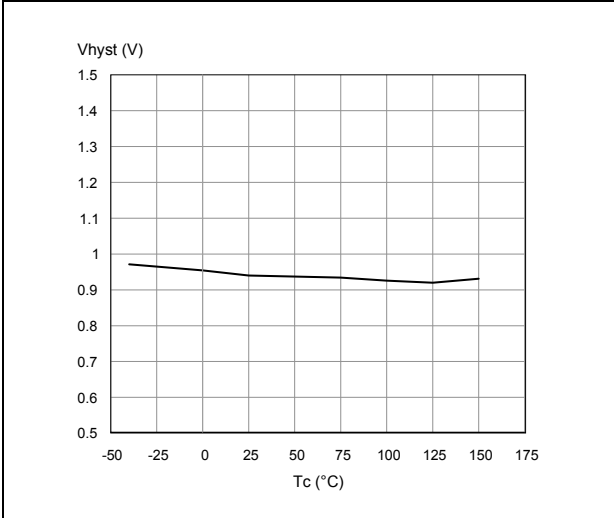


Figure 20. Overvoltage shutdown

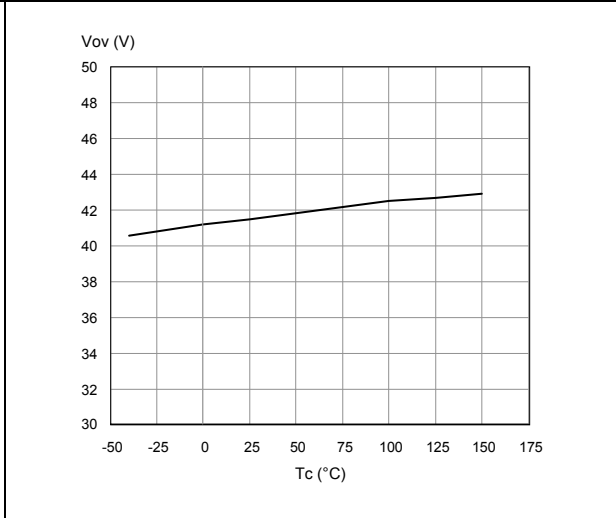


Figure 21. Turn-on voltage slope

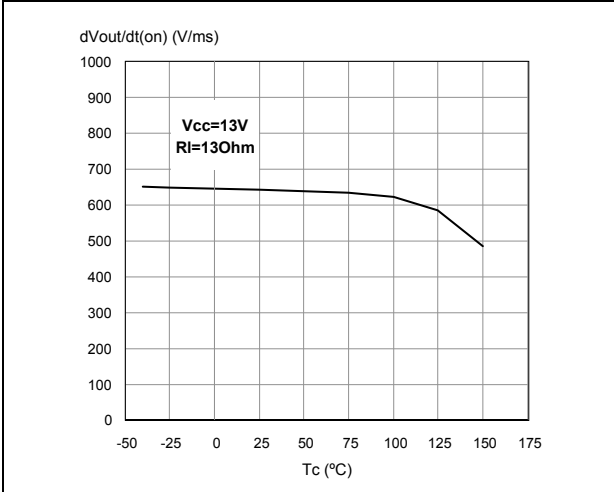


Figure 22. Turn-off voltage slope

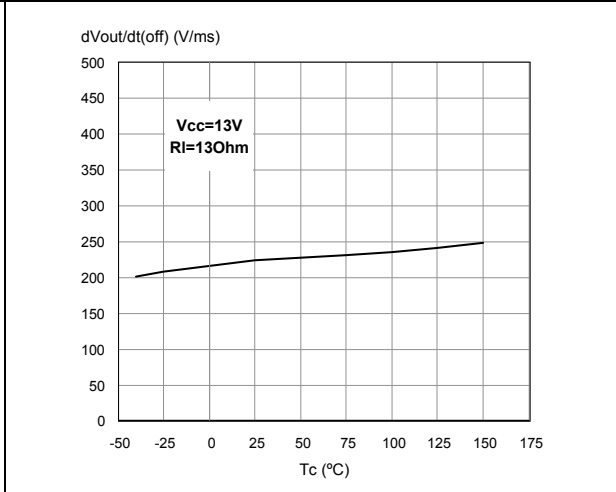
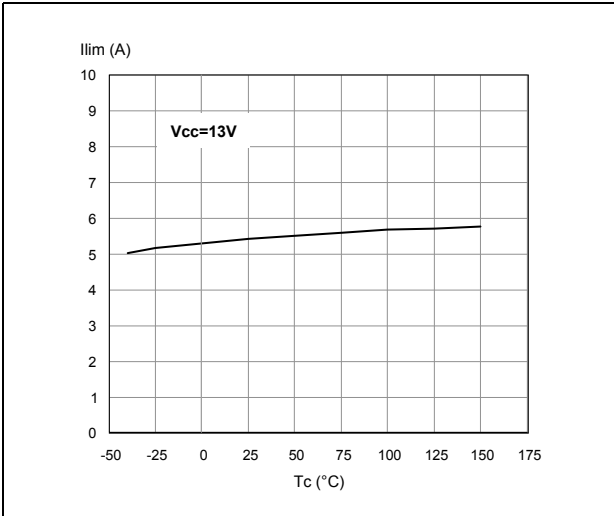


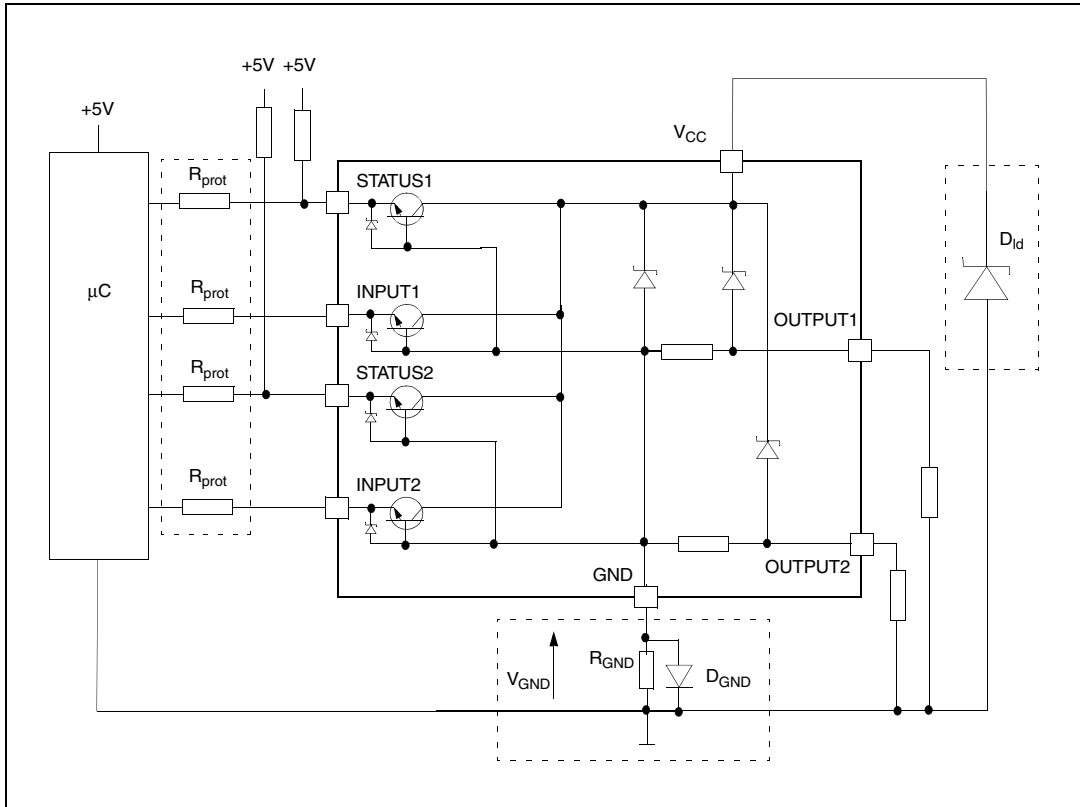
Figure 23. I<sub>LIM</sub> vs T<sub>case</sub>





### 3 Application information

Figure 24. Application schematic



#### 3.1 GND protection network against reverse battery

This section provides two solutions for implementing a ground protection network against reverse battery.

##### 3.1.1 Solution 1: a resistor in the ground line (R<sub>GND</sub> only)

This can be used with any type of load.

The following show how to dimension the R<sub>GND</sub> resistor:

**Equation 1:**

$$R_{GND} \leq 600 \text{ mV} / I_{S(on)max}$$

**Equation 2**

$$R_{GND} \geq (-V_{CC}) / (-I_{GND})$$

where -I<sub>GND</sub> is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device datasheet.

Power dissipation in  $R_{GND}$  (when  $V_{CC} < 0$  during reverse battery situations) is:

$$P_D = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSDs. Please note that the value of this resistor should be calculated with [Equation 1](#) where  $I_{S(on)max}$  becomes the sum of the maximum on-state currents of the different devices.

Please note that, if the microprocessor ground is not shared by the device ground, then the  $R_{GND}$  produces a shift ( $I_{S(on)max} * R_{GND}$ ) in the input thresholds and the status output values. This shift varies depending on how many devices are ON in the case of several high-side drivers sharing the same  $R_{GND}$ .

If the calculated power dissipation requires the use of a large resistor, or several devices have to share the same resistor, then ST suggests using solution 2 below.

### 3.1.2 Solution 2: a diode ( $D_{GND}$ ) in the ground line

A resistor ( $R_{GND} = 1 \text{ k}\Omega$ ) should be inserted in parallel to  $D_{GND}$  if the device is driving an inductive load. This small signal diode can be safely shared amongst several different HSD. Also in this case, the presence of the ground network produces a shift ( $\approx 600 \text{ mV}$ ) in the input threshold and the status output values if the microprocessor ground is not common with the device ground. This shift not varies if more than one HSD shares the same diode/resistor network. Series resistor in INPUT and STATUS lines are also required to prevent that, during battery voltage transient, the current exceeds the Absolute Maximum Rating. Safest configuration for unused INPUT and STATUS pin is to leave them unconnected.

## 3.2 Load dump protection

$D_{ld}$  is necessary (voltage transient suppressor) if the load dump peak voltage exceeds the  $V_{CC}$  maximum DC rating. The same applies if the device is subject to transients on the  $V_{CC}$  line that are greater than those shown in the ISO T/R 7637/1 table.

## 3.3 MCU I/O protection

If a ground protection network is used and negative transients are present on the  $V_{CC}$  line, the control pins are pulled negative. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the microcontroller I/O pins from latching up.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of microcontroller I/Os:

$$-V_{CCpeak} / I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

### Example

For the following conditions:

$$V_{CCpeak} = -100 \text{ V}$$

$$I_{latchup} \geq 20 \text{ mA}$$

$$V_{OH\mu C} \geq 4.5 \text{ V}$$

$$5 \text{ k}\Omega \leq R_{prot} \leq 65 \text{ k}\Omega$$

Recommended values are:

$$R_{\text{prot}} = 10 \text{ k}\Omega$$

### 3.4 Open-load detection in off-state

Off-state open-load detection requires an external pull-up resistor ( $R_{\text{PU}}$ ) connected between OUTPUT pin and a positive supply voltage ( $V_{\text{PU}}$ ) like the +5 V line used to supply the microprocessor.

The external resistor has to be selected according to the following requirements:

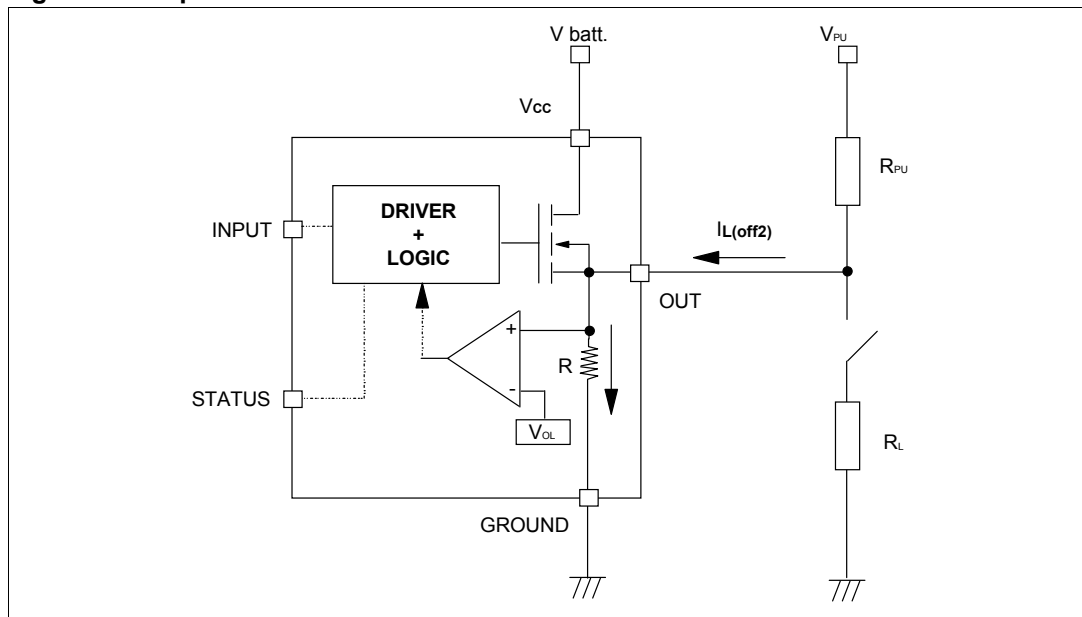
1. No false open-load indication when load is connected: in this case we have to avoid  $V_{\text{OUT}}$  to be higher than  $V_{\text{OLmin}}$ ; this results in the following condition  

$$V_{\text{OUT}} = (V_{\text{PU}} / (R_{\text{L}} + R_{\text{PU}}))R_{\text{L}} < V_{\text{OLmin}}$$
2. No misdetection when load is disconnected: in this case the  $V_{\text{OUT}}$  has to be higher than  $V_{\text{OLmax}}$ ; this results in the following condition  $R_{\text{PU}} < (V_{\text{PU}} - V_{\text{OLmax}}) / I_{\text{L(off2)}}$ .

Because  $I_{\text{s(OFF)}}$  may significantly increase if  $V_{\text{out}}$  is pulled high (up to several mA), the pull-up resistor  $R_{\text{PU}}$  should be connected to a supply that is switched OFF when the module is in standby.

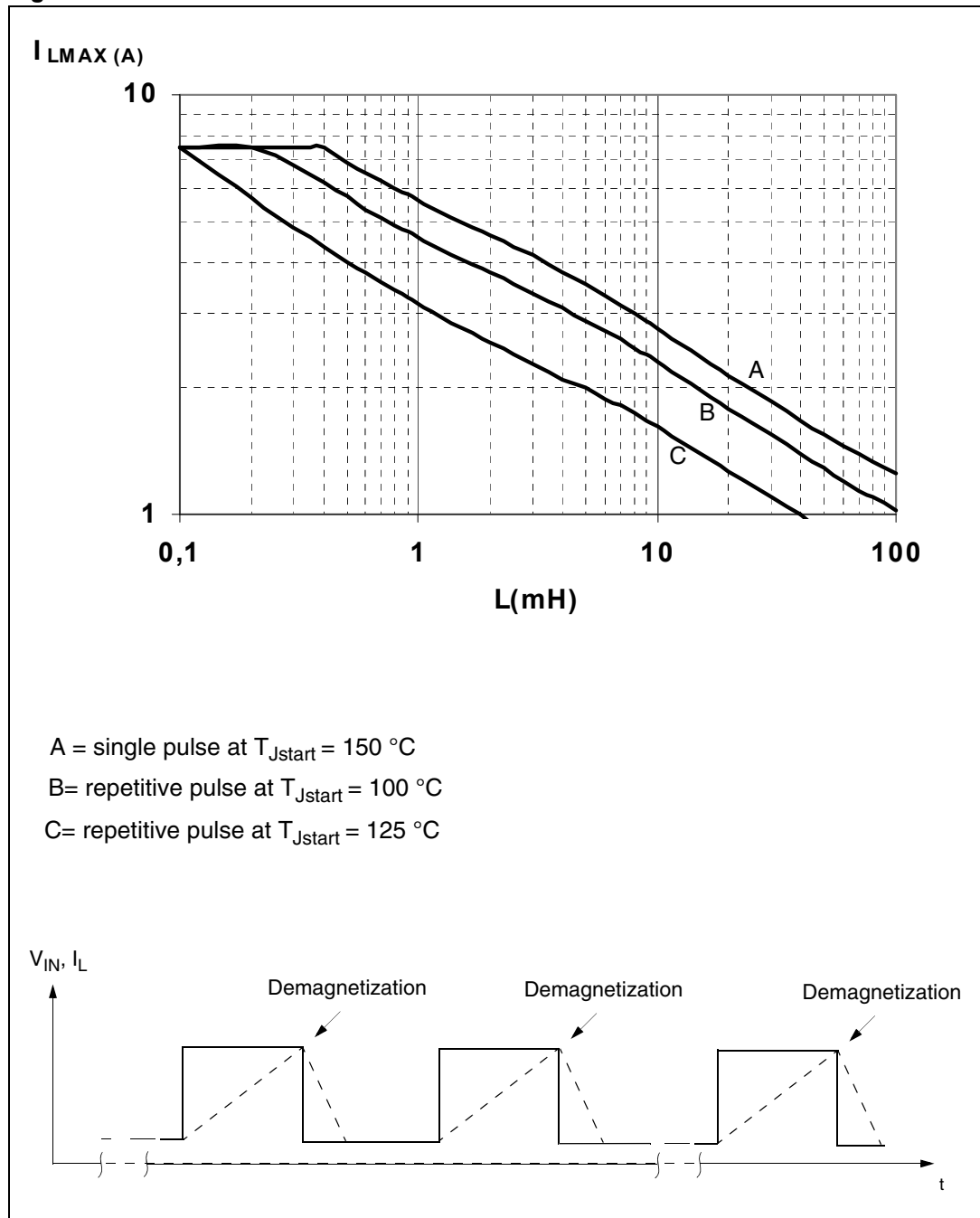
The values of  $V_{\text{OLmin}}$ ,  $V_{\text{OLmax}}$  and  $I_{\text{L(off2)}}$  are available in [Section 2.3: Electrical characteristics](#).

**Figure 25. Open-load detection in off-state**



### 3.5 Maximum demagnetization energy ( $V_{CC} = 13.5\text{ V}$ )

Figure 26. Maximum turn-off current versus load inductance<sup>(1)</sup>

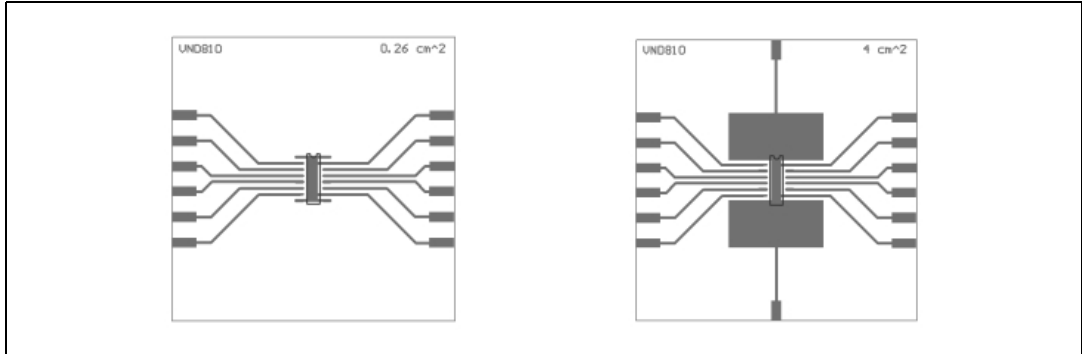


1. Values are generated with  $R_L = 0\ \Omega$ .  
 In case of repetitive pulses,  $T_{Jstart}$  (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves B and C.

## 4 Package and PCB thermal data

### 4.1 SO-16 thermal data

Figure 27. SO-16 PC board<sup>(1)</sup>



1. Layout condition of  $R_{th}$  and  $Z_{th}$  measurements (PCB FR4 area = 58 mm x 58 mm, PCB thickness = 1.6 mm, Cu thickness = 35  $\mu$ m, Copper areas: 0.26 cm<sup>2</sup>, 4 cm<sup>2</sup>).

Figure 28.  $R_{thj-amb}$  vs PCB copper area in open box free air condition

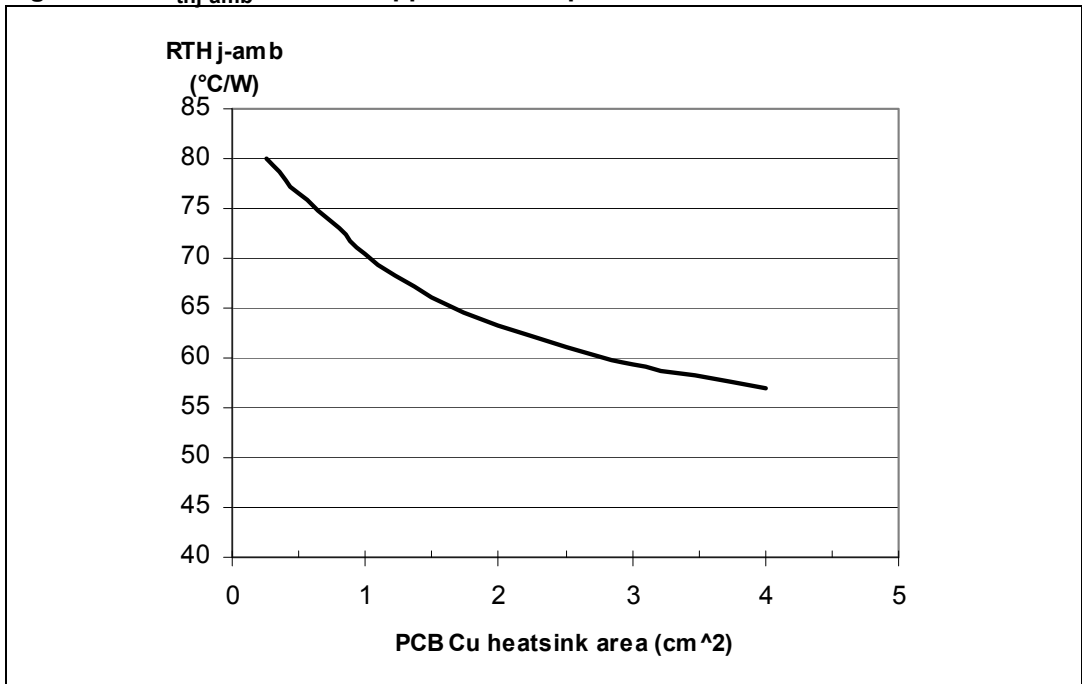
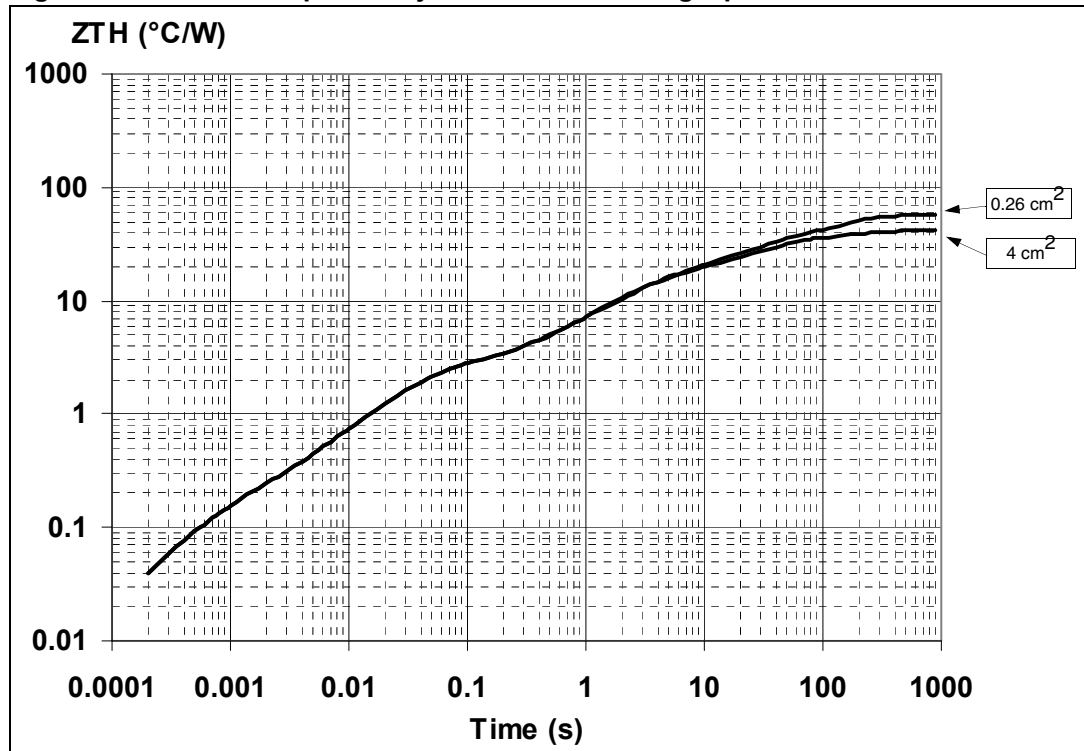


Figure 29. Thermal impedance junction ambient single pulse



Equation 3: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where  $\delta = t_p/T$

Figure 30. Thermal fitting model of a quad channel HSD in SO-16

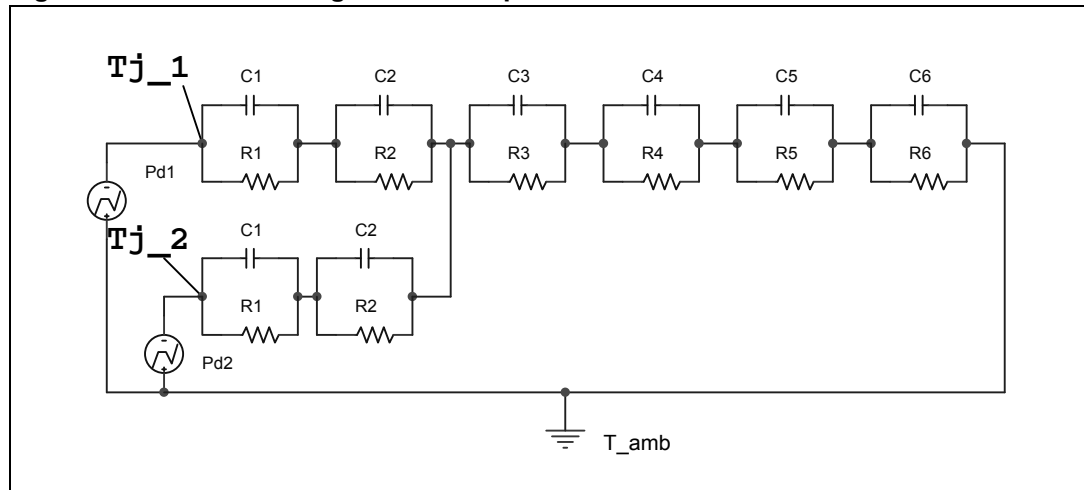


Table 16. Thermal parameters

| Area / island (cm <sup>2</sup> ) | 0.5    | 4  |
|----------------------------------|--------|----|
| R1 (°C/W)                        | 0.35   |    |
| R2 (°C/W)                        | 1.8    |    |
| R3 (°C/W)                        | 4.5    |    |
| R4 (°C/W)                        | 10     |    |
| R5 (°C/W)                        | 16     |    |
| R6 (°C/W)                        | 48     | 25 |
| C1 (W.s/°C)                      | 0.0001 |    |
| C2 (W.s/°C)                      | 7E-04  |    |
| C3 (W.s/°C)                      | 6E-03  |    |
| C4 (W.s/°C)                      | 0.2    |    |
| C5 (W.s/°C)                      | 0.7    |    |
| C6 (W.s/°C)                      | 2      | 4  |

## 5 Package and packing information

### 5.1 ECOPACK® packages

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com).

ECOPACK® is an ST trademark.

### 5.2 SO-16 package information

Figure 31. SO-16 package dimensions

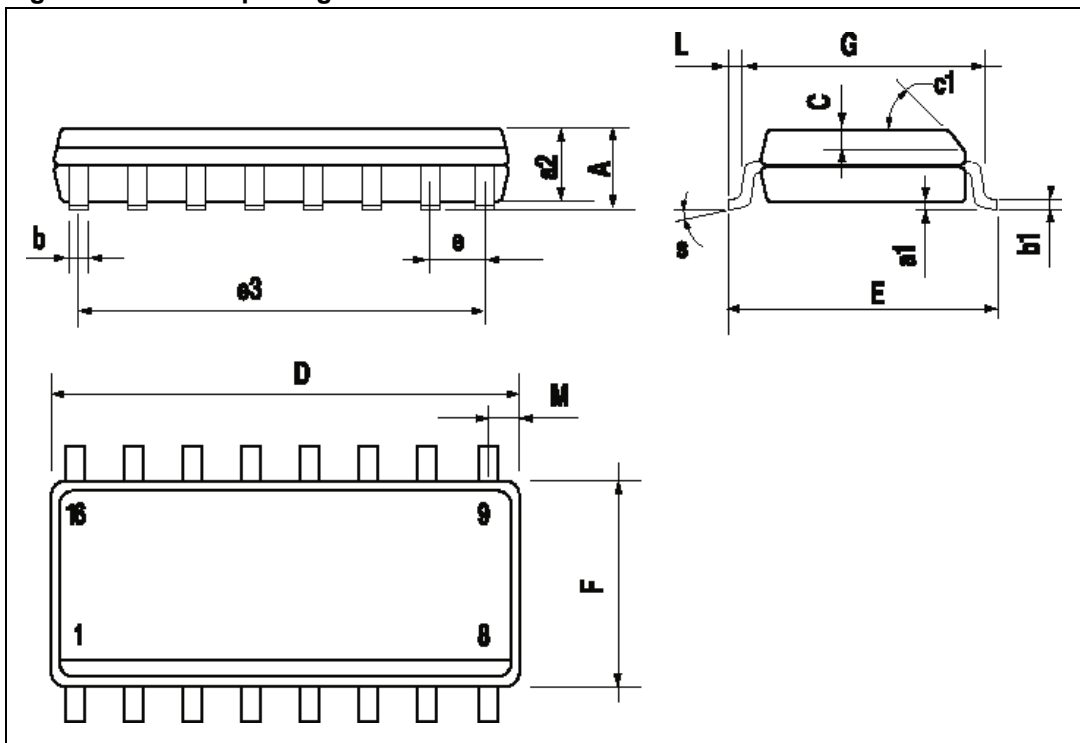




Table 17. SO-16 mechanical data

| DIM. | mm.        |      |      |
|------|------------|------|------|
|      | Min.       | Typ. | Max. |
| A    |            |      | 1.75 |
| a1   | 0.1        |      | 0.2  |
| a2   |            |      | 1.65 |
| b    | 0.35       |      | 0.46 |
| b1   | 0.19       |      | 0.25 |
| C    |            | 0.5  |      |
| c1   | 45° (typ.) |      |      |
| D    | 9.8        |      | 10   |
| E    | 5.8        |      | 6.2  |
| e    |            | 1.27 |      |
| e3   |            | 8.89 |      |
| F    | 3.8        |      | 4.0  |
| G    | 4.6        |      | 5.3  |
| L    | 0.5        |      | 1.27 |
| M    |            |      | 0.62 |
| S    |            |      | 8°   |

### 5.3 SO-16 packing information

Figure 32. SO-16 tube shipment (no suffix)

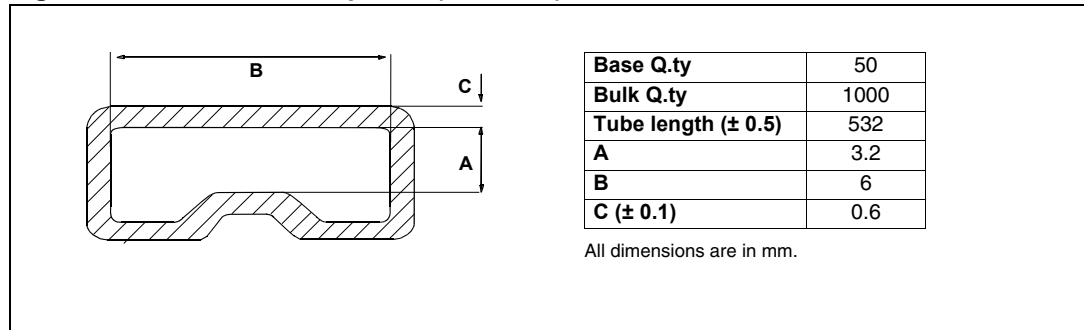
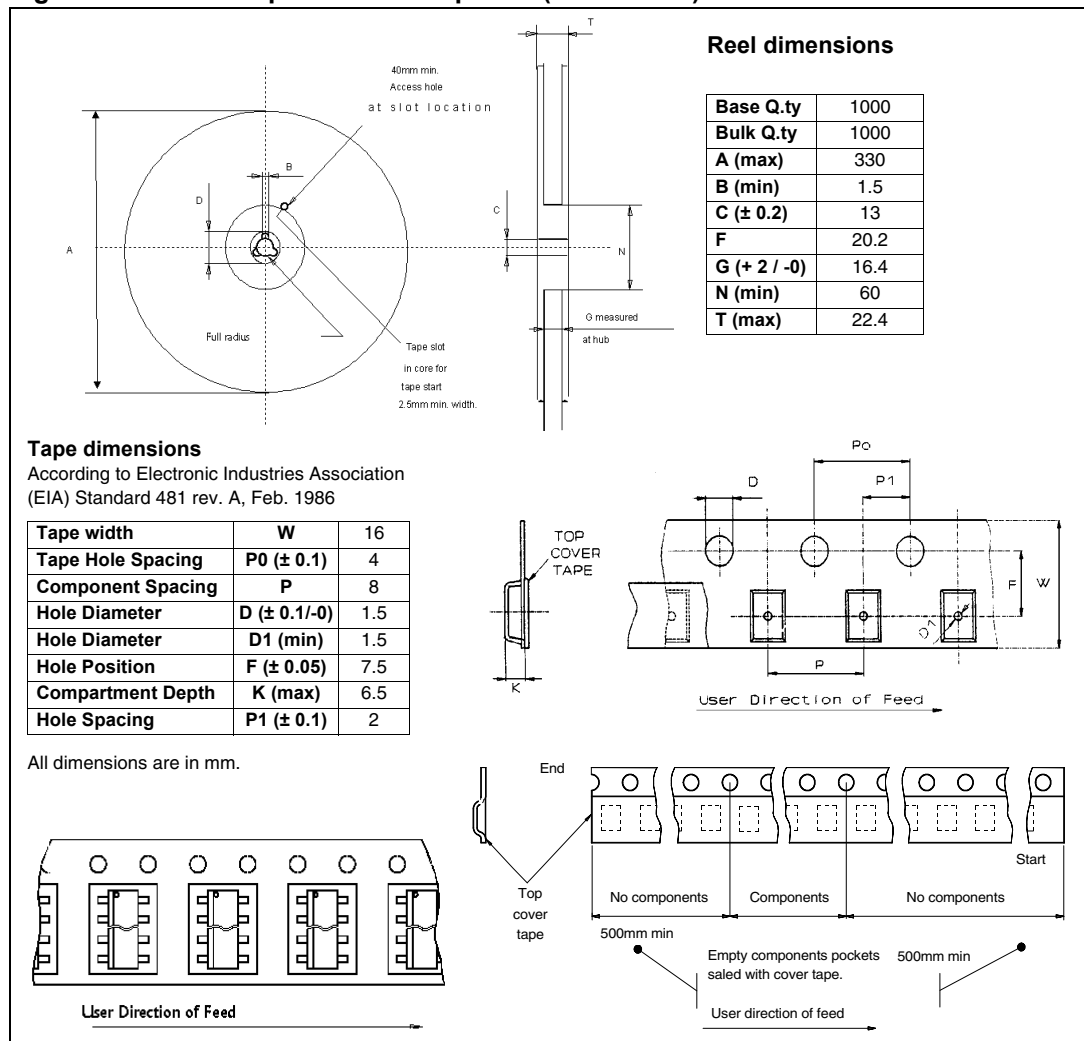


Figure 33. SO-16 tape and reel shipment (suffix "TR")



## 6 Revision history

**Table 18. Document revision history**

| Date        | Revision | Changes            |
|-------------|----------|--------------------|
| 20-Jul-2010 | 1        | Initial release.   |
| 19-Sep-2013 | 2        | Updated Disclaimer |